

DDS Advanced Tutorial

Best-Practice Data-Centric Programming with DDS

OMG Tech Meeting, Berlin 2013

19/06/2013

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Agenda

- DDS
 - Introduction
 - Architecture
 - Hands on
 - Common Use Cases
 - Best Practices
- Success Cases

Introduction and Background

Introduction: Everything is distributed

- Enterprise Internet
- Internet of Things
- Cloud Computing
- Industry 4.0
- ...



Next-generation systems needs:

- Scalability
- Integration & Evolution
- Robustness & Availability
- Performance
- Security

“Real World” Systems are integrated using a Data Model

- Grounded on the “physics” of the problem domain
 - Tied to the nature of the sensors and real objects in the system (vehicles, device types, ...)
- Provides governance across disparate teams & organizations
 - The “ N^2 ” integration problem is reduced to a “ N ” problem
- Increased decoupling from use-cases and components
 - Avoids over constraining applications
- Open, Evolvable, Platform-Independent
 - The use-cases, algorithms might change between missions or versions of the system

App

App

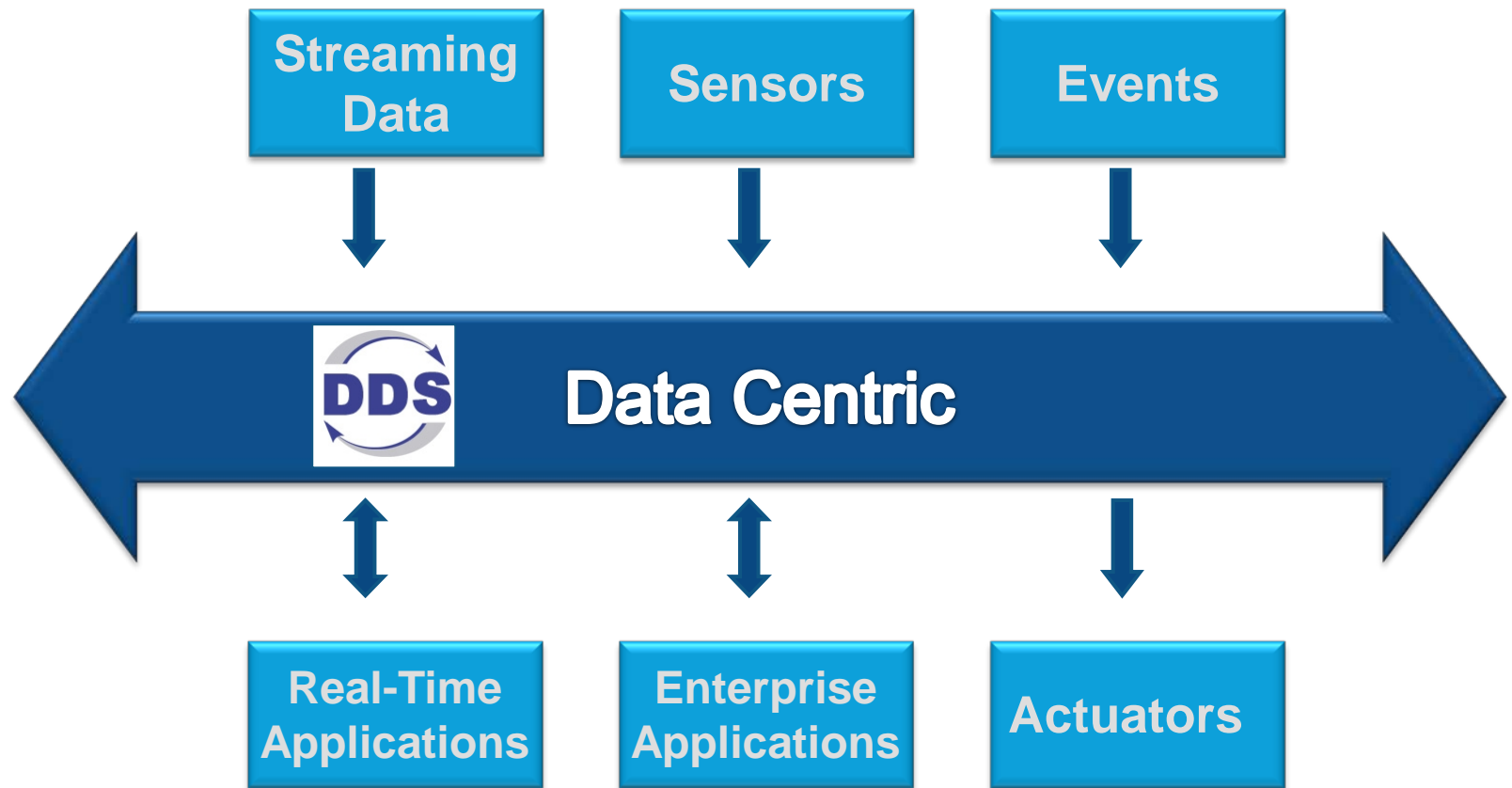
App

Realizing this data-model requires a middleware infrastructure

Challenge

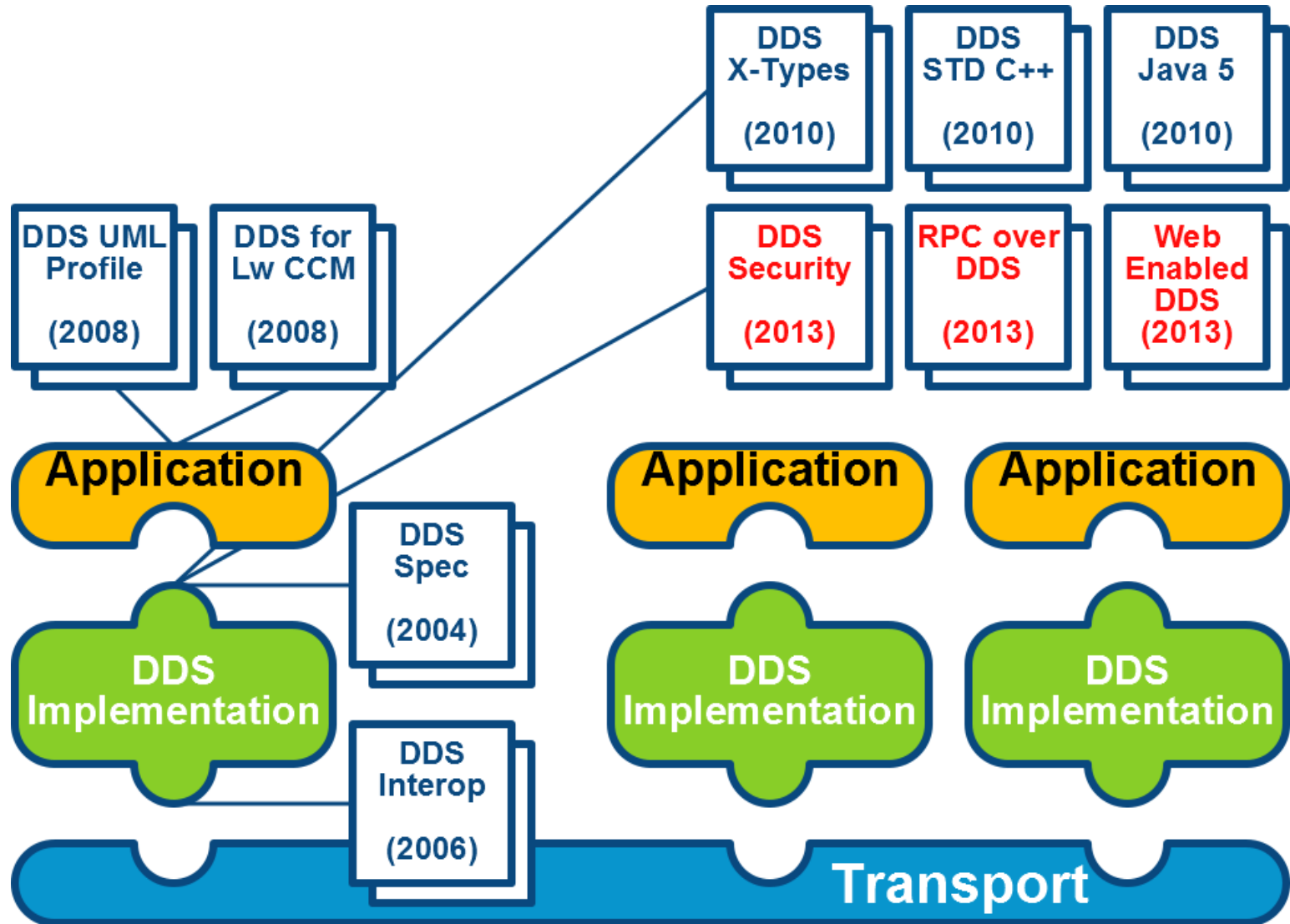
- Everything is connected, and we should enable communication between the different nodes.
- And this means:
 - Common protocols
 - Common Data Types
 - Known interfaces
 - Different QoS over different datalinks and performance requirements.
 - Different communications patterns.
 - Broad platform and programming language support.
 - Good Data Models!
 - ...

DDS: Standards-based Integration Infrastructure for Critical Applications



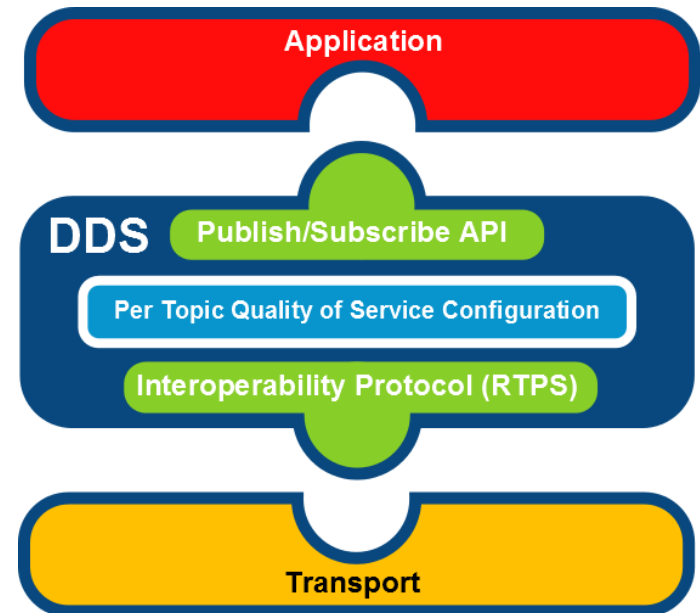


DDS Family of Specifications



Broad Adoption

- Vendor independent
 - API for **portability**
 - Wire protocol for **interoperability**
- Multiple implementations
 - 10 of API
 - 8 support RTPS
- Heterogeneous
 - C, C++, Java, .NET (C#, C++/CLI)
 - Linux, Windows, VxWorks, other embedded & real time
- Loosely coupled



DDS adopted by key programs in Europe

- *European Air Traffic Control*
 - *DDS proposed for interoperate ATC centers*
- *Spanish Army*
 - *DDS is mandated for C2 Interoperability (ethernet, radio & satellite)*
- *UK Generic Vehicle Architecture*
 - *Mandates DDS for vehicle comm.*
 - *Mandates DDS-RTPS for interop.*



US-DoD mandates DDS for data-distribution

- DISR (formerly JTA)
 - DoD Information Technology Standards Registry
- US Navy Open Architecture
- Army, OSD
 - UCS, Unmanned Vehicle Control
- SPAWAR NESI
 - *Net-centric Enterprise Solutions for Interoperability*
 - *Mandates DDS for Pub-Sub SOA*



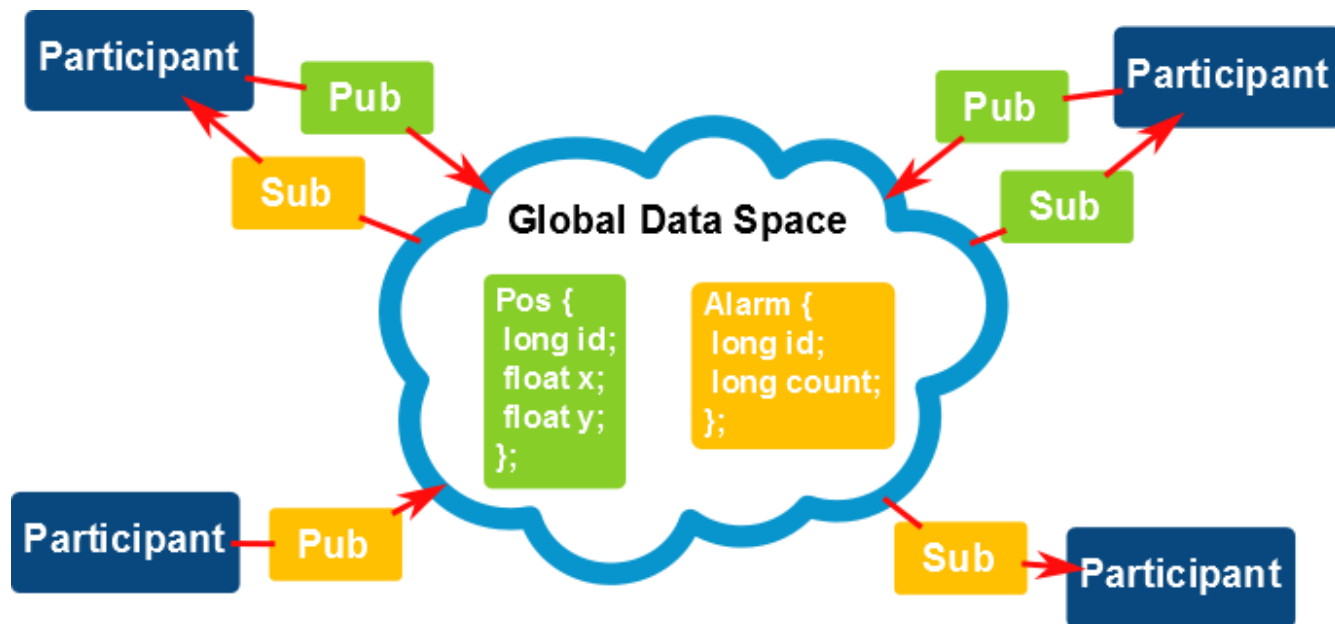
DDS Architecture

DDS

- DDS (Data Distribution Service for Real-Time Systems) is a OMG specification for a pub/sub data centric model (DCPS, Data Centric Publish/Subscribe) for Real-Time data comms in distributed systems.
- DDS is a networking middleware that:
 - Simplifies and Standardizes data flows in distributed real-time systems.
 - Provides robust comms (no single point of failure) and efficient (minimum latency)
 - Provides all kind of QoS to shape the data flows and deliver predictable results.

DDS

DDS uses the concept of **Global Data Space**. In this Space we define **topics** of data, and the **publishers** publish samples of these topics. DDS distributes these samples to all the **subscribers** of those topics. Any node can be a publisher or a subscriber.



Why DDS? Decoupled model

- **Space (location)**
 - Automatic Discovery ensures network topology independence
- **Redundancy:**
 - It is possible to configure redundant publishers and subscribers, primary/secondary and takeover schemas supported
- **Time:**
 - The reception of data does not need to be synchronous with the writing. A subscriber may, if so configured, receive data that was written even before the subscriber joined the network.
- **Platform:**
 - Applications do not have to worry about data representation, processor architecture, Operating System, or even programming language on the other side
- **Implementation:**
 - DDS Protocol is also an standard. Different implementations interoperate.

Why DDS? Fully configurable

Volatility

QoS Policy

DURABILITY

HISTORY

READER DATA LIFECYCLE

WRITER DATA LIFECYCLE

LIFESPAN

Infrastructure

ENTITY FACTORY

RESOURCE LIMITS

Delivery

RELIABILITY

TIME BASED FILTER

DEADLINE

CONTENT FILTERS

User QoS

QoS Policy

USER DATA

TOPIC DATA

GROUP DATA

Presentation

PARTITION

PRESENTATION

DESTINATION ORDER

Redundancy

OWNERSHIP

OWNERSHIP STRENGTH

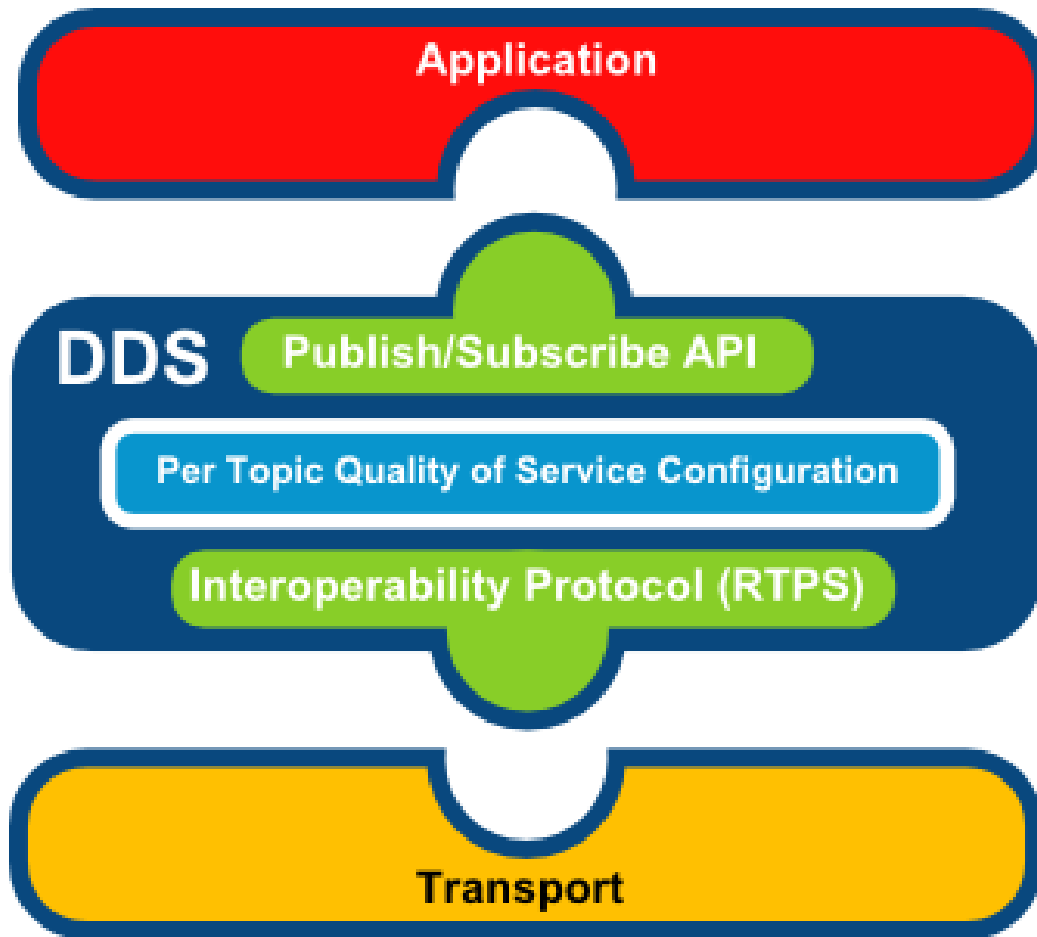
LIVELINESS

Transport

LATENCY BUDGET

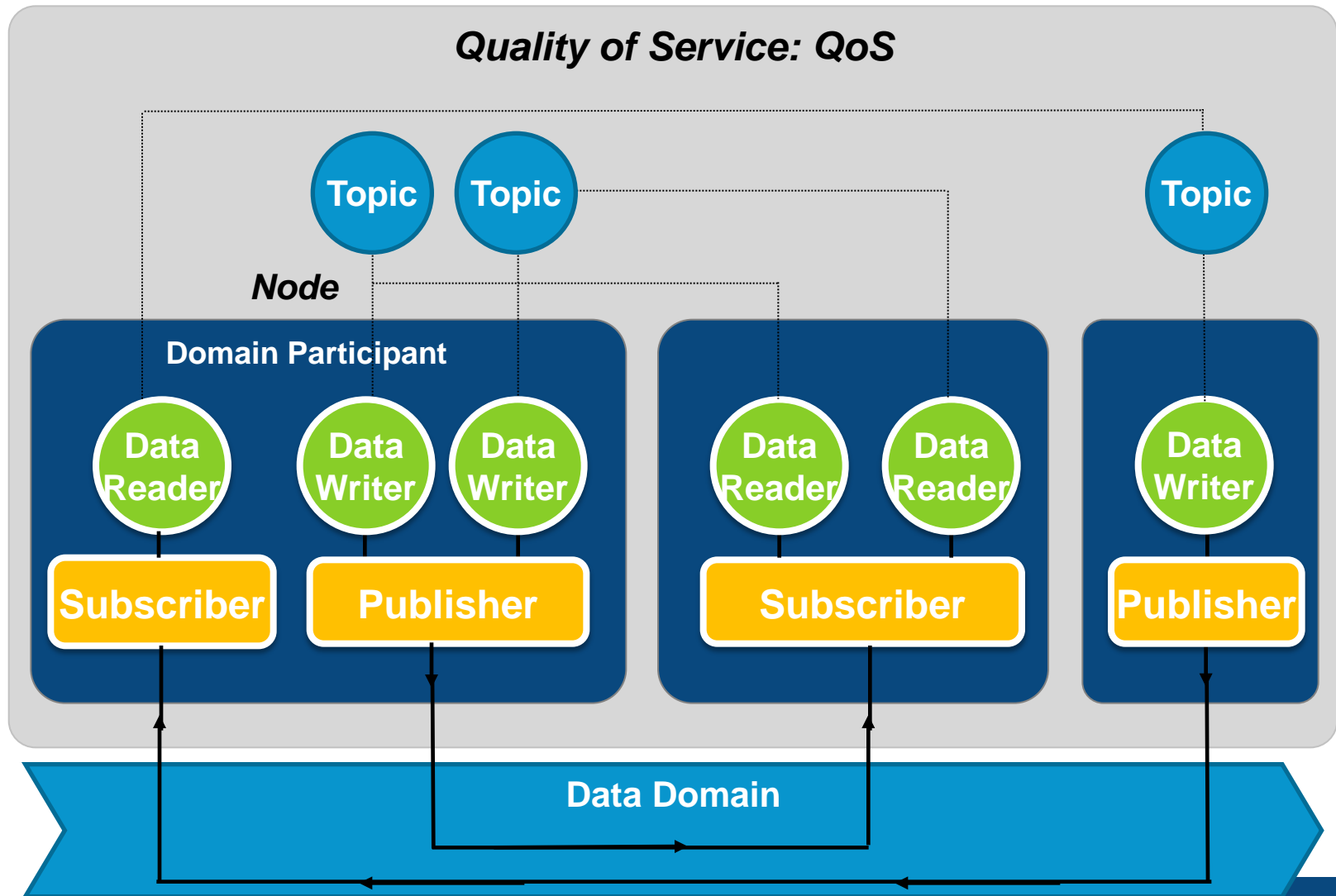
TRANSPORT PRIORITY

DDS Infrastructure



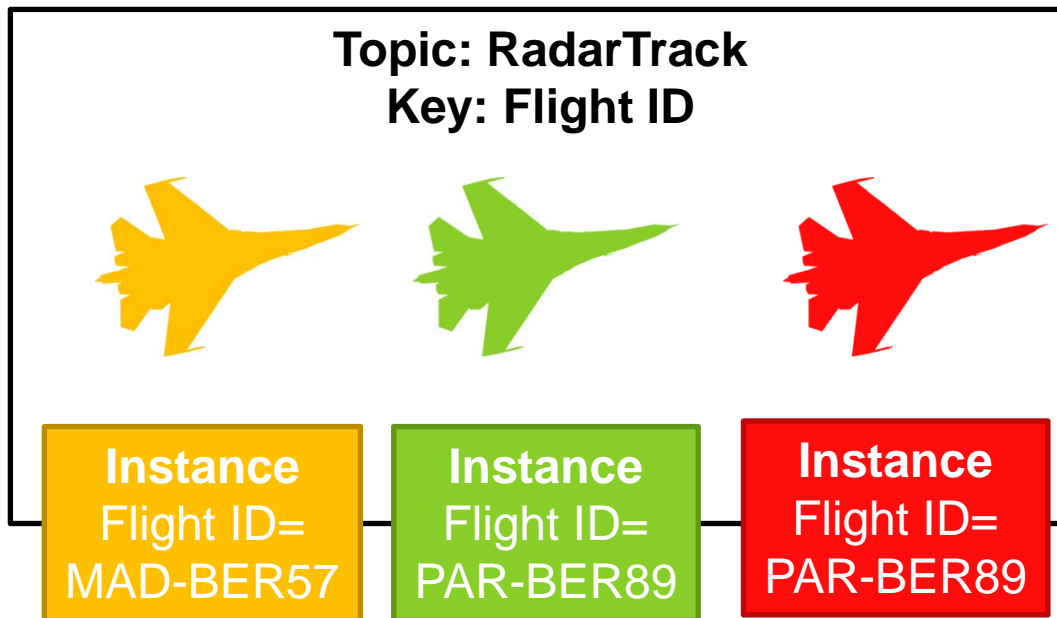
- Standard API for portability.
- RTPS can be implemented over any transport
- No central Broker/Service
- Different Comm channel per topic

The DDS Model



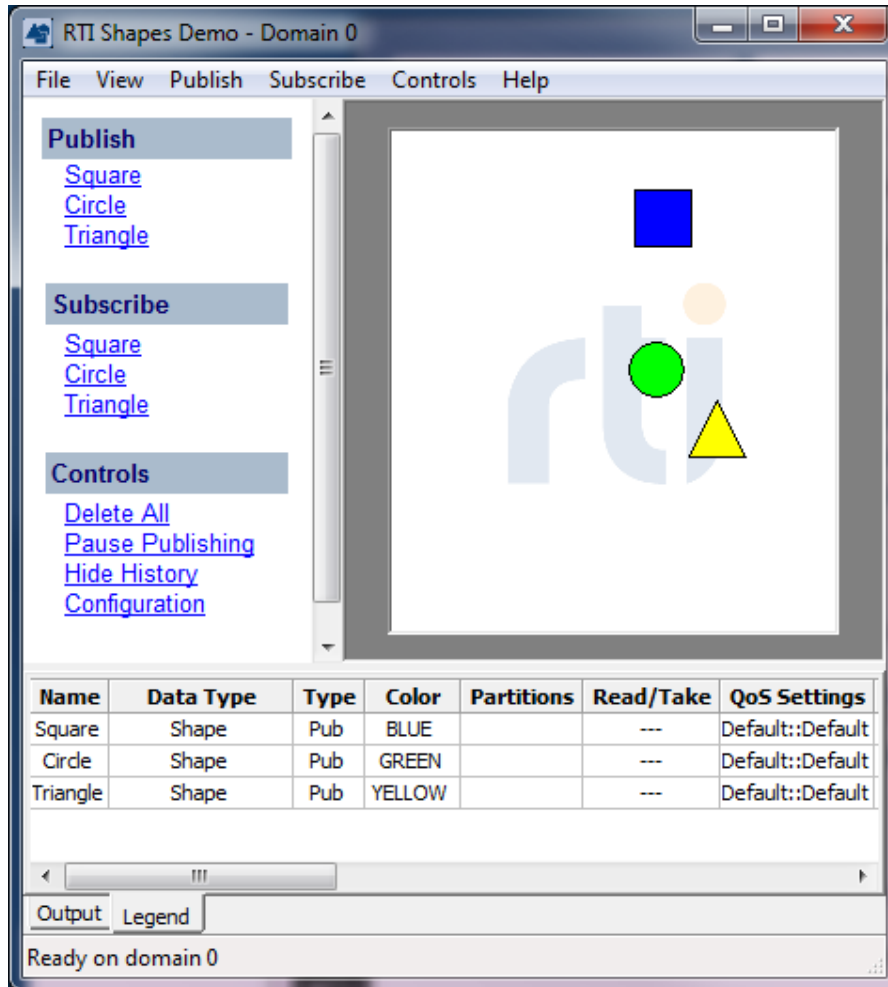
Topics, Instances and Keys

- **Topic**: A set of similar objects, sharing a common Data Type
- **Instance**: A particular object of the set
- **Key**: Fields of the Data Type to identify an object.



Qos
Applied by
Instance.

Demo

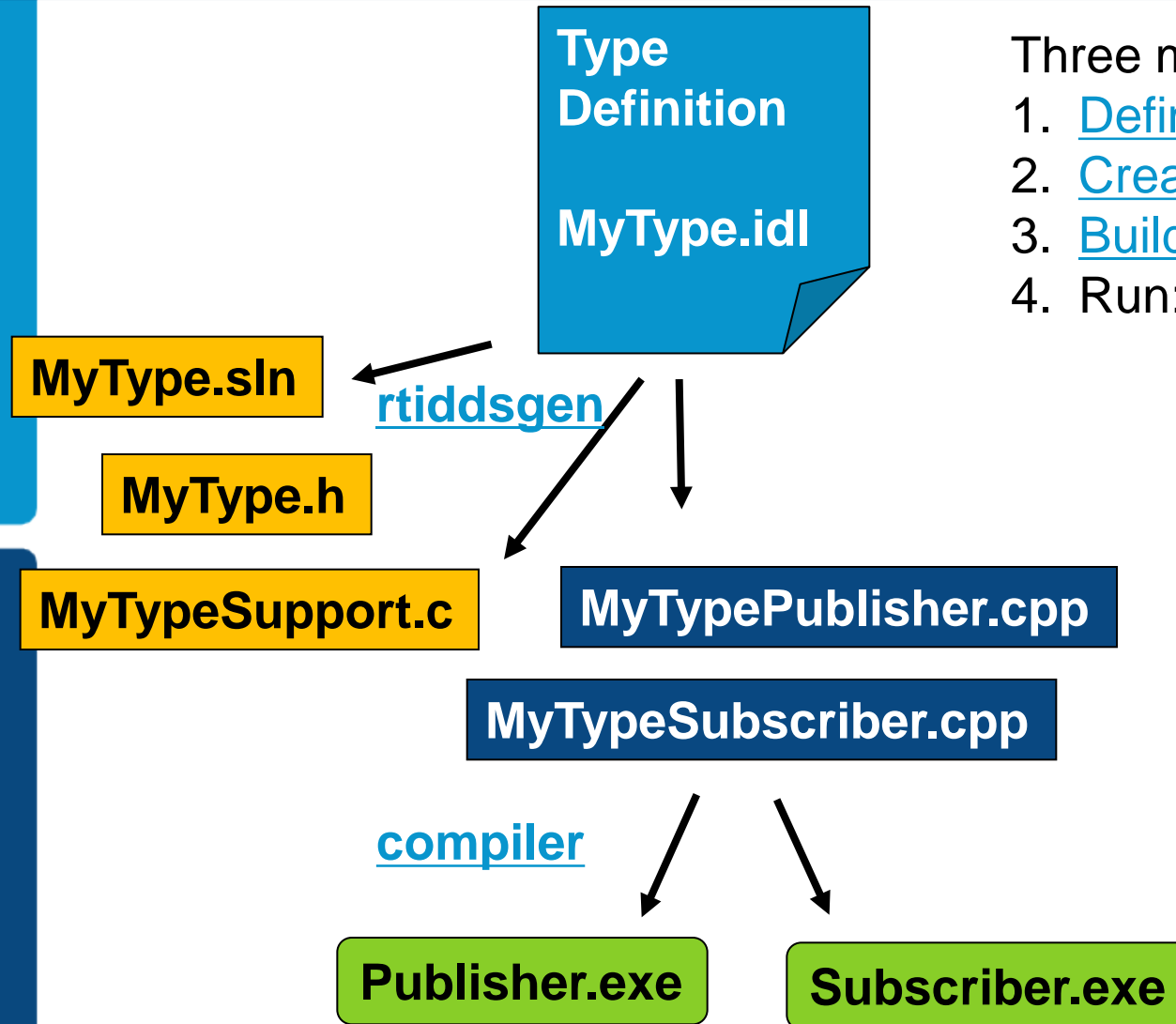


```
const long STR_LEN=24;
struct ShapeType {
    string<MSG_LEN> color; //@key
    long x;
    long y;
    long shapesize;
};
```

- 3 **Topics**:
 - Square, Circle, Triangle
- Color is the **KEY**

Hands On: A Hello World

Hands-on Example (C++)



Three minutes to a running app!!

1. [Define your data](#)
2. [Create your project](#)
3. [Build](#)
4. Run: [publisher subscriber](#)

Aux:

[File Browser](#)
[Console](#)
[Delete Files](#)
[rtiddsspy](#)

Example #1 - Hello World

We will use this data-type :

```
const long MSG_LEN=256;
struct HelloMsg {
    string<MSG_LEN> user; //@key
    string<MSG_LEN> msg;
};
```

Side Note: IDL vs. XML



The same data-type can also be described in XML.
This is part of the DDS X-Types specification

```
<const name="MSG_LEN" type="long" value="256"/>
<struct name="HelloMsg">
  <member name="user" key="true" type="string"
    stringMaxLength="MSG_LEN"/>
  <member name="msg" type="string"
    stringMaxLength="MSG_LEN" />
</struct>
```


Generate type support (for C++) [Windows]

```
rtiddsgen HelloMsg.idl -language C++ -example x64Win64VS2010\  
-replace -ppDisable
```

- Look at the directory you should see:
 - HelloMsg-64-vs2010.sln
 - And Several other files...
- Open the Solution:
HelloMsgPublisher.cxx
- Compile from visual studio

Generate type support (for C++) [Linux]

```
rtiddsgen HelloMsg.idl -language C++ -example i86Linux2.6gcc4.4.3\  
-replace -ppDisable
```

- Look at the directory you should see:
 - makefile_hello_i86Linux2.6gcc4.4.3
 - And Several other files...
- Open the source files:
 - HelloMsgPublisher.cxx
 - HelloMsgSubscriber.cxx
- Compile:
 - make -f makefile_hello_i86Linux2.6gcc4.4.3

Generate type support (for Java - Linux)

```
rtiddsgen HelloMsg.idl -language Java -example i86Linux2.6gcc4.4.3jdk\  
-replace -ppDisable
```

- Look at the directory you should see:
 - makefile_hello_i86Linux2.6gcc4.4.3jdk
 - And Several other files...
 - Look at HelloMsgPublisher.java
 - Look at HelloMsgSubscriber.java
- You can use the makefile to build and the Java programs:
gmake -f makefile_hello_i86Win32jdk

Execute the program [Windows]

- C++:
 - On one window run:
 - `objs\i86Win32VS2005\HelloMsgPublisher.exe`
 - On another window run:
 - `objs\i86Win32VS2005\HelloMsgSubscriber.exe`
- Java
 - On one window run:
 - `gmake -f makefile_hello_i86Win32jdk HelloMsgPublisher`
 - On another window run:
 - `gmake -f makefile_hello_i86Win32jdk HelloMsgSubscriber`
- You should see the subscribers getting an empty string...

Execute the program [Linux]

- C++:
 - On one window run:
 - `objs/i86Linux2.6gcc4.4.3/HelloMsgPublisher.exe`
 - On another window run:
 - `objs/i86Linux2.6gcc4.4.3/HelloMsgSubscriber.exe`
- Java
 - On one window run:
 - `gmake -f makefile_hello_i86Linux2.6gcc4.4.3jdk HelloMsgPublisher`
 - On another window run:
 - `gmake -f makefile_hello_i86Linux2.6gcc4.4.3jdk HelloMsgSubscriber`
- You should see the subscribers getting an empty string...

Writing some data

- Modify `HelloMsg_publisher.cxx`:

```
/* Main loop */
for (count=0; (sample_count == 0) || (count < sample_count); ++count) {

    printf("Writing HelloMsg, count %d\n", count);

    /* Modify the data to be sent here */
    sprintf(instance->user,"%s","eProxima");
    sprintf(instance->msg,"Writing HelloMsg, user eProxima, count %d",count);
    retcode = HelloMsg_writer->write(*instance, instance_handle);
}
```

Writing some data (performance tip)

- Modify `HelloMsg_publisher.cxx`:

```
/* For a data type that has a key, if the same instance is going to be
   written multiple times, initialize the key here
   and register the keyed instance prior to writing */
```

```
sprintf(instance->user,"%s","eProsima");
```

```
instance_handle = HelloMsg_writer->register_instance(*instance);
```

```
/* Main loop */
```

```
for (count=0; (sample_count == 0) || (count < sample_count); ++count) {
```

```
    printf("Writing HelloMsg, count %d\n", count);
```

```
    /* Modify the data to be sent here */
```

```
sprintf(instance->msg,"Writing HelloMsg, user eProsima, count %d",count);
```

```
retcode = HelloMsg_writer->write(*instance, instance_handle);
```

Example: Publication

```
// Entities creation
DomainParticipant participant =
    TheParticipantFactory->create_participant(
        domain_id, participant_qos, participant_listener);

Publisher publisher = domain->create_publisher(
    publisher_qos, publisher_listener);

Topic topic = domain->create_topic(
    "MyTopic", "MyType", topic_qos, topic_listener);

DataWriter writer = publisher->create_datawriter(
    topic, writer_qos, writer_listener);

MyTypeDataWriter twriter = MyTypeDataWriter::narrow(writer);

MyType my_instance;
twriter->write(my_instance);
```


Example: Subscription

```
// Entities creation
Subscriber subscriber = domain->create_subscriber(
    subscriber_qos, subscriber_listener);

Topic topic = domain->create_topic(
    "MyTopic", "MyType",
    topic_qos, topic_listener);

DataReader reader = subscriber->create_datareader(
    topic, reader_qos, reader_listener);

// Use listener-based or wait-based access
```

How to Get Data? (Listener-Based)

```
// Listener code
MyListener::on_data_available( DataReader reader )
{
    MyTypeSeq received_data;
    SampleInfoSeq sample_info;
    MyTypeDataReader treader = TextDataReader::narrow(reader);

    treader->take( &received_data, &sample_info, ...)
    // Use received_data
    printf("Got: %s\n", received_data[0]->contents);
}
```

How to Get Data? (WaitSet-Based)

```
// Creation of condition and attachement
Condition foo_condition =
    treader->create_readcondition(...);
waitset->add_condition(foo_condition);

// Wait
ConditionSeq active_conditions;
waitset->wait(&active_conditions, timeout);

// Wait returns when there is data (or timeout)
MyTypeSeq received_data;
SampleInfoSeq sample_info;

treader->take_w_condition
(&received_data,
 &sample_info,
 foo_condition);

// Use received_data
printf("Got: %s\n", received_data[0]->contents);
```

Listeners, Conditions & WaitSets

Middleware must notify user application of relevant events:

- Arrival of data
- But also:
 - QoS violations
 - Discovery of relevant entities
- These events may be detected asynchronously by the middleware
 - ... Same issue arises with POSIX signals

DDS allows the application to choose:

- Either to get notified asynchronously using a **Listener**
- Or to wait synchronously using a **WaitSet**

Both approaches are unified using STATUS changes

Status Changes

DDS defines

- A set of enumerated STATUS
- The statuses relevant to each kind of DDS Entity

DDS entities maintain a value for each STATUS

STATUS	Entity
INCONSISTENT_TOPIC	Topic
DATA_ON_READERS	Subscriber
LIVELINESS_CHANGED	DataReader
REQUESTED_DEADLINE_MISSED	DataReader
REQUESTED_INCOMPATIBLE_QOS	DataReader
DATA_AVAILABLE	DataReader
SAMPLE_LOST	DataReader
SUBSCRIPTION_MATCH	DataReader
LIVELINESS_LOST	DataWriter
OFFERED_INCOMPATIBLE_QOS	DataWriter
PUBLICATION_MATCH	DataWriter

```
struct LivelinessChangedStatus
{
    long active_count;
    long inactive_count;
    long active_count_change;
    long inactive_count_change;
}
```

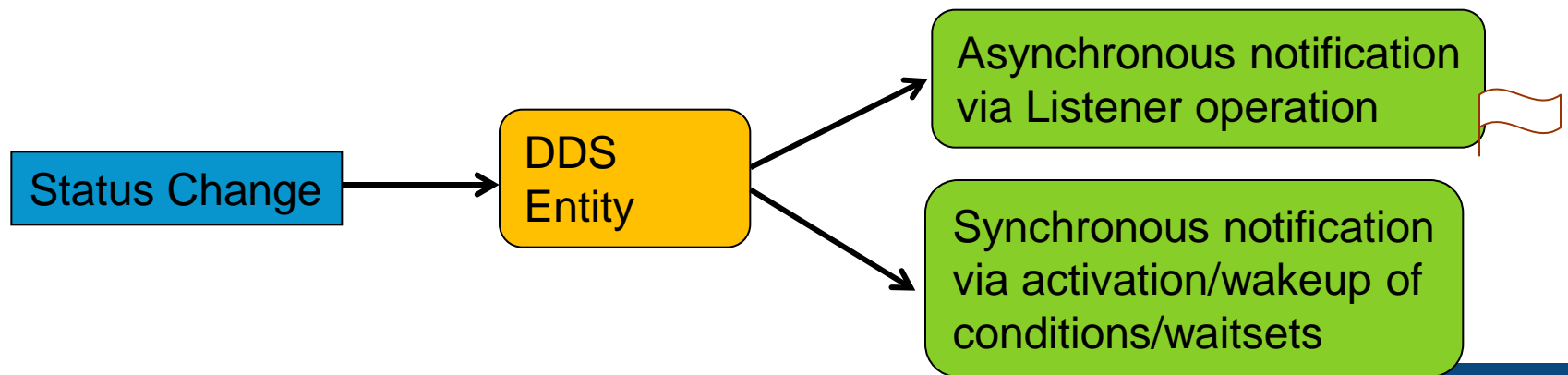
Listeners, Conditions and Statuses

- A DDS Entity is associated with:
 - A listener of the proper kind (if attached)
 - A StatusCondition (if activated)
- The Listener for an Entity has a separate operation for each of the relevant statuses

STATUS	Entity	Listener operation
INCONSISTENT_TOPIC	Topic	on_inconsistent_topic
DATA_ON_READERS	Subscriber	on_data_on_readers
LIVELINESS_CHANGED	DataReader	on_liveliness_changed
REQUESTED_DEADLINE_MISSED	DataReader	on_requested_deadline_missed
RUQUESTED_INCOMPATIBLE_QOS	DataReader	on_requested_incompatible_qos
DATA_AVAILABLE	DataReader	on_data_available
SAMPLE_LOST	DataReader	on_sample_lost
SUBSCRIPTION_MATCH	DataReader	on_subscription_match
LIVELINESS_LOST	DataWriter	on_liveliness_lost
OFFERED_INCOMPATIBLE_QOS	DataWriter	on_offered_incompatible_qos
PUBLICATION_MATCH	DataWriter	on_publication_match

Listeners & Condition duality

- A StatusCondition can be selectively activated to respond to any subset of the statuses
- An application can wait changes in sets of StatusConditions using a WaitSet
- Each time the value of a STATUS changes DDS
 - Calls the corresponding Listener operation
 - Wakes up any threads waiting on a related status change



Example #2 - Command-Line Shapes

We will use this data-type :

```
const long STR_LEN=24;
struct ShapeType {
    string<MSG_LEN> color; //@key
    long x;
    long y;
    long shapesize;
};
```


Example #2 - Command-Line Shapes

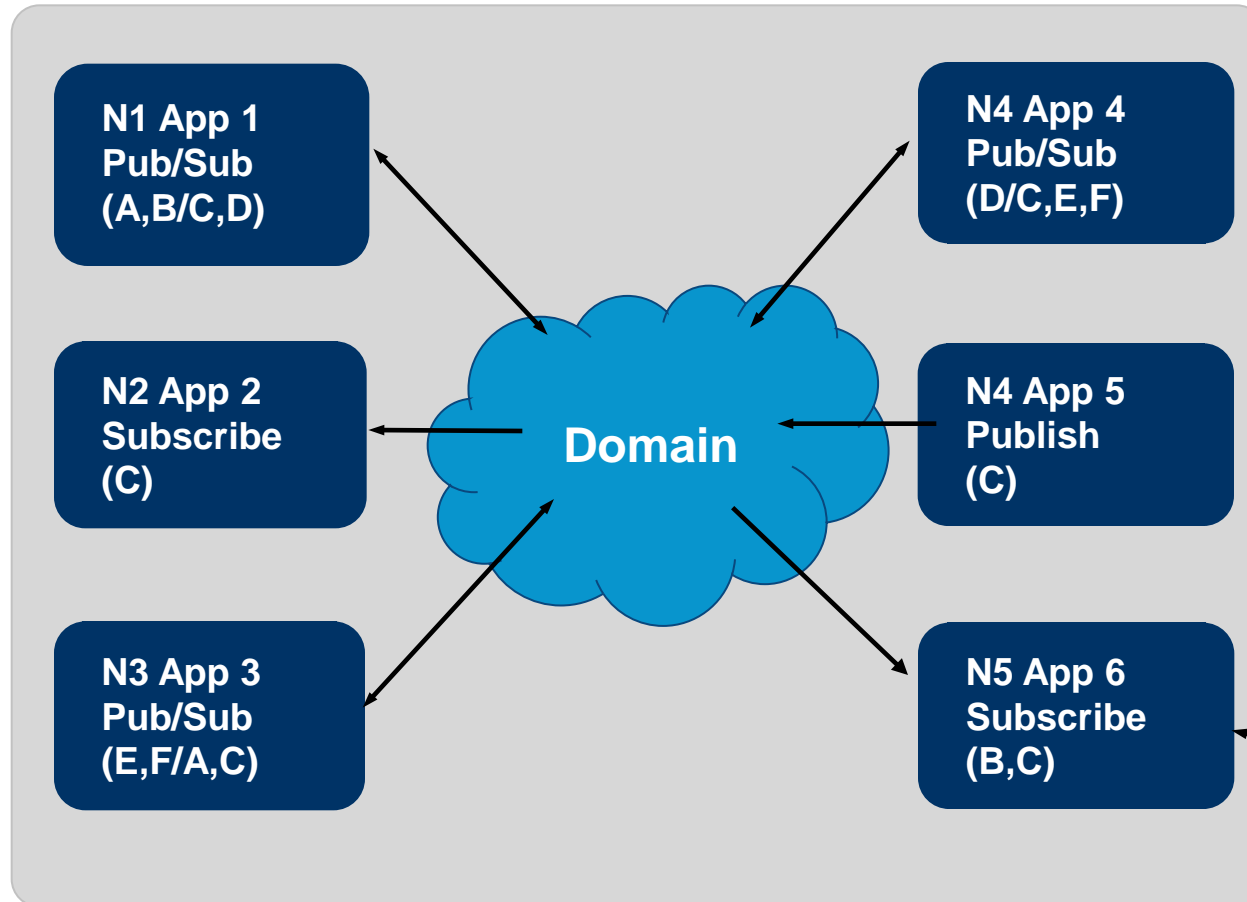
- Edit the publisher and subscriber
 - Change the TopicName to “Square” (or “Circle” or “Triangle”)
- Change the publisher to do something interesting
 - Use colors such as “GREEN” “RED” “YELLOW”
 - Keep the ‘x’ and ‘y’ between 0 and 260
 - Keep the ‘shapesize’ between 0 and 80

Using DDS: Common Use Cases

Common use cases

1. Isolating Subsystems
2. Detecting presence of applications
3. Discovering who is publishing/subscribing what
4. Publishing data that outlives its source
5. Keeping a “last-value” cache of objects
6. Monitoring and detecting the health of application elements
7. Building a highly-available system
8. Limiting data-rates
9. Controlling data received by interest set

1. Isolating Subsystems: Domain and Domain Participants

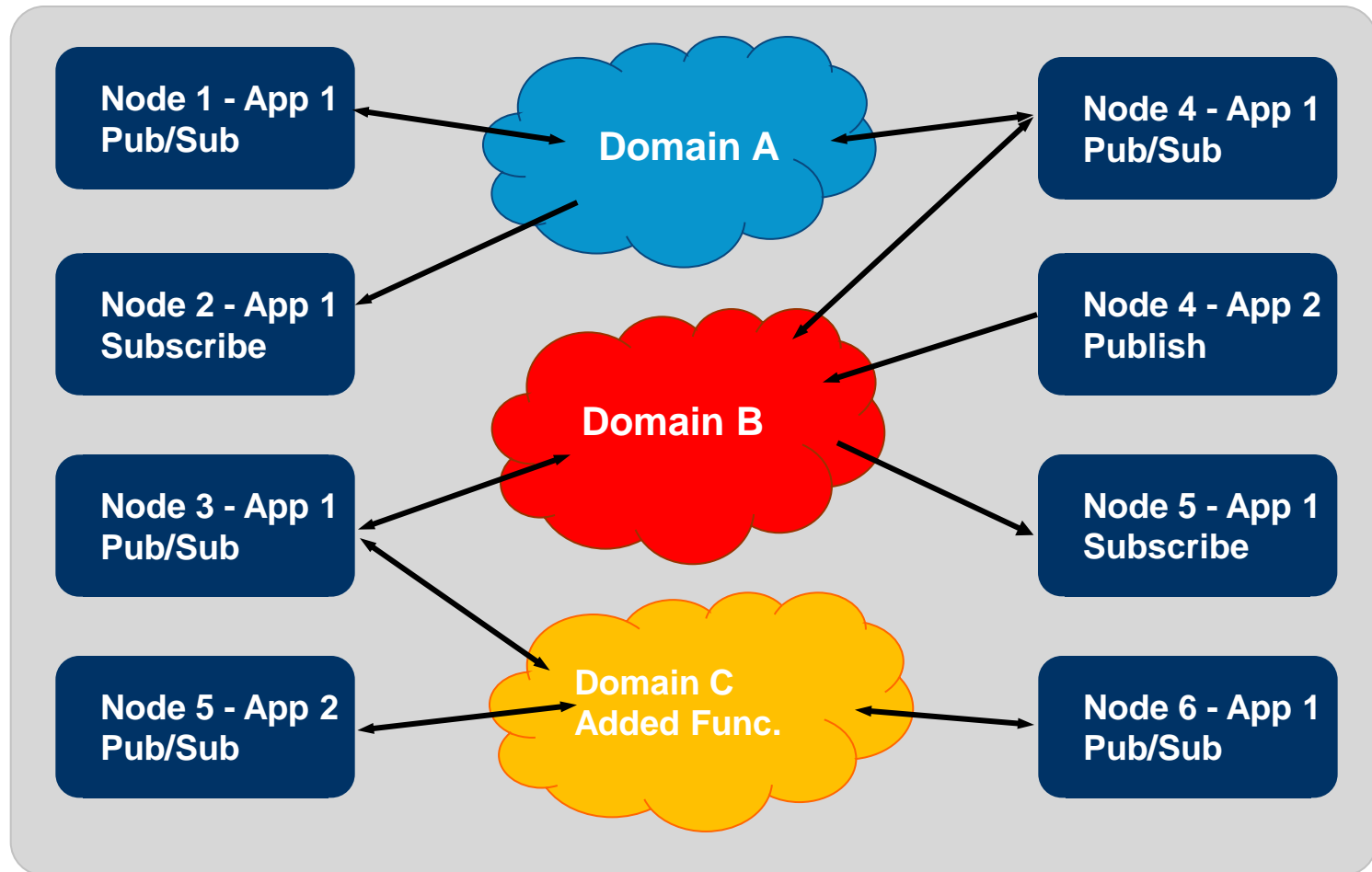


Single 'Domain' System

- Container for applications that want to communicate
- Applications can join or leave a domain in any order
- New Applications are “Auto-Discovered”
- An application that has joined a domain is also called a “Domain Participant”

1. Isolating Subsystems: Domain and Domain Participants

Using Multiple domains for Scalability, Modularity & Isolation



2. Detecting presence of applications

DDS builtin Discovery Service

- DDS provides the means for an application to discover the presence of other participants on the Domain
 - The Topic “DCPSParticipants” can be read as a regular Topic to see when DomainParticipants join and leave the network
- Applications can also include meta-data that is sent along by DDS discovery

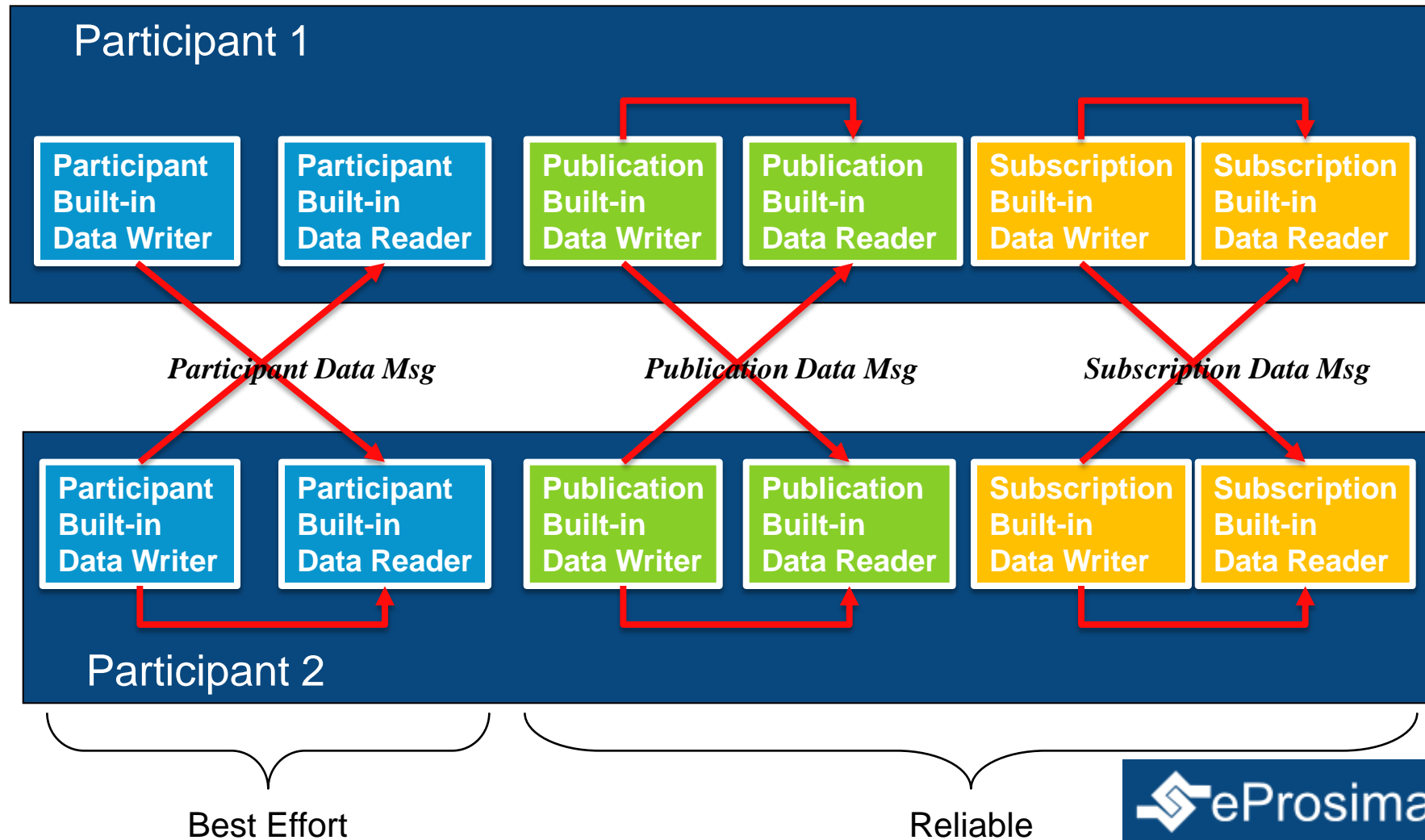
[shapes_demo](#)

[discovery_in_excel](#)

2. Discovery: How it works

- DDSI Spec Standardized the default mechanism
- Two phase-Discovery
 - 1. Simple Participant Discovery Protocol (SPDP)
 - Best Effort
 - Participant Presence Announcements
 - 2. Simple Endpoint Discovery Protocol (SEDP)
 - Reliable
 - EndPoint information (Publications, Subscriptions, Topics) sent between the different participants

2. Discovery: How it works



3. Discovering who is publishing/subscribing DDS builtin Discovery Service

- DDS provides the means for an application to discover all the other DDS Entities in the Domain
 - The Topics “DCPSPublications”, “DCPSSubscriptions”, “DCPSTopics”, and “DCPSParticipants” be read to observe the other entities in the domain

[shapes_demo](#)

[Analyzer](#)

Example: Accessing discovery information

```
reader = participant
    ->get_builtin_subscriber()
    ->lookup_datareader("DCPSSubscription");

reader_listener = new DiscoveryListener();
reader->set_listener(reader_listener);
```

Example: Displaying discovery information

```
DDS_SubscriptionBuiltinTopicData* subscriptionData =  
    DDSSubscriptionBuiltinTopicDataTypeSupport::create_data();  
DDS_SampleInfo *info = new DDS_SampleInfo();  
  
...  
  
do {  
    retcode = subscriptionReader  
        ->take_next_sample( *subscriptionData, *info);  
  
    DDSSubscriptionBuiltinTopicDataTypeSupport  
        ::print_data (subscriptionData);  
}  
while ( retcode != DDS_RETCODE_NO_DATA );
```

[shapes_demo](#)

[Discovery Example](#)

4. Publishing data that outlives its source: DDS DURABILITY QoS

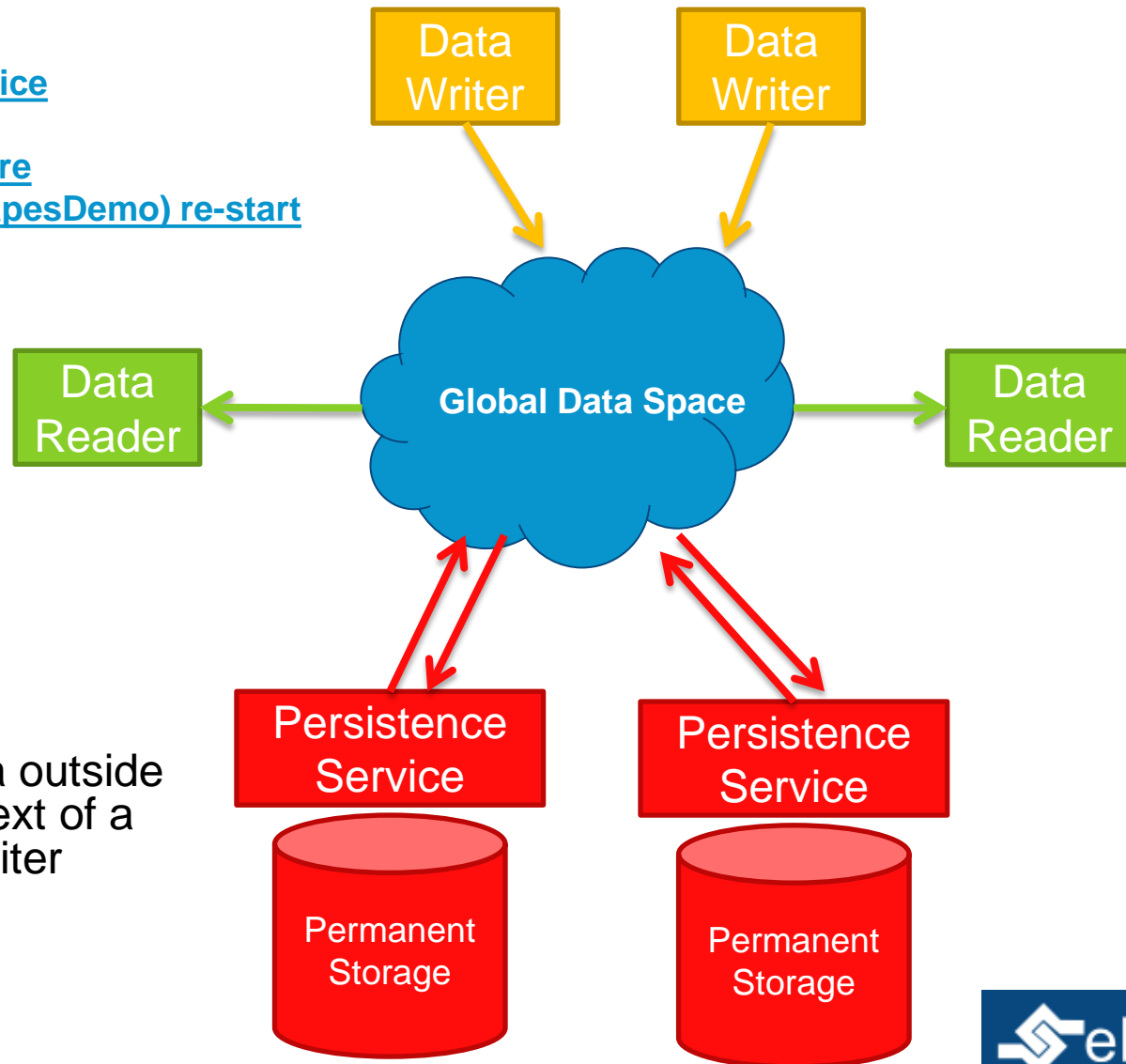
DURABILITY QoS can be set to:

- VOLATILE -- No durability (default)
- TRANSIENT_LOCAL
 - Durability provided by the DataWriter
 - Late joiners will get data as long as writer is still present
- TRANSIENT
 - Durability provided by external “persistence” service
 - Late joiners will get data as long as persistence is still present
- PERSISTENT
 - Durability provided by external “persistence” service
 - Persistence service must store/sync state to permanent storage
 - Persistence service recover state on re-start
 - Late joiners will get data even if persistence service crashes and re-starts

4. Publishing data that outlives its source: Persistence Service

Demo:

1. [PersistenceService](#)
2. [ShapesDemo](#)
3. [Application failure](#)
4. [Application \(ShapesDemo\) re-start](#)



Persists data outside
of the context of a
DataWriter

Persistence Demo

- Run persistence service:
 - Config: defaultDisk -- from RTI_PERSISTENCE_SERVICE
- Run Shapes demo
 - Persistence Qos profile
 - Publish
 - Kill with process explorer (kill process)
- Run Shapes demo
 - Persistence Qos profile
 - Subscribe

5. Keeping a “Last value” cache

- A last-value cache is already built-in into every Writer in the system
 - Can used in combination with a Durable Writer
- A late joiner will automatically initialize to the last value
- Last value cache can be configure with history depth greater than 1
- The Persistence Service can be used to provide a last value cache for durable data

QoS: History – Last x or All

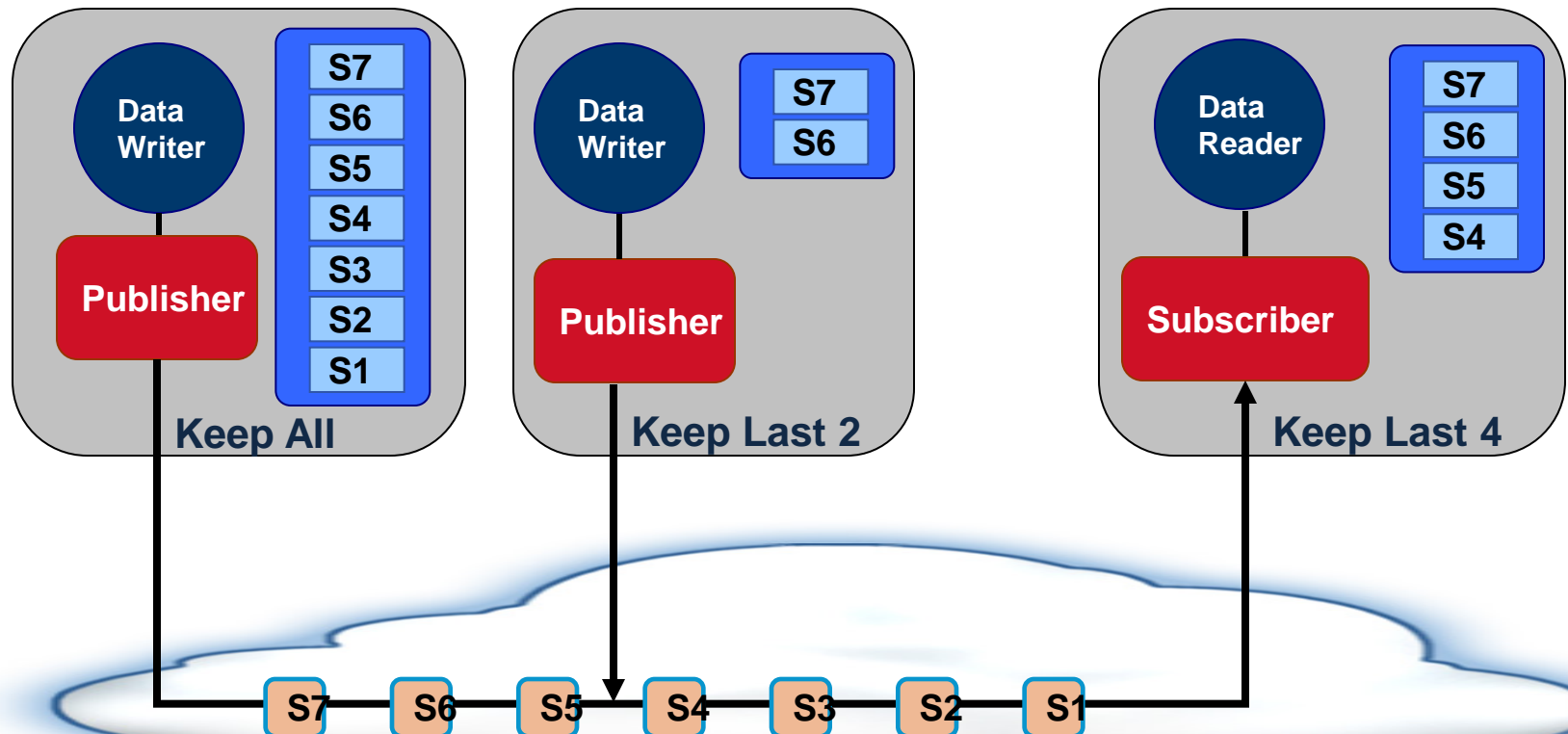
KEEP_ALL:

Publisher: keep all until delivered

Subscriber: keep each sample until the application processes that instance

KEEP_LAST: “depth” integer for the number of samples to keep at any one time

[demo_history](#)



5. Monitoring the health of applications: Liveliness QoS – Classic watchdog/deadman switch

- DDS can monitor the presence, health and activity of DDS Entities (Participant, Reader, Writer)
- Use Liveliness QoS with settings
 - AUTOMATIC
 - MANUAL_BY_PARTICIPANT
 - MANUAL_BY_TOPIC
- This is a request-offered QoS
- Answers the question: “Is no news good news?”

QoS: Liveliness: Type and Duration

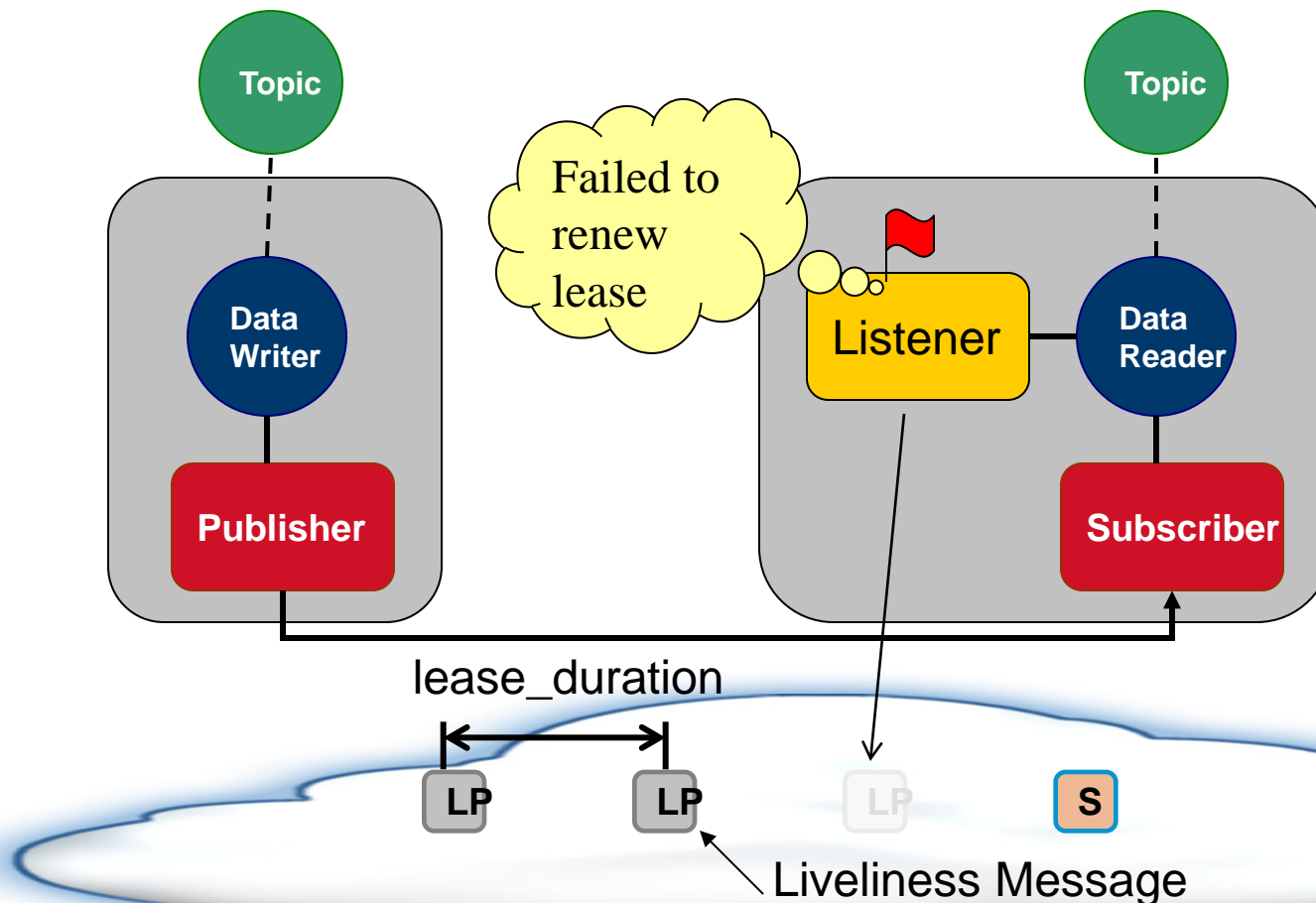
[liveliness_example](#)

Type: Controls who is responsible for issues of 'liveliness packets'

AUTOMATIC = Infrastructure Managed

MANUAL = Application Managed

[kill_apps](#)

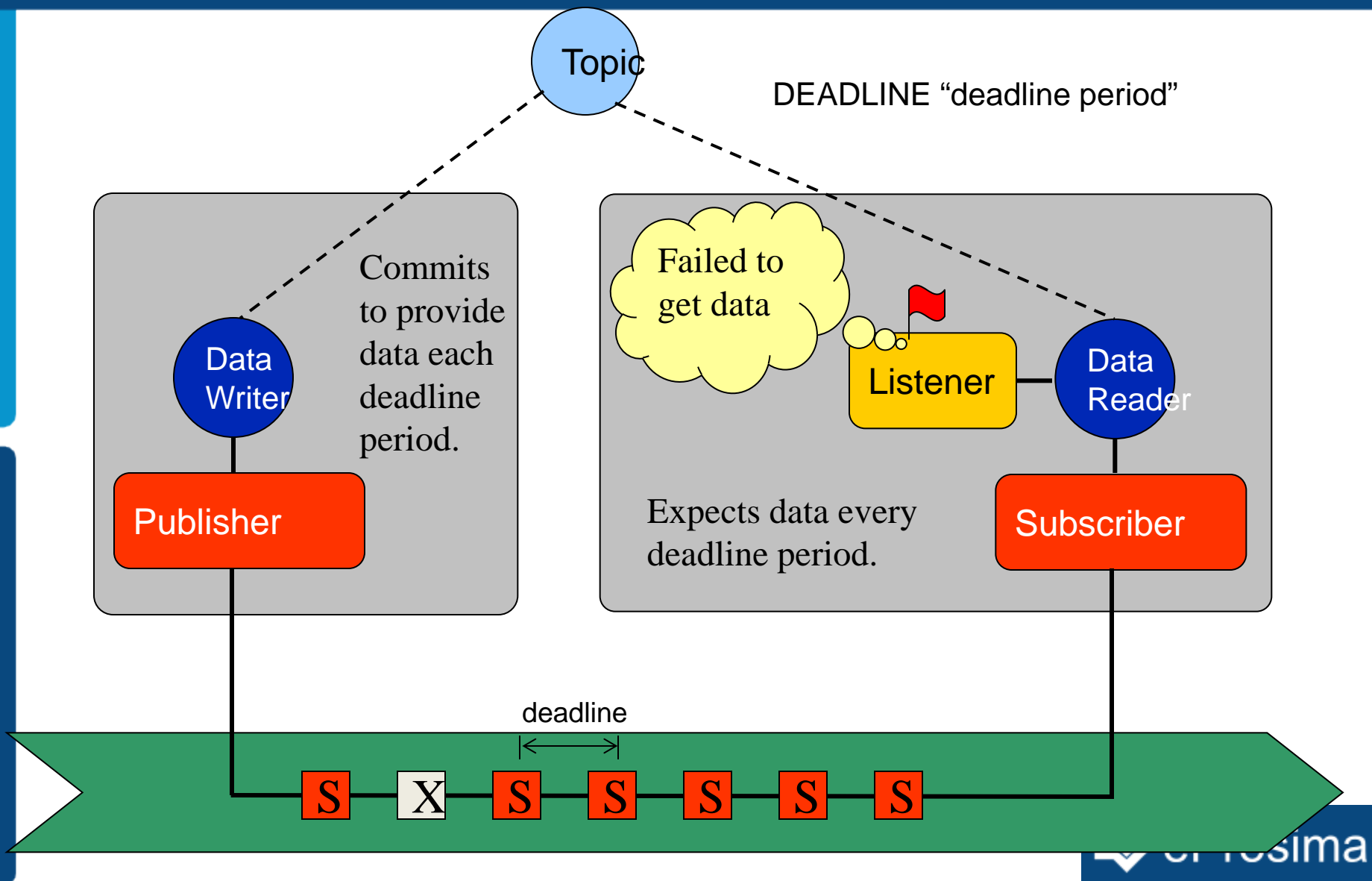


5. Monitoring the health of data-objects: Deadline QoS

- DDS can monitor activity of each individual data-instance in the system
- This is a request-offered QoS
- If an instance is not updated according to the contract the application is notified.
- Failover is automatically tied to this QoS

QoS: Deadline

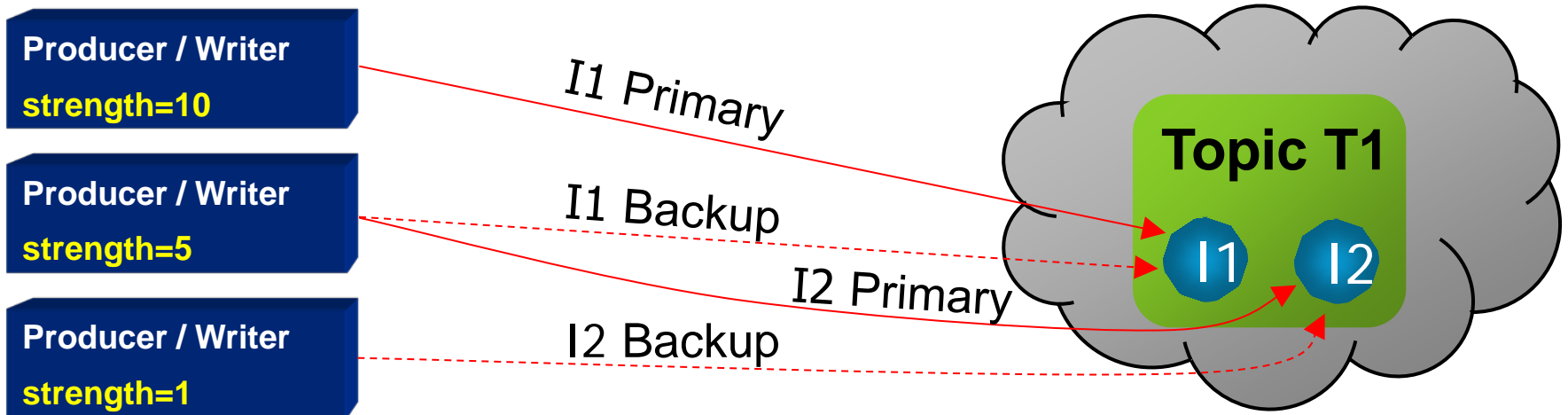
deadline example



5. Building a highly-available system

- HA systems require combining multiple patterns, many directly supported by DDS:
 - Detection of presence -> DDS Discovery
 - Detection of Health and activity -> DDS LIVELINESS
 - > DDS DEADLINE
 - Making data survive application & system failures
 - > DDS DURABILITY
 - Handling redundant data sources and failover
 - > DDS OWNERSHIP

Ownership and High Availability

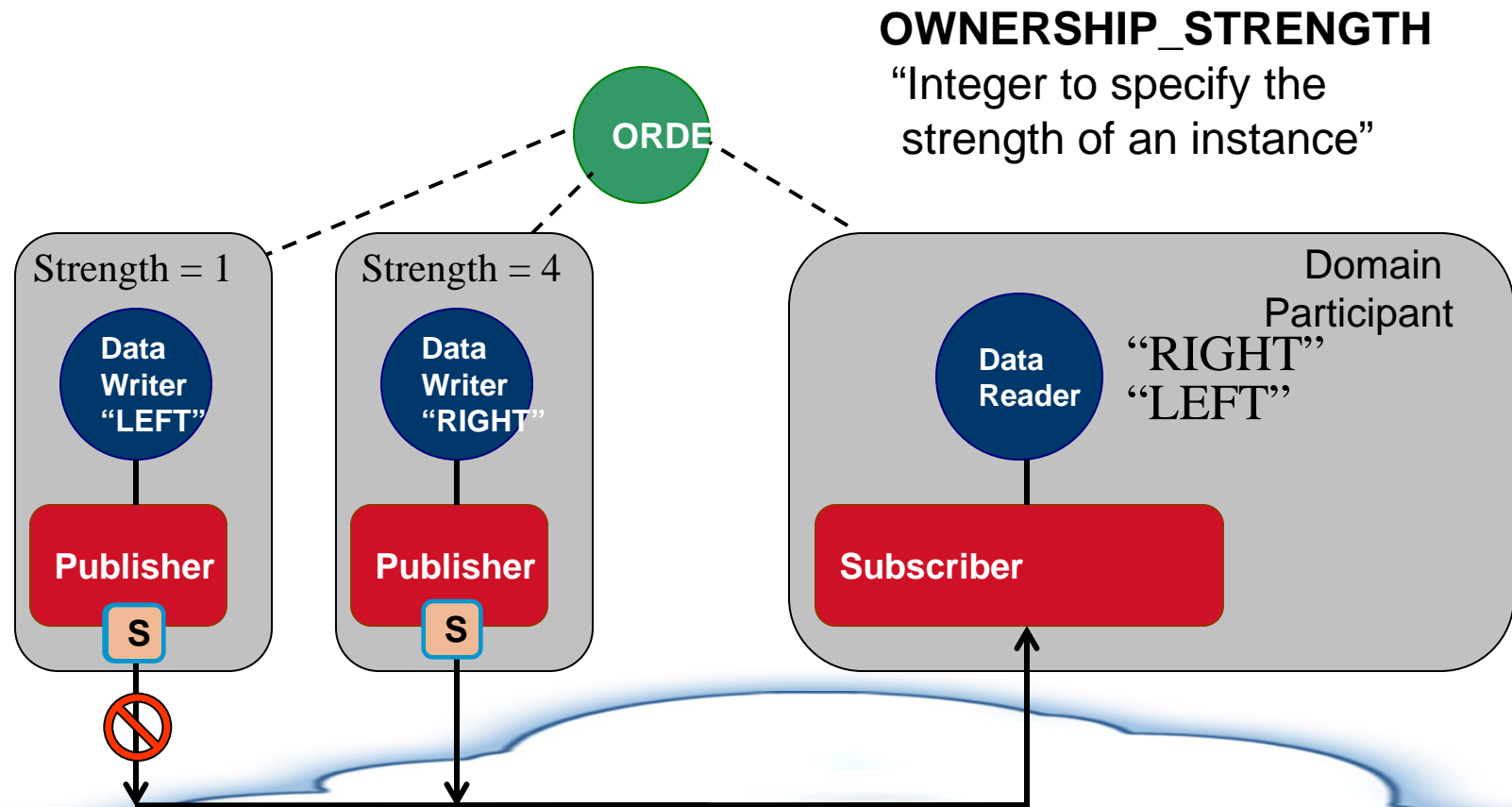


- Owner determined per subject
- Only extant writer with highest strength can publish a subject (or topic for non-keyed topics)
- Automatic failover when highest strength writer:
 - Loses liveliness
 - Misses a deadline
 - Stops writing the subject
- Shared Ownership allows any writer to update the subject

[Start demo](#)

QoS: Ownership Strength

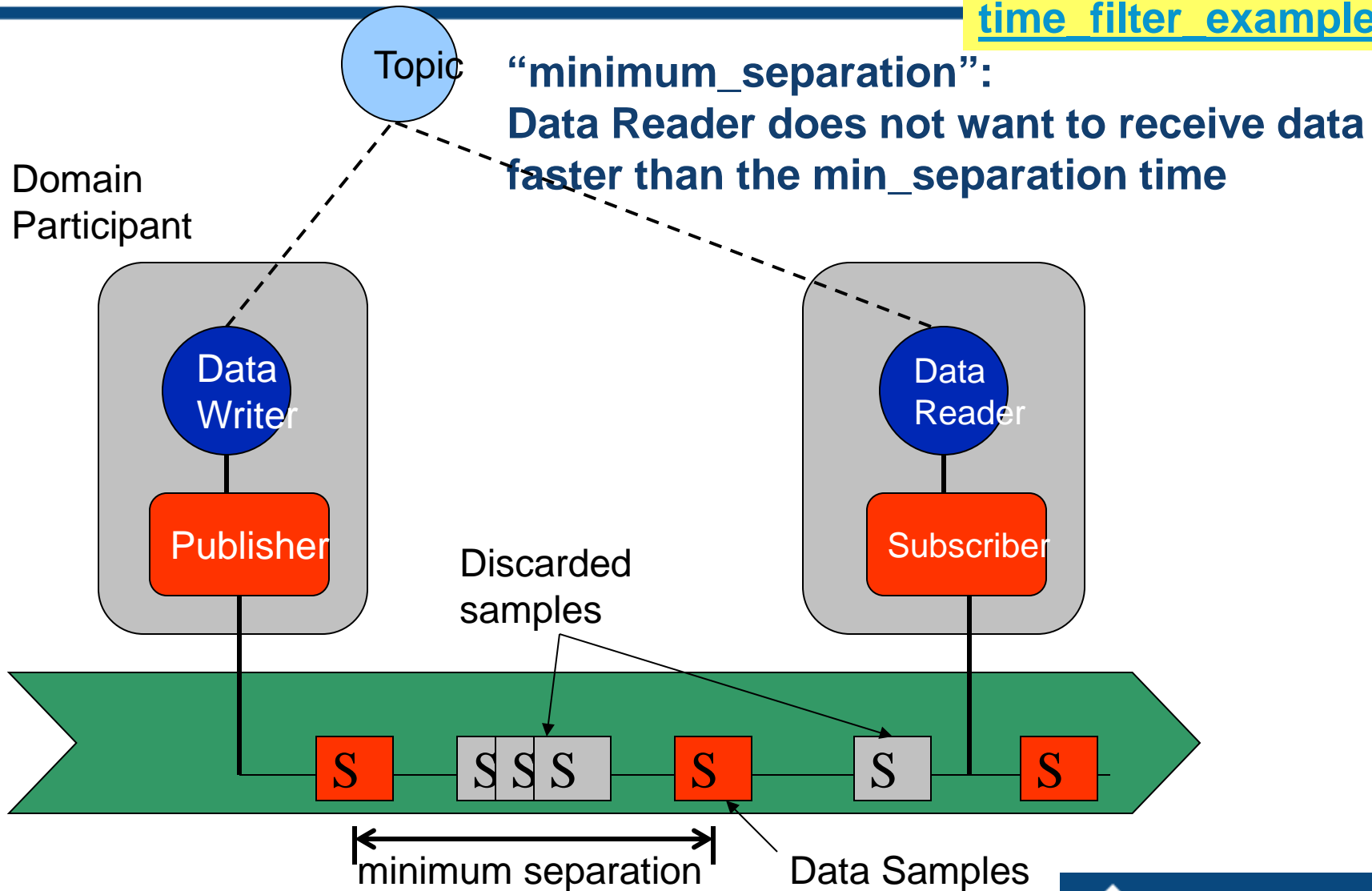
Specifies which DataWriter is allowed to update the values of data-objects



Note: Only applies to Topics with Ownership = Exclusive

8. Limiting data-rates: QoS: TIME_BASED_FILTER

time filter example



9. Controlling data received by interest set

Content-Based Filtering

Instance 1 Value = 249

Instance 2 Value = 230

Instance 3 Value = 275

Instance 4 Value = 262

Instance 5 Value = 258

Instance 6 Value = 261

Instance 7 Value = 259

⋮

Content Filtered
Topic

Topic

"Filter Expression "
Ex. Value > 260

[content_filter_example](#)

The Filter Expression and Expression Params will determine which instances of the Topic will be received by the subscriber.

Using DDS: Best Practices

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Best Practices Summary

1. Start by defining a data model, then map the data-model to DDS domains, data types and Topics.
2. Fully define your DDS Types; do not rely on opaque bytes or other custom encapsulations.
3. Isolate subsystems into DDS Domains.
4. Use keyed Topics. For each data type, indicate the fields that uniquely identify the data object.
5. Large teams should create a targeted application platform with system-wide QoS settings.

See http://www.rti.com/docs/DDS_Best_Practices_WP.pdf

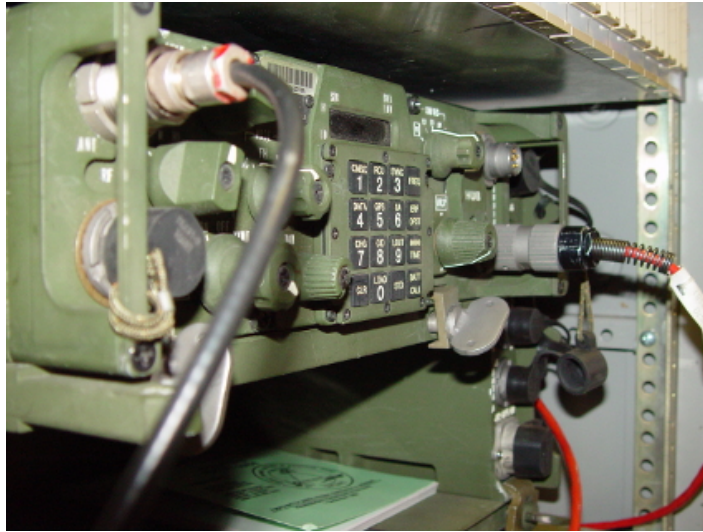
Why defining the proper keys for your data types is important

Many advanced features in DDS depend on the use of keys

- History cache.
- Ensuring regular data-object updates.
- Ownership arbitration and failover management.
- Integration with other data-centric technologies (e.g. relational databases)
- Integration with visualization tools (e.g. Excel)
- Smart management of slow consumers and applications that become temporarily disconnected.
- Achieving consistency among observers of the Global Data Space

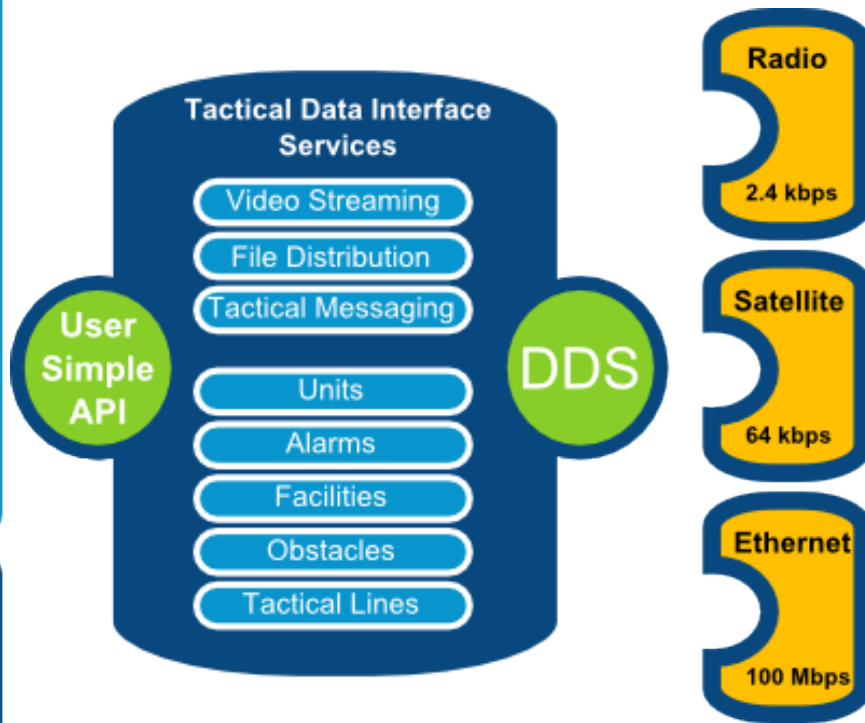
Some Success Cases

RTI DDS DIL Plugins: Disconnected and Intermittent Links

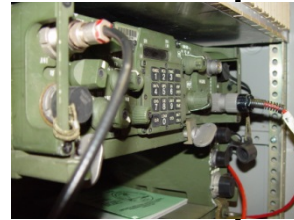


- eProsimas developed the plugins for the Spanish Army Tactical Radios, and later were acquired by RTI.
- Allow the use of DDS in very low bandwidth links, such as **Tactical Radios** and **Satellite**.
 - Tested from 2400 bps

Tactical Data Interface: Spanish Army

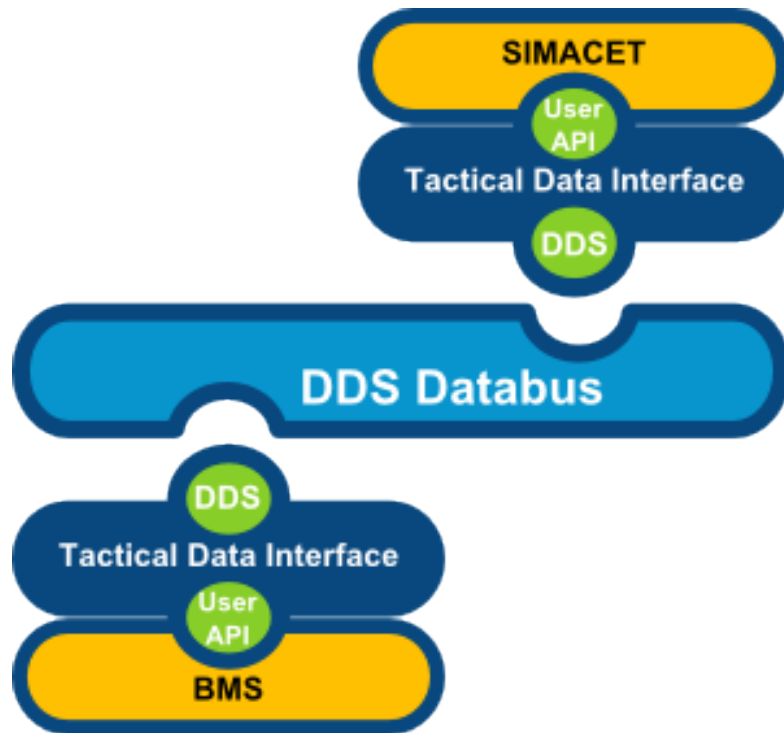


- C2 Interoperability Comm layer:
 - Tactical Radios
 - From 2400bps
 - Satellite
- Mandated for all the Spanish Army C2 systems.
 - Already implemented in the their main C2 systems



eProsima developed the army C2 comm layer using RTI Connex DDS optimized for low bandwidth environments. The project included the design of the Data Model and QoS requisites for the Army.

C2 Systems: INDRA & Amper



- eProsimas Provides a DDS based comm layer for **INDRA and Amper C2 Systems**.



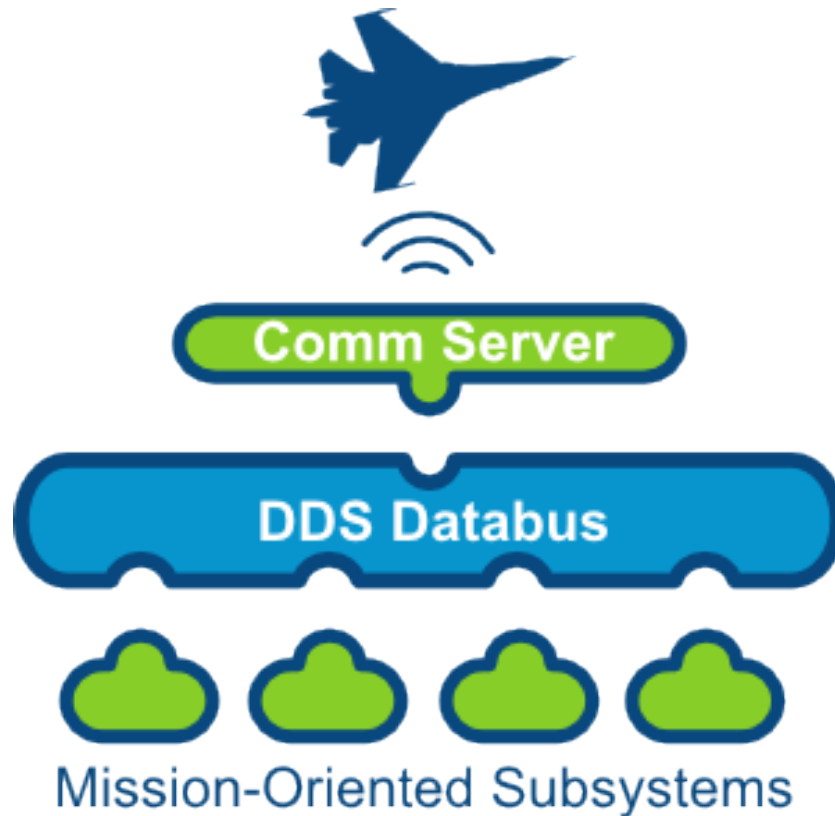
eProsimas implemented the mandated Spanish Army Tactical Data Interface for Simacet (Main Spanish Army C2 System, Amper) and BMS (Tanks C2 System, INDRA & Amper)

SESAR - INDRA ATC



- eProsimas provides middleware research and prototyping for ATC Interoperability
- Among the different middleware technologies studied, DDS and WS are the SESAR proposed technologies for ATC interoperability.

Cassidian: nEURon and Atlante GS



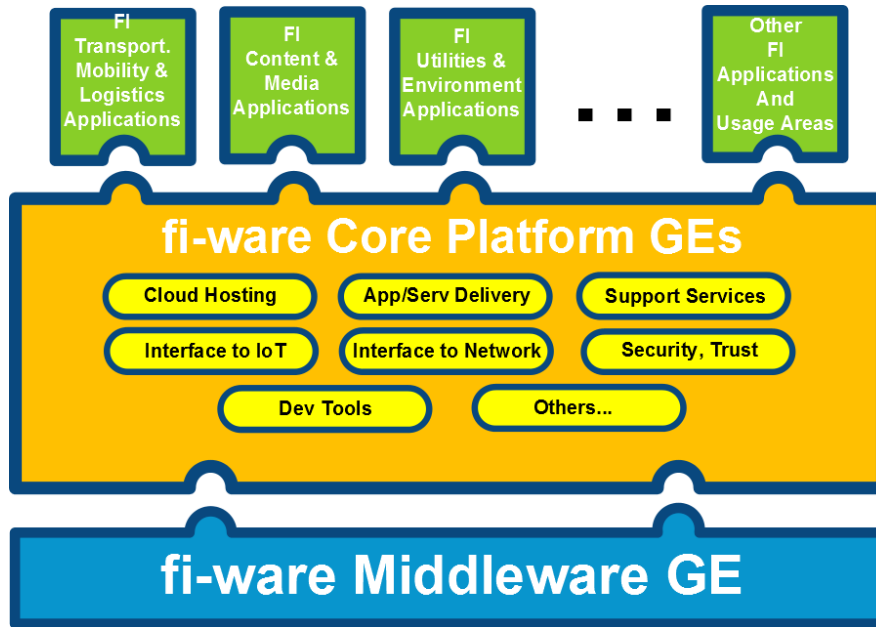
- eProsimas provides the **comm layer** for the ground station comm server.



eProsimas Non-Intrusive Recorder is used to record the communications for later analysis.



FI-WARE Middleware



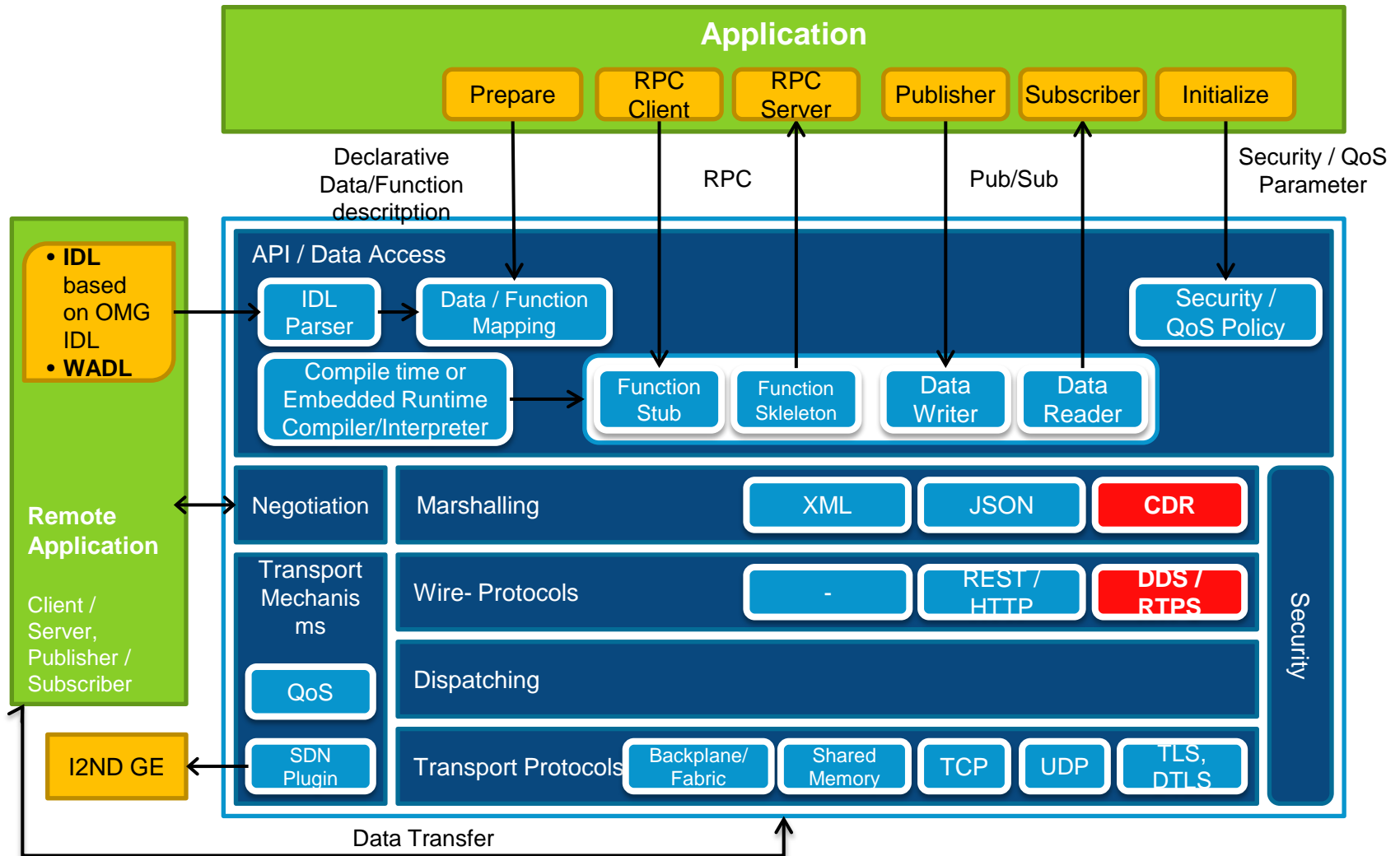
- eProsima has been selected to develop **Future Internet Middleware** in the FI-WARE programme.
- **DDS** will be the core technology

Fi-WARE is a consortium of over more than 30 companies and universities including Telefonica, Siemens, SAP, Atos...

eProsima will partner in this project with the German Universities DKFI and CISPA and the Swiss ZHAW.



FI-WARE Middleware: DDS Based



Thank you!

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