



# OMG Standards at Work In The Industrial Internet Of Things, Reston, March 17<sup>th</sup>, 2016

## *From Testbed to International Standards – The Track & Trace Example*

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# Track & Trace Testbed

## Testbed overview

### Collaborators

Testbed Leads: Bosch, TechMahindra, Cisco + PTC  
ThingWorx

### Market Segment

Industrial Manufacturing  
Power Tool Fleet Management

### Goal

Manage hand-held industrial tools in manufacturing, maintenance and industrial environments

### Features & Commercial Benefits

High-precision indoor localization  
Real-Time Mapping to 3D PLM data  
Asset Management, Work Management  
Monitor/Control Quality

## Approach & Status

### Phased Approach

Phase 1: Simple solution, fast GTM<sup>1</sup>  
Phase 2: High-precision, advanced solution

### Current Status

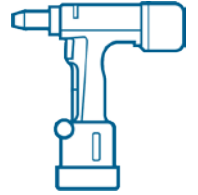
Approval by IIC STC in Dec 2014 as  
the first public IIC Testbed  
Milestone 1: Live Demo at BCW15 ✓  
Milestone 2: Initiate GTM Phase 1 ✓  
Milestone 3: High precision localization ✓



<sup>1</sup> GTM – Go to market

<sup>2</sup> Steering Committee

# Power Tools in Assembly Lines





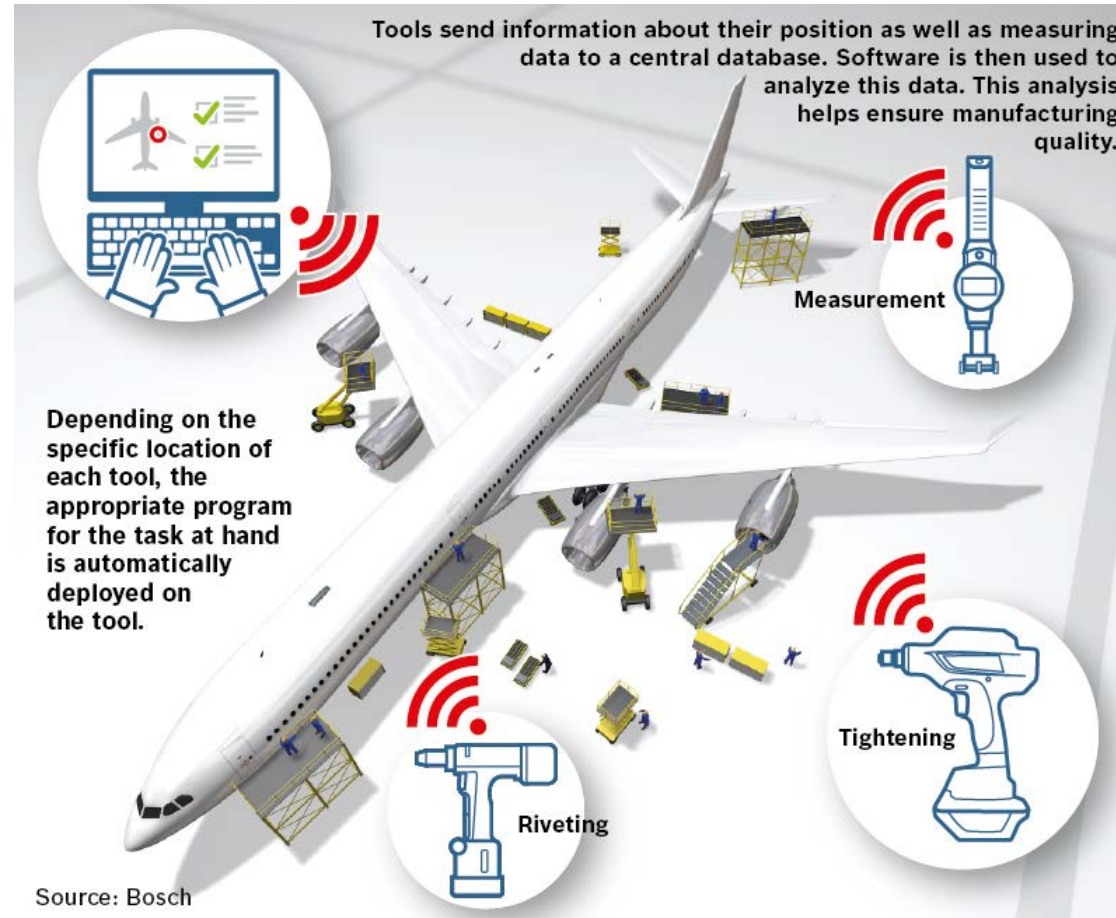
## Example: Nexo Corless Wi-Fi nutrunner



### Key technical data

- Rotational speeds of up to 1,500 rpm
- Torque of up to 50 Nm in the output expansion stage
- Acquisition of torque and angle of rotation possible
- 2.4 and 5 GHz Wi-Fi
- Integrated screw point lighting
- Suitable for class A tightening connections in accordance with VDI/VDE2862

# Track & Trace Testbed



# T&T Phase 1: Tool Fleet - Status & History

## Connected Tools

### Overview

#	TYPE	NAME	SERIAL NO	IP	CONNECTION	STATUS
1		BCW-Nexo-1	311000312	192.168.0.130	 Online	 Ready
2		BCW-Nexo-2	517000847	192.168.0.131	 Online	 Ready



FLEET MANAGEMENT > Tools

## Bosch Nexo



Connection  
Online



Tool Status  
Ready



Battery  
45 %

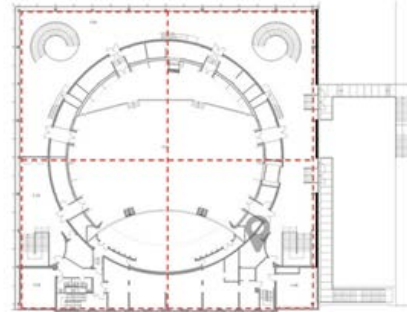


Position  
ZoneD

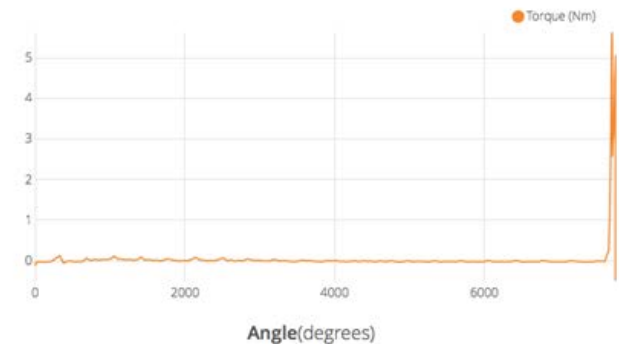


LAST TIGHTENING  
PROCESS  
**OK**  
ID 842  
Program 0

### Tool Livetracking



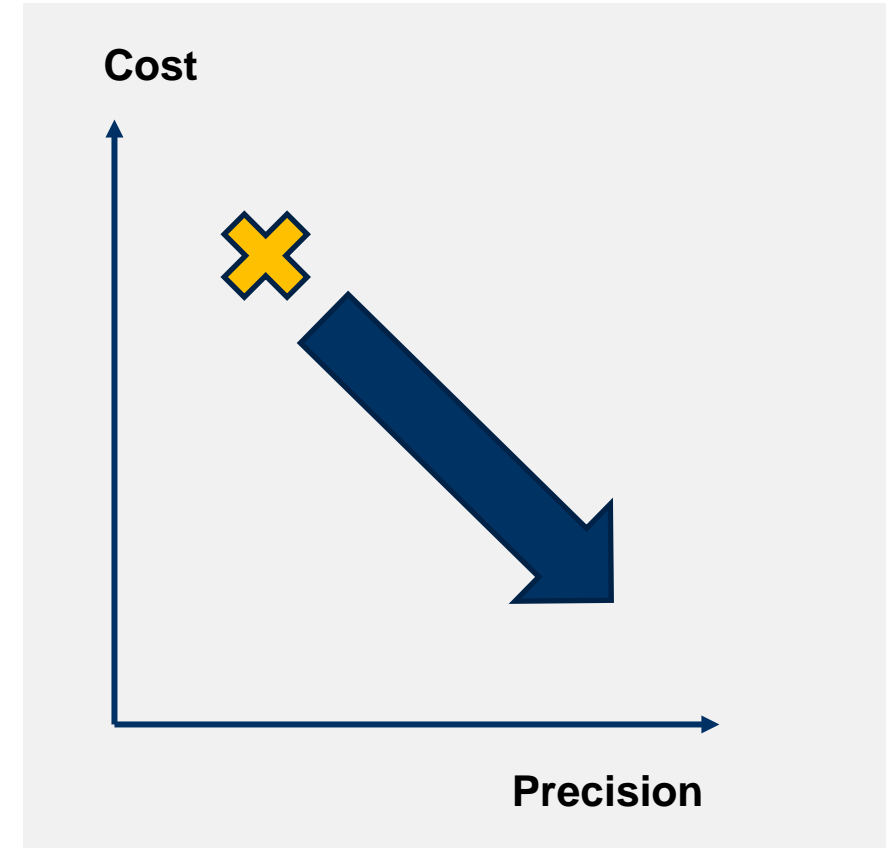
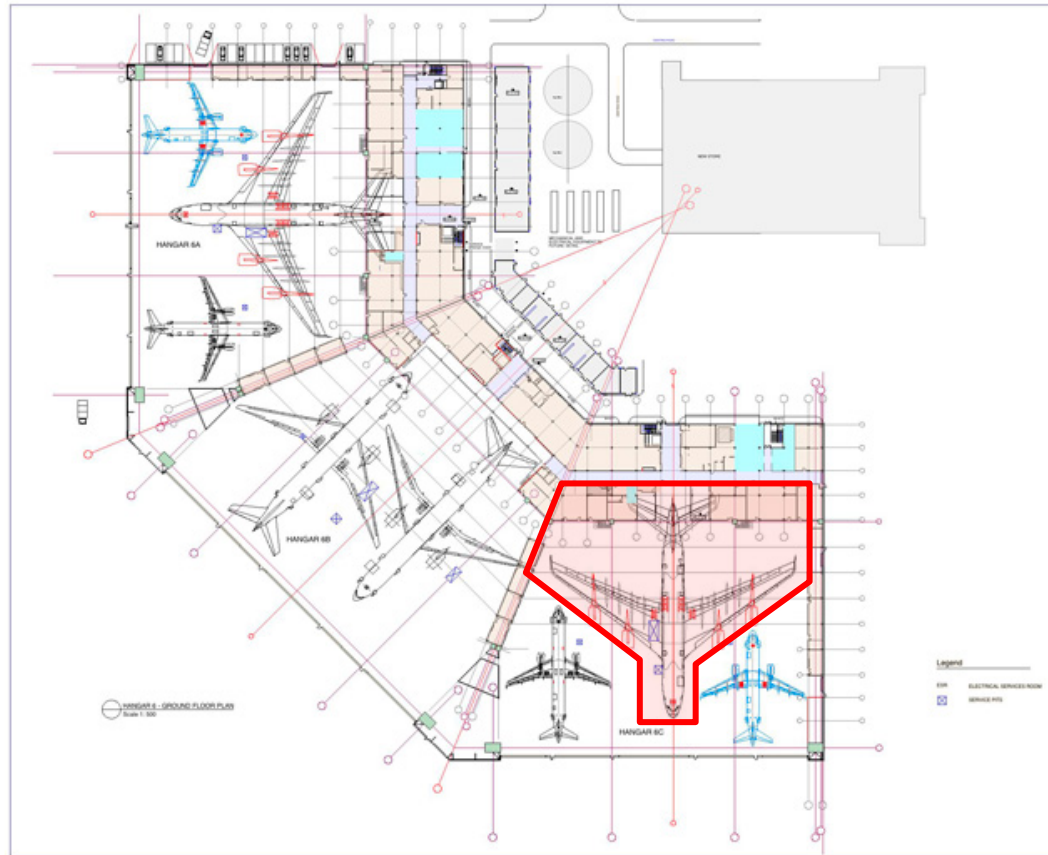
### Last Tightening Process



# T&T Phase 1: (Big) Data Analytics

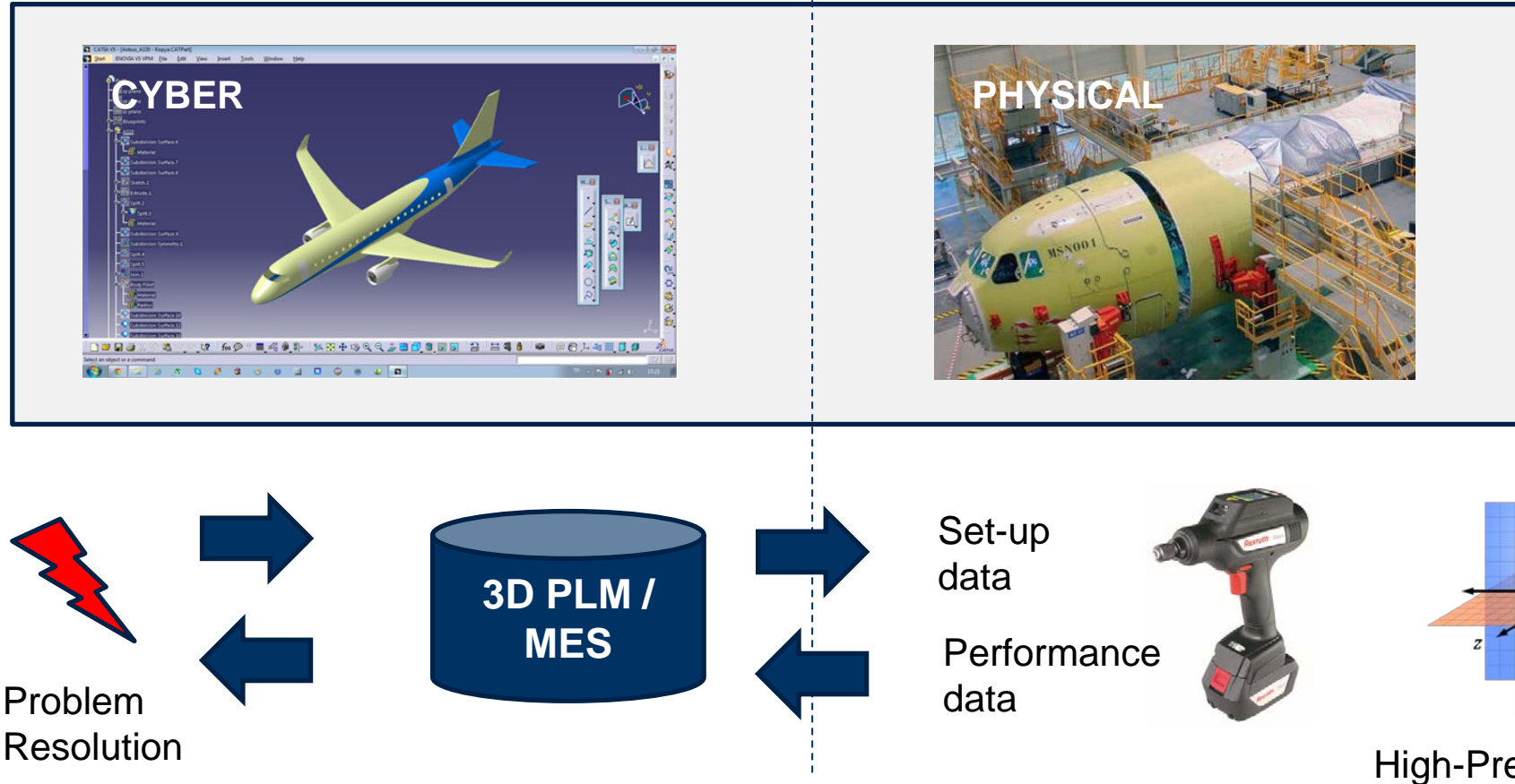


# T&T Phase 1: Indoor Localization



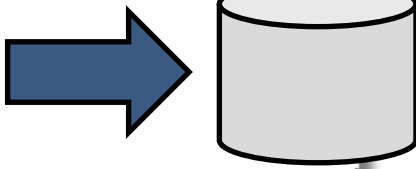


# T&T Phase 2: Goal



# T&T: Open Source & Standardization

```
functionblock Nutrunner {  
  displayname "Nutrunner"  
  description "Function block model for Nutrunner"  
  vendor www.bosch.com  
  category demo  
  version 1.0  
  
  configuration{  
    // Describes the current defined configuration of the nutrunner  
    optional program as int  
  }  
  
  status {  
    // Defines the status updates a Nutrunner provides  
    optional lastMaintenance as datetime  
    optional totalCycles as int  
    optional totalCyclesSinceLastMaintenance as int  
    optional currentTorque as float  
    optional currentAngle as float  
    optional nutrunnerStatus as string  
    optional batteryStatus as int  
    optional systemStatus as systemStatus  
  }  
  
  operations{  
    // Operations which can be invoked on the device  
    getArchivedTighteningResult(tighteningId as int) returns tighteningResult  
    getTorque() returns float  
  }  
}
```



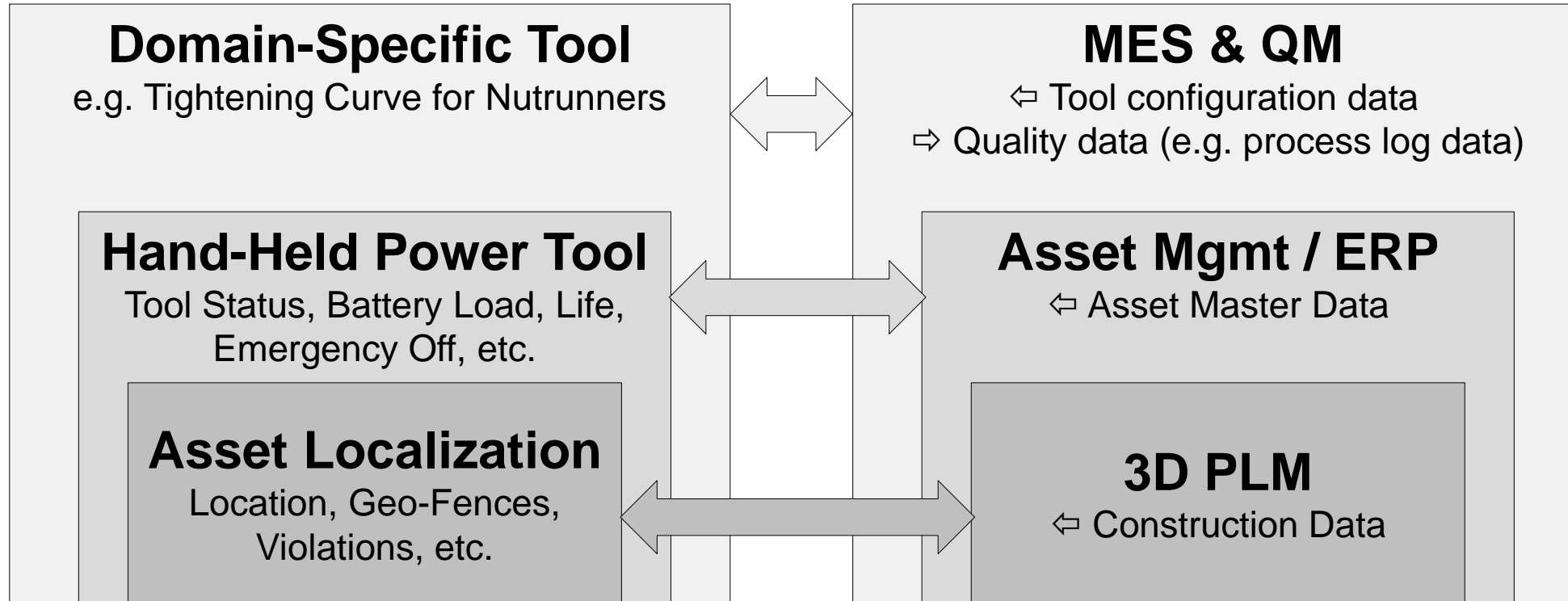
Vorto (Eclipse Foundation/Open Source):

- Information Models for the IoT
- Repository to manage large numbers of versioned interfaces for IoT Assets and Devices
- Ideal fit for heterogeneous fleets of different power tools (T&T)

Standardization: Currently liaising with OMG to define process for standardization of T&T interfaces (based on Vorto)



# T&T: Open Source & Standardization



# Track & Trace Open Source and Standardization

## Requirements

- ➔ Support for Indoor and Outdoor Localization incl. Geo-Fences, Events, etc.
- ➔ Support a big variety of technologies and products
- ➔ Outcome needs to be modeled as Function Blocks as well as Information Models
  - Incl. Accuracy, events, angulating methods,
- ➔ Function blocks and Information Models shall be available as Open Source in the Vorto Repository (EPL)
- ➔ Integration in 3D PLM, Asset Management Systems, MES via Vorto Code Generators



# Track and Trace Open Source and Standardization

## Next Steps

- ➔ Define additional Use Cases related to the Track & Trace Testbed
- ➔ Collection of localization technologies and products and analyse their capabilities
  - GSM, UMTS, Satellite, GPS, Wifi, RFID, UWB, LORA, SigFox,
  - Ubisense, Cisco, S3 ID, Zebra, Quantitec, Decawave
- ➔ Evaluate the feasibility of a Vorto UML code generator

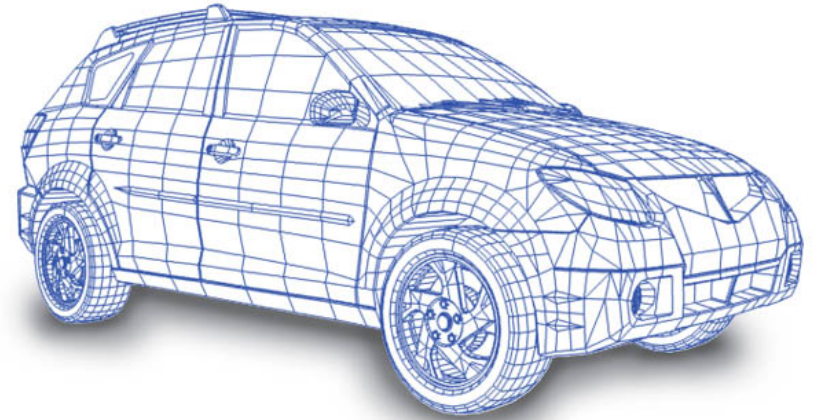
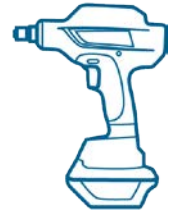
# GTM & T&T Customer Advisory Board

## → GTM

- Gather and validate requirements and use cases
- Initiate PoCs and initial projects

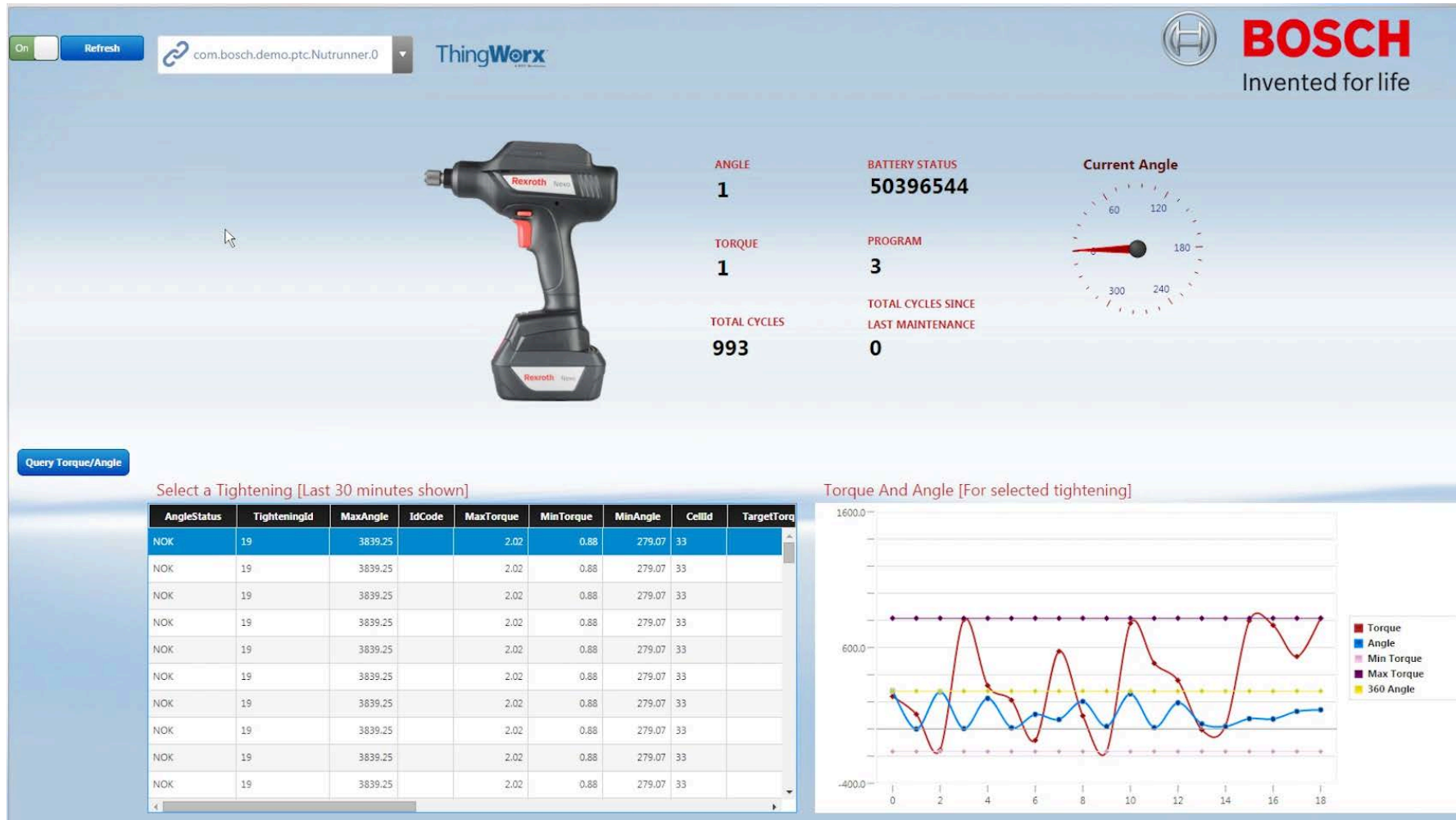
## → CAB (Customer Advisory Board)

- One large OEM
- One aircraft manufacturer
- One aircraft operator



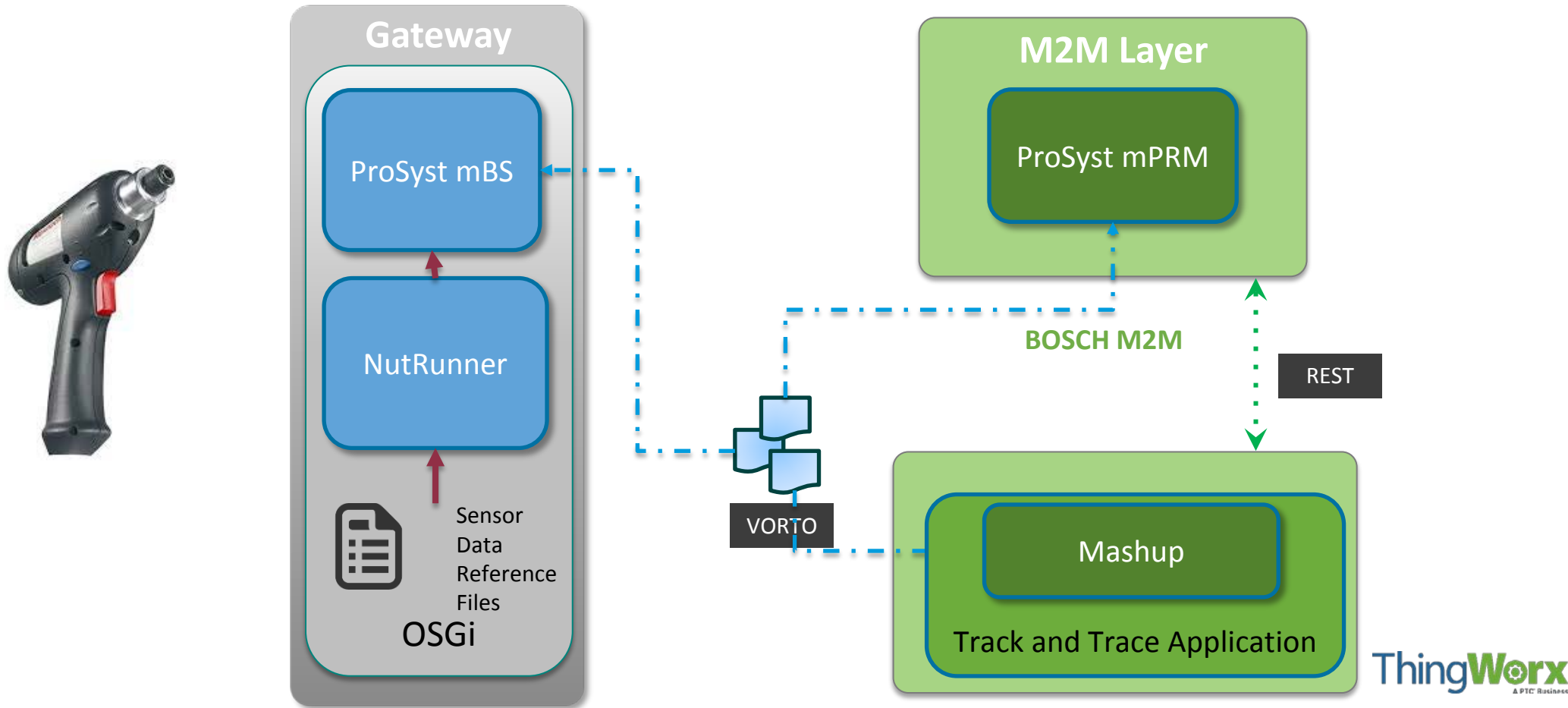


# An Example for a NUTRUNNER MASHUP





# Architecture



# Questions? Thank You!

