# MDE4DRE: Model Driven Engineering for Distributed Real-time & Embedded Systems

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Institute for Software Integrated Systems

Vanderbilt University Nashville, Tennessee





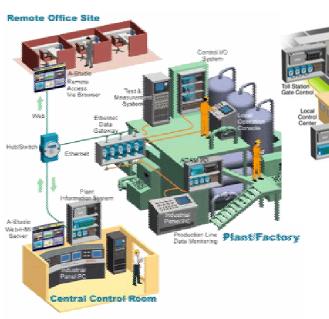
#### **Tutorial Outline**

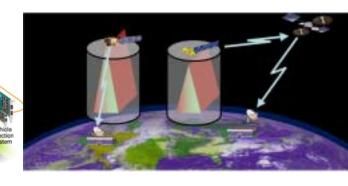
- 1. Introduction
- 2. The Basics
- 3. Case Studies
- 4. Assembly & Packaging
- 5. QoS Provisioning
- 6. Deployment planning
- 7. Middleware Configuration
- 8. Continuous QoS Validation
- 9. Middleware Customization & Analysis
- 10. Future directions/Work-in-progress
- 11. Concluding Remarks





### Distributed Real-time & Embedded (DRE) Systems





- Network-centric and large-scale "systems of systems"
  - e.g., industrial automation, emergency response
- Different communication semantics
  - e.g., pub-sub

Satisfying tradeoffs between multiple (often conflicting)
QoS demands

e.g., secure, real-time, reliable, etc.

Regulating & adapting to (dis)continuous changes in runtime environments

 e.g., online prognostics, dependable upgrades, keep mission critical tasks operational, dynamic resource mgmt

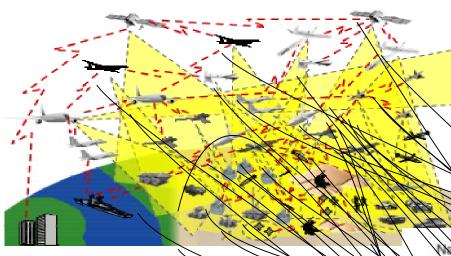
DRE systems increasingly adopting service oriented architectures







## Challenges in Realizing DRE Systems



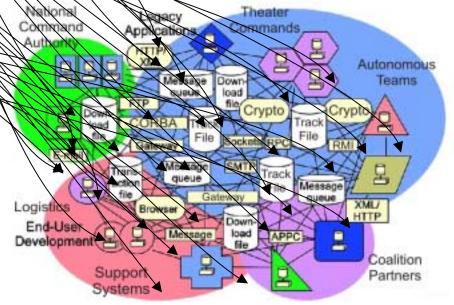
Variability in the *problem space* (domain expert role)

- Functional diversity
- Composition, deployment and configuration diversity
- QoS requirements diversity

Variability in the **solution space** (systems integrator role)

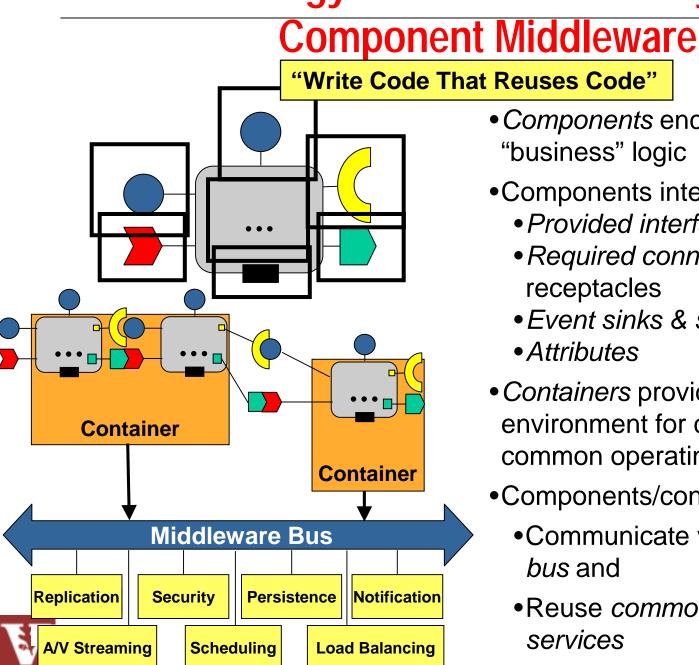
- Diversity in platforms, languages, protocols & tool environments
- Enormous accidental & inherent complexities

Mapping *problem* artifacts to *solution* artifacts is hard



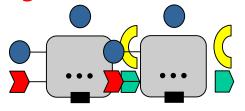


#### **Technology Enablers for DRE systems:**

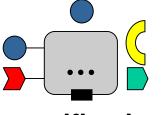


- Components encapsulate application "business" logic
- Components interact via ports
  - Provided interfaces, e.g., facets
  - Required connection points, e.g., receptacles
  - Event sinks & sources
  - Attributes
- Containers provide execution environment for components with common operating requirements
- Components/containers can also
  - Communicate via a middleware bus and
  - •Reuse common middleware services

### Lifecycle Issues in DRE Systems



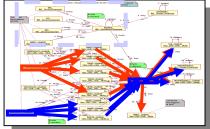
#### composition & packaging

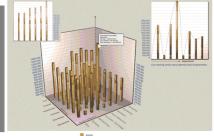


specification

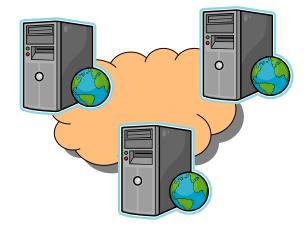


Project of the Aviation System Capacity Program





analysis, validation & verification



## deployment planning & QoS provisioning

Domain-specific
Services

Common Services

Distribution
Middleware
Infrastructure
Middleware

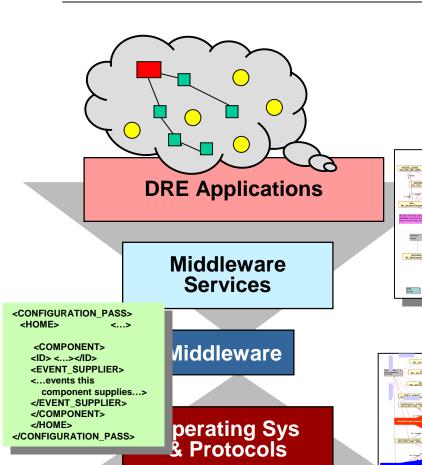
Operating System & Network Stack

## configuration & optimization





#### Tutorial Focus: Model Driven Engineering (MDE)



Hardware & Networks

- Develop, validate, & standardize generative software technologies that:
  - 1. Model
  - 2. Analyze
  - 3. Synthesize &
  - 4. Provision

multiple layers of middleware & application components that require simultaneous control of multiple quality of service properties end-to-end

 Specialization is essential for inter-/intra-layer optimization & advanced product-line architectures



Goal is *not* to replace programmers per se – it is to provide *higher-level domain-specific languages* for middleware/application developers & users



#### **OMG D&C Specification**

#### Specification & Implementation

 Defining, partitioning, & implementing appln functionality as standalone components

#### Assembly & Packaging

 Bundling a suite of software binary modules & metadata representing app components

#### Installation

Populating a repository with packages required by app

#### Configuration

 Configuring packages with appropriate parameters to satisfy functional & systemic requirements of an application without constraining to physical resources

#### **Planning**

 Making deployment decisions to identify nodes in target environment where packages will be deployed

#### Preparation

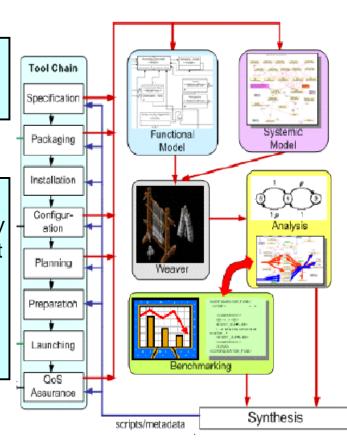
Moving binaries to identified entities of target environment

#### Launching

Triggering installed binaries & bringing appln to ready state

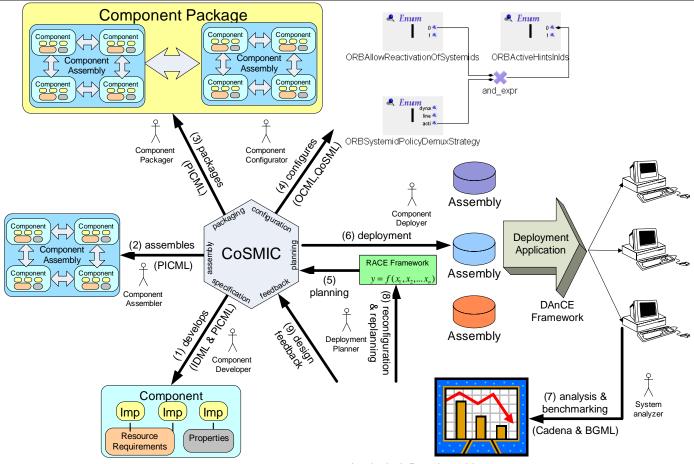
#### **QoS Assurance & Adaptation**

 QoS validation, runtime (re)configuration & resource management to maintain end-to-end QoS



OMG Deployment & Configuration (D&C) specification (ptc/05-01-07)

#### **Our MDE Solution: CoSMIC**



- Analysis & Benchmarking
- CoSMIC tools e.g., PICML used to model application components, CQML for QoS
- Captures the data model of the OMG D&C specification
- Synthesis of static deployment plans for DRE applications
- Capabilities being added for QoS provisioning (real-time, fault tolerance)





# Part 1 The Basics

Tools & Technologies

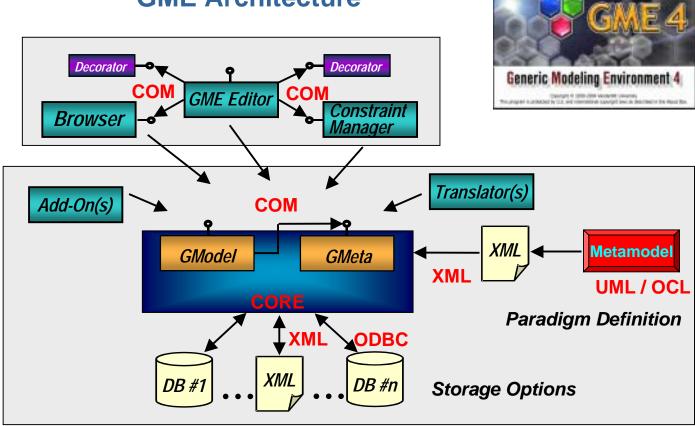
## Technology Enabler: Generic Modeling Environment (GME)

"Write Code That Writes Code That Writes Code!"

**GME Architecture** 

Application Developers (Modelers)

MDE Tool Developer (Metamodeler)

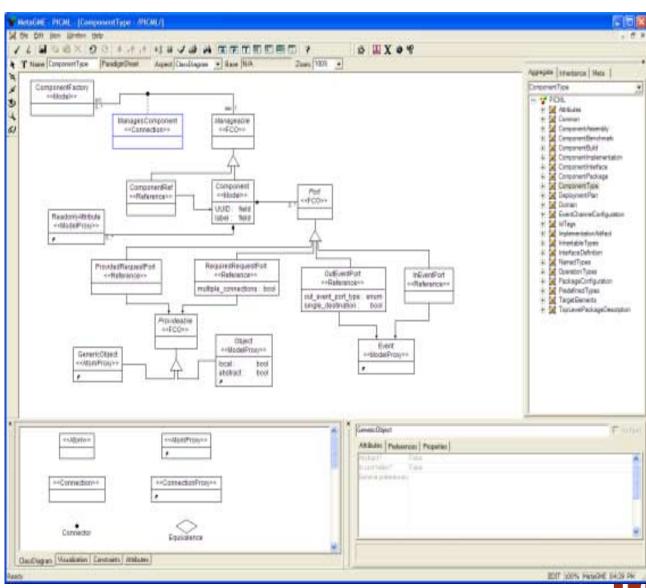


**Goal: Correct-by-construction DRE systems** 





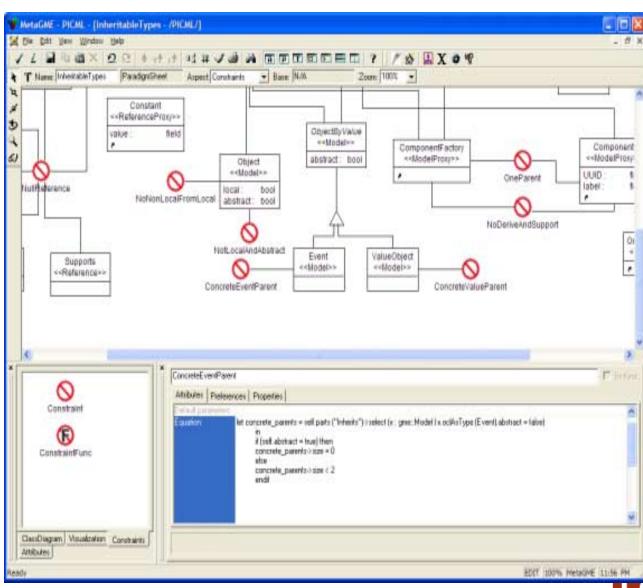
- •Tool developers use MetaGME to develop a domain-specific graphical modeling environment
  - Define syntax & visualization of the environment via metamodeling







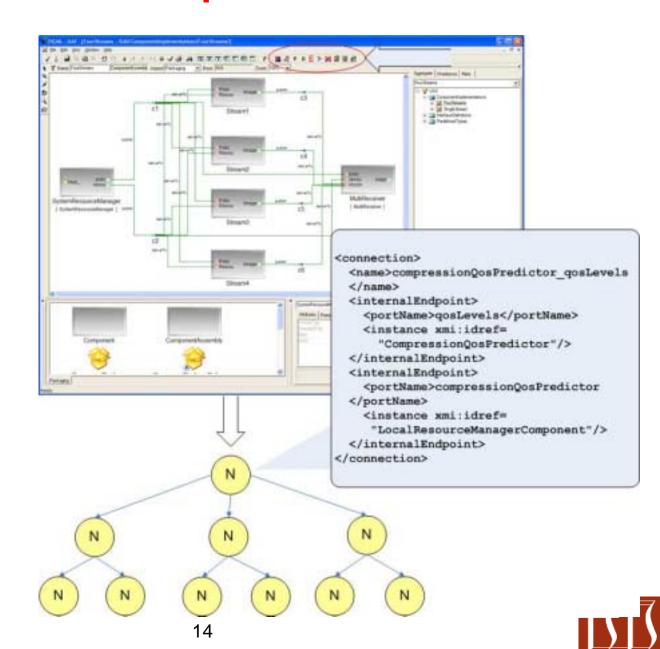
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  - Define static semantics via Object Constraint Language (OCL)



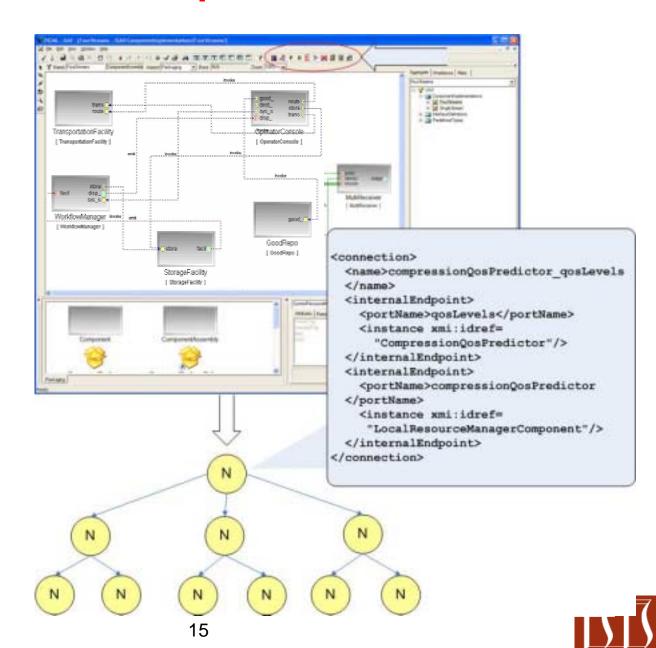




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  - Define static semantics via Object Constraint Language (OCL)
  - Dynamic semantics implemented viamodel interpreters

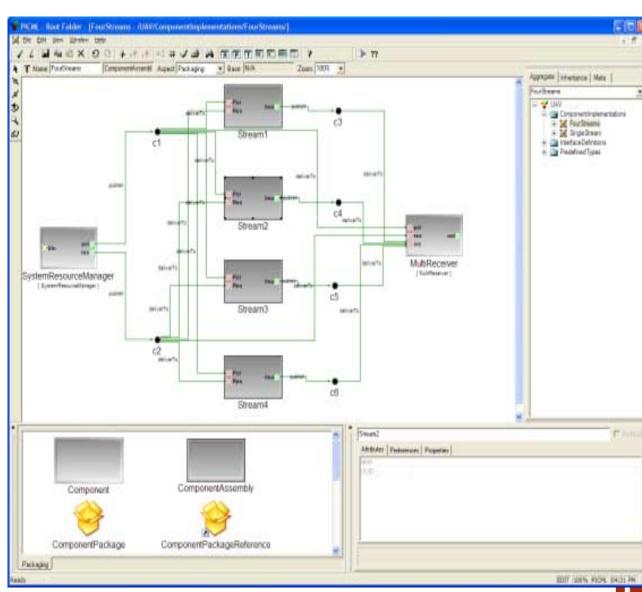


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#### MDE Application Development with GME

- Application developers use modeling environments created w/MetaGME to build applications
  - Capture elements & dependencies visually

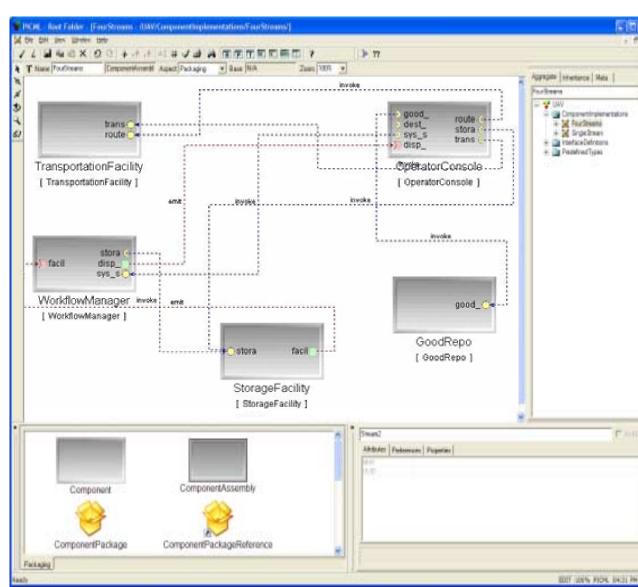






### MDE Application Development with GME

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## MDE Application Development with GME

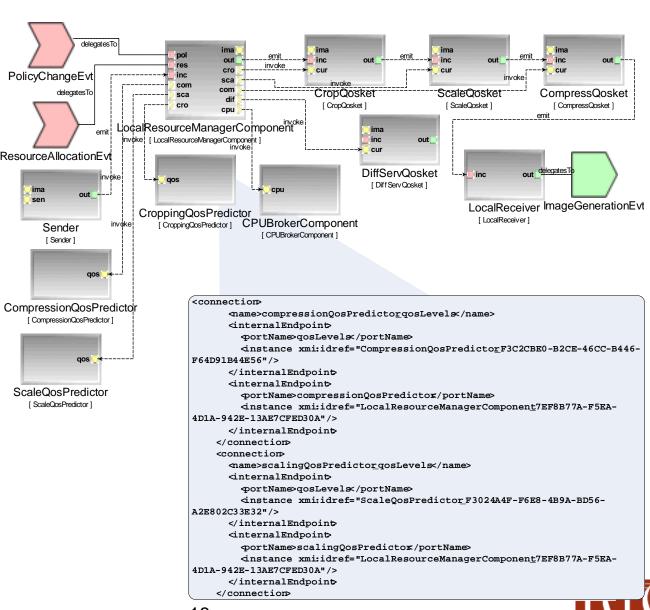
• Application

developers use
modeling environments
created w/MetaGME to Resource Allocation Evit
build applications

Capture elements & dependencies visually

 Model interpreter produces something useful from the models

e.g., code, simulations, deployment descriptions & configurations

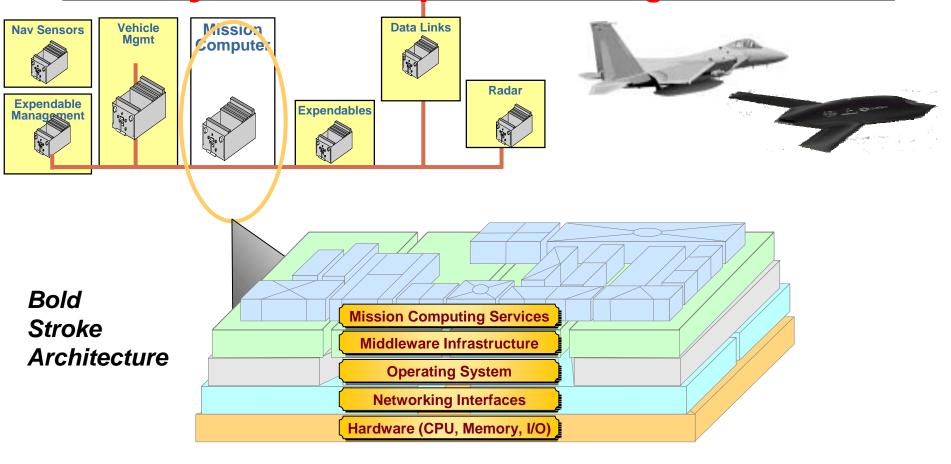


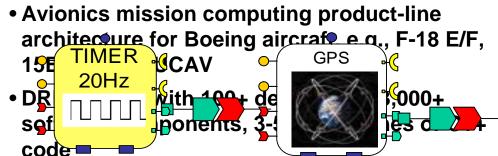


## Part 2 Case Studies

Bold Stroke
Robot Assembly
NASA Space Mission
Shipboard Computing
Modern Office
Stock Application

## DRE System Example 1: Boeing Bold Stroke

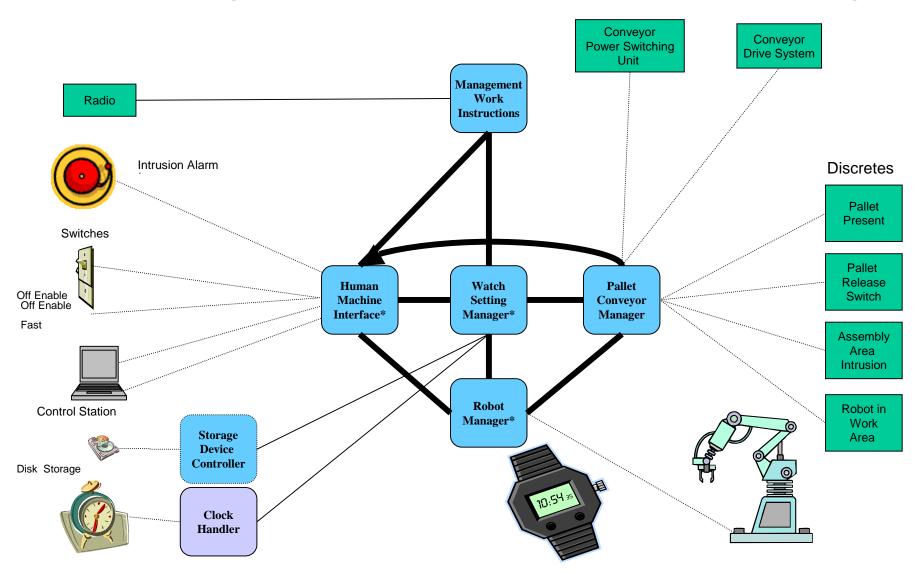




 Based on COTS hardware, networks, operating systems, & middleware



## DRE System Example 2: RobotAssembly





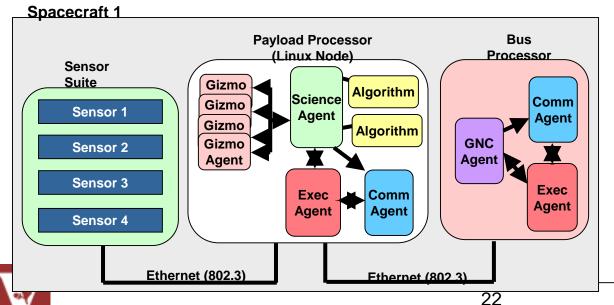


DRE System Example 3: NASA MMS Mission

- NASA's Magnetospheric MultiScale (MMS) space mission consists of four identically instrumented spacecraft & a ground control system
  - Collect mission data
  - Send it to ground control at appropriate time instances





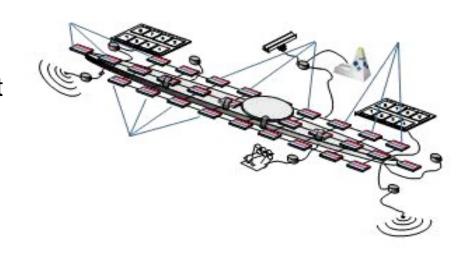


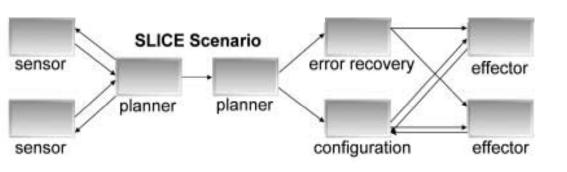
- MMS application components are bundled together into hierarchical assemblies
- Assembly package metadata conveys component interconnections & implementation
   alternatives

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## DRE System Example 4: Shipboard Computing

- Use case drawn from DARPA ARMS program
- Dynamic resource management for mission critical applications
- Multiple application workflows replicated in multiple data centers



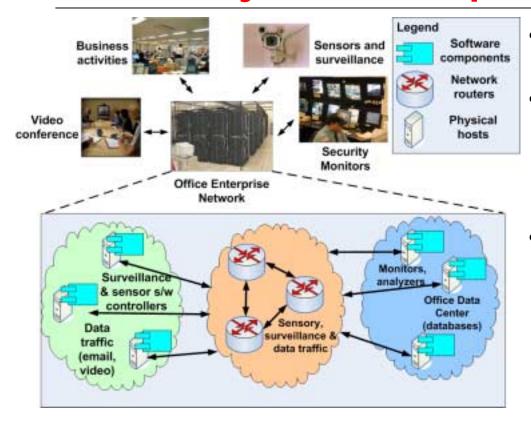


 SLICE scenario depicts an application workflow





### **DRE System Example 5: Modern Office**



- Office traffic operates over IP networks & Fast ethernets
- Multiple application flows:
  - Email
  - Videoconferencing
  - Sensory (e.g., fire alarms)
- Differing network QoS requirements
  - Fire alarm highest priority
  - Surveillance multimedia
  - Temperature sensing best effort
- QoS provisioned using DiffServ

#### **Network QoS Provisioning Steps**

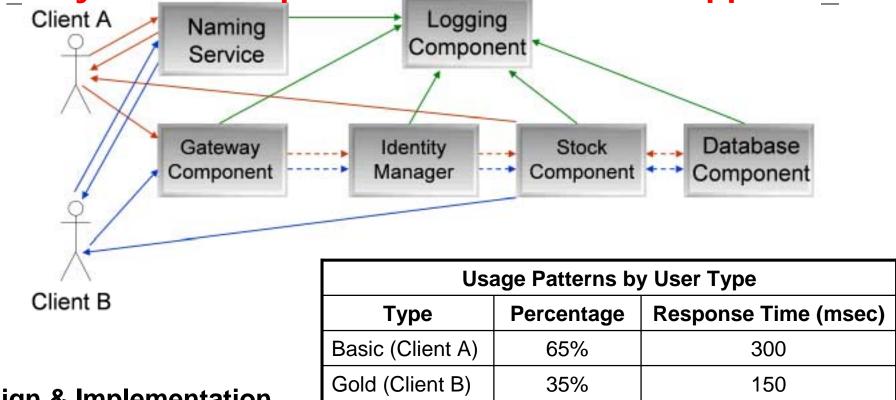
- 1. Specify network QoS requirements for each application flow
- 2. Allocate network-level resources and DiffServ Code Points (DSCP) for every application flow joining two end points



Mark outgoing packet with the right DSCP values



DRE System Example 6: Distributed Stock Application



#### **Design & Implementation**

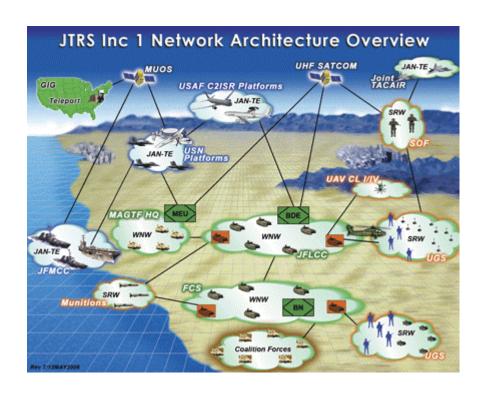
- Functionality developed as components
- Target architectures include multiple different nodes.
- Each component in the DSA is scheduled to complete its development at different times in development lifecycle



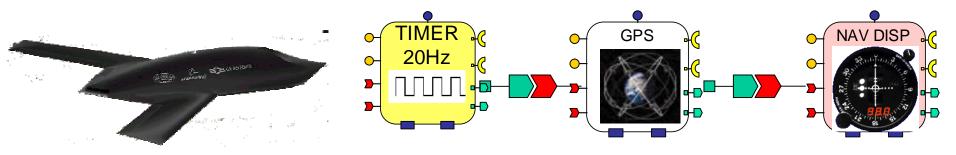


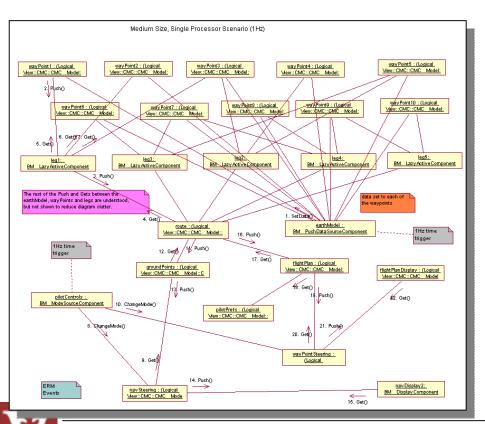
## Part 3 Modeling DRE Application Workflows

Assembly & Packaging



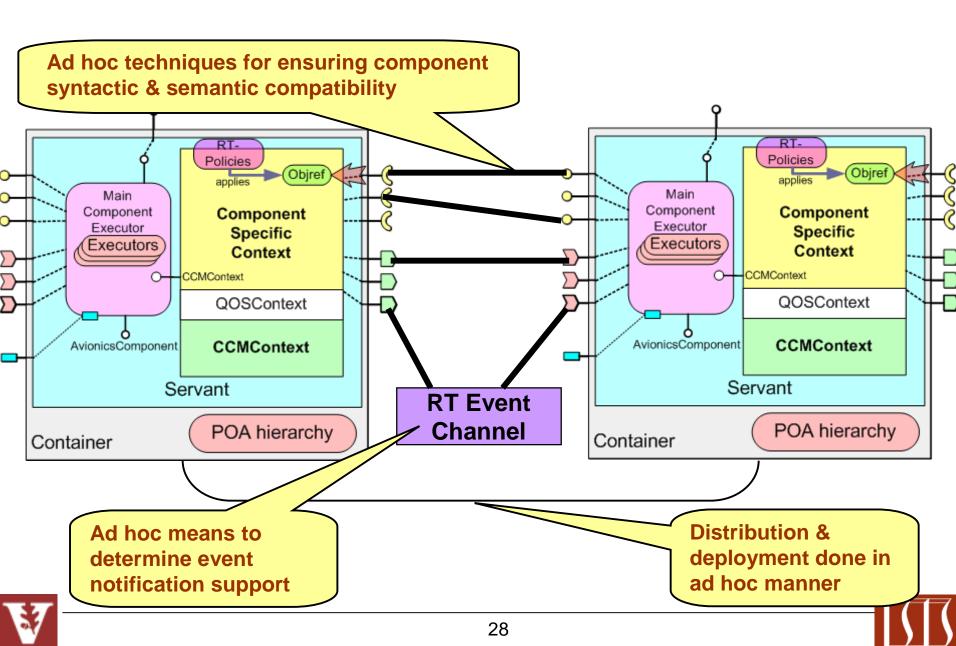
## **Assembly & Packaging Problem**





- Application components are bundled together into assemblies
- Several different assemblies tailored towards delivering different end-toend QoS and/or using different algorithms can be part of the package
  - •e.g., large-scale DRE systems require 100s-1,000s of components
- Packages describing the components
   & assemblies can be scripted via
   XML descriptors

## Assembly & Packaging Challenges (1/2)



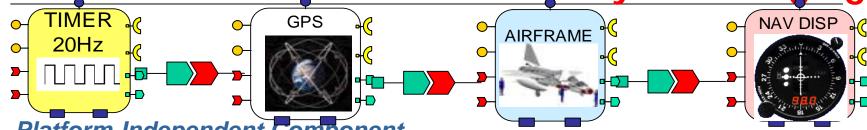
## Assembly & Packaging Challenges (2/2)

```
Existing practices
                                                            involve handcrafting
                                                            XML descriptors
           <!- Associate components with impls -->
           <componentfiles>
               <componentfile id="RateGenerator">
                  <fileinarchive name="HouseRateGen.csd"/>
               </componentfile>
XML file in
excess of 3,000
               <componentfile id="HiResGPS">
lines, even for
                  <fileinarchive name="aGPS.csd"/>
medium sized
               </componentfile>
scenarios
               <componentfile id="cockpitDisplay">
                  <fileinarchive name="navDisplay-if.csd"/>
               </componentfile>
            </componentfiles>
                                                   Modifications to the
                                                   assemblies requires
                                                   modifying XML file
```

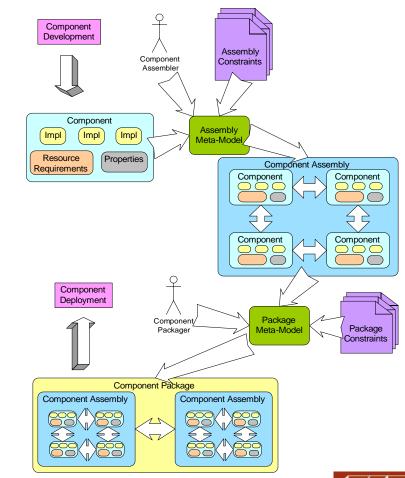




CoSMIC MDE Solution for Assembly & Packaging



- Platform-Independent Component Modeling Language (PICML)
- Developed in Generic Modeling Environment (GME)
- Core of Component Synthesis using Model-Integrated Computing (CoSMIC) toolchain
- Capture elements & dependencies visually
- Define "static semantics" using Object Constraint Language (OCL)
- Define "dynamic semantics" via model interpreters
  - Also used for generating domain specific meta-data

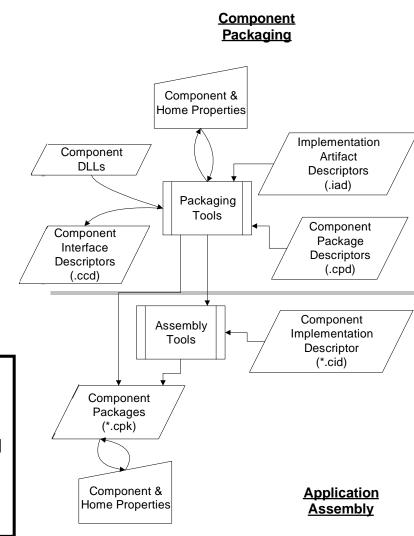






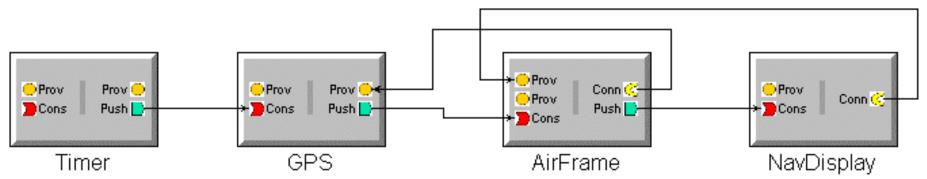
## **Example Metadata Generated by PICML**

- Component Interface Descriptor (.ccd)
  - Describes the interface, ports, properties of a single component
- Implementation Artifact Descriptor (.iad)
  - Describes the implementation artifacts (e.g., DLLs, OS, etc.) of one component
- Component Package Descriptor (.cpd)
  - Describes multiple alternative implementations of a single component
- Package Configuration Descriptor (.pcd)
  - Describes a configuration of a component package
- Top-level Package Descriptor (package.tpd)
  - Describes the top-level component package in a package (.cpk)
- Component Implementation Descriptor (.cid)
  - Describes a specific implementation of a component interface
  - Implementation can be either monolithic- or assembly-based
  - Contains sub-component instantiations in case of assembly based implementations
  - Contains inter-connection information between components
- Component Packages (.cpk)
  - A component package can contain a single component
  - A component package can also contain an assembly



Based on OMG (D&C) specification (ptc/03-06-03)

#### **Example Output from PICML**



#### A Component Implementation Descriptor (\*.cid) file

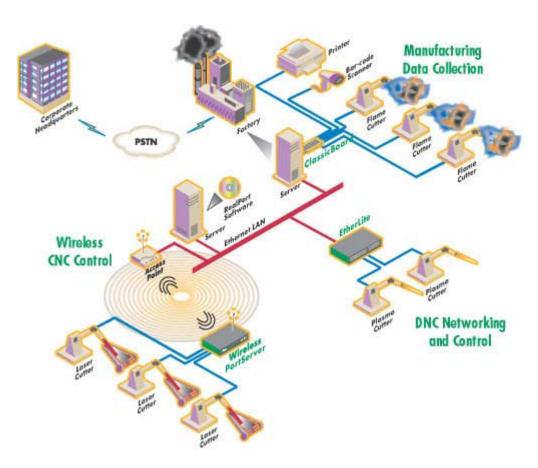
- Describes a specific implementation of a component interface
- Contains inter-connection information between components

```
<ComponentAssemblyDescription id="a HUDDisplay">
<connection>
   <name>GPS-RateGen</name>
   <internalEndPoint>
      <portName>Refresh</portName>
      <instance>a GPS</instance>
   </internalEndPoint>
   <internalEndPoint>
      <portName>Pulse</portName>
      <instance>a RateGen</instance>
   </internalEndPoint>
 </connection>
  <connection>
    <name>NavDisplay-GPS</name>
    <internalEndPoint>
       <portName>Refresh</portName>
       <instance>a NavDisplay</instance>
    </internalEndPoint>
    <internalEndPoint>
       <portName>Ready</portName>
       <instance>a GPS</instance>
    </internalEndPoint>
 </connection>
</ComponentAssemblyDescription>
```

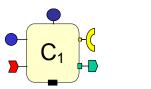


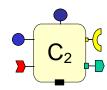
## Part 4 DRE System QoS Provisioning

**QoS Modeling** 



## Sources of Variability Impacting QoS (1/3)





- Understand the sources of variability in the problem/solution space that impacts QoS
- Find solutions to automate the mapping of the problem space to solution space

#### Per-component concerns

- Problem space: Functionality often supplied as third party COTS
- Solution space: Implementations for different platforms and languages
- *P->S mapping challenges*:
  - Implementations must match platform and language choice
  - Choice of implementation impacts end-to-end QoS

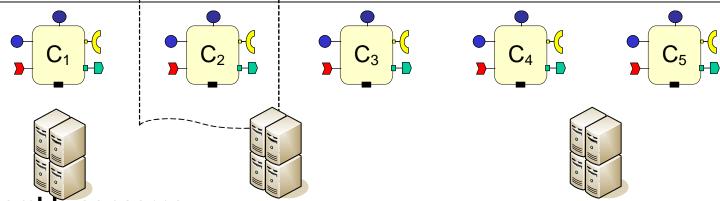
#### Communication concerns

- Problem space: Choice of communication paradigms (pub-sub, RPC, MOM) and requirements on QoS
- Solution space: Diversity in communication mechanisms e.g, CORBA IIOP, Java RMI, DDS, Event channels, and QoS mechanisms e.g., DiffServ, IntServ, MPLS
- P->S mapping challenges:
  - Decoupling application logic from provisioning communication QoS
  - Right optimizations in communication paths needed to enhance QoS
  - Redundancy and mixed mode communications needed to support QoS





## Sources of Variability Impacting QoS (2/3)



- Assembly concerns
  - Problem space: Discovering services and composing them together
  - Solution space: Interfaces and their semantics must match
  - P->S mapping challenges:
    - Must ensure functional and systemic compatibility in composition
    - Heterogeneity in platforms and languages in composition impacts QoS

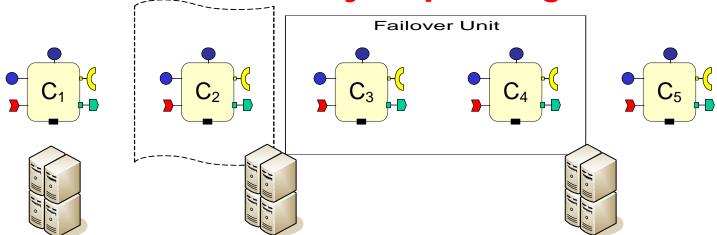
#### • Deployment concerns

- Problem space: Need resources e.g., CPU, memory, bandwidth, storage
- Solution space: Diversity in resource types and their configurations
- P->S mapping challenges:
  - How to select and provision resources such that end-to-end QoS is realized?
  - How to (re)allocate resources to maintain end-to-end QoS?
  - How to place components so that near optimal QoS tradeoffs are made?
  - How to allow sharing of components or assemblies?





## Sources of Variability Impacting QoS (3/3)



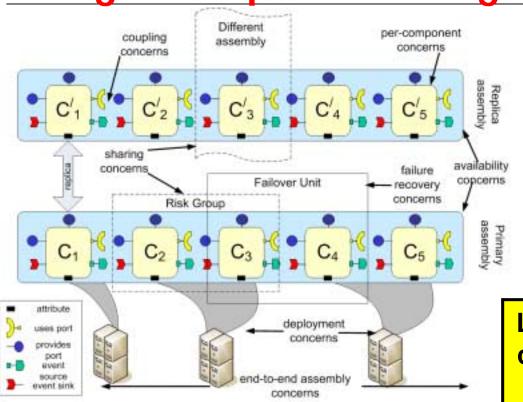
#### Configuration concerns

- Problem space: Multiple QoS requires right set of configurations
  - What is the unit of failover? What is the replication degree? Are entire assemblies replicated?
  - How to define access control rights?
  - Determining system task partitioning, schedulability
  - Defining network resource needs
- Solution space: Platforms provide high degree of configuration flexibility
- P->S mapping challenges:
  - What configuration options control a specific dimension of QoS?
  - How do different configuration options interact with each other?
  - How to configure heterogeneous platforms?
  - What impact deployment decisions 3 fave on configurations?





### A Single Perspective: Tangling of QoS Issues

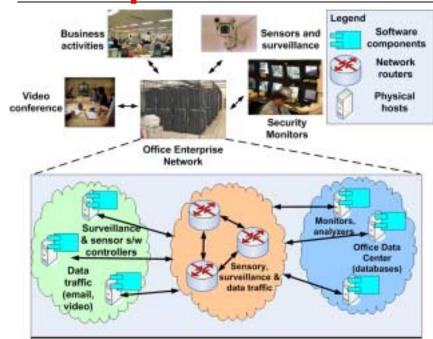


- Demonstrates numerous tangled para-functional concerns
- Significant sources of variability that affect endto-end QoS
- QoS concerns tangled across system lifecycle

Lifecycle-wide separation of concerns (SoC) & variability management is the key

Design-time Deployment-time Run-time

#### Requirements of a Solution Approach



Radio Conveyer Drive Management/Vork Power System Switching Unit Alarm Palet Present HumanMachin WatchSettingM PalletConveyer einterface Manager anager Patet Release Switch Order Validation Switch RobotManager Assembly Area intrusion Clock Handler Robot Am Control Station Robot In Work Hardware Interfaces Area Component interactions

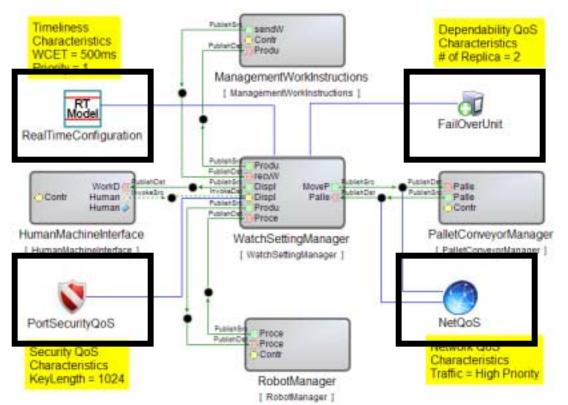
- Need expressive power to define QoS intent in the problem space, and perform design-time analysis
  - e.g., network QoS needs of application flows or end-to-end latencies
- Need to decouple DRE system functionality from systemic capabilities in the solution space
  - e.g., decouple robot manager logic from fault tolerance configurations
- Need to automate the mapping from problem to solution space
  - e.g., automate the (re)deployment and (re)configuration of system functionality to maintain QoS
- Need to provide a hosting platform with dynamic adaptation capabilities
  - e.g., survivability management of robot manager



# Component QoS Modeling Language (CQML)

#### Objectives:

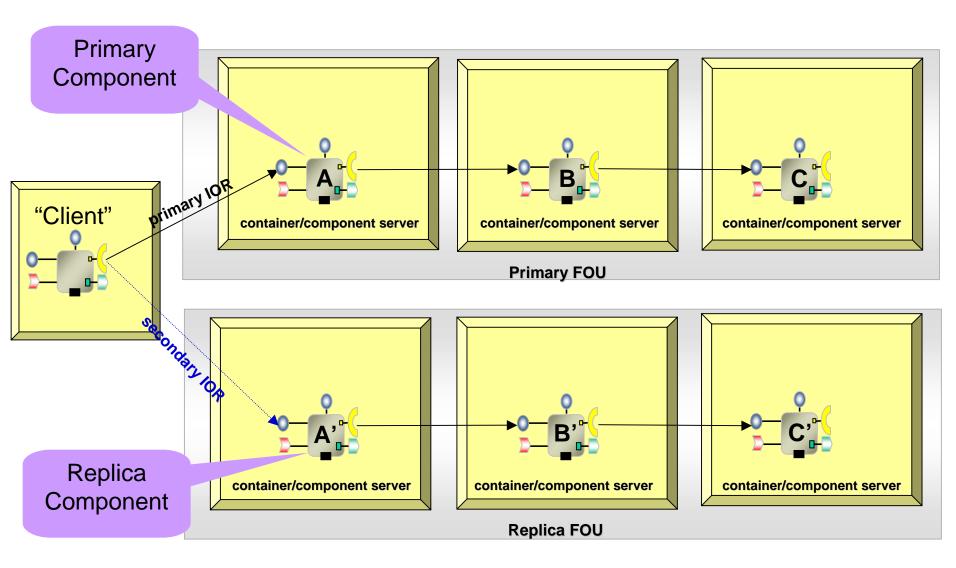
- Express QoS design intent
- Model crosscutting QoS concerns
- Perform design-time QoS tradeoff analysis



#### Challenges:

- Intuitive QoS abstractions
- Separation as well as unification of QoS concerns
  - 4 types of QoS modeling capabilities
    - Real-time
    - Fault tolerance
    - Security
    - Network QoS
  - Developed as overlay on a composition modeling language
  - Facility to integrate behavioral modeling
  - Unified internal mechanism for QoS integration
  - Pluggable back end analysis tools for QoS tradeoff analysis
    - e.g., Times tool

## **Example of Failover Unit Intent**







# **CQML FT Modeling Abstractions**

QoS Enhancements to PICML (Platform Independent Component Modeling Language)
Metamodel

- Fail-over Unit (FOU): Abstracts away details of granularity of protection (e.g. Component, Assembly, App-string)
- Replica Group (RPG): Abstracts away fault-tolerance policy details (e.g. Active/passive replication, statesynchronization, topology of replica)
- Shared Risk Group (SRG): Captures associations related to risk. (e.g. shared power supply among processors, shared LAN)

Model Interpreter (component placement constraint solver): Encapsulates an algorithm for component-node assignment based on replica distance metric



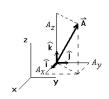
Protection granularity concerns



State-synchronization concerns



Component Placement constraints



Replica Distance Metric



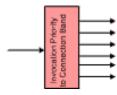


# **CQML RT & NetQoS Modeling Abstractions**

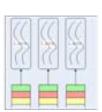
- Real-time modeling provided by the RT-Model element
  - Leverages known patterns of real-time programming usage:
    - e.g., real-time CORBA
  - Enables modeling of:
    - Priority models
    - Banded connections
    - Thread pools
    - Thread pools with Lanes
    - Resources e.g., CPU, memory
- Network QoS modeling allows modeling QoS per application flow
  - Classification into high priority, high reliability, multimedia and best effort classes
  - Enables bandwidth reservation in both directions
  - Client propagated or server declared models











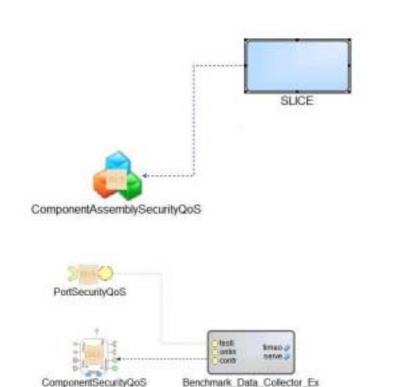






# **CQML Security Modeling Abstractions**

- Focus on role based access control
- Fine-grained:
  - Interface Operation
  - Assembly Property
  - Component Attribute
- Coarse-grained:
  - Interface
  - Set of Operations
  - Class of Operations (based on Required Rights corba:gsum)
  - Inter-Component Execution Flow (Path in an Assembly)





Track





[ Benchmark\_Data\_Collector\_Ex ]

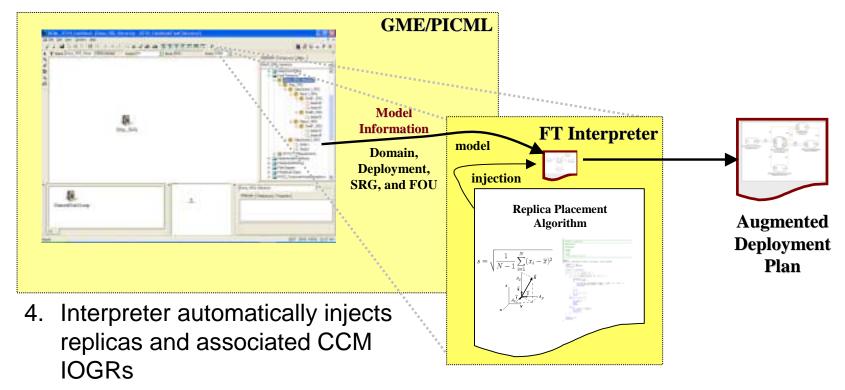






# Modeling & Generative Steps in CQML

- 1. Model components and application strings in PICML
- e.g., Model Fail Over Units (FOUs) and Shared Risk Groups (SRGs) using CQML
- 3. Generate deployment plan

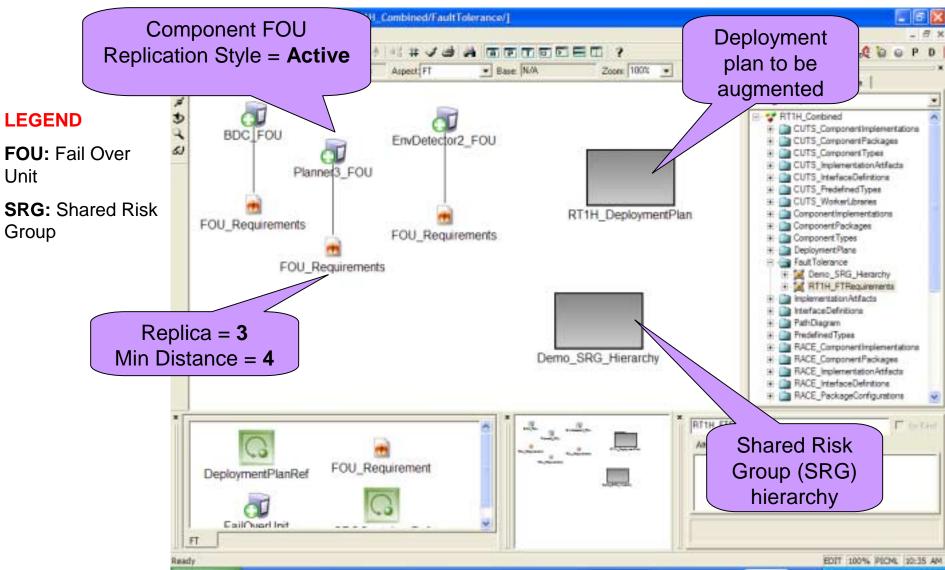


 Distance-based constraint algorithm determines replica placement in deployment descriptors.





# **Example: FT Requirements Modeling in CQML**

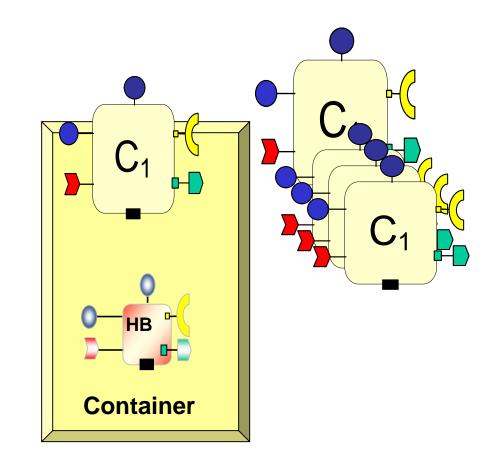






### **Automated Sample FT QoS Provisioning**

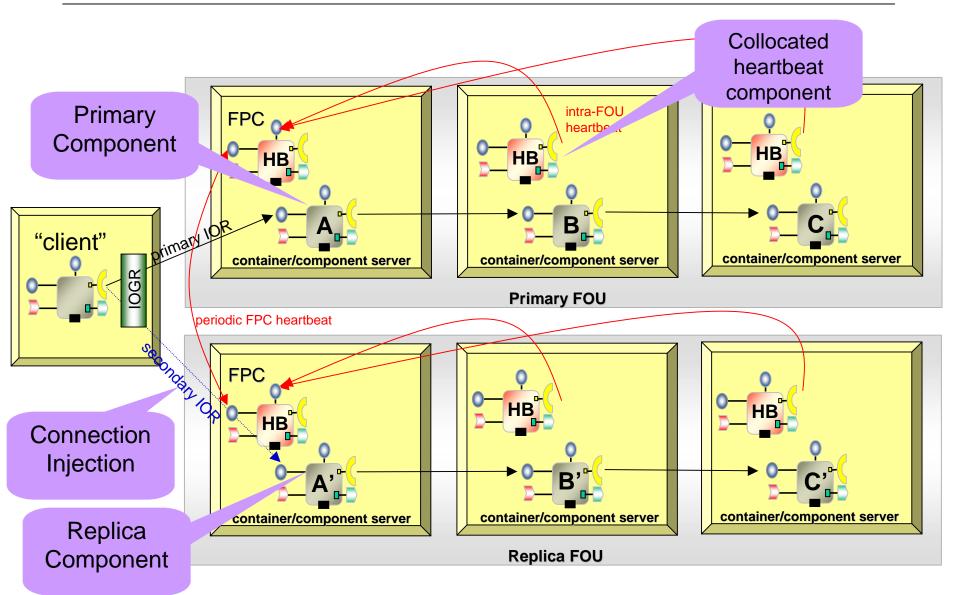
- Automatic Injection of replicas
  - Augmentation of deployment plan based on number of replicas
- Automatic Injection of FT infrastructure components
  - E.g. Collocated "heartbeat" (HB) component with every protected component.
- Automatic Injection of connection meta-data
  - Specialized connection setup for protected components (e.g. Interoperable Group References IOGR)







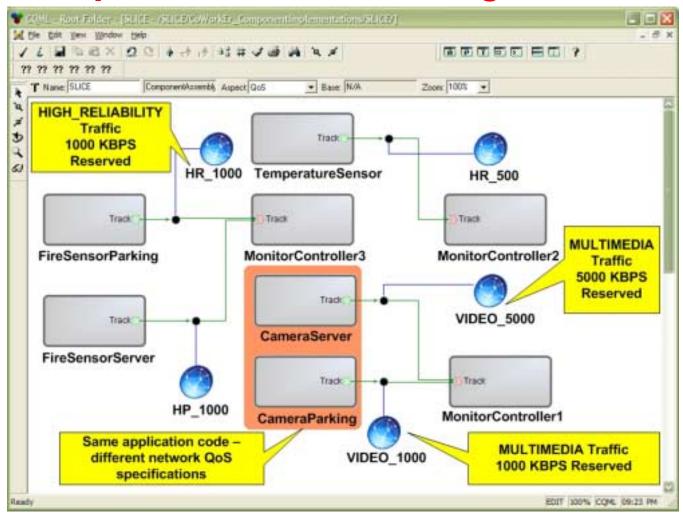
# **Automated Heartbeat Component Injection**







# **Example: NetQoS Modeling in CQML**



- Expressing QoS intent for application flows
- Multiple connections sharing QoS can use same

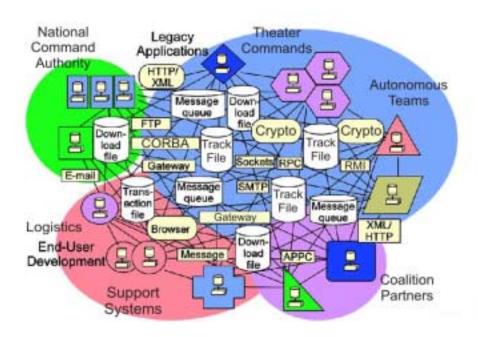


element



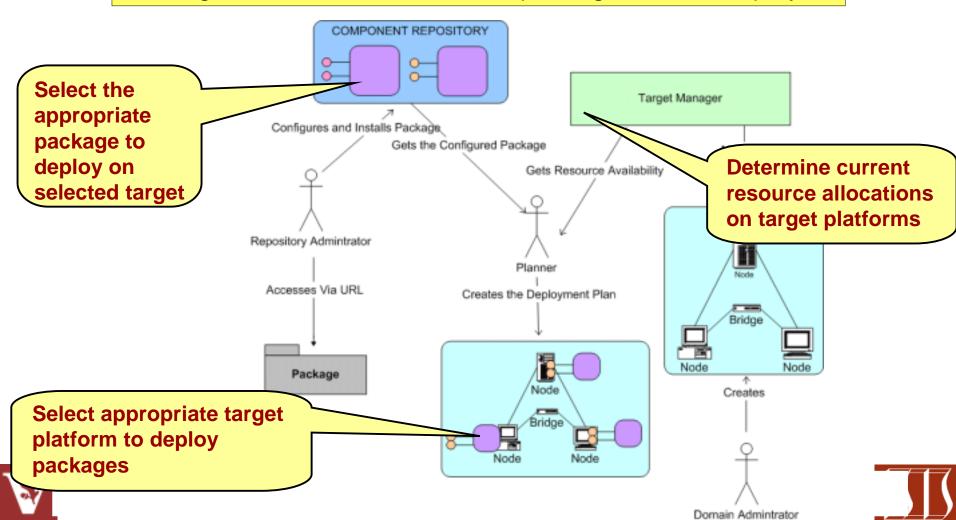
# Part 5 DRE System Deployment Planning

#### Placement Algorithms

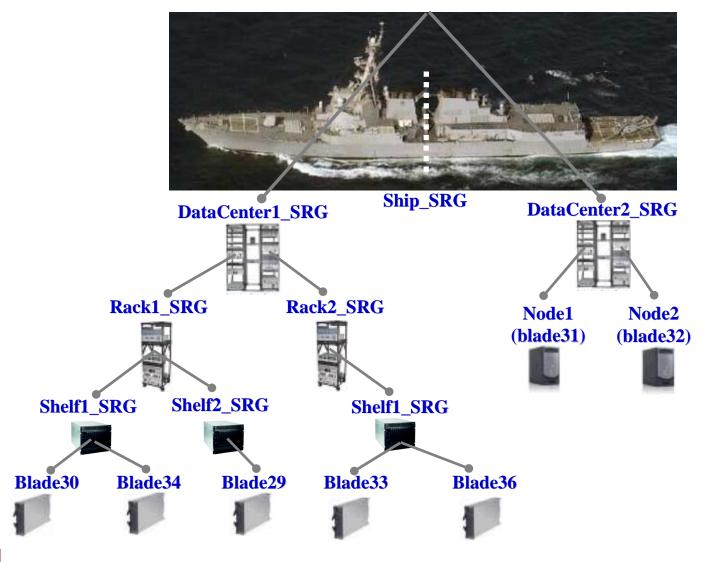


# **Deployment Planning Problem**

Component integrators must make appropriate deployment decisions, including identifying the entities (e.g., CPUs) of the target environment where the packages will be deployed



# **Example of Shared Risk Group Intent**





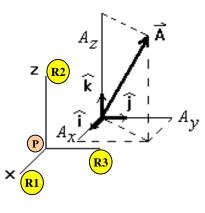


# **Example Replica Placement Algorithm**

Define N orthogonal vectors, one for each of the distance values computed for the N components (with respect to a primary) and vector-sum these to obtain a resultant. Compute the magnitude of the resultant as a representation of the <u>composite distance</u> captured by the placement

- 1. Compute the distance from each of the replicas to the primary for a placement.
- 2. Record **each distance as a vector**, **where** <u>all</u> vectors are orthogonal.
- 3. Add the vectors to obtain a resultant.
- Compute the magnitude of the resultant.
- 5. Use the resultant in all comparisons (either among placements or against a threshold)
- 6. Apply a penalty function to the composite distance (e.g. pair wise replica distance or uniformity)

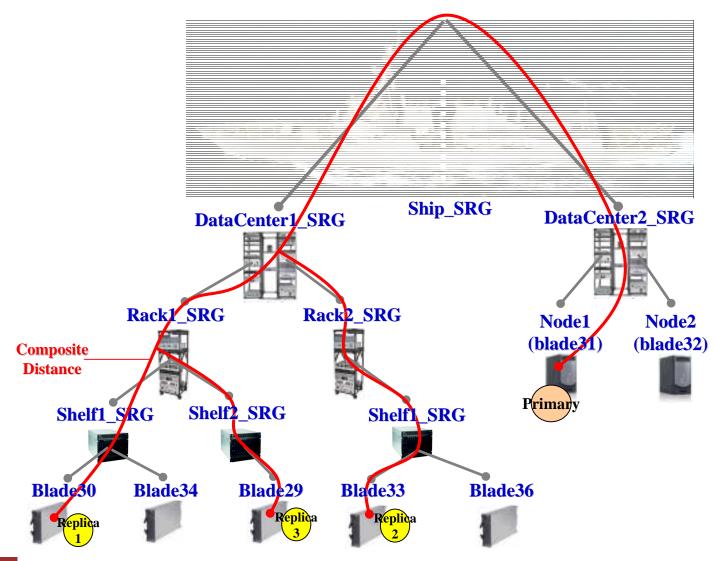
$$s = \sqrt{\frac{1}{N-1} \sum_{i=1}^{N} (x_i - \overline{x})^2}$$







## **Example: Automated Component Placement**

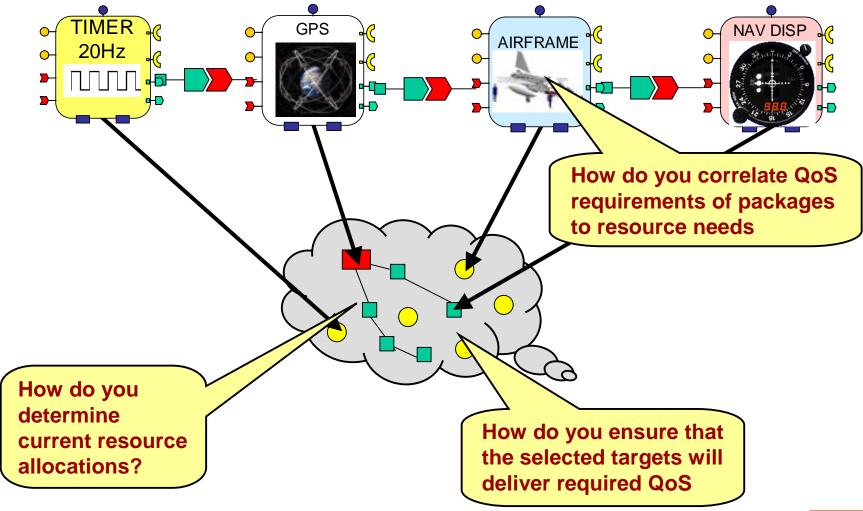






# **Deployment Planning Challenges**

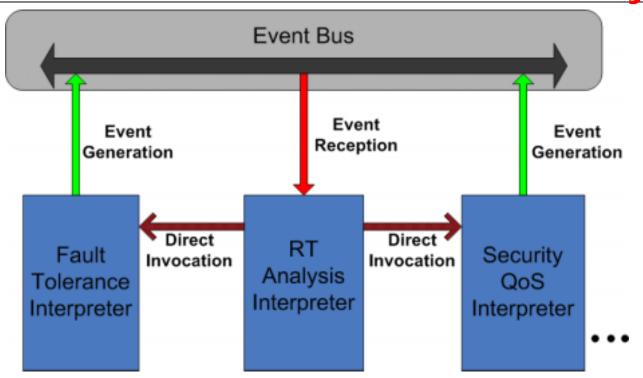
How to ensure a particular deployment configuration maximizes QoS







#### **CQML QoS Unification & Tradeoff Analysis**

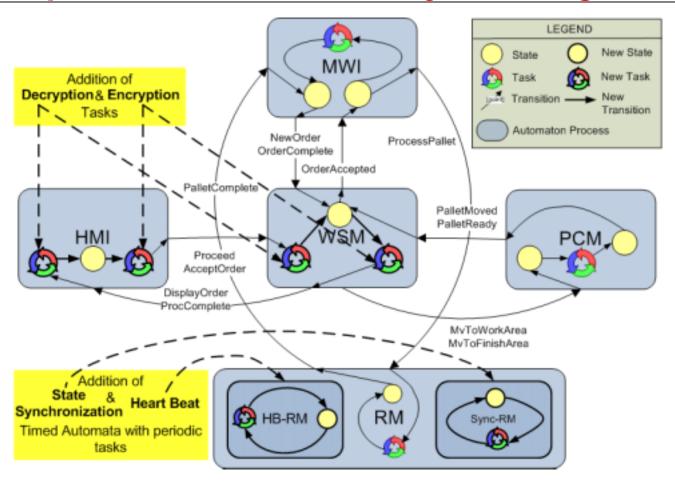


- Leverages QoS and behavioral models
- Model interpretation using an EventBus framework
- Each QoS dimension publishes its modeled QoS requirements
- A particular QoS dimension is chosen as the driver e.g., real-time
  - Acts as subscriber of events generated by other dimensions
  - Driver interpreter integrates other QoS dimensions making tradeoffs on the way



Pluggable back end analysis and generative tools

#### Example: QoS Tradeoff Analysis using TIMES tool



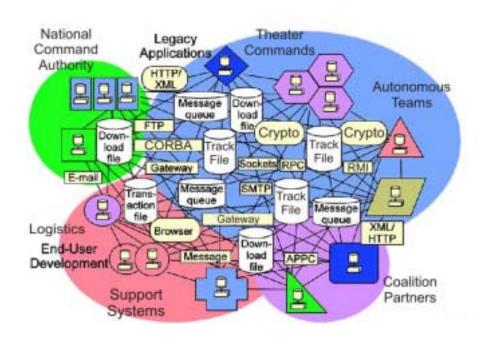
- CQML EventBus architecture weaves in FT and Security concerns into RT concerns
- Feeds to backend schedulability analysis tools e.g., Times





# Part 6 Configuring Middleware for DRE Systems

#### Middleware Configuration Options



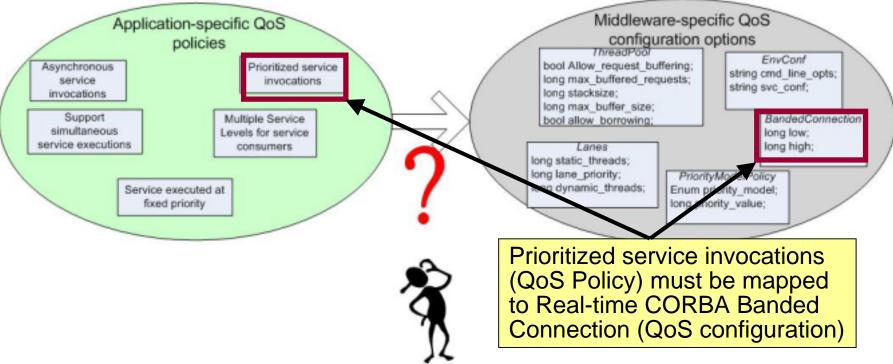
Domain-specific
Services

Common Services

Distribution
Middleware
Infrastructure
Middleware

Operating System & Network Stack

Translating QoS Policies to QoS Options

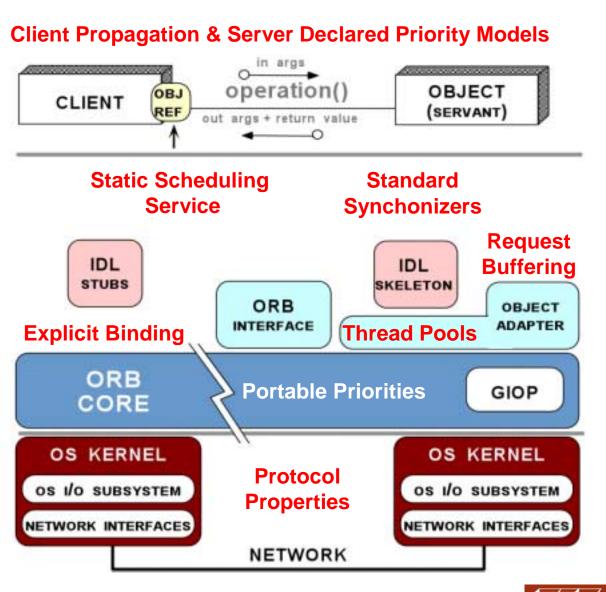


- Large gap between application QoS policies & middleware QoS configuration options
  - Bridging this gap is necessary to realize the desired QoS policies
- The mapping between application-specific QoS policies & middlewarespecific QoS configuration options is non-trivial, particular for large systems

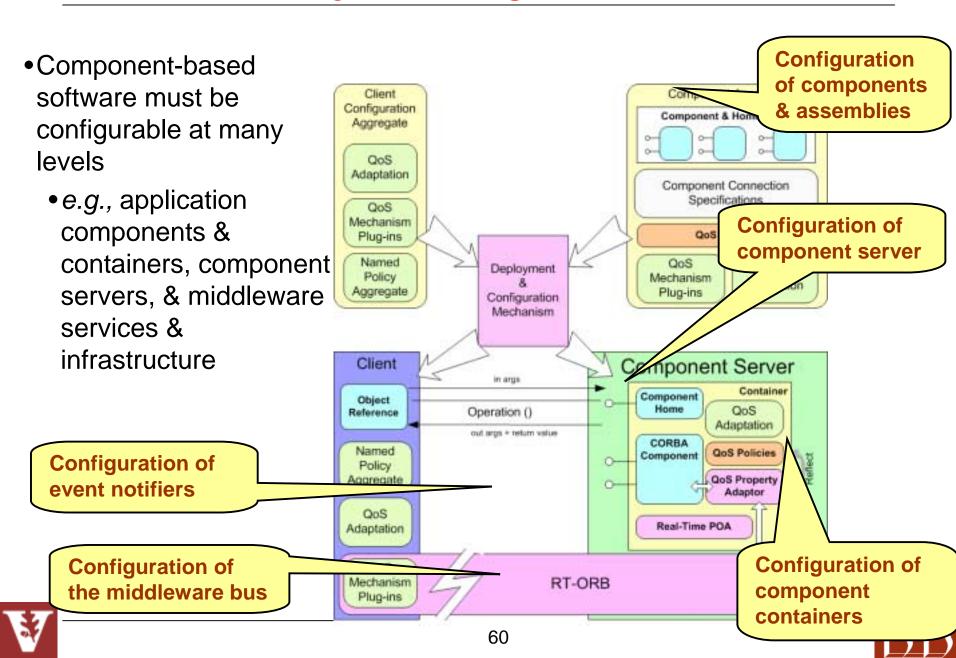


# Challenge 1: Mapping QoS Policies to QoS Options

- Conventional mapping approach requires deep understanding of the middleware configuration space
  - e.g., multiple
     types/levels of QoS
     policies require
     configuring
     appropriate number
     of thread pools,
     threadpool lanes
     (server) & banded
     connections (client)

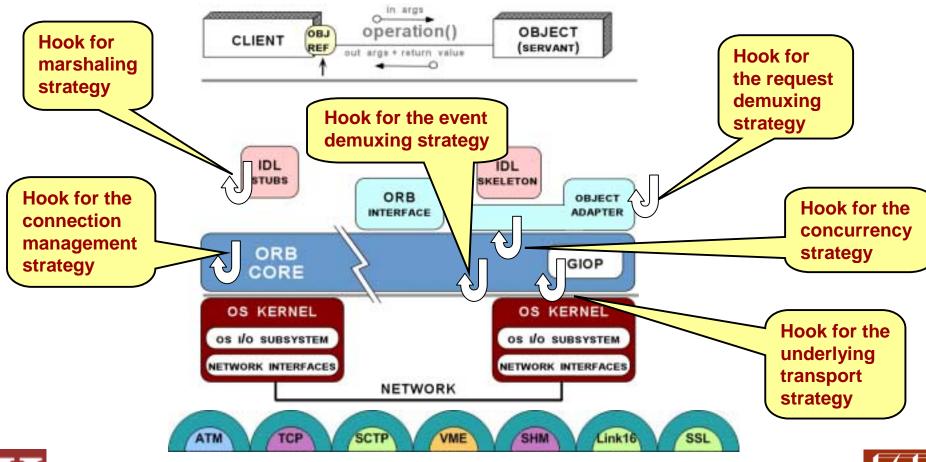


# The Multilayer Configuration Problem



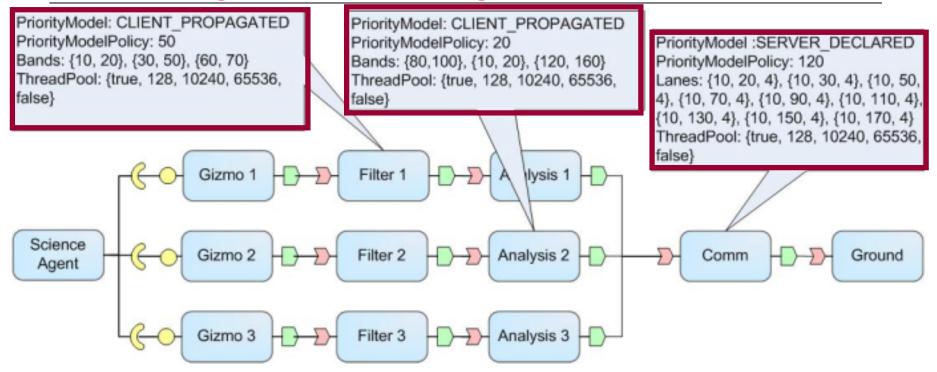
# **Example: The M/W Bus Configuration**

Component middleware is characterized by a large *configuration* space that maps known variations in the application requirements space to known variations in the middleware solution space





# Challenge 2: Choosing QoS Option Values



- Individually configuring component QoS options is tedious & error-prone
  - e.g., ~10 distinct QoS options per component & ~140 total QoS options for entire NASA MMS mission prototype
- Manually choosing valid values for QoS options does not scale as size & complexity of applications increase





# **Example: Configuring Container Policies**

Thread Pool

Thread Pool

Prio = 200

Prio = 100

Determine various middleware policies for server objects e.g., security, lifetime, replication Determine thread pool sizes; how are they shared; number of lanes and their priorities; if borrowing is enabled

Determine end-to-end priority propagation model to use

Ensure semantic compatibility among chosen configurations

 This "glue code" is traditionally handcrafted server object management middleware

Container

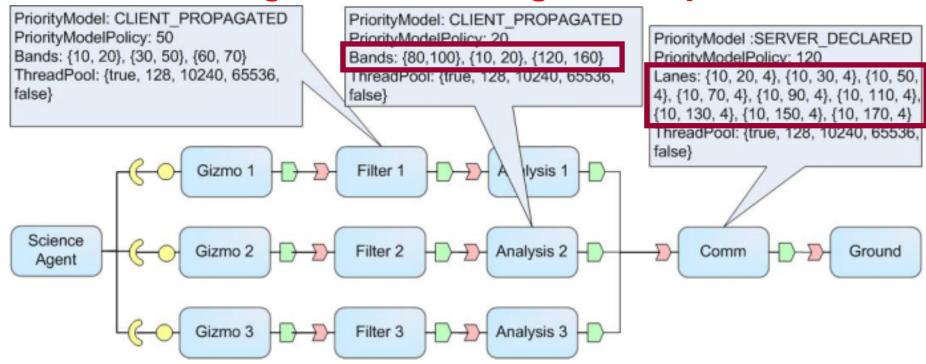
Determine the server object management policies

**Determine right buffer sizes** 

 Existing techniques for metadata configurations rely on ad hoc manual configurations e.g., CORBA server-side programming



## **Challenge 3: Validating QoS Options**

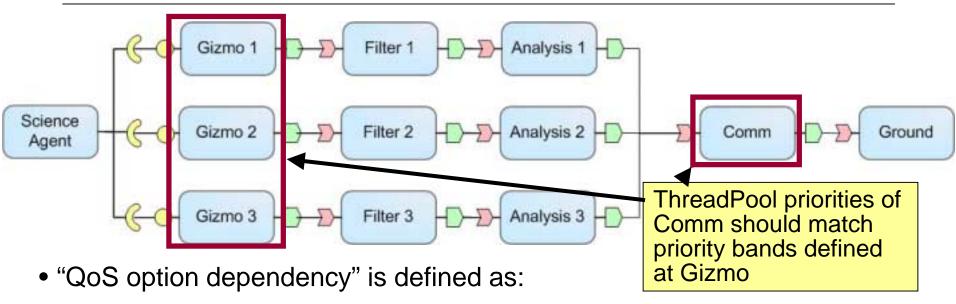


- Each QoS option value chosen should be validated
  - e.g., Filter priority model is CLIENT\_PROPAGATED, whereas Comm priority model is SERVER\_DECLARED
- Each system reconfiguration (at design time) should be validated
  - e.g., reconfiguration of *bands* of Analysis should be validated such that the modified value corresponds to (some) *lane* priority of the Comm



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# Challenge 4: Resolving QoS Option Dependencies

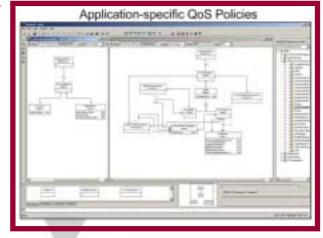


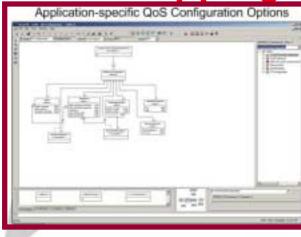
- Dependency between QoS options of different components
- Manually tracking dependencies is hard or in some cases infeasible
  - Dependent components may belong to more than one assembly
  - Dependency may span beyond immediate neighbors
    - -e.g., dependency between Gizmo & Comm components
- Empirically validating configuration changes by hand is tedious, errorprone, & slows down development & QA process considerably
  - Several iterations before desired QoS is achieved (if at all)



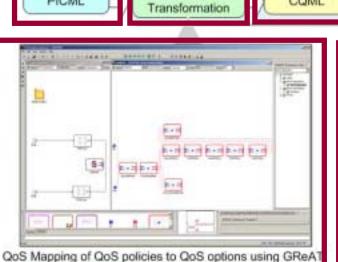
Solution Approach: Model-Driven QoS Mapping

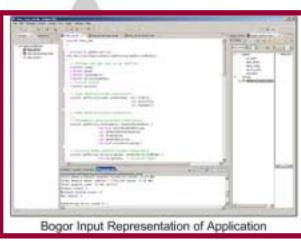
- QUality of service pICKER (QUICKER)
  - Model-driven engineering (MDE) tools model application QoS policies
  - Provides
     automatic
     mapping of QoS
     policies to QoS
     configuration
     options
  - Validates the generated QoS options





Model Checker





 Automated QoS mapping & validation tools can be used iteratively throughout the development process



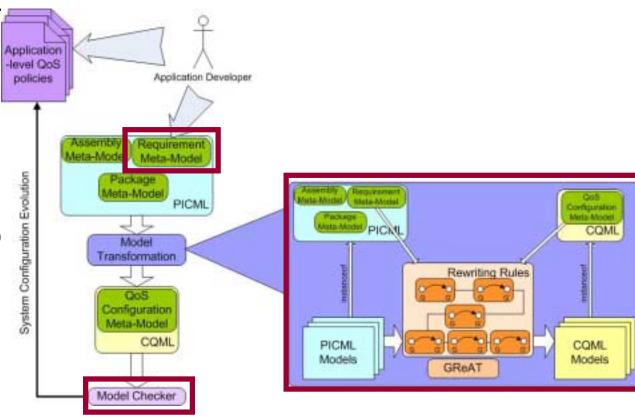


Target Platforn

# **QUICKER Enabling MDE Technologies**

Enhanced Platform
 Independent Component
 Modeling Language
 (PICML), a DSML for
 modeling component based applications

- QoS mapping uses
   Graph Rewriting &
   Transformation (GReAT)
   model transformation
   tool
- Customized Bogor model-checker used to define new types & primitives to validate QoS options





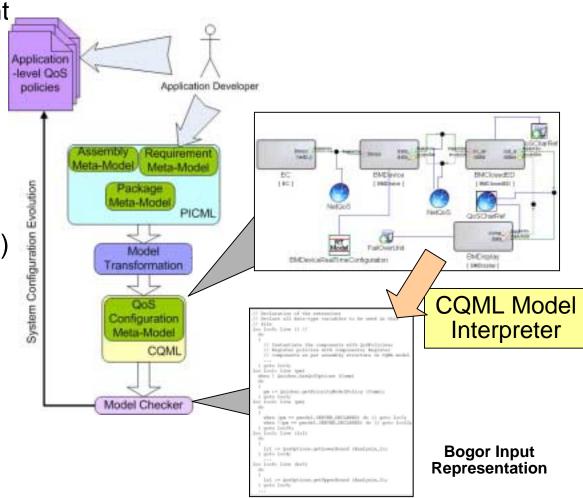


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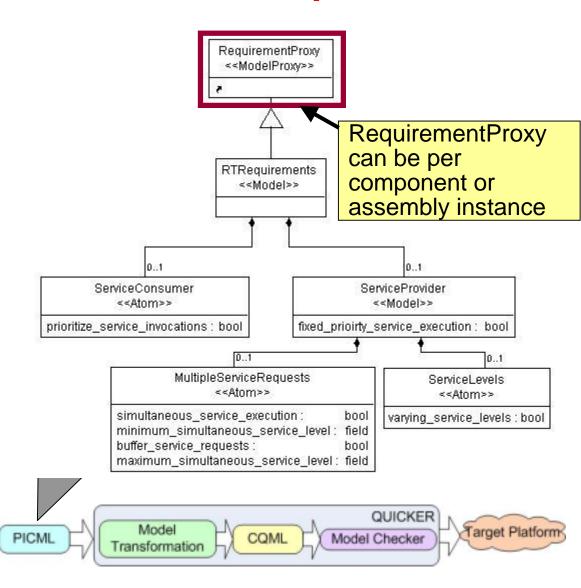


 CQML Model interpreter generates Bogor Input Representation (BIR) of DRE system from its CQML model



## QUICKER: Transformation of QoS policies(1/2)

- Platform-Independent
   Modeling Language
   (PICML) represents
   application QoS policies
  - PICML captures policies in a platformindependent manner
  - Representation at multiple levels
    - e.g., component- or assembly-level

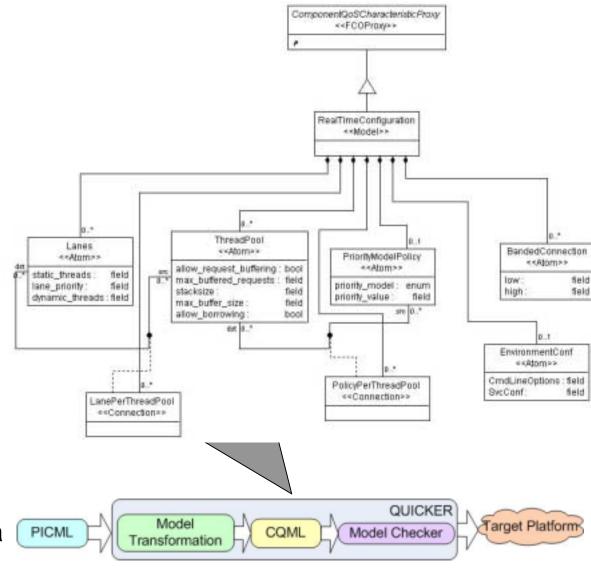






# QUICKER: Transformation of QoS policies (1/2)

- Platform-Independent
   Modeling Language
   (PICML) represents
   application QoS policies
  - PICML captures policies in a platformindependent manner
  - Representation at multiple levels
    - e.g., component- or assembly-level
- Component QoS Modeling Language (CQML) represents QoS options
  - CQML captures QoS configuration options in a platform-specific manner

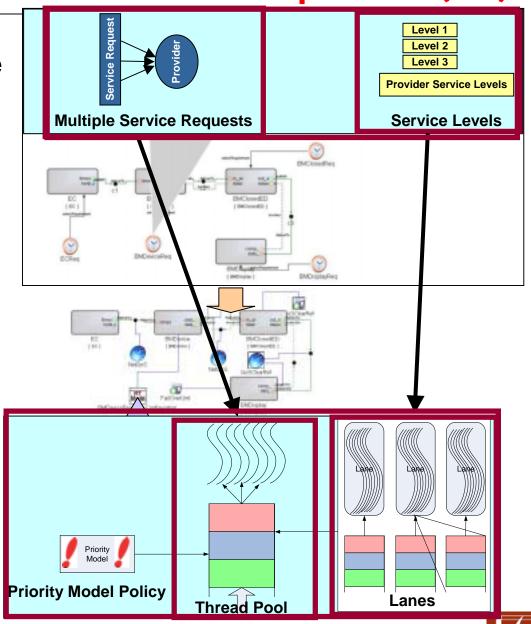






#### QUICKER: Transformations of QoS policies(2/2)

- Translation of application QoS policies into middleware QoS options
  - Semantic translation rules specified in terms of input (PICML) & output (CQML) type graph
    - e.g., rules that translate multiple application service requests & service level policies to corresponding middleware QoS options
  - QUICKER transformation engine maps QoS policies (in PICML) to QoS configuration options (in CQML)





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#### QUICKER: Validation of QoS Options (1/2)

- 1. Representation of middleware QoS options in Bogor model-checker
  - BIR extensions allow representing domain-level concepts in a system model
  - QUICKER defines new BIR extensions for QoS options
    - Allows representing QoS options & domain entities directly in a Bogor input model
      - -e.g., CCM components, Realtime CORBA lanes/bands are first-class Bogor data types
  - Reduces size of system model by avoiding multiple low-level variables to represent domain concepts & QoS options

```
extension QoSOptions for
edu.ksu.cis.bogor.module.QoSOptions.QoSOptionsModule
                             be used for
  typedef lane;
  typedef band;
  typedef threadpool;
  typedef prioritymodel;
  typedef policy;
  expdef QoSOptions.lane createLane
  int static, int priority, int dynamic);
  // ThreadPool constructor.
  expdef QoSOptions.threadpool
  createThreadPool (boolean allowregbuffering,
  int maxbufferedrequests, int stacksize, int
   maxbuffersize, boolean allowborrowing);
  // Set the band(s) for QoS policy.
  actiondef registerBands (QoSOptions.policy
  policy, QoSOptions.band ...);
  // Set the lane(s) for QoS policy.
  actiondef registerLanes (QoSOptions.policy
  policy, QoSOptions.lane ...);
extension Quicker for
edu.ksu.cis.bogor.module.Quicker
  // Defines the new type.
  typedef Component;
  // Component Constructor.
  expdef Quicker.Component
  createComponent (string component);
  // Set the QoS policy for the component.
  actiondef registerQoSOptions (Quicker.Component
    component, QoSOptions.policy policy);
  // Make connections between components.
  actiondef connectComponents (Quicker.Component
    server, Quicker. Component client);
```



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### QUICKER: Validation of QoS Options (2/2)

- 2. Representation of properties (that a system should satisfy) in Bogor
  - BIR primitives define language constructs to access & manipulate domain-level data types, e.g.:
    - Used to define rules that validate QoS options & check if property is satisfied
- 3. Automatic generation of BIR of DRE system from CQML models

Rule determines if ThreadPool priorities at Comm match priority bands at Analysis

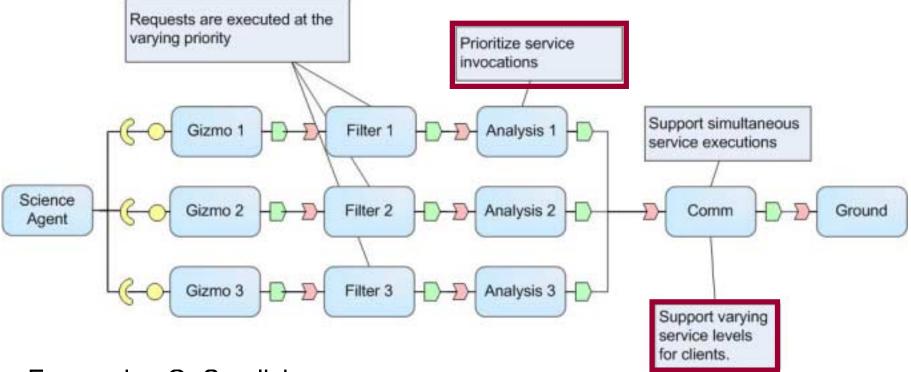
Model interpreters auto-generate Bogor Input Representation of a system from its CQML model

```
Declaration of the extensions
// Declare all data-type variables to be used in this
oc loc0: live {} //
   // Instantiate the components with QoSPolicies;
   // Register policies with components; Register
   // components as per assembly structure in CQML model
 when ! Quicker.hasQoSOptions (Comm)
   pm := Quicker.getPriorityModelPolicy (Comm);
   goto loc2;
   when (pm == pmodel.SERVER_DECLARED) do {} goto loc3;
   when ! (pm == pmodel.SERVER_DECLARED) do () goto loc12
loc loc3: live {lr1}
   lr1 := QosOptions.getLowerBound (Analysis_1);
   goto loc4;
loc loc8: live {hr3}
   lr1 := QosOptions.getUpperBound (Analysis_3);
   goto loc9;
```





Soln: Translating Policies to Options (1/2)



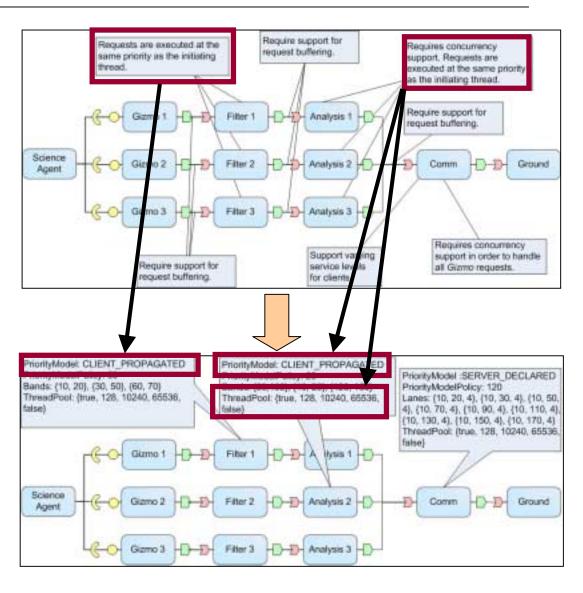
- Expressing QoS policies
  - PICML modes application-level QoS policies at high-level of abstraction
    - e.g., multiple service levels support for Comm component, service execution at varying priority for Analysis component
  - Reduces modeling effort
    - e.g., ~25 QoS policy elements for MMS mission vs. ~140 QoS options





### Soln: Translating Policies to Options (2/2)

- Mapping QoS policies to QoS options
  - GReAT model transformations automate the tedious & error-prone translation process
- Transformations generate QoS configuration options as CQML models
  - Allow further transformation by other tools
    - e.g., code optimizers & generators
  - Simplifies application development & enhances traceability

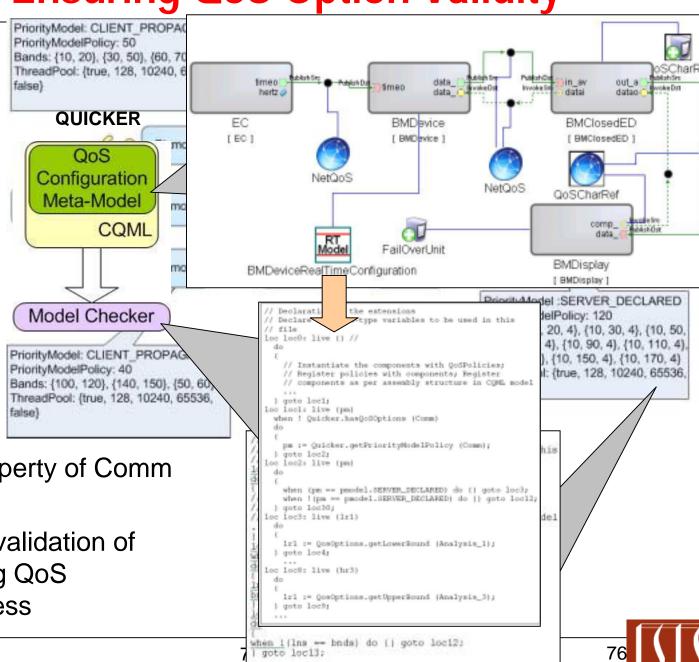






### Soln: Ensuring QoS Option Validity

- CQML model interpreter generates BIR specification from CQML models
- BIR primitives
   used to check
   whether a given
   set of QoS options
   satisfies a system
   property
  - e.g., fixed priority service execution, a property of Comm component
- Supports iterative validation of QoS options during QoS configuration process

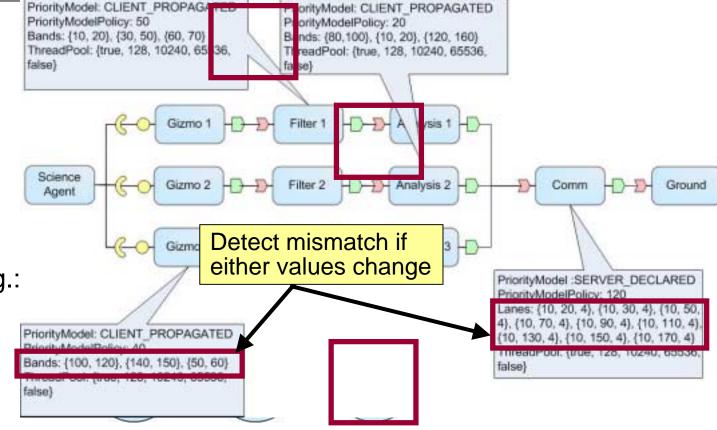


### Soln: Resolving QoS Option Dependencies

 Dependency structure maintained in Bogor used to track dependencies between QoS options of components, e.g.:

> Analysis & Comm are connected

> Gizmo & Comm are dependent



**Dependency Structure of MMS Mission Components** 

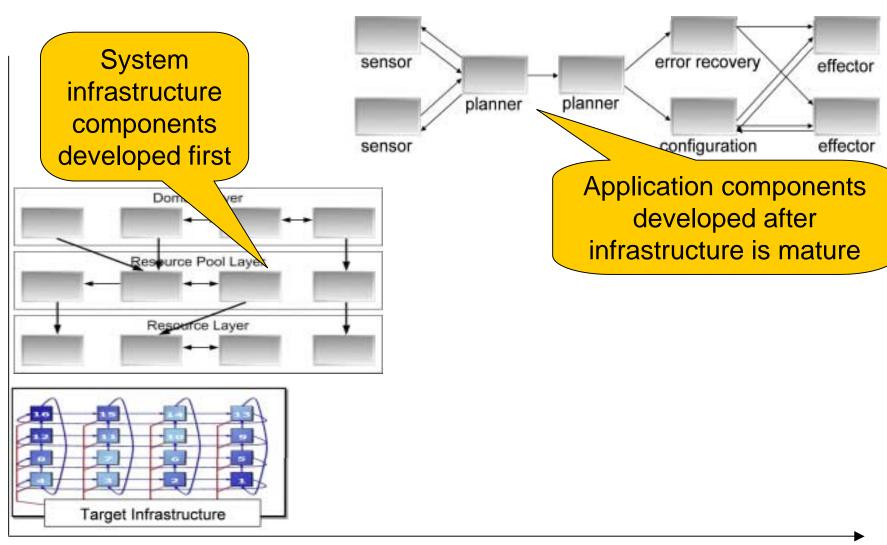
 Change(s) in QoS options of dependent component(s) triggers detection of potential mismatches

e.g., dependency between Gizmo invocation priority & Comm lane priority

## Part 7 Continuous System QoS Validation using "What If" Analysis

MDE for Emulation Techniques

### Serialized Phasing in DRE Systems (1/2)



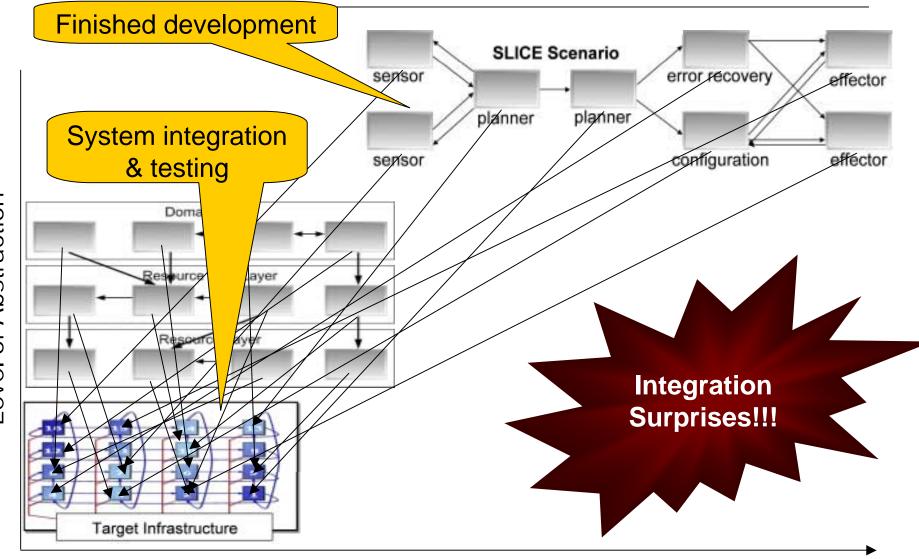
**Development Timeline** 





# evel of Abstraction

### Serialized Phasing in DRE Systems (2/2)

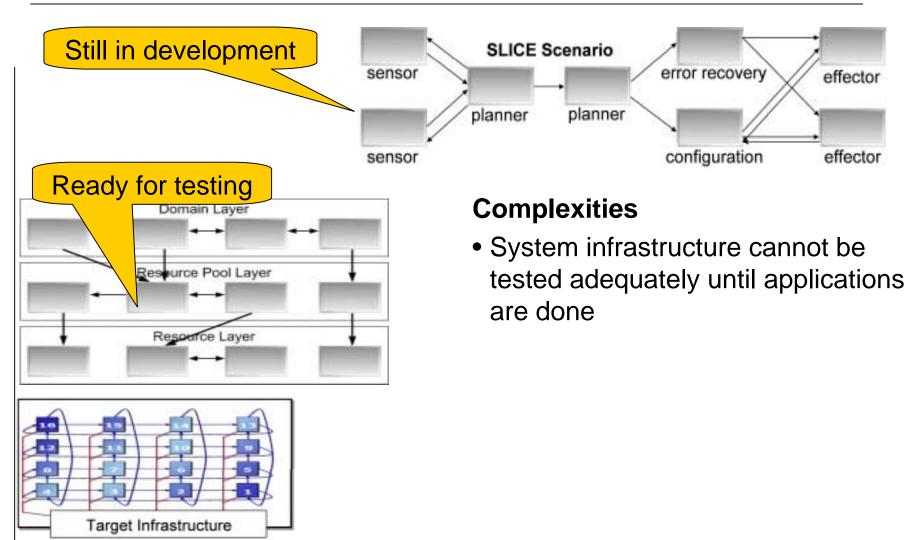


Development Timeline





### **Complexities of Serialized Phasing**

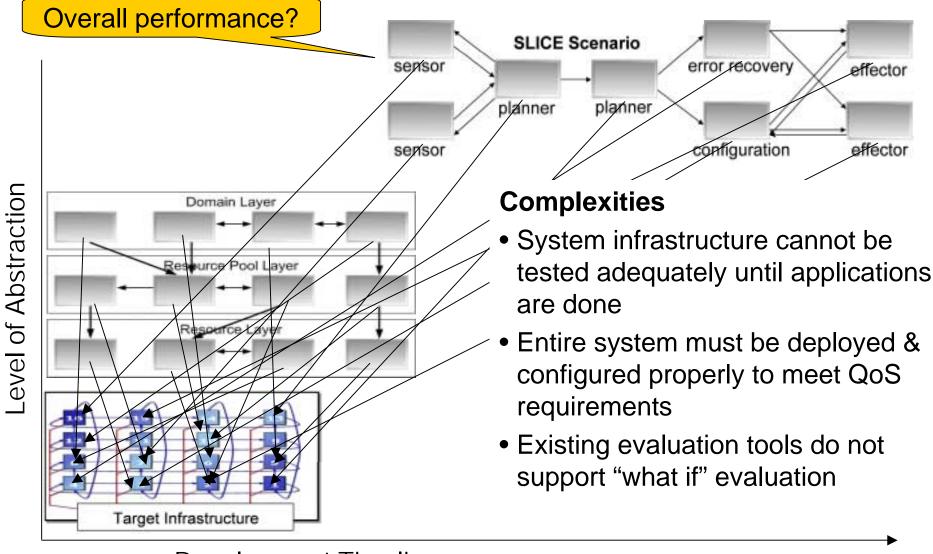








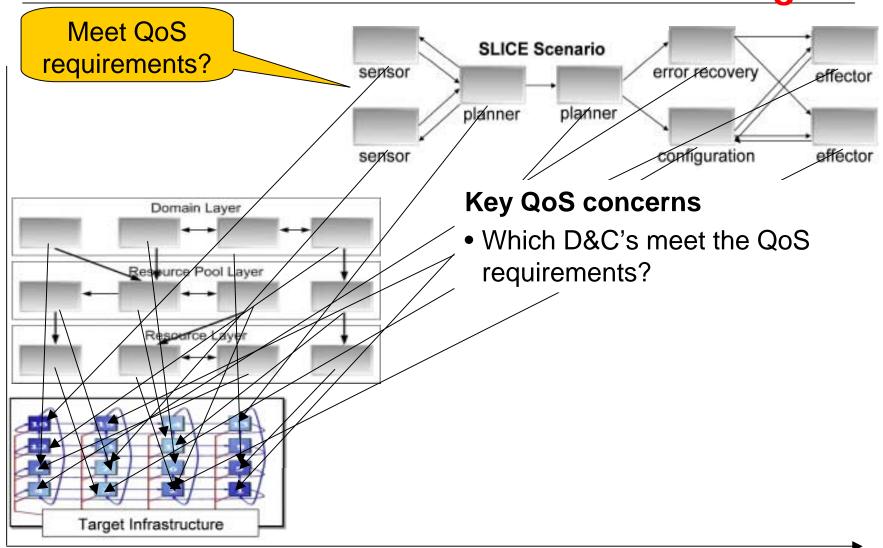
### **Complexities of Serialized Phasing**



**Development Timeline** 



### **QoS Concerns with Serialized Phasing**

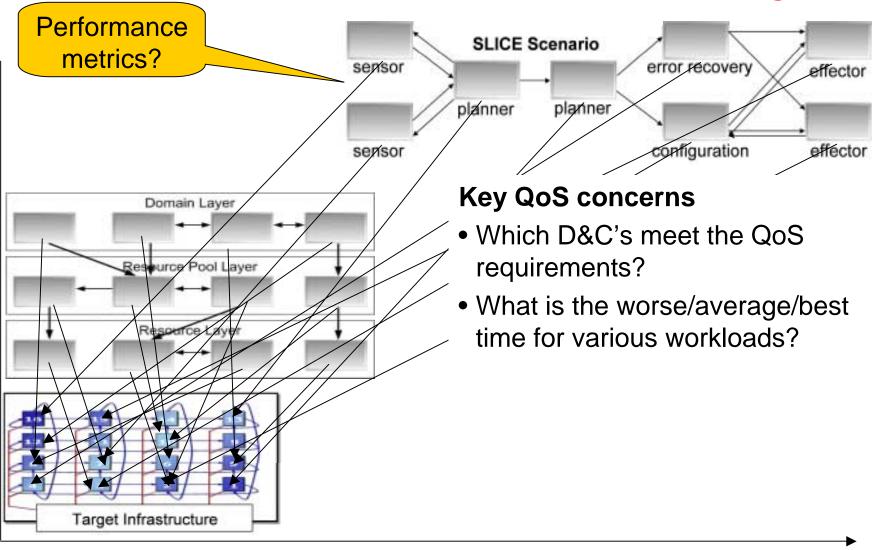


**Development Timeline** 





### **QoS Concerns with Serialized Phasing**

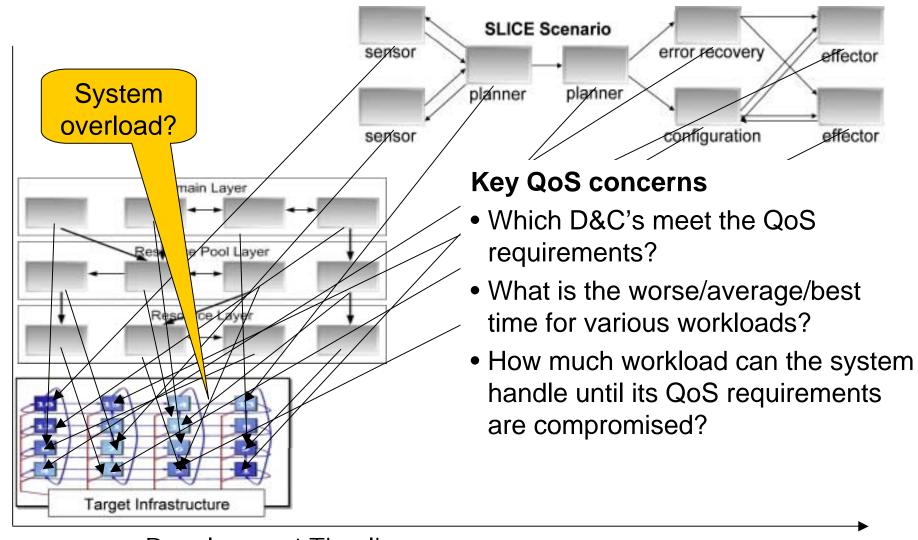








### **QoS Concerns with Serialized Phasing**



**Development Timeline** 



### Approach: Emulate Behavior using Next Generation

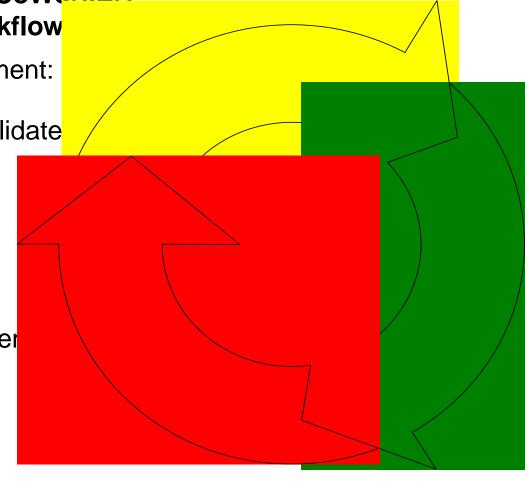
System Execution Modeling Tools
Component Workload Emulator (CoWorkEr)

Utilization Test Suite (CUTS) Workflow

While target system under development:

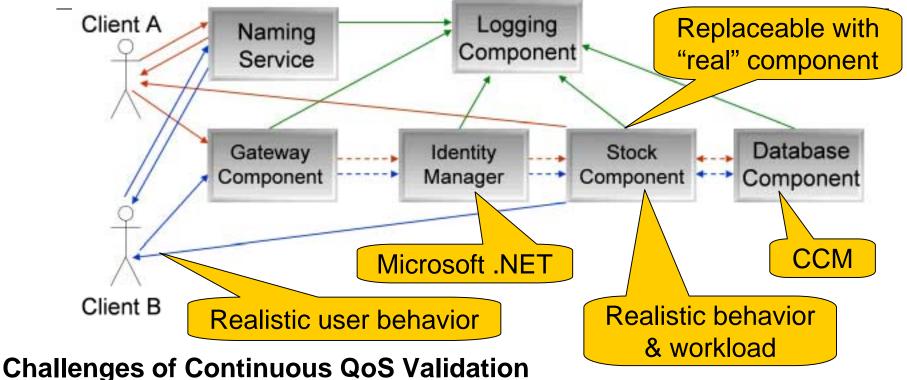
 Use a domain-specific modeling language (DSML) to define & validate infrastructure specifications & requirements

- 2. Use DSML to define & validate application specifications & requirements
- Use middleware & MDE tools to generate D&C metadata so system conforms to its specifications & requirements
- 4. Use analysis tools to evaluate & verify QoS performance
- 5. Redefine system D&C & repeat



Enables testing on target infrastructure throughout the development lifecycle http://www.dre.vanderbilt.edu/~hillj/docs/publications/CUTS-RTCSA06.pdf

### **Distributed Stock Application Challenges**



- 1. Emulating Business Logic: Emulated components must resemble their counterparts in both supported interfaces & behavior
- 2. Realistic Mapping of Emulated Behavior: Behavior specification should operate at a high-level of abstraction & map to realistic operations
- 3. Technology Independence: Behavior specification should not be tightly coupled to a programming language, middleware platform, hardware technology, or MDE tool



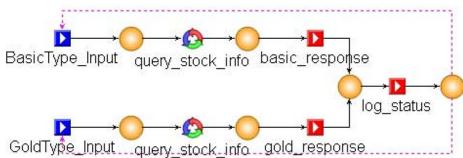
#### **DSMLs for Continuous QoS Validation**

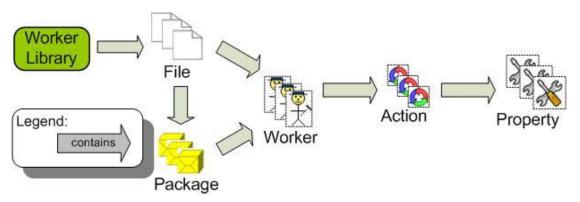
#### **Component Behavior Modeling Language (CBML)**

- a high-level domain-specific modeling language for capturing the behavior of components
  - e.g., its actions & states

#### Workload Modeling Language (WML)

 a domain-specific modeling language for capturing workload, & used to parameterize the actions on CBML





CBML & WML were both developed using GME (http://www.isis.vanderbilt.edu/projects/GME)

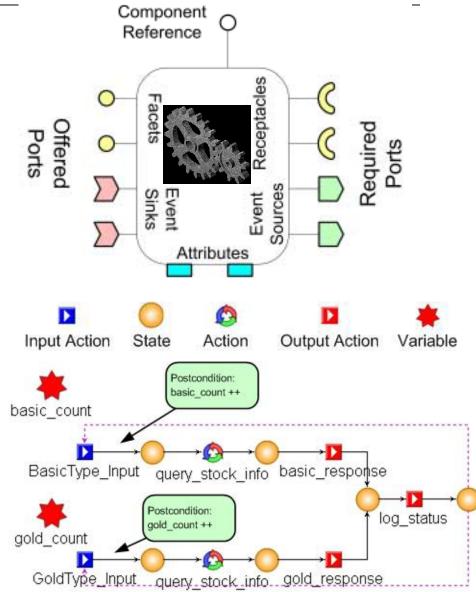
#### The Component Behavior Modeling Language

#### Context

- Component's behavior can be classified as: communication & internal actions
- Need to define these actions as close as possible to their real counterpart (i.e., Challenge 1)

#### **Research Contributions of CBML**

- Based on the semantics of Input/Output (I/O) Automata
  - i.e., contains representative elements
- Behavior is specified using a series of action to state transitions
- Transitions have preconditions that represent guards & effects have postconditions that determine the new state after an action occurs
- Variables are used to store state & can be used within pre & postconditions







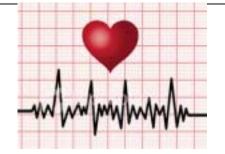
#### **Domain-Specific Extensions to CBML**

#### **Context**

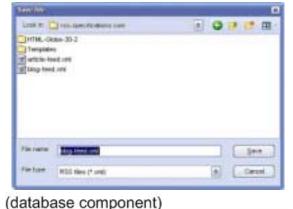
- Some aspects of componentbased systems are not first-class entities in I/O automata
  - e.g., lifecycle events & monitoring notification events
- Extended CBML (without affecting formal semantics) to support domain-specific extensions

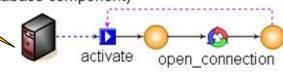
#### **Domain-Specific Extensions**

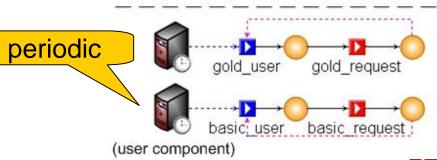
- Environment events input actions to a component that are triggered by the hosting system rather than another component
- Periodic events input actions from the hosting environment that ccur periodically











### **Ensuring Scalability of CBML**

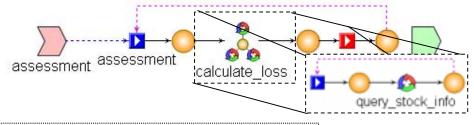
#### Context

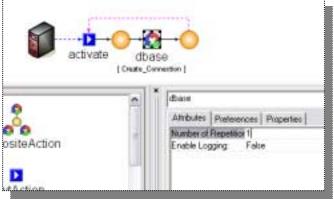
- One of the main goals of higherlevel of abstraction is simplicity & ease of use
- It is known that one of the main drawbacks of automata languages is scalability

#### **Usability Extensions**

- Composite Action contains other actions & helps reduce model clutter
- Repetitions determines how many times to repeat an action to prevent duplicate sequential actions
- Log Action an attribute of an Action element that determines if the action should be logged
- **Tool Specific** GME add-on that auto-generates required elements (e.g., states)











The Workload Modeling Language

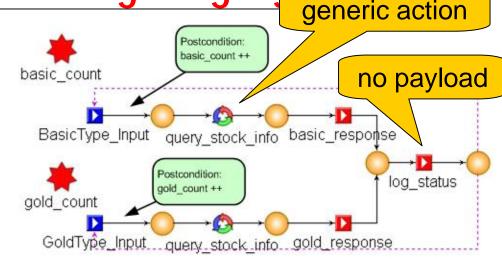
Context

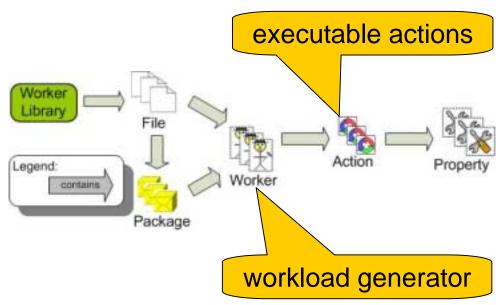
 CBML as a standalone language is sufficient enough to capture behavior of a component

 For emulation purposes, it does not capture the reusable objects of a component & its workload (i.e., Challenge 2)

#### **Research Contributions of WML**

- Middleware, hardware, platform, & programming language independent DSML
- Used to define workload generators (workers) that contains actions to represent realistic operations
- Defined using a hierarchical structure that resembles common object-oriented programming packaging techniques that are consistent with conventional component technologies









#### **Integrating WML Models with CBML Models**

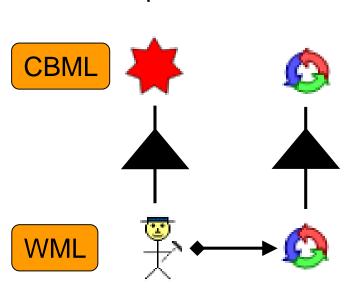
#### **Context**

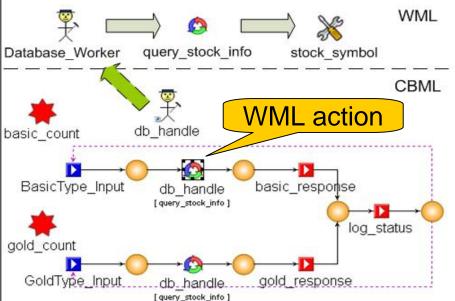
- CBML & WML are standalone DSMLs with a distinct purpose
  - i.e., model behavior & workload, respectively

 WML is designed to complement CBML by providing CBML with reusable operations that can map to realistic operations

#### **Integration Enablers**

- WML worker elements have same model semantics as variables
- WML actions have same modeling semantics as CBML actions
- Allows WML elements to be used in CBML models







Legend:

contains

references

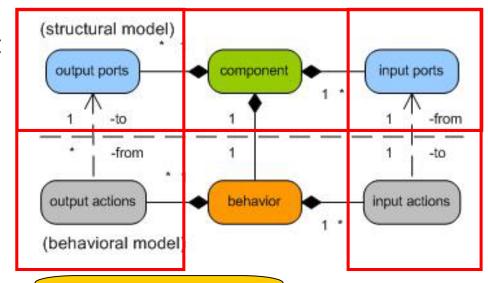
### Integrating Behavioral and Structural DSMLs

#### Context

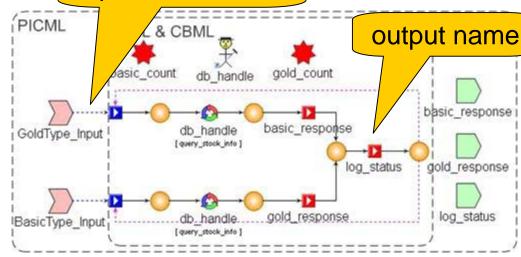
- Structural DSML (e.g., the Platform Independent Component Modeling Language (PICML)) capture the makeup of component-based systems
- There is no correlation between a component's ports & its behavior

#### **Integration Enablers**

- Defined a set of connector elements that allow structural DSMLs to integrate with (or contain) CBML models
- Input ports directly connect to Input Action elements
- Output actions have the same name as their output port to reduce model clutter
  - i.e., prevent many to one connections



input connections







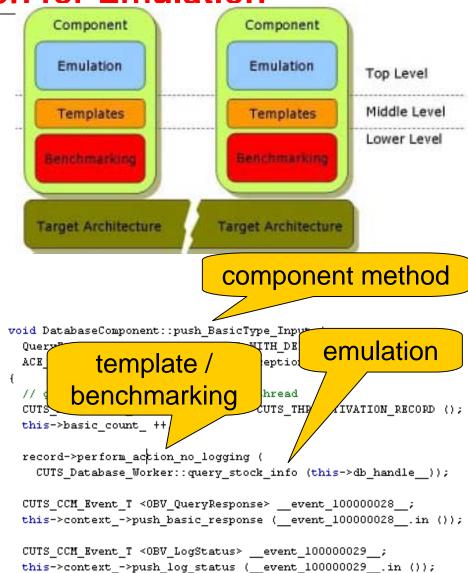
#### **Code Generation for Emulation**

#### **Context**

- The generation technique should not be dependent on the underlying technology
- Although we are targeting CUTS, would should be able to generate emulation code for any benchmarking framework

#### **Generation Enablers**

- Emulation layer represents the application layer's "business logic" where elements in WML used to parameterize CBML behavior are mapped to this layer
- Template layer acts as a bridge between the upper emulation layer & lower benchmarking layer to allows each to evolve independently of each other
- Benchmark layer the actual benchmarking framework (e.g., CUTS)





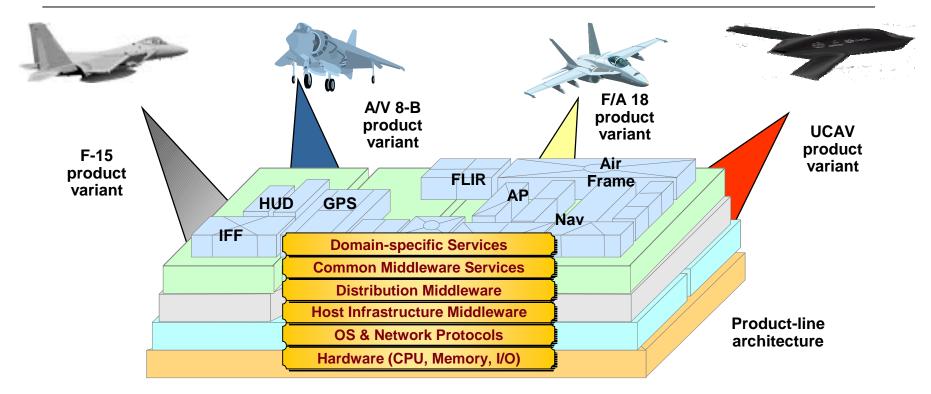
### Part 8 Usecase-driven Middleware Optimizations

Feature Oriented CUStomizer (FOCUS)

&

Pattern Oriented Software Architecture Modeling Language (POSAML)

#### Optimizations for Product-line Architectures

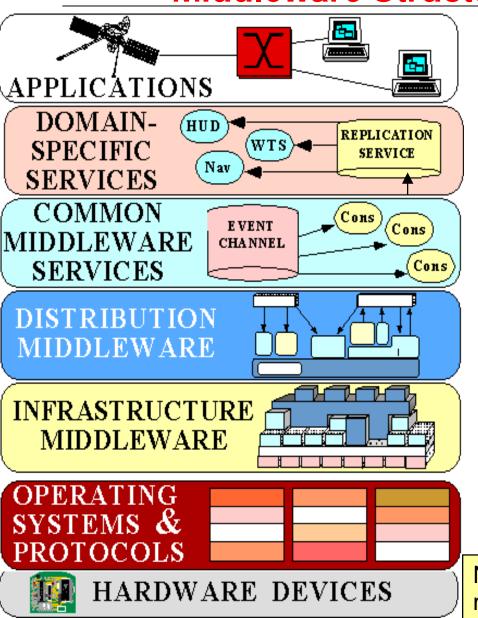


- •PLAs define a framework of components that adhere to a common architectural style with a clean separation of commonalities and appropriate provisions for incorporating variations
- *Middleware* factors out many reusable general-purpose & domain-specific services from traditional DRE application responsibility





### Middleware Structure & Functionality



- There are layers of middleware, just like there are layers of networking protocols
- Standards-based COTS middleware helps:
  - Control end-to-end resources & QoS
  - Leverage hardware & software technology advances
  - Evolve to new environments & requirements
  - Provide a wide array of reusable, offthe-shelf developer-oriented services

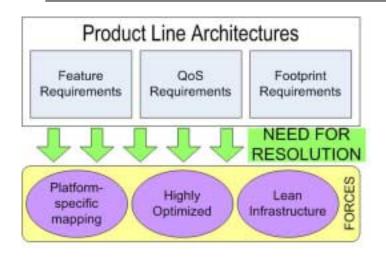
#### Problem

 Manually provisioning middleware is tedious, errorprone, & costly over system lifecycles

Need an intuitive, visual and declarative mechanism for middleware provisioning.



### **Technology Gaps in Middleware for PLAs**



- PLAs have very "focused but crosscutting" requirements of underlying middleware infrastructure
  - Optimized for the platform
  - Lean footprint
  - Efficient configuration & deployment
  - Support run-time adaptations & reconfigurations
- Standards middleware development & optimizations philosophy catered to maintaining "generality, wide applicability, portability & reusability"
  - OS, compiler and hardware independent
  - e.g., CORBA, J2EE. .NET
- These technology gaps are hindering PLA progress => adverse economic and societal consequences
  - e.g. shortcomings of pre-postulated





### Middleware Specialization Catalog

### Specification-imposed specializations

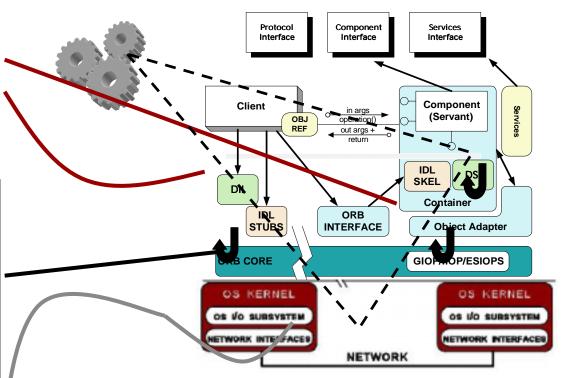
- Layer-folding
- Constant propagation
- Memoization

#### Framework specializations

- Aspect Weaving techniques
  - Bridge → Reactor
  - Template method → Protocol
  - Strategy → Messaging, Wait, Demultiplexing

### Deployment platform specializations

- Unroll copy loops
- Use emulated exceptions
- Leverage zero-copy data transfer buffers



- Development of reusable specialization patterns
- Identifying specialization points in middleware where patterns are applicable
- Domain-specific language (DSL) tools & process for automating the specializations



### Feature Oriented CUStomizer (FOCUS)

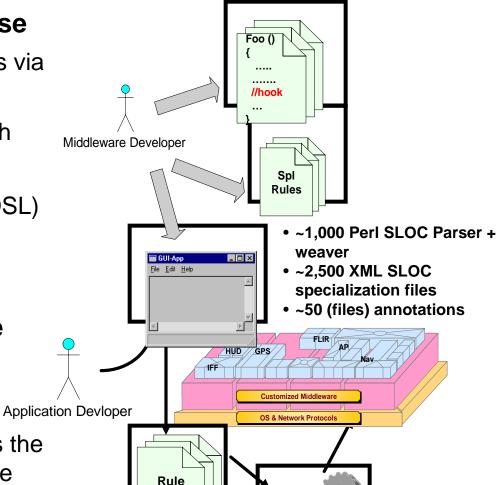
FOCUS addresses specialization challenges by building specialization language, tool, & process to capture & automate middleware specializations

#### **Middleware Instrumentation Phase**

- Capture specialization transformations via FOCUS specialization language
- Annotate middleware source code with specialization directives
- Create a domain-specific language (DSL) to capture middleware variability

#### Middleware Specialization Phase

- Analyzes & determines the type of specializations applicable
- FOCUS transformation engine selects the appropriate transformations & uses the annotations to automate specializations



selection

101



### **FOCUS Specialization Language (FSL)**

#### FOCUS uses an XML DTD to create a DSL for capturing

#### Capability to specialize base implementations at in

 Framework specialization requires code to be copied from derived to base classes
 FSL Approach

<copy-from-source>: Copy code from a specific point to a specific point between different files <start-hook> → start copying

<end-hook> → hook to stop copying

<dest-hook> → destination



<substitute>
 <search>ACE\_Reactor\_Impl</search>
 <replace>ACE\_Select\_Reactor\_Impl</replace>
</substitute>

<copy-from-source>
 <source>Select\_Reactor.h</source>
 <copy-hook-start>HOOK-START </copy-hook-start>
 <copy-hook-end>HOOK-END </copy-hook-end>
 <dest-hook>HOOK-COPY</dest-hook>
</copy-from-source>

### Capability to perform code substitutions

- Devirtualize interfaces
- Replace base classes with derived class

#### **FSL Approach**

<substitute>: Capability to do<search> ... <replace> on code

### Capability to weave code at specified points

• The layer folding specializations require code to be woven in along the request processing path

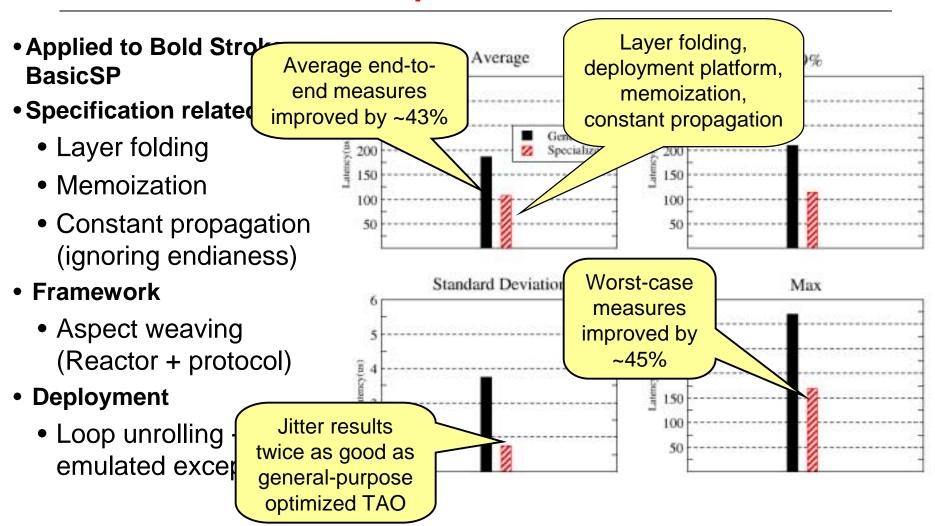
#### **FSL Approach**

 <add>: <hook> that specifies the annotated point; <data> where data is specified

```
<add>
<hook>FORWARD_DECL</hook>
<data>#include

"Select_Reactor.h"</data>
<add>
```

### **Cumulative Specialization Results**



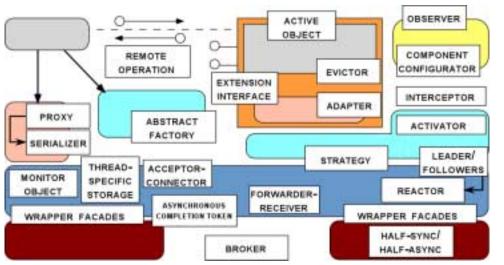
- End-to-end client side throughput improved by ~65%.
- Results exceeded the hypothesis & evaluation criteria





### **Automation Tool Requirements (1/2)**

Criteria 1: Intuitive management of middleware variabilities that impact performance in significant ways

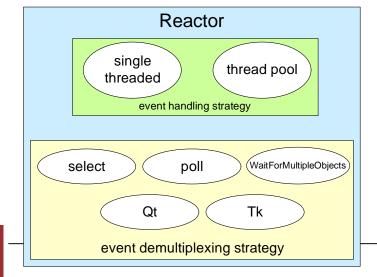




- Incurred due to variations in the compositions of mw building blocks
- Need to address compatibility in the compositions and individual configurations
- Dictated by needs of the domain
- E.g., Leader-Follower makes no sense in a single threaded Reactor

#### Must account for Per-Block Configuration Variability

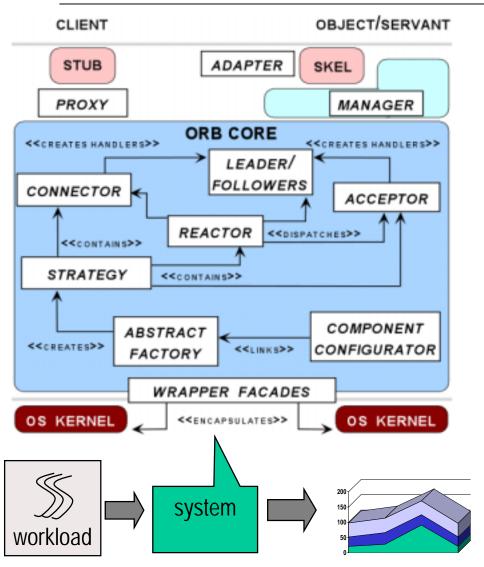
- Incurred due to variations in implementations & configurations for a patterns-based building block
- E.g., single threaded versus thread-pool based reactor implementation dimension that crosscuts the event demultiplexing strategy (e.g., select, poll,





WaitForMultipleObjects

### **Automation Tool Requirements (2/2)**



**Criteria 2:** Visual separation of concerns within the Unified Framework

#### Separation of concerns

- Unified framework must separate the provisioning and validating stages
- Different actors should be able to use the visual aids in different stages of the application lifecycle

**Criteria 3:** Unified framework for middleware provisioning and QoS validation

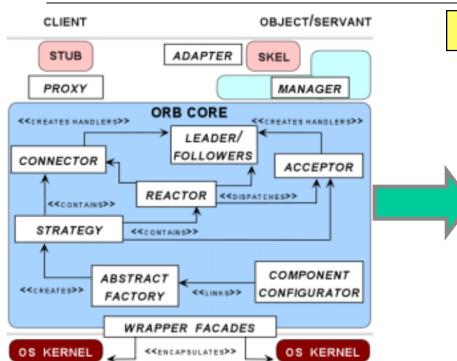
### Unified framework for provisioning and validating

- Provisioning decisions should be coupled with QoS validation
- Decisions at one stage drive decisions at the next stage

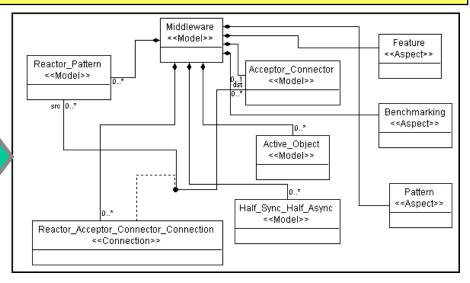




### **POSAML: A Visual Provisioning Tool**



Metamodel for the POSA pattern language



Middleware

<<ModelProxy>>

Thread\_Queue 
<<Atom>>

Thread Queue Options:

End Point Connection

<<Connection>>

End\_Points

<<Atom>>

HostName: field

enum

Acceptor\_Connector

<<ModelProxy>>

field

Protocol:

Middleware

<<Model>>

Concurrency

<<Atom>>

Concurrency\_Options: enum

Reactor\_Concurrency\_Connection

<<Connection>>

Reactor Type

<<Atom>>

Reactor\_Type\_Options : enum

Reactor\_Thread\_Queue\_Connection

<<Connection>>

Reactor\_Type\_Connection

<<Connection>>

Reactor Pattern

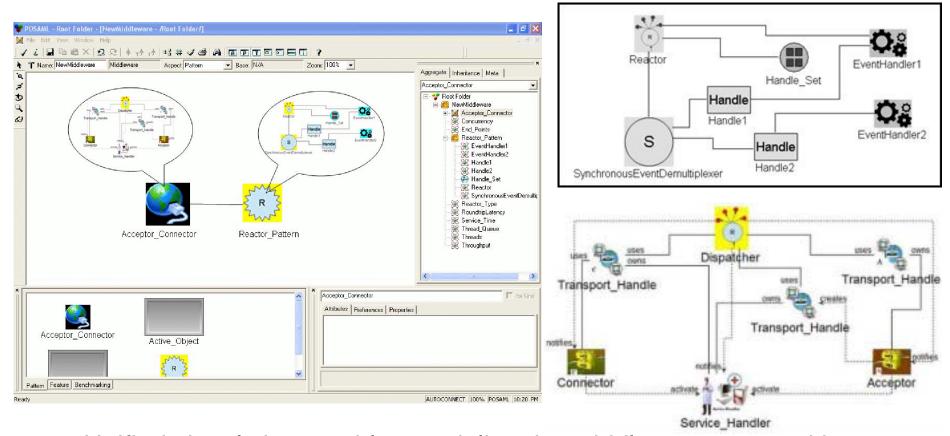
<<ModelProxy>>

dat 0.dat 0

- POSAML GME-based modeling language for middleware composition
- Provides a structural composition model
- Captures variability in blocks
- Generative programming capabilities to synthesize different artifacts e.g., benchmarking, configuration, performance modeling.

Feature modeling metamodel in POSAML

#### **POSAML Unified Framework**

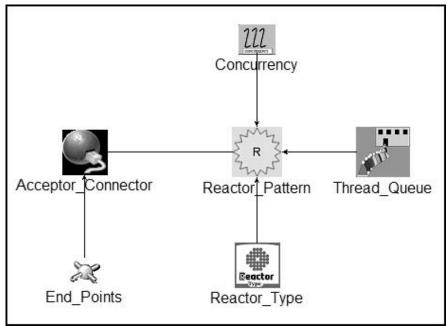


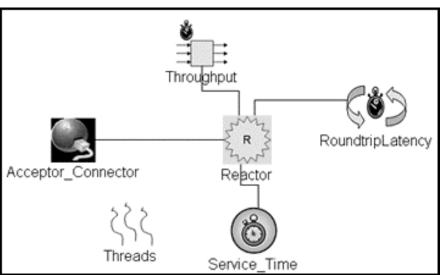
- Unified visual view enables modeling the middleware composition as a set of interacting patterns
- Individual patterns can be visually configured
  - E.g., reactor and acceptor-connector patterns

POSAML languages conforms to the POSA pattern language enabling error-free composition of building blocks.



### **POSAML Separation of Concerns**





- POSAML separates pattern feature modeling from pattern benchmarking
- Feature model allows selecting features of each pattern
  - E.g., reactor and acceptorconnector shown with concurrency models
- Benchmarking view separated from feature view
  - E.g., selecting parameters for elements of the pattern
- Views are unified under the hood



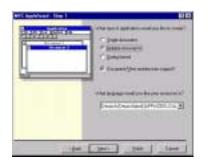


### **Structure Spectrum of DSLs**

#### Routine configuration

#### Creative construction

#### **Wizards**



### Feature-based configuration



matrix

format

bounds checking

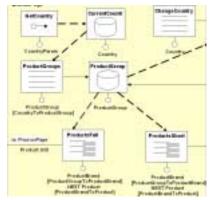
Frtn-like

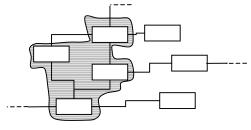
# scr4 scr5 scr6 scr7 scr8 rect lower rilang with scr12 scr10 scr11 scr12

Path through a decision tree

Subtree of a feature tree

### Graph-like language (with user-defined elements)



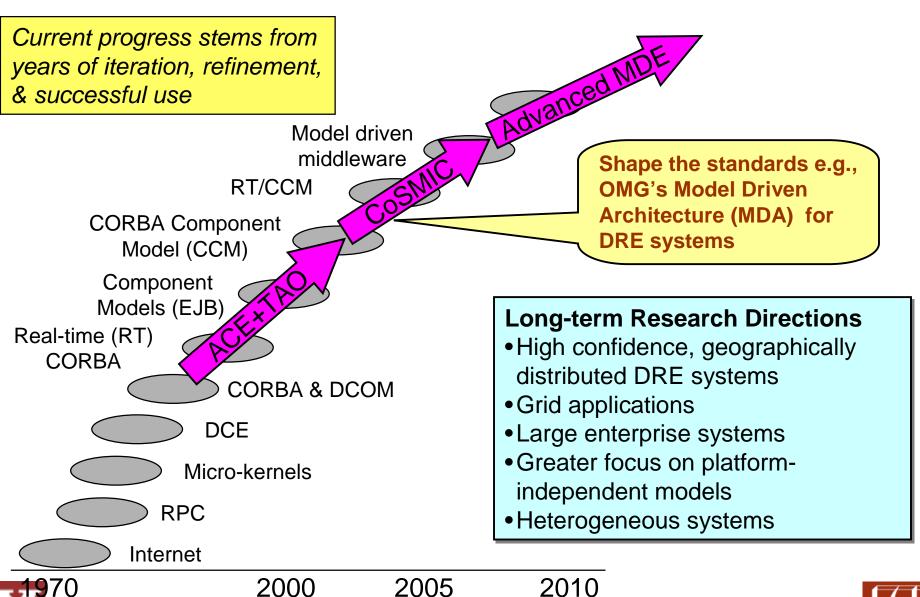


Subgraph of an (infinite) graph





#### Research Impact & Future Work



110

Year



### **Acknowledgments**

This tutorial is made possible due to the efforts of students, collaborators & mentors

#### DOC Students & Staff

- Krishnakumar Balasubramanian
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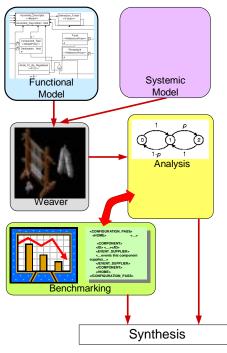
#### Mentors

- Dr. Doug Schmidt
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- Dr. Gabor Karsai
- Dr. Joe Loyall
- Dr. Joe Cross



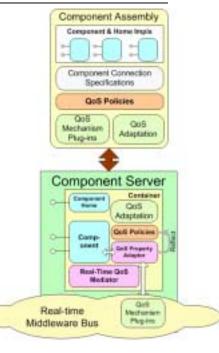


### **DOC Group Research on DRE Systems**



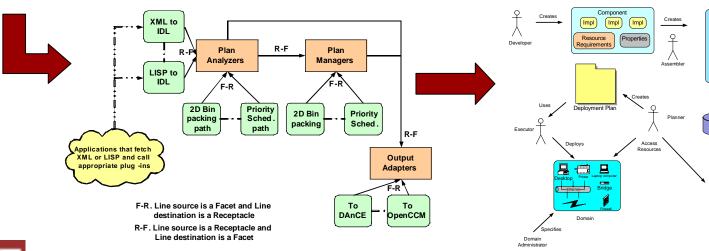
#### **Multiple Levels of Abstraction**

- CoSMIC Modeling Deployment & Configuration (D&C) crosscutting concerns
- RACE Resource and Control Engine
- DAnCE Deployment And Configuration Engine
- CIAO QoS-enabled component middleware



Package

COMPONENT REPOSITORY





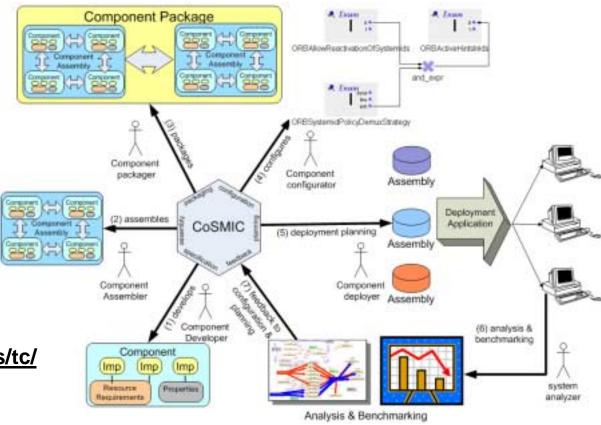




### **Concluding Remarks**

- Model-Driven Engineering (MDE) is an important emerging generative technology paradigm that addresses key lifecycle challenges of DRE middleware & applications
- OMG PSIG on Model Integrated Computing

www.omg.org/news/meetings/tc/agendas/mic.htm



Many hard R&D problems with model-driven engineering remain unresolved!!

- CoSMIC MDE tools are based on the Generic Modeling Environment (GME)
  - CoSMIC is available from <u>www.dre.vanderbilt.edu/cosmic</u>
  - GME is available from www.isis.vanderbilt.edu/Projects/gme/default.htm