



Your systems. Working as one.

DDS Advanced Tutorial

The Evolution of the DataBus



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Agenda

Introduction and Background

Data-Centricity 101

Software Installation

Exercise: Shapes

Developer and Run-time Tools

Exercise: Ping, Spy, Analyzer, Recorder, Persistence

Your first Application

Getting started with DDS and XML

Exercise: Adjusting QoS

Defining your own data-types

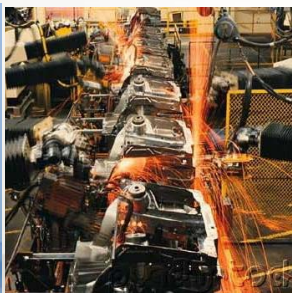
Building a chat application

Systems that interact with the Real World

- Must adapt to changing environment
- Cannot stop processing the information
- Live within world-imposed timing



Beyond traditional interpretation of real-time



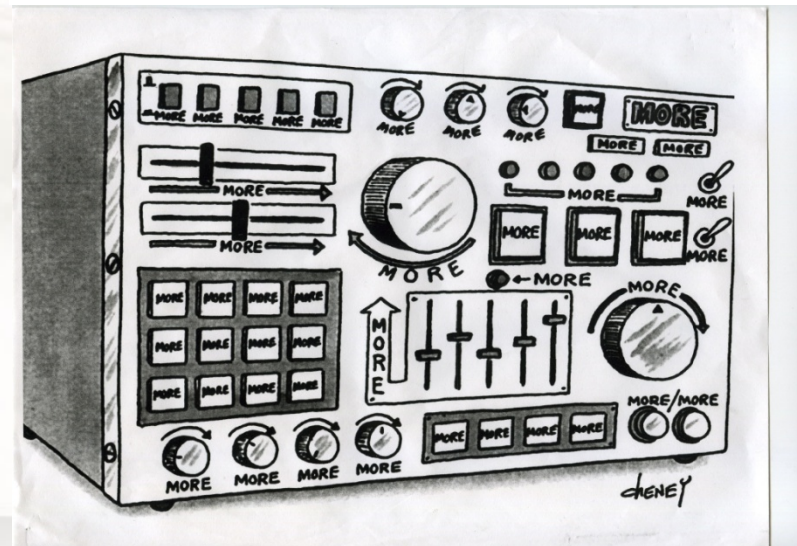
Challenge: More Data, More Speed, More Sources

TRENDS:

- Growing Information Volume
- Lowering Decision Latency
- Increasing System Availability
- Accelerating technology insertion and deployment

Next-generation systems needs:

- Scalability
- Integration & Evolution
- Robustness & Availability
- Performance
- Security



“Real World” Systems are integrated using a Data Model



- Grounded on the “physics” of the problem domain
 - Tied to the nature of the sensors and real objects in the system (vehicles, device types, ...)
- Provides governance across disparate teams & organizations
 - The “ N^2 ” integration problem is reduced to a “ N ” problem
- Increased decoupling from use-cases and components
 - Avoids over constraining applications
- Open, Evolvable, Platform-Independent
 - The use-cases, algorithms might change between missions or versions of the system

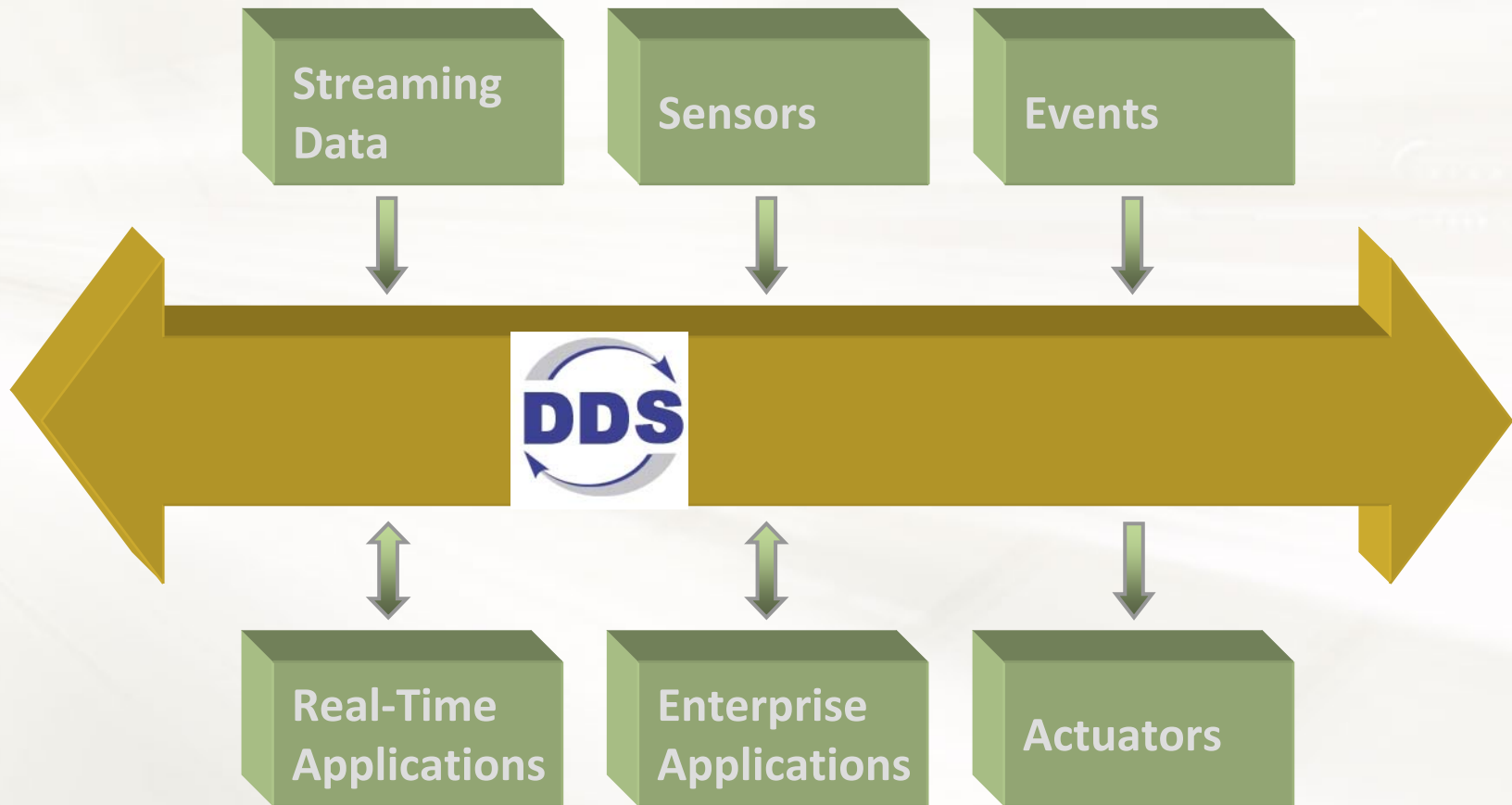
App

App

App

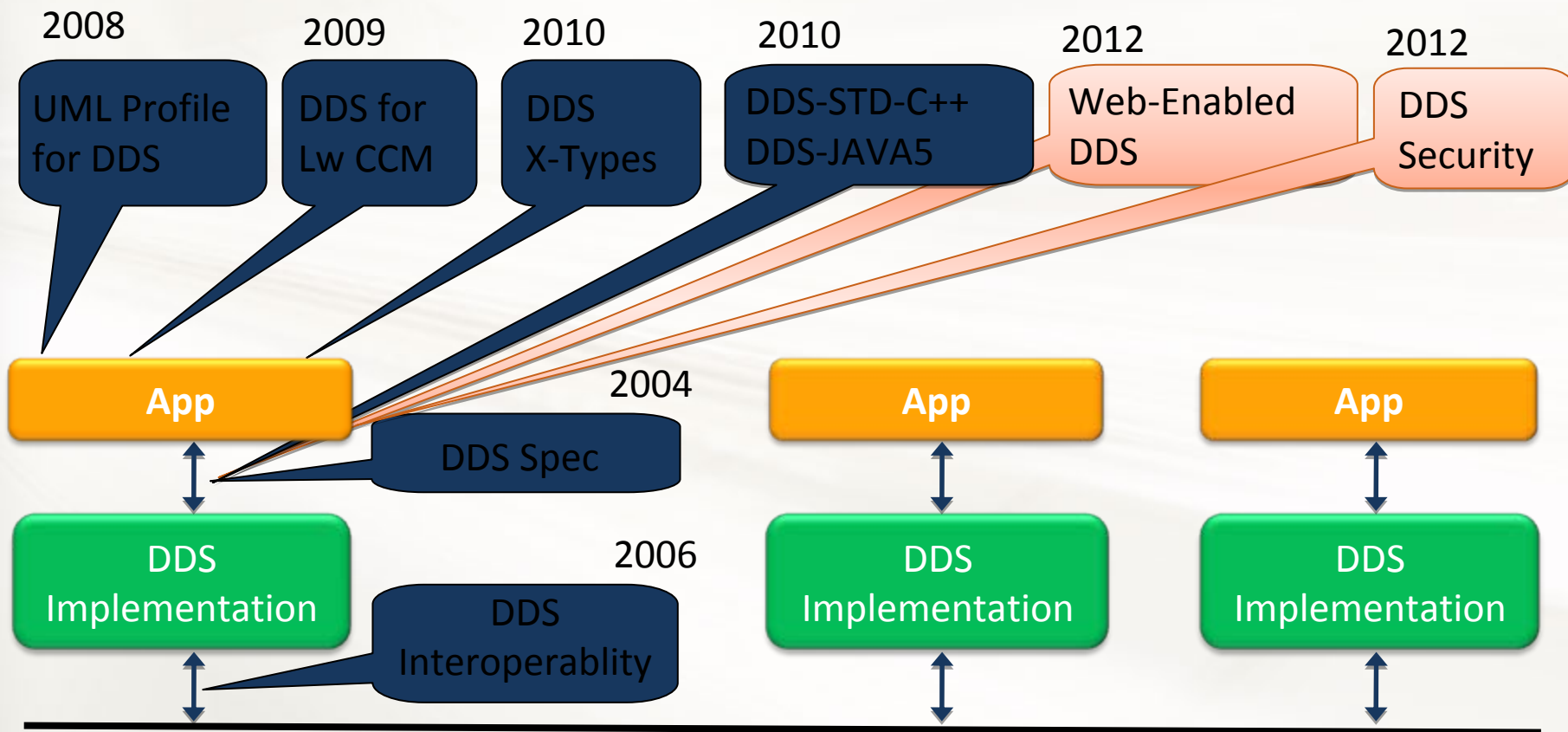
Realizing this data-model requires a middleware infrastructure

DDS: Standards-based Integration Infrastructure for Critical Applications





Family of Specifications

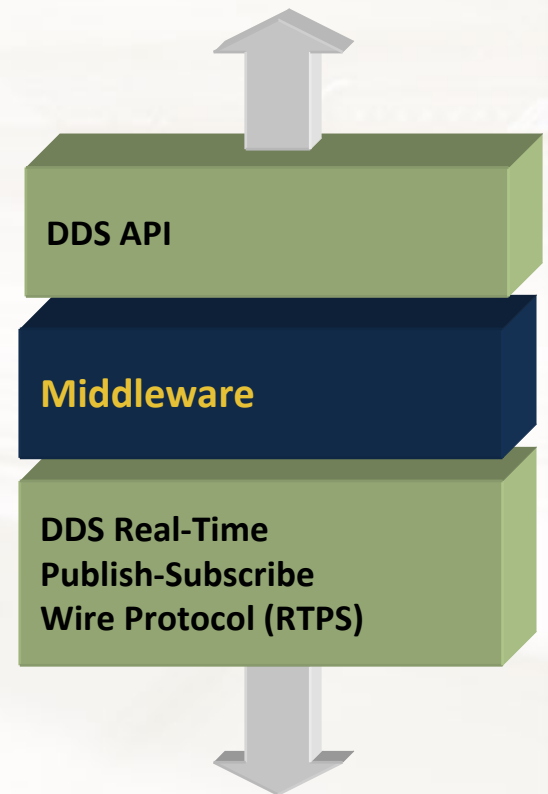


Network / TCP / UDP / IP

Broad Adoption

- Vendor independent
 - API for portability
 - Wire protocol for interoperability
- Multiple implementations
 - 10 of API
 - 8 support RTPS
- Heterogeneous
 - C, C++, Java, .NET (C#, C++/CLI)
 - Linux, Windows, VxWorks, other embedded & real-time
- Loosely coupled

Cross-vendor portability



Cross-vendor interoperability

US-DoD mandates DDS for data-distribution

- DISR (formerly JTA)
 - DoD Information Technology Standards Registry
- US Navy Open Architecture
- Army, OSD
 - UCS, Unmanned Vehicle Control
- SPAWAR NESI
 - *Net-centric Enterprise Solutions for Interoperability*
 - *Mandates DDS for Pub-Sub SOA*



DDS adopted by key programs

- *European Air Traffic Control*
 - *DDS used to interoperate ATC centers*
- *UK Generic Vehicle Architecture*
 - *Mandates DDS for vehicle comm.*
 - *Mandates DDS-RTPS for interop.*
- **DISR**
 - Mandates DDS for Pub-Sub API
 - Mandates DDS-RTPS for Pub-Sub Interop
- **US Navy Open Architecture**
 - Mandates DDS for Pub-Sub
- *SPAWAR NESI*
 - *Mandates DDS for Pub-Sub SOA*



Evolution of DataBus

Data-centricity basics

Everyday Example: Calendaring

Alternative Process #1 (message-centric):

1. Email: “Meeting Monday at 10:00.”
2. Email: “Here’s dial-in info for meeting...”
3. Email: “Meeting moved to Tuesday”
4. You: “Where do I have to be? When?”
5. You: (*sifting through email messages...*)

Example: Calendaring

Alternative Process #2:

1. Calendar: (*add meeting Monday at 10:00*)
2. Calendar: (*add dial-in info*)
3. Calendar: (*move meeting to Tuesday*)
4. You: “Where do I have to be? When?”
5. You: (*check calendar. Contains consolidated-state*)

The difference is state!

The infrastructure consolidates changes and maintains it

What's the Difference? *State*.

- **Objects have identity and attributes**
 - The meeting will run **1:00–2:00** in the **conference room**.
 - My friend's phone number is **555-1234** his email is...
 - The car is **blue** and is **traveling north** from **Sunnyvale** at **65 mph**.
- **...whether they exist in the real world, in the computer, or both**
- **...whether or not we observe or acknowledge them**

“State” (“data”) is a snapshot of those attributes and characteristics.

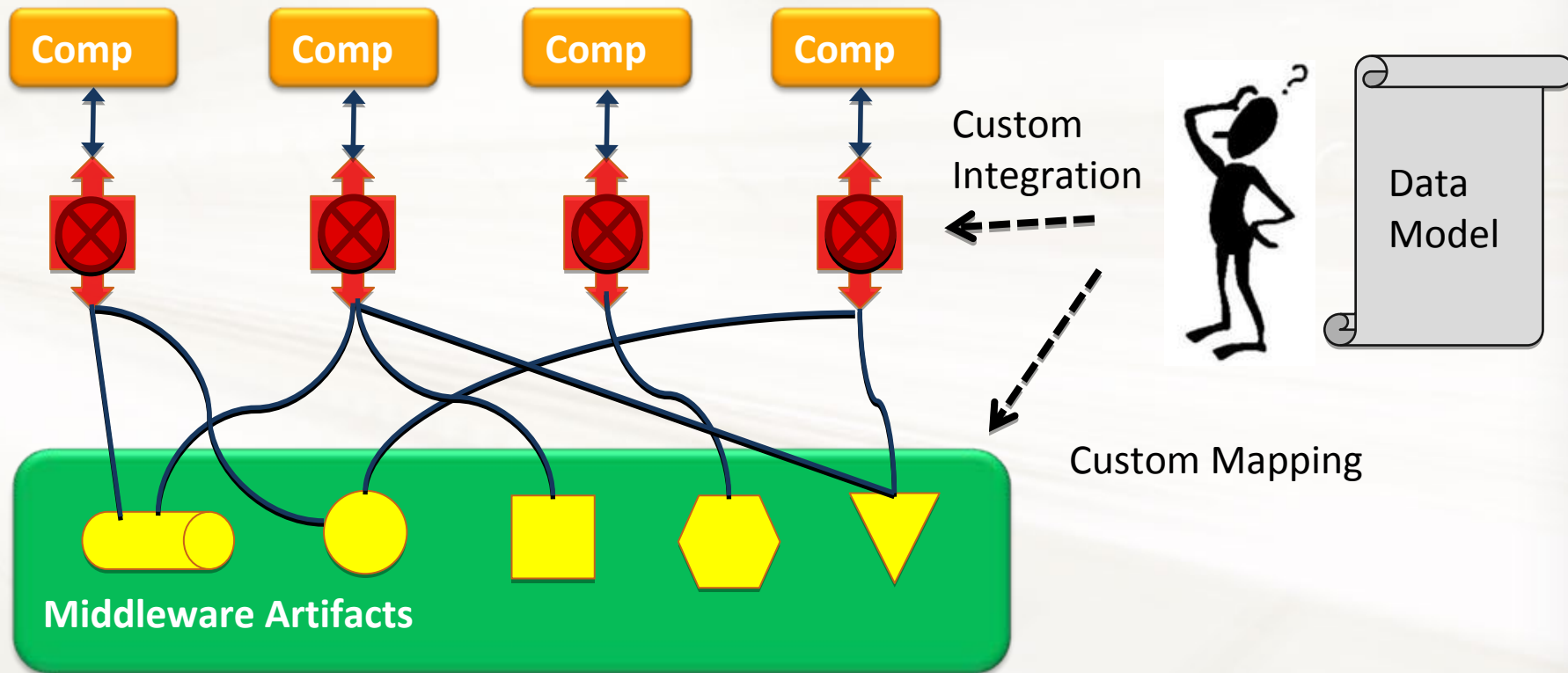
If the infrastructure maintains the state, the application does not need to re-construct it...

Why is it better to have the (data-centric) middleware manage the state?



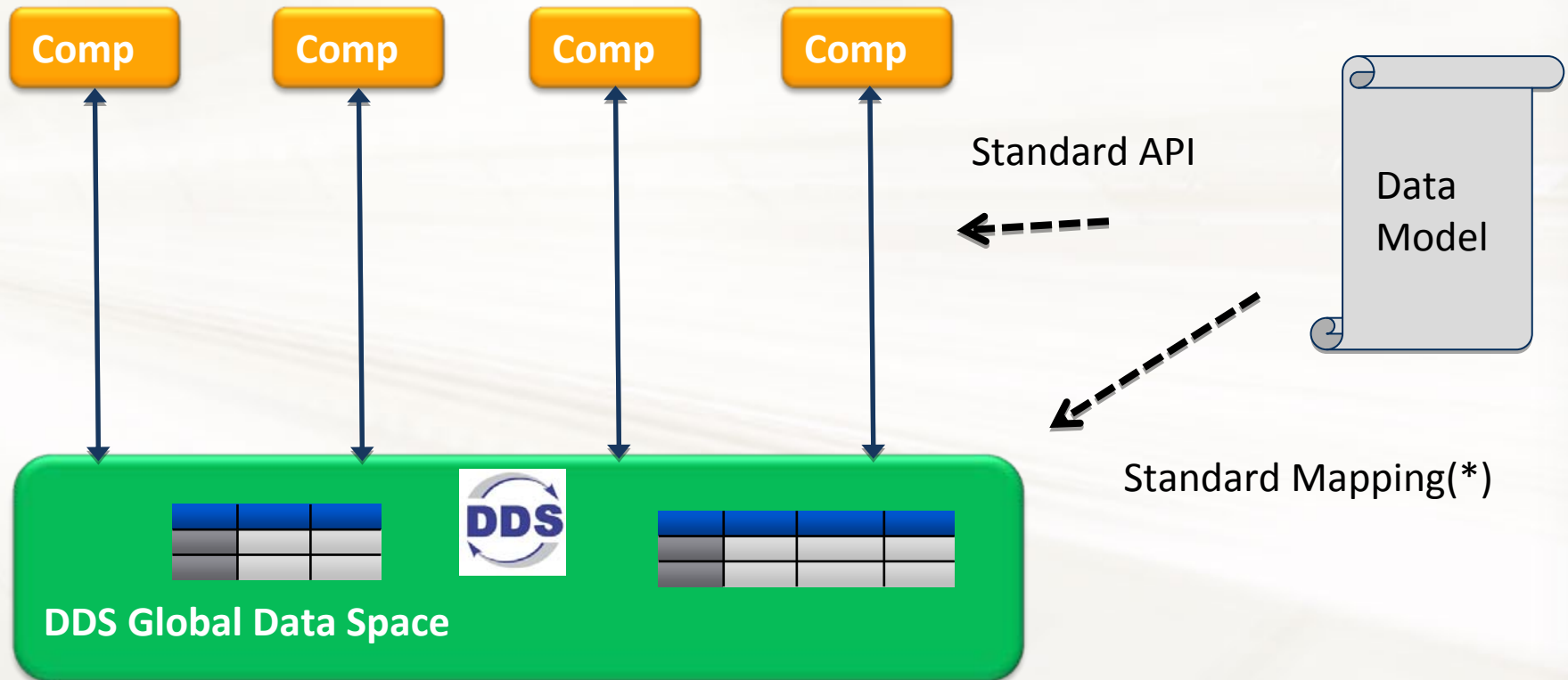
- **Reconstructing the state of an object is hard**
 - Must infer based on all previous messages
 - Maintaining all these messages is expensive
 - Each app makes these inferences
=> duplicate effort
- **Reconstructing state is not robust**
 - Many copies of state => may be different => bugs
vs. Uniform operations on state => fewer bugs
 - Any missing change compromises integrity
- **State awareness results in better performance**
 - Middleware can be smart about what to send and when
- **Data-type awareness simplifies programming**
 - Middleware supports direct definition and instantiation of the data-model

Integrating components to generic middleware technology



Akin to implementing an OO design on a Procedural Language:
Requires mapping inheritance, encapsulation, exceptions, ...

Integrating components to data-centric middleware technology



No custom mappings / code necessary

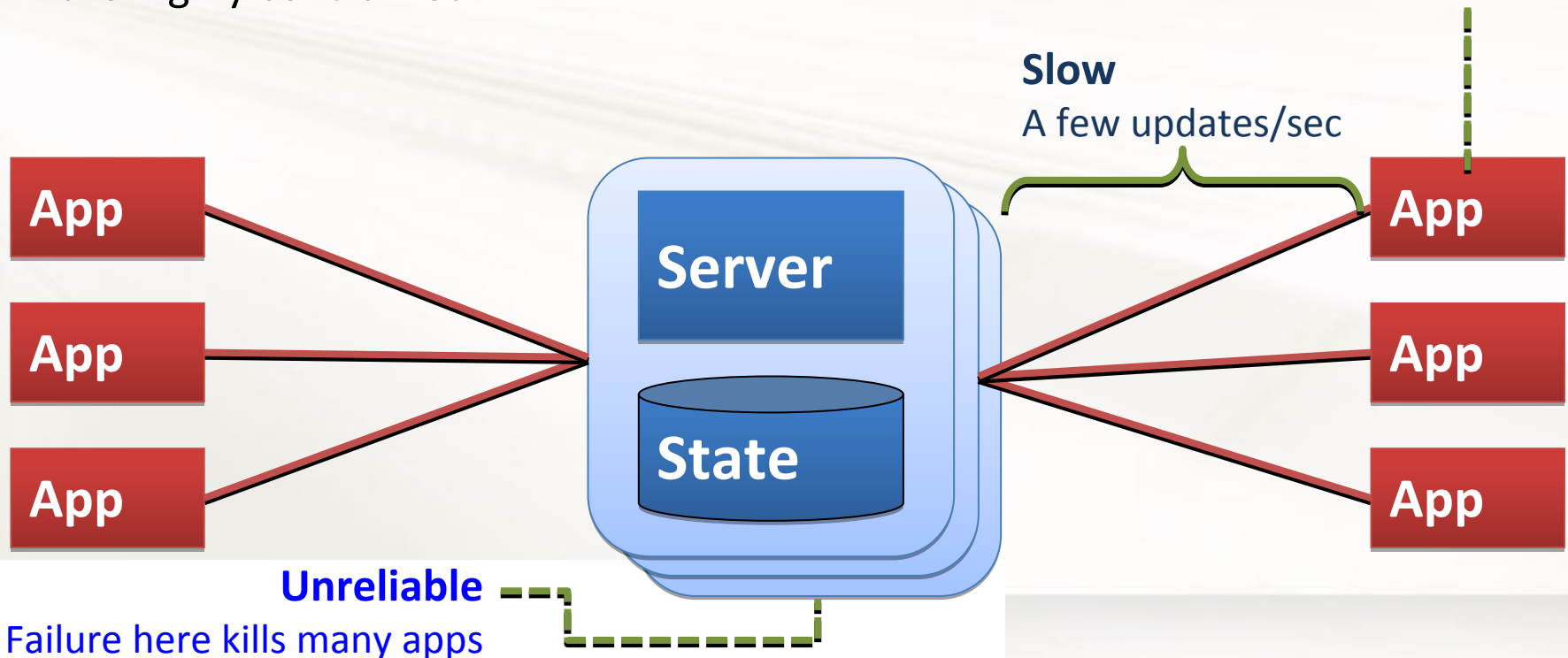
Direct support for data-centric actions: create, dispose, read/take

Traditional data-centric technologies not suited to scalable near real-time systems

Other data-centric technologies:

- Databases: SQL
- Web: HTTP (mostly)

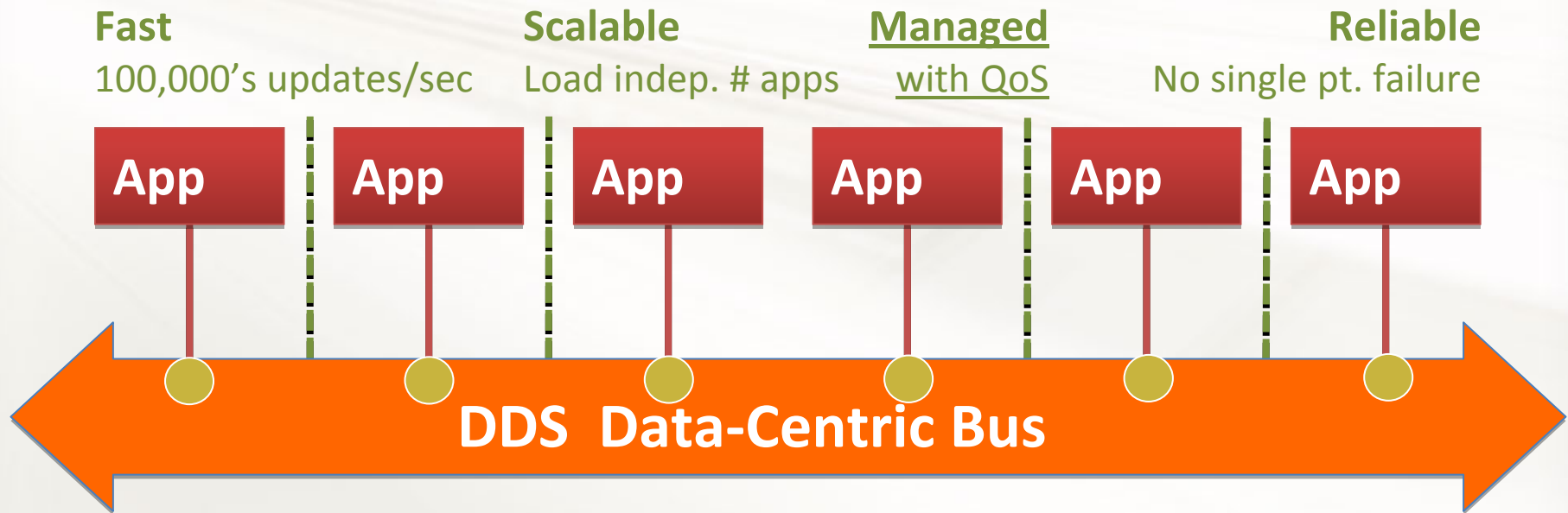
- ...assume the world changes slowly
- ...use network resources inefficiently
- ...are highly centralized



DDS is decentralized. Can be deployed without servers/brokers

DDS:

- ...allows you to observe frequent changes
- ...uses network resources efficiently
- ...is **peer-to-peer and decentralized**

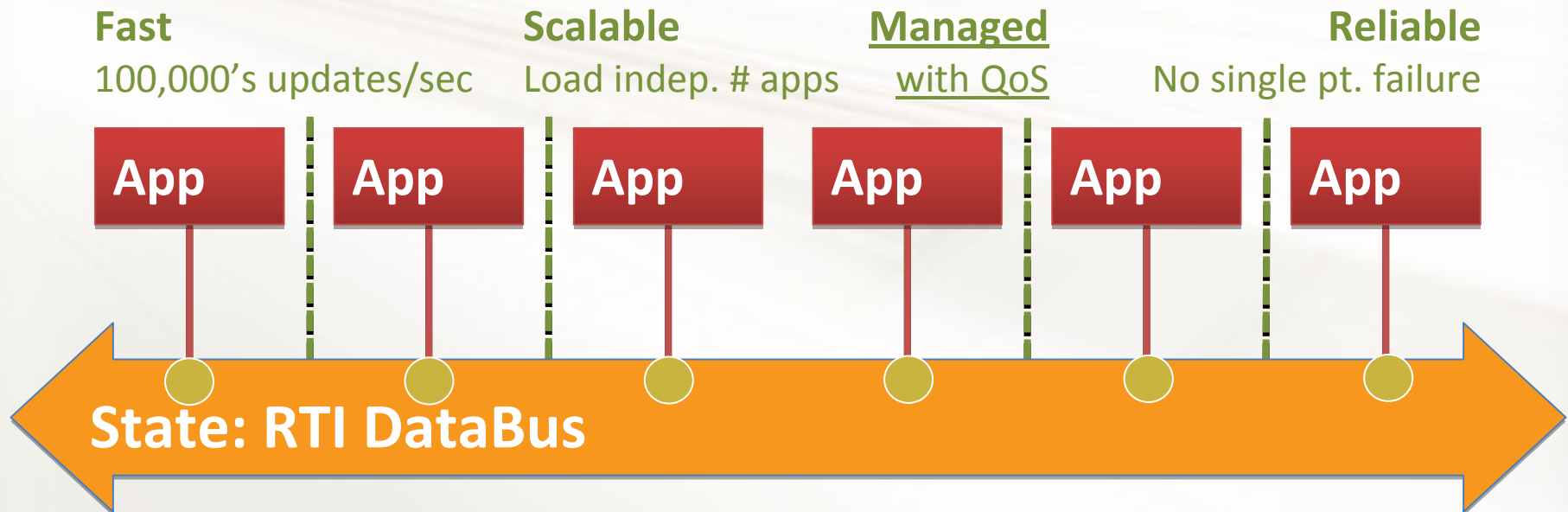


RTI Data-Centric DataBus

Meets the needs of Operational Systems

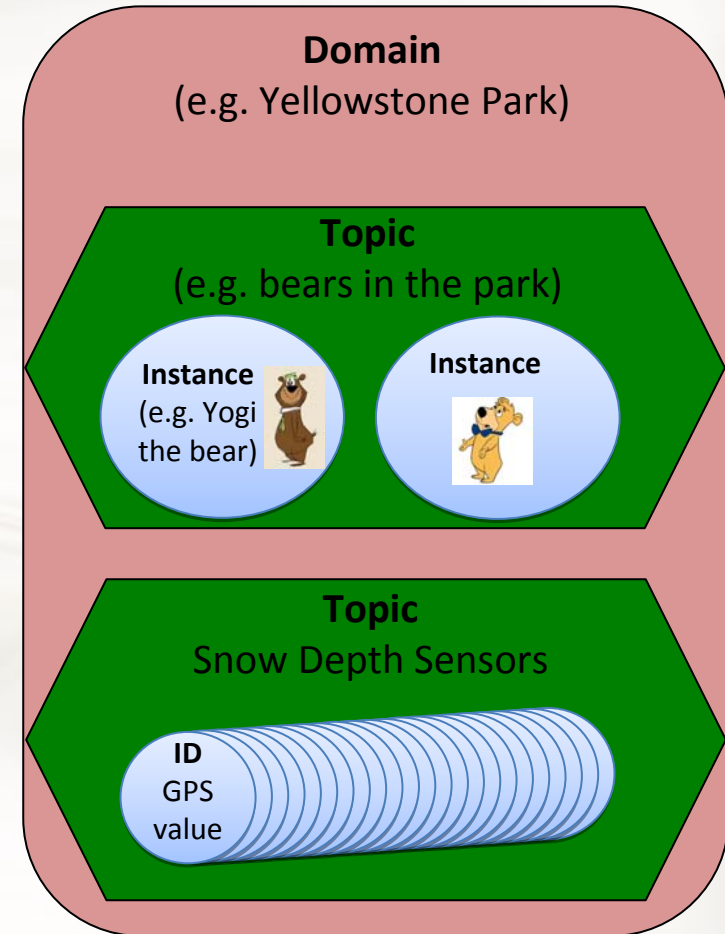
Blue-Force tracker replaced home-brew messaging w/ RTI Context DDS:

- Tracks 20x more objects with fewer failures
- ...with 97% less code (*1.5M lines* → *50K*)
- ...with 99% less CPU resources (*88 cores* → *0.8*)



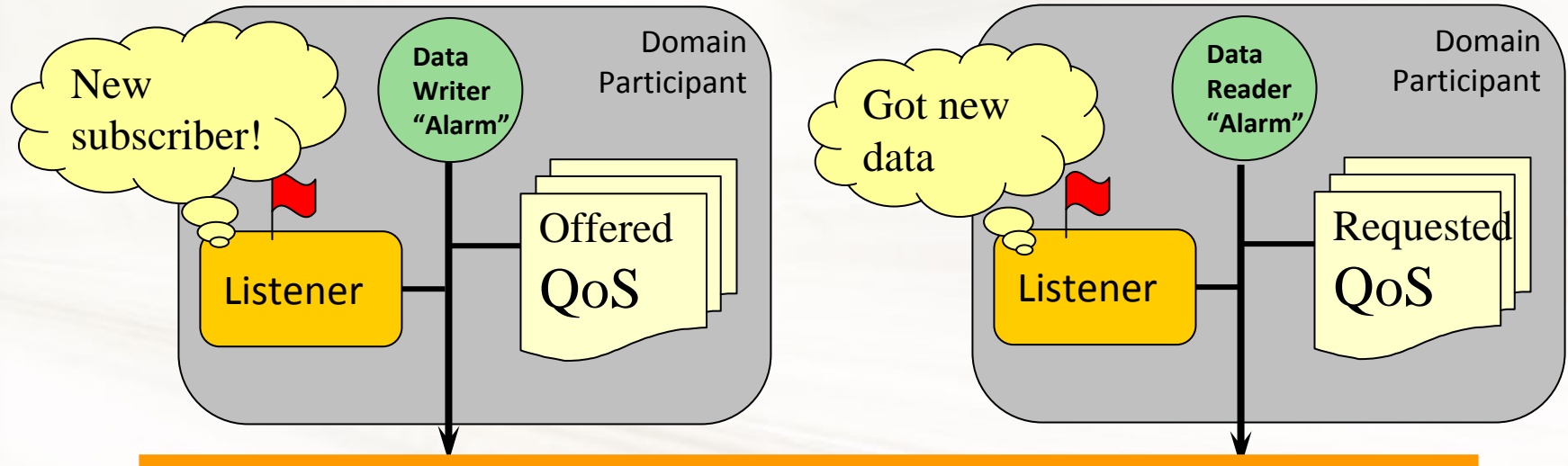
DDS Addressing: Data-Objects in the Global Data Space

- **Domain**: world you're talking about
- **Topic**: group of similar objects
 - Similar structure ("type") *what*
 - Similar way they change over time ("QoS") *when*
how
- **Instance**: individual object
- **DataWriter**: source of observations about a set of data-objects (Topic)
- **DataReader**: observer of a set of data-objects (Topic)



Data-Centric Communications Model

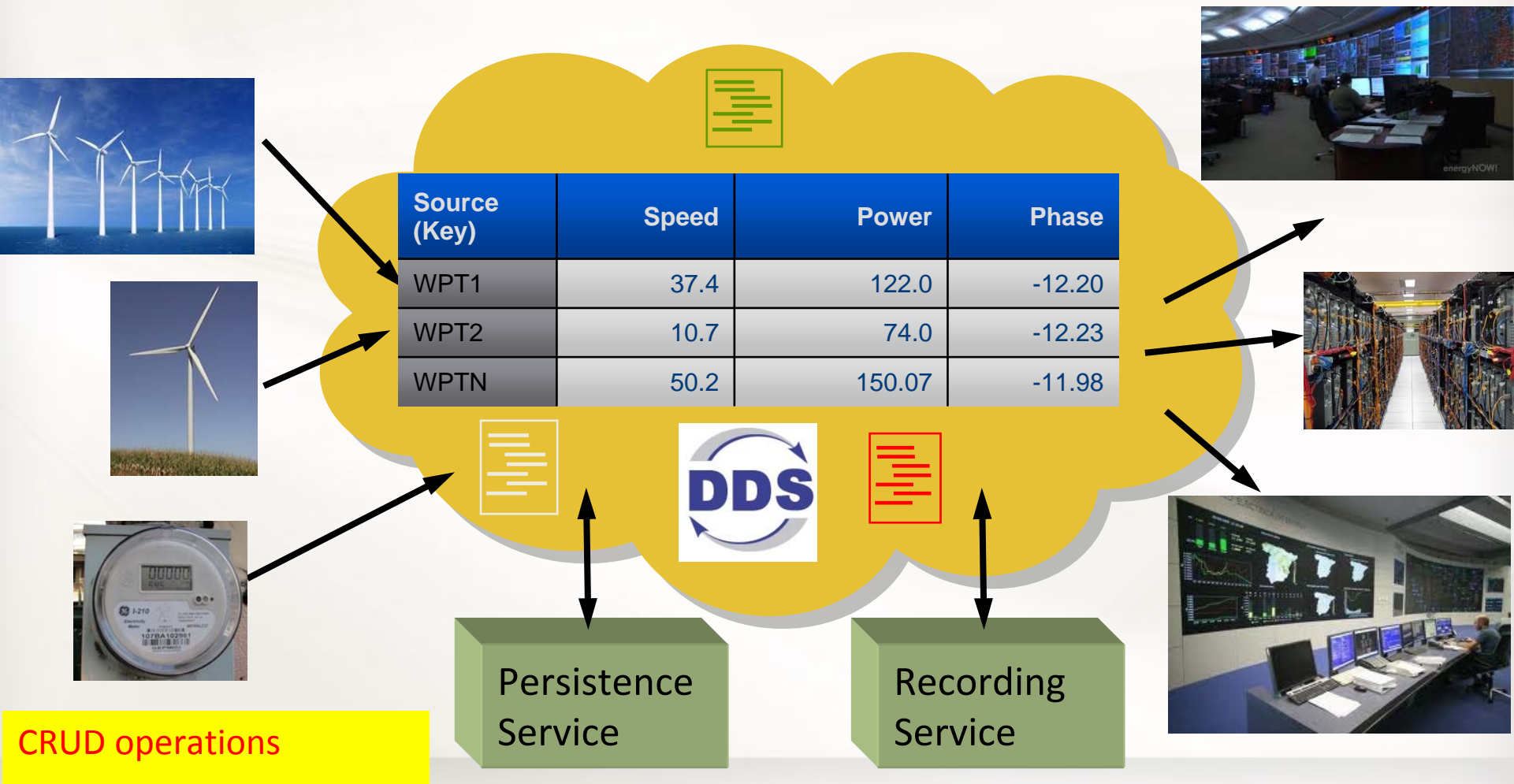
example



- **Participants** scope the global data space (domain)
- **Topics** define the data-objects (collections of subjects)
- **DataWriters** publish data on Topics
- **DataReaders** subscribe to data on Topics
- **QoS Policies** are used configure the system
- **Listeners** are used to notify the application of events

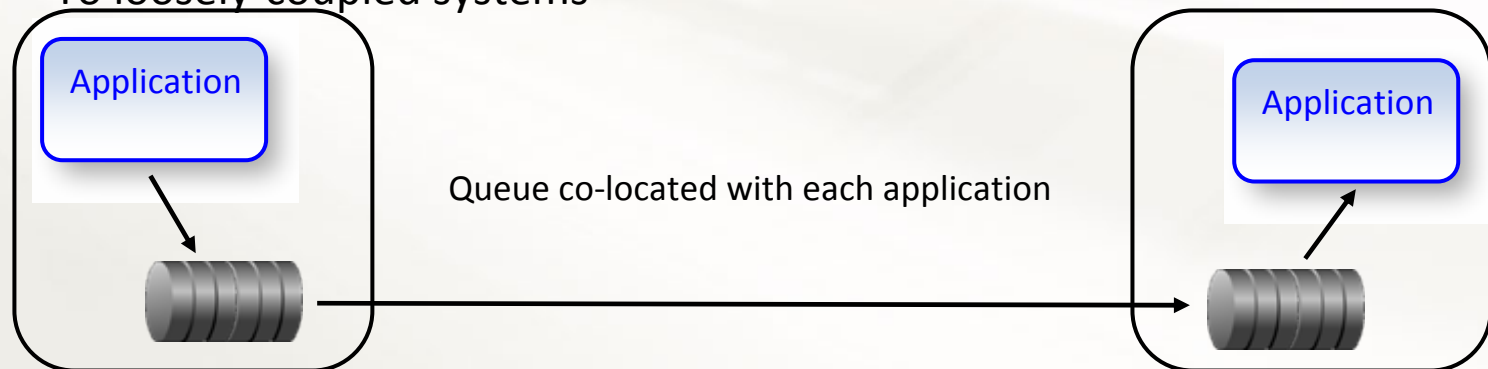
Data-Centric Qos-Aware Pub-Sub Model

Virtual, decentralized global data space



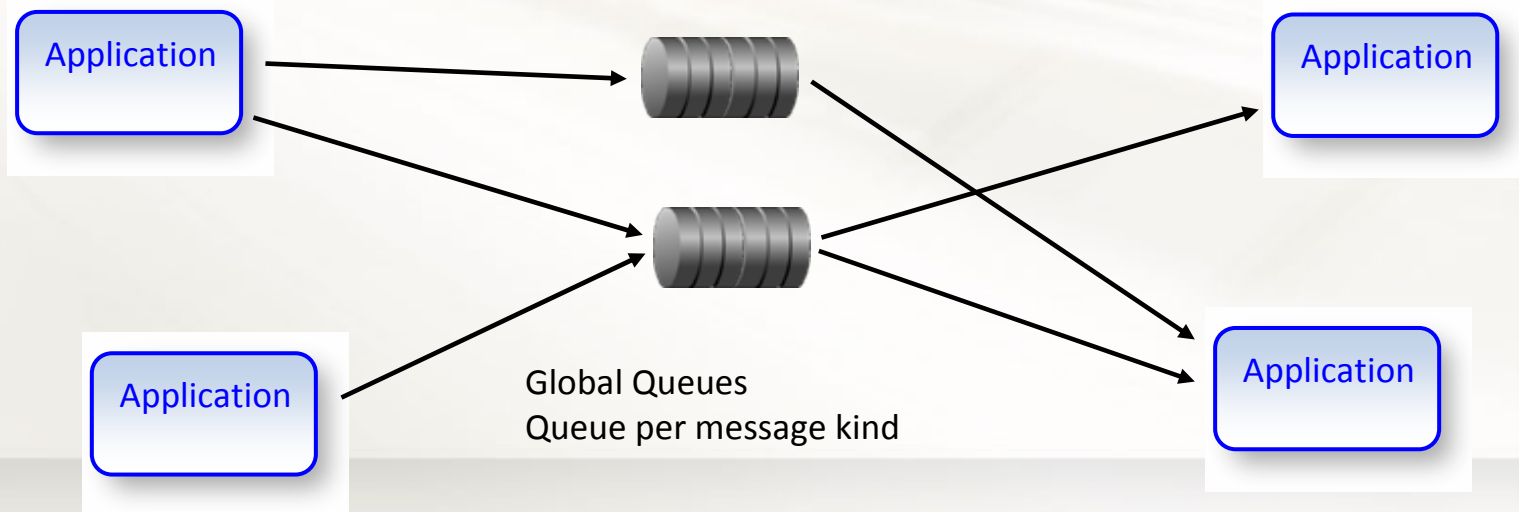
Do-yourself Message-Centric System

- Model
 - 1-1, FIFO
- Applications coupled in Lifespan & Content
 - Both must be present simultaneously
 - Everything sent is received
- Excellent performance
- Doesn't scale
 - To large-scale systems
 - To loosely-coupled systems



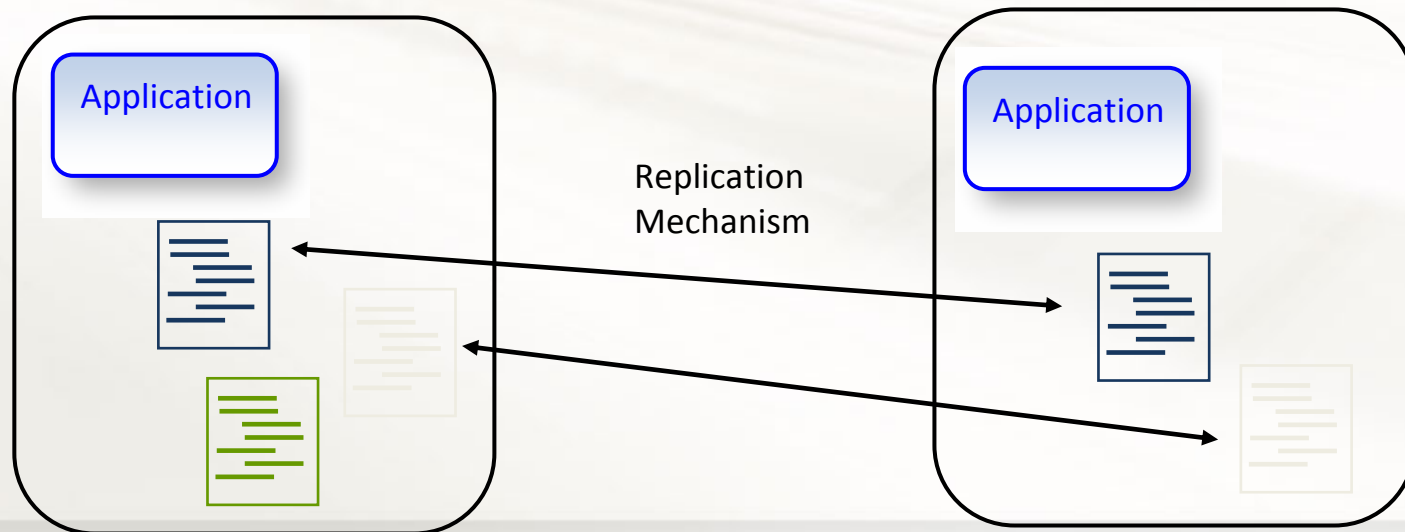
Middleware-based Message-Centric Systems (JMS)

- Model
 - Broker-based, $n \rightarrow n$ communication
 - Independent messages, No state
- Coupling
 - Not coupled in Lifespan
 - Coupled in Order and Content (presentation)
- Worse performance
- Better scalability



Do-yourself Data-Centric System

- Model
 - Shared/replicated structured data/state
 - Asynchronous, Selective sharing
- Coupling:
 - Coupled in Lifespan, Decoupled in Presentation & Content
- Excellent performance & scalability



Middleware-based Data-Centric Systems (DDS)

- Shared data-space, shared state
- Asynchronous communication
- Decoupled in Lifespan, Content, presentation
- Excellent performance & scalability
- Subsumes Message-Centric via QoS

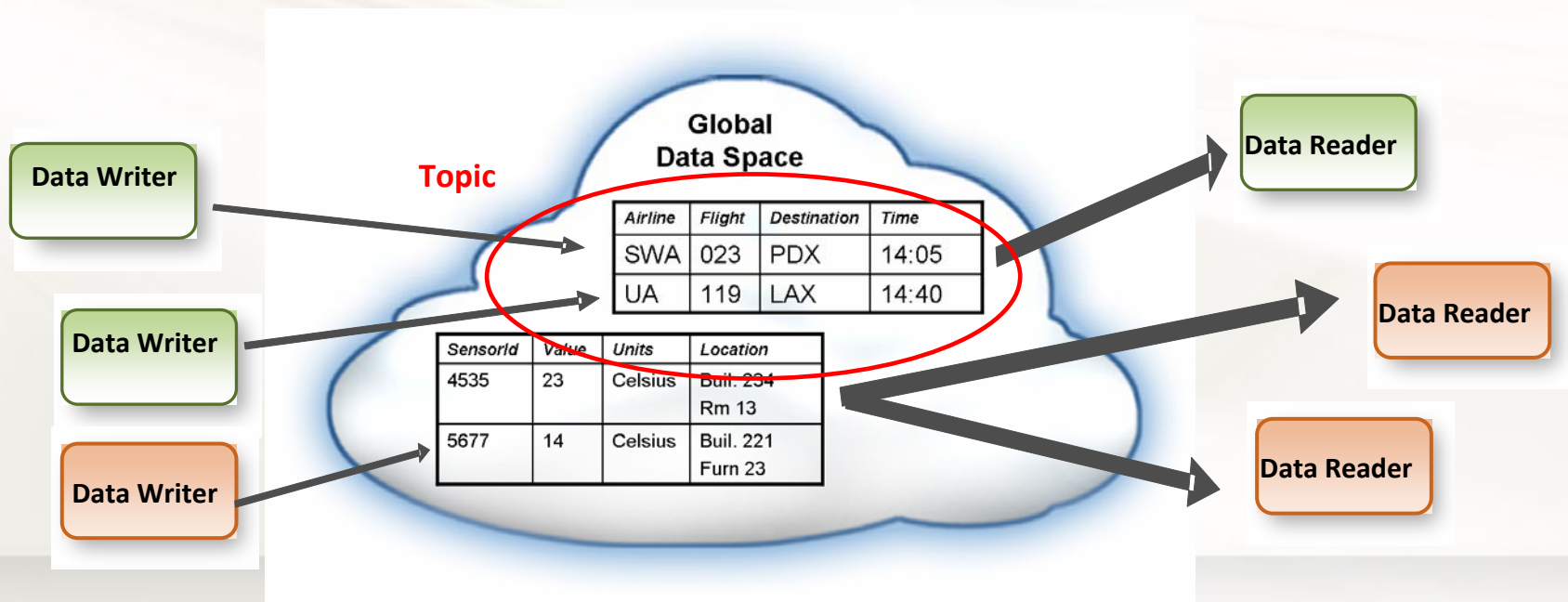


Data-Centric Model

example

“Global Data Space” generalizes Subject-Based Addressing

- Data objects addressed by **DomainId**, **Topic** and **Key**
- **Domains** provide a level of isolation
- **Topic** groups homogeneous subjects (same data-type & meaning)
- **Key** is a generalization of **subject**
 - **Key** can be any set of fields, not limited to a “x.y.z ...” formatted string

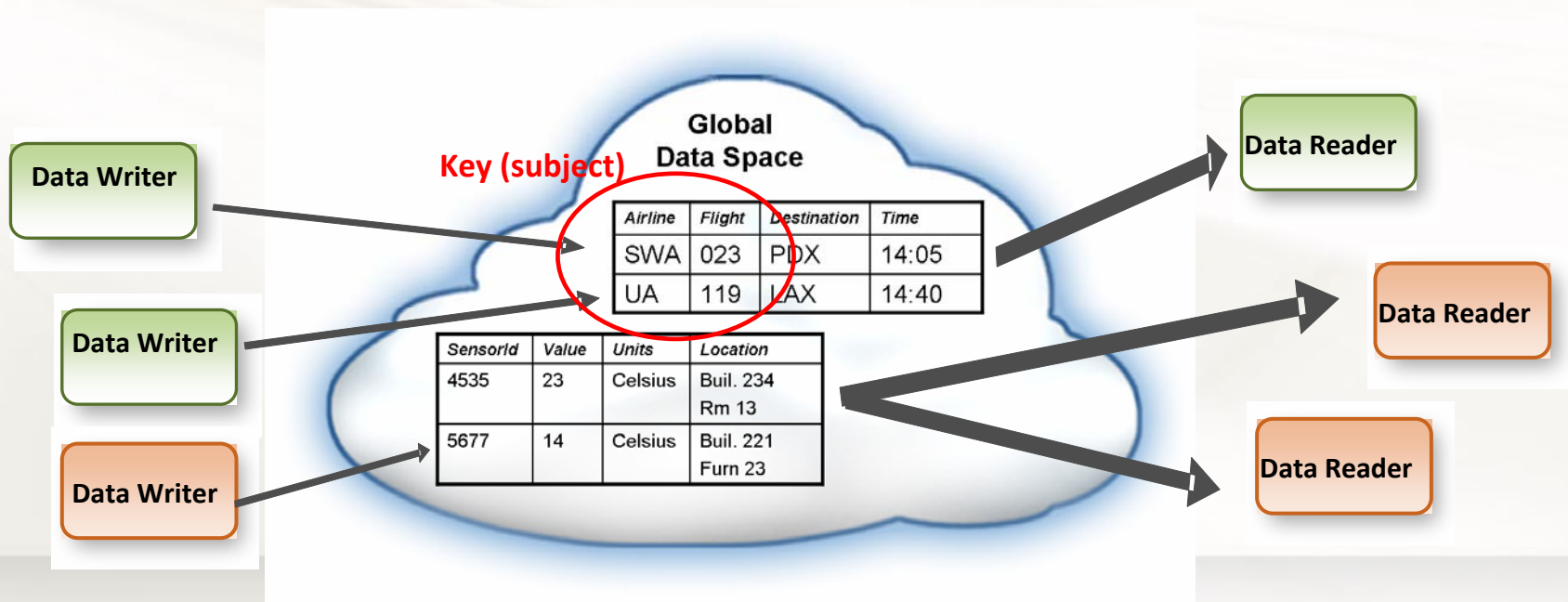


Data-Centric Model

example

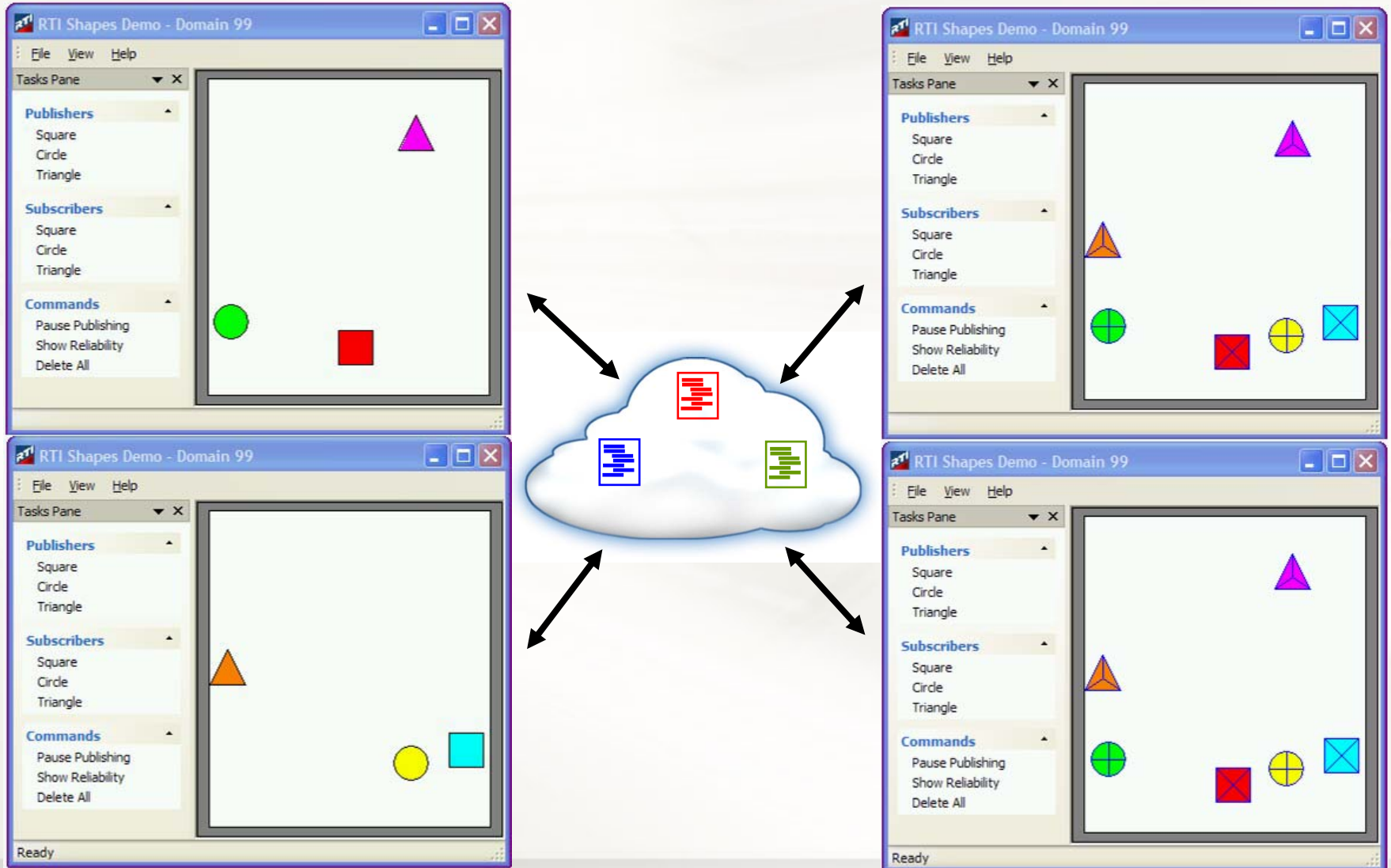
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Demo: Publish-Subscribe

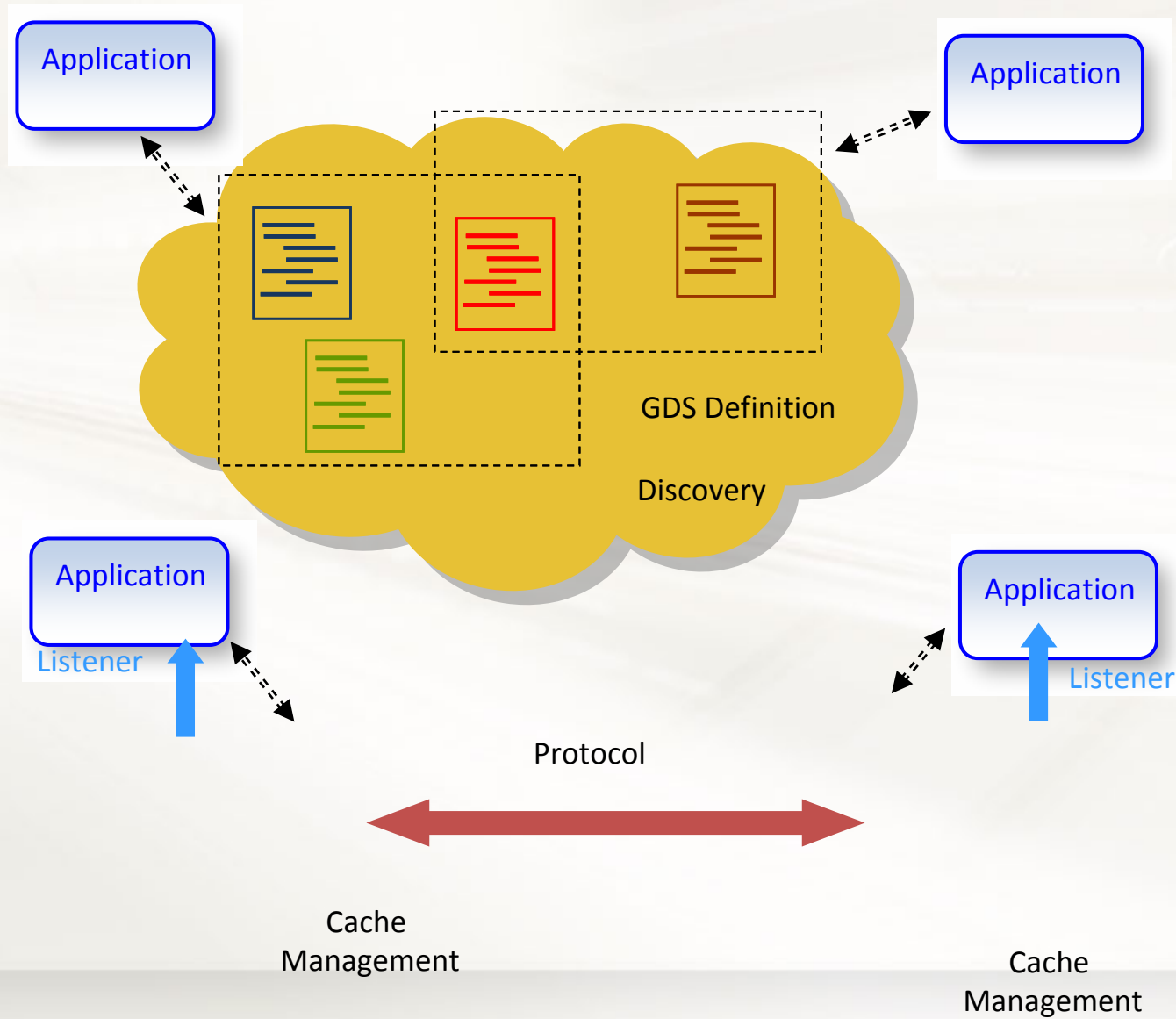
[ShapesDemo](#)



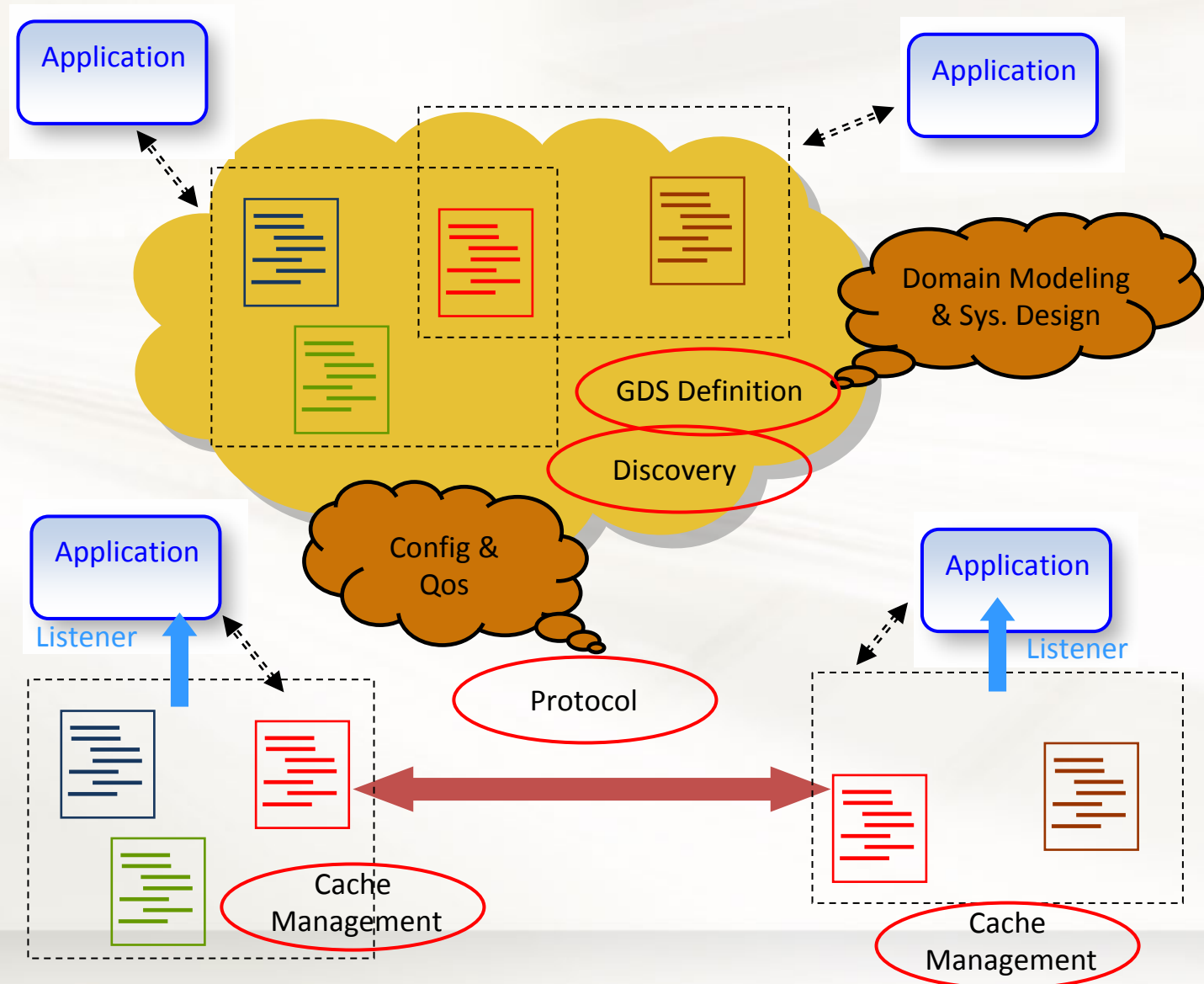
Real-Time Quality of Service (QoS)

	QoS Policy	
Volatility	DURABILITY	User QoS
	HISTORY	
	READER DATA LIFECYCLE	
	WRITER DATA LIFECYCLE	
Infrastructure	LIFESPAN	Presentation
	ENTITY FACTORY	
	RESOURCE LIMITS	
	RELIABILITY	
Delivery	TIME BASED FILTER	Redundancy
	DEADLINE	
	CONTENT FILTERS	
	QoS Policy	
	USER DATA	User QoS
	TOPIC DATA	
	GROUP DATA	
	PARTITION	Presentation
	PRESENTATION	
	DESTINATION ORDER	
	OWNERSHIP	Redundancy
	OWNERSHIP STRENGTH	
	LIVELINESS	
	LATENCY BUDGET	Transport
	TRANSPORT PRIORITY	

Components/Mechanics of the GDS

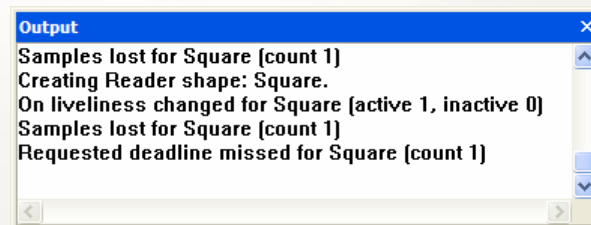
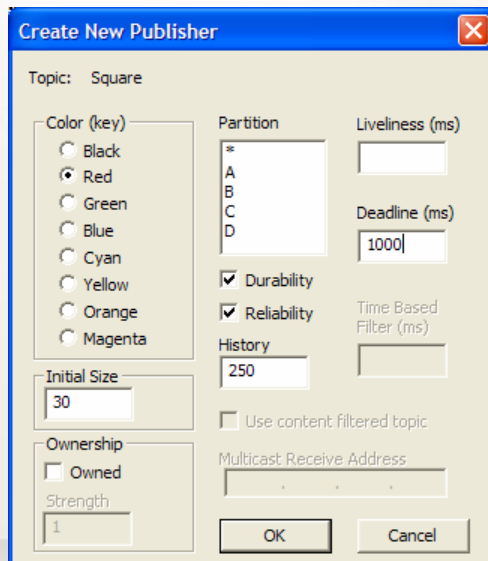
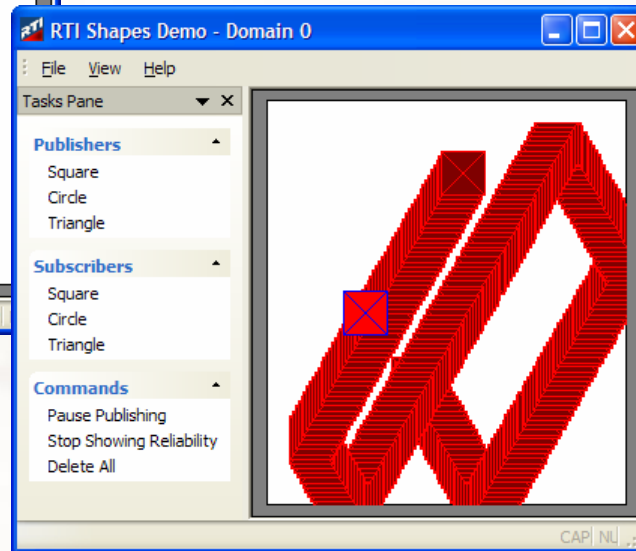
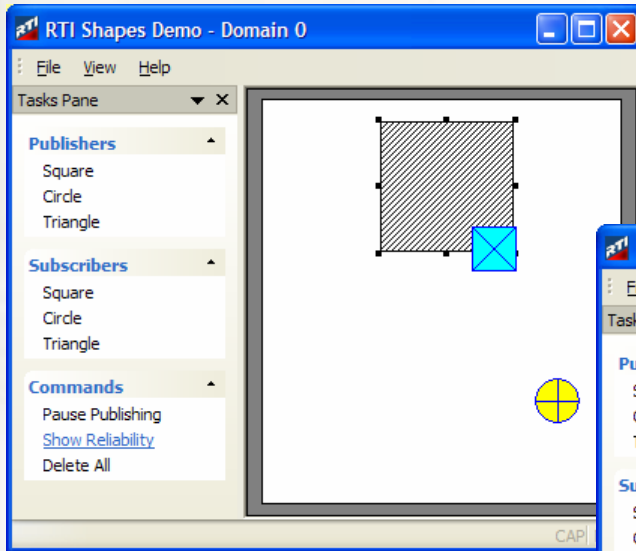


Components/Mechanics of the GDS



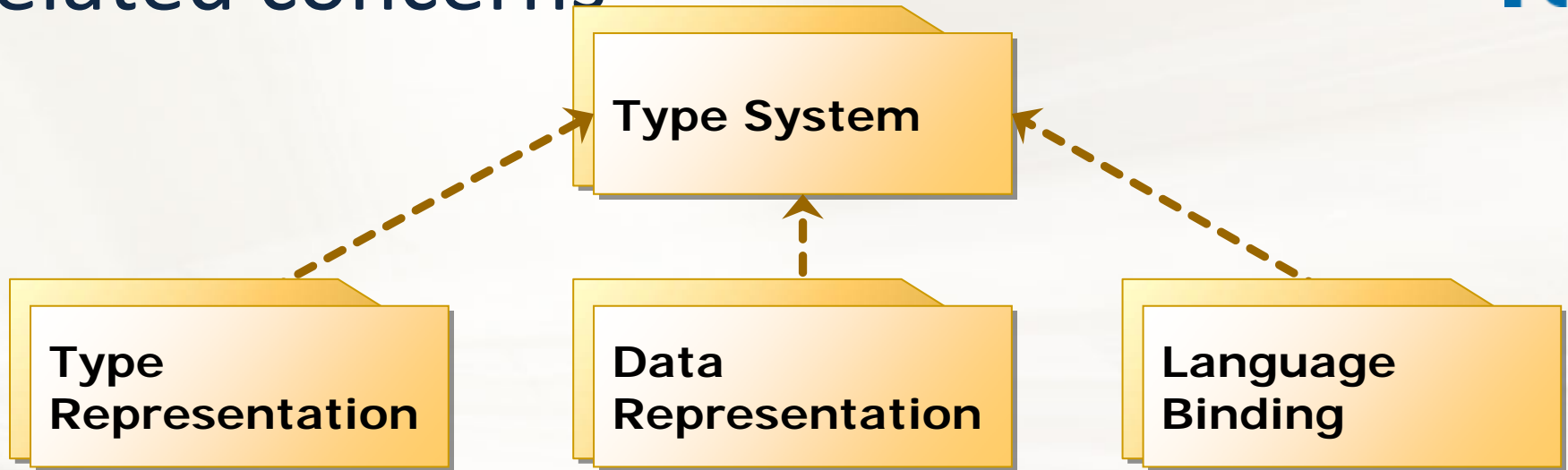
Let's try the QoS

- Detecting presence
- History cache
- Deleting objects
- Ownership
- Liveliness
- Filtering
- Durability



DDS Type-System (X-Types Specification)

Related concerns



- **Type System:** DDS data objects have a type
- **Language Binding:** Objects are manipulated using a Language Binding to some programming language
- **Data Representation:** Objects can be serialized for file storage and network transmission
- **Language Binding:** Types are manipulated using a Language Binding to some programming language
- **Type Representation:** Types can be serialized for file storage and network transmission

X-Types Overview

1. **Type System:** abstract definition of what types can exist
 - Expressed as UML *meta-model*
 - Including *substitutability*, *compatibility* rules
 - Mostly *familiar* from IDL
2. **Type Representations:** languages for describing types
 - *IDL*
 - *XML* and *XSD*
 - *TypeObject*
3. **Data Representations:** languages for describing data
 - *CDR*
 - *XML*

X-Types Overview

4. Language Binding: programming APIs

- *“Plain Language”*: extension of existing IDL-to-language bindings
- *Dynamic*: reflective API for types and objects, defined in UML (conceptual model) and IDL (API)

5. Use by DDS: application of type/data representations to middleware

- Data *encapsulation*, QoS *compatibility*
- *Type compatibility* as applied to endpoint matching
- *Built-in types*

Example

Type Representation

IDL:
Foo.idl

```
struct Foo {  
    string name;  
    long ssn;  
};
```

Language Binding

IDL to Language Mapping:
Foo.h
Foo.c
FooTypeSupport.c

```
struct Foo {  
    char *name;  
    int ssn;  
};
```

```
Foo f = {"hello", 2};
```

Data Representation

IDL to CDR:

```
00000006  
68656C6C  
6F000000  
00000002
```

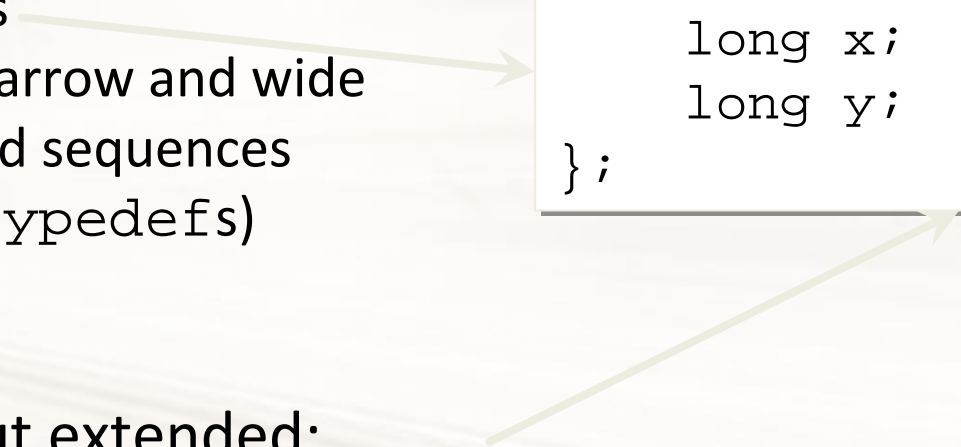

Type System Overview

- * *Type System is not defined in terms of IDL.
I'm explaining in terms of IDL for clarity.*

- Entirely familiar from IDL:

- Primitives
- Strings, narrow and wide
- Arrays and sequences
- Aliases (typedefs)
- Unions
- Modules

```
struct OriginalLandData {  
    long x;  
    long y;  
};
```



- As in IDL, but extended:

- *Structures*— including single inheritance
- *Enumerations*— specify bit width and constant values

- New relative to IDL:

- *Maps*—like `std::map` or `java.util.Map`;
- *Annotations*—for extensibility

Type System Extensibility: Metadata

- **Annotation = structured metadata** attached to type or type member
 - *Annotation type* defines annotation members, their names, and their types
 - *Annotation usage* provides values for annotation type's members
- **Established programming practice**
 - In Java: `@MyAnnotation int x;`
 - In C#: `[MyAnnotation] int x;`

DB Table
name: string

DB Table
name = "Track"

Metadata in IDL: Non-Standard Metadata



- **Java-like annotation syntax:** already familiar
- **Annotation type:**

```
@Annotation local interface MyAnnotation {  
    long value1();  
    double value2();  
};
```

- **Annotation usage:**

```
struct MyStruct {  
    @MyAnnotation(value1 = 42, value2 = 42.0)  
    long my_field;  
};
```

The Example

- Radar system uses “Original Land Data” (OLD):

```
struct OriginalLandData {  
    long x;  
    long y;  
};
```

Type System Extensibility: Structures

Collection of members, of same or different types.

Each member has:

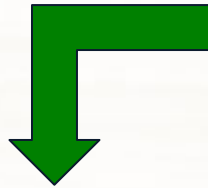
- A *unique name* (string)
- A *unique ID* (unsigned integer)
- Additional *metadata*:
 - *Key / NotKey*
 - *Optional vs. required*—Does value always exist? (6.5.6, 6.5.19)
 - Important semantics: Think null vs. non-null value
 - Universal concept: C, C++, Java, .Net, SQL, XSD, ...
 - Important for interop: If I have a field in my type that you don't, what do I do with data from you?
 - Important for representational efficiency: Skip a field with well-defined semantics
 - *Note*: Keys always required; otherwise, identity breaks down
 - *Shareable/ NotShareable*
 - Member data should not be stored in-line with container
 - Certain language mappings will map to a pointer
 - Allows writing shared data without making extra copies

Type Extensibility: Example

// OLD

```
struct OriginalLandData {  
    long x;  
    long y;  
};
```

is-assignable-from

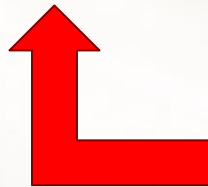


// NEW1

```
struct NextEnhancedWorldview1 {  
    long x;  
    long y;  
    TrackKindEnum kind;  
};
```

// NEW2

```
struct NextEnhancedWorldview2 {  
    long y; // out of order!  
    long x; // out of order!  
};
```



! is-assignable-from

But see later how to make it assignable...

Type Compatibility: Example (Revisited)



```
// NEW1
```

```
@Extensibility(MUTABLE_EXTENSIB  
ILITY)
```

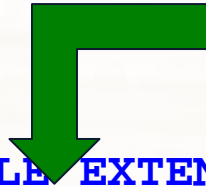
```
struct NextEnhancedWorldview1 {  
    long x;  
    long y;  
    TrackKindEnum kind;  
};
```

```
// NEW2
```

```
@Extensibility(MUTABLE_EXTENSIB  
ILITY)
```

```
struct NextEnhancedWorldview2 {  
    @ID(1) long y;  
    @ID(2) long z;  
    @ID(0) long x;  
};
```

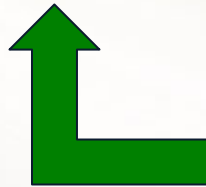
is-assignable-from



```
// OLD
```

```
@Extensibility(MUTABLE_EXTEN  
SIBILITY)
```

```
struct OriginalLandData {  
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    long y;  
};
```

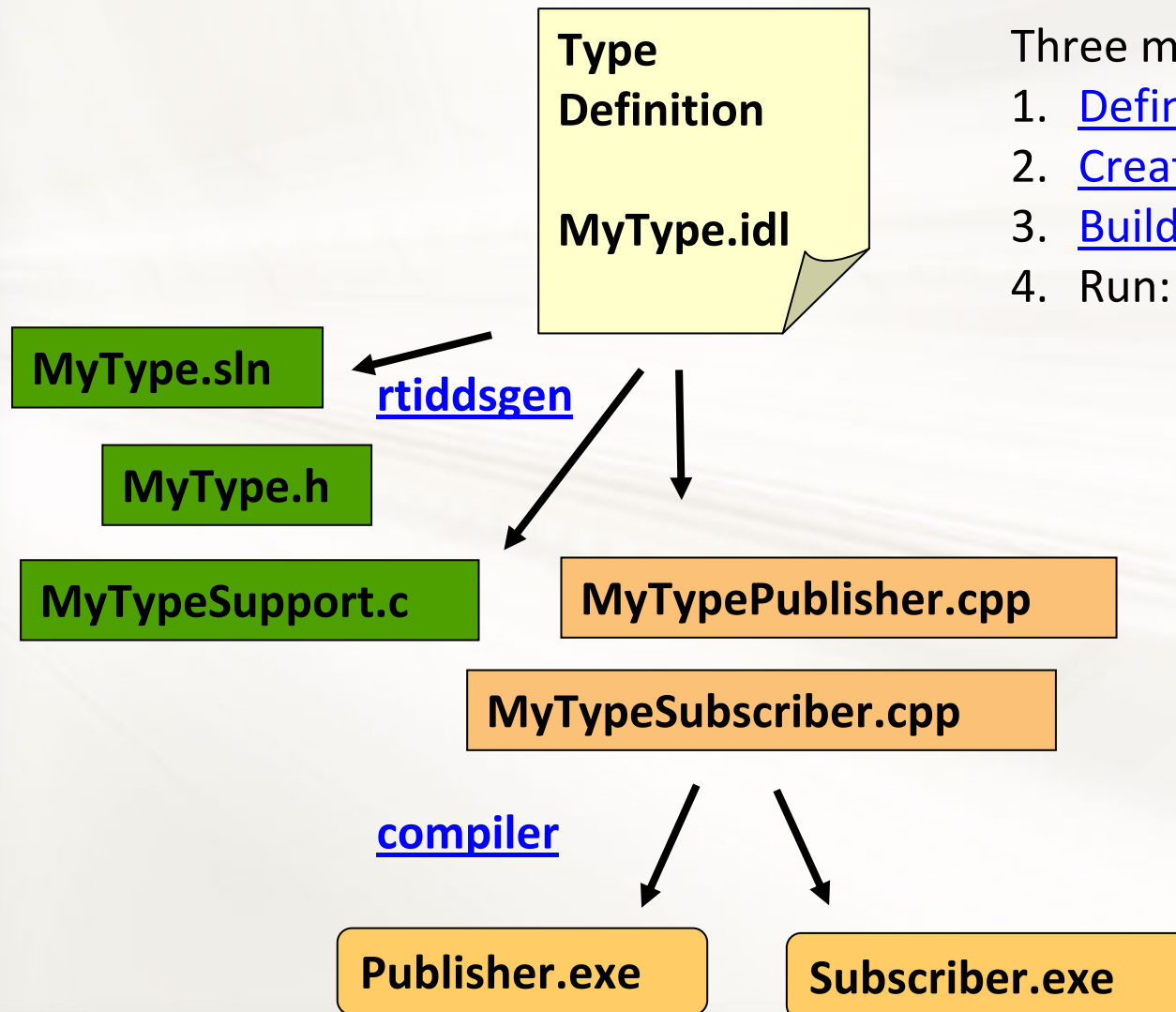


is-assignable-from

Hand's on DDS

The first application

Hands-on Example (C++)



Three minutes to a running app!!

1. [Define your data](#)
2. [Create your project](#)
3. [Build](#)
4. Run: [publisher subscriber](#)

Aux:

[File Browser](#)

[Console](#)

[Delete Files](#)

[rtiddsspy](#)

Example #1 - Hello World

We will use this data-type :

```
const long MSG_LEN=256;  
struct Hello {  
    string<MSG_LEN> user; //@key  
    string<MSG_LEN> msg;  
};
```

Side Note: IDL vs. XML



The same data-type can also be described in XML. This is part of the DDS X-Types specification

```
<const name="MSG_LEN" type="long" value="256"/>
<struct name="Hello">
  <member name="user" key="true" type="string"
    stringMaxLength="MSG_LEN"/>
  <member name="msg" type="string"
    stringMaxLength="MSG_LEN" />
</struct>
```

Generate type support (for C++) [Linux]



```
rtiddsgen HelloWorld.idl -language C++ -example i86Linux2.6gcc4.4.3\  
-replace -ppDisable
```

- Look at the directory you should see:
 - makefile_hello_i86Linux2.6gcc4.4.3
 - And Several other files...
- Open the source files:
 - HelloMsgPublisher.cxx
 - HelloMsgSubscriber.cxx
- Compile:
 - make -f makefile_hello_i86Linux2.6gcc4.4.3

Generate type support (for Java)

```
rtiddsgen HelloWorld.idl -language Java -example i86Linux2.6gcc4.4.3jdk\  
-replace -ppDisable
```

- Look at the directory you should see:
 - makefile_hello_i86Linux2.6gcc4.4.3jdk
 - And Several other files...
 - Look at HelloMsgPublisher.java
 - Look at HelloMsgSubscriber.java
- You can use the makefile to build and the Java programs:
gmake -f makefile_hello_i86Win32jdk

Execute the program [Windows]

- C++:
 - On one window run:
 - `objs\i86Win32VS2005\HelloMsgPublisher.exe`
 - On another window run:
 - `objs\i86Win32VS2005\HelloMsgSubscriber.exe`
- Java
 - On one window run:
 - `gmake -f makefile_hello_i86Win32jdk HelloMsgPublisher`
 - On another window run:
 - `gmake -f makefile_hello_i86Win32jdk HelloMsgSubscriber`
- You should see the subscribers getting an empty string...

Execute the program [Linux]

- C++:
 - On one window run:
 - `objs/i86Linux2.6gcc4.4.3/HelloMsgPublisher.exe`
 - On another window run:
 - `objs/i86Linux2.6gcc4.4.3/HelloMsgSubscriber.exe`
- Java
 - On one window run:
 - `gmake -f makefile_hello_i86Linux2.6gcc4.4.3jdk HelloMsgPublisher`
 - On another window run:
 - `gmake -f makefile_hello_i86Linux2.6gcc4.4.3jdk HelloMsgSubscriber`
- You should see the subscribers getting an empty string...

Example: Publication

```
// Entities creation
```

```
DomainParticipant participant =  
    TheParticipantFactory->create_participant(  
        domain_id, participant_qos, participant_listener);
```

```
Publisher publisher = domain->create_publisher(  
    publisher_qos, publisher_listener);
```

```
Topic topic = domain->create_topic(  
    "MyTopic", "Text", topic_qos, topic_listener);
```

```
DataWriter writer = publisher->create_datawriter(  
    topic, writer_qos, writer_listener);
```

```
TextDataWriter twriter = TextDataWriter::narrow(writer);
```

```
TextStruct my_text;  
twriter->write(&my_track);
```

Example: Subscription

```
// Entities creation
```

```
Subscriber subscriber = domain->create_subscriber(  
    subscriber_qos, subscriber_listener);
```

```
Topic topic = domain->create_topic(  
    "Track", "TrackStruct",  
    topic_qos, topic_listener);
```

```
DataReader reader = subscriber->create_datareader(  
    topic, reader_qos, reader_listener);
```

```
// Use listener-based or wait-based access
```

How to Get Data? (Listener-Based)

// Listener creation and attachment

```
Listener listener = new MyListener();  
reader->set_listener(listener);
```

// Listener code

```
MyListener::on_data_available( DataReader reader )  
{  
    TextSeq received_data;  
    SampleInfoSeq sample_info;  
    TextDataReader reader = TextDataReader::narrow(reader);  
  
    treader->take( &received_data, &sample_info, ...)  
    // Use received_data  
    printf("Got: %s\n", received_data[0]->contents);  
}
```

How to Get Data? (WaitSet-Based)

```
// Creation of condition and attachement
Condition foo_condition =
    treader->create_readcondition(...);
waitset->add_condition(foo_condition);

// Wait
ConditionSeq active_conditions;
waitset->wait(&active_conditions, timeout);

// Wait returns when there is data (or timeout)
FooSeq received_data;
SampleInfoSeq sample_info;

treader->take_w_condition
    (&received_data,
     &sample_info,
     foo_condition);

// Use received_data
printf("Got: %s\n", received_data[0]->contents);
```

Listeners, Conditions & WaitSets

Middleware must notify user application of relevant events:

- Arrival of data
- But also:
 - QoS violations
 - Discovery of relevant entities
- These events may be detected asynchronously by the middleware
 - ... Same issue arises with POSIX signals

DDS allows the application to choose:

- Either to get notified asynchronously using a **Listener**
- Or to wait synchronously using a **WaitSet**

Both approaches are unified using STATUS changes

Status Changes

DDS defines

- A set of enumerated STATUS
- The statuses relevant to each kind of DDS Entity

DDS entities maintain a value for each STATUS

STATUS	Entity
INCONSISTENT_TOPIC	Topic
DATA_ON_READERS	Subscriber
LIVELINESS_CHANGED	DataReader
REQUESTED_DEADLINE_MISSED	DataReader
REQUESTED_INCOMPATIBLE_QOS	DataReader
DATA_AVAILABLE	DataReader
SAMPLE_LOST	DataReader
SUBSCRIPTION_MATCH	DataReader
LIVELINESS_LOST	DataWriter
OFFERED_INCOMPATIBLE_QOS	DataWriter
PUBLICATION_MATCH	DataWriter

```
struct LivelinessChangedStatus
{
    long active_count;
    long inactive_count;
    long active_count_change;
    long inactive_count_change;
}
```

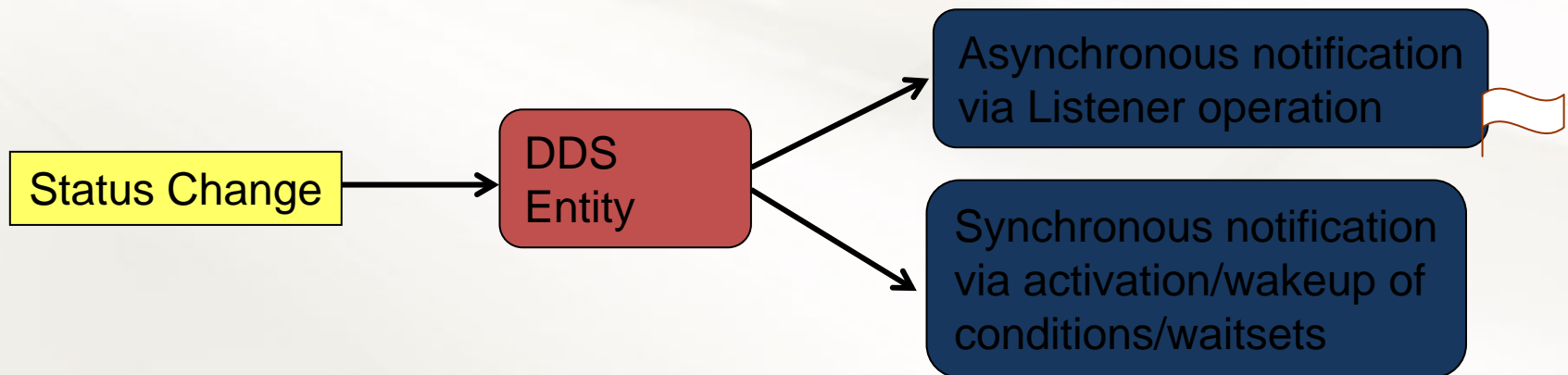

Listeners, Conditions and Statuses

- A DDS Entity is associated with:
 - A listener of the proper kind (if attached)
 - A StatusCondition (if activated)
- The Listener for an Entity has a separate operation for each of the relevant statuses

STATUS	Entity	Listener operation
INCONSISTENT_TOPIC	Topic	on_inconsistent_topic
DATA_ON_READERS	Subscriber	on_data_on_readers
LIVELINESS_CHANGED	DataReader	on_liveliness_changed
REQUESTED_DEADLINE_MISSED	DataReader	on_requested_deadline_missed
REQUESTED_INCOMPATIBLE_QOS	DataReader	on_requested_incompatible_qos
DATA_AVAILABLE	DataReader	on_data_available
SAMPLE_LOST	DataReader	on_sample_lost
SUBSCRIPTION_MATCH	DataReader	on_subscription_match
LIVELINESS_LOST	DataWriter	on_liveliness_lost
OFFERED_INCOMPATIBLE_QOS	DataWriter	on_offered_incompatible_qos
PUBLICATION_MATCH	DataWriter	on_publication_match

Listeners & Condition duality

- A StatusCondition can be selectively activated to respond to any subset of the statuses
- An application can wait changes in sets of StatusConditions using a WaitSet
- Each time the value of a STATUS changes DDS
 - Calls the corresponding Listener operation
 - Wakes up any threads waiting on a related status change



Example #2 - Command-Line Shapes



We will use this data-type :

```
const long STR_LEN=24;
struct ShapeType {
    string<MSG_LEN> color; //@key
    long x;
    long y;
    long shapesize;
};
```

Example #2 - Command-Line Shapes



- Edit the publisher and subscriber
 - Change the TopicName to “Square” (or “Circle” or “Triangle”)
- Change the publisher to do something interesting
 - Use colors such as “GREEN” “RED” “YELLOW”
 - Keep the ‘x’ and ‘y’ between 0 and 260
 - Keep the ‘shapsize’ between 0 and 80

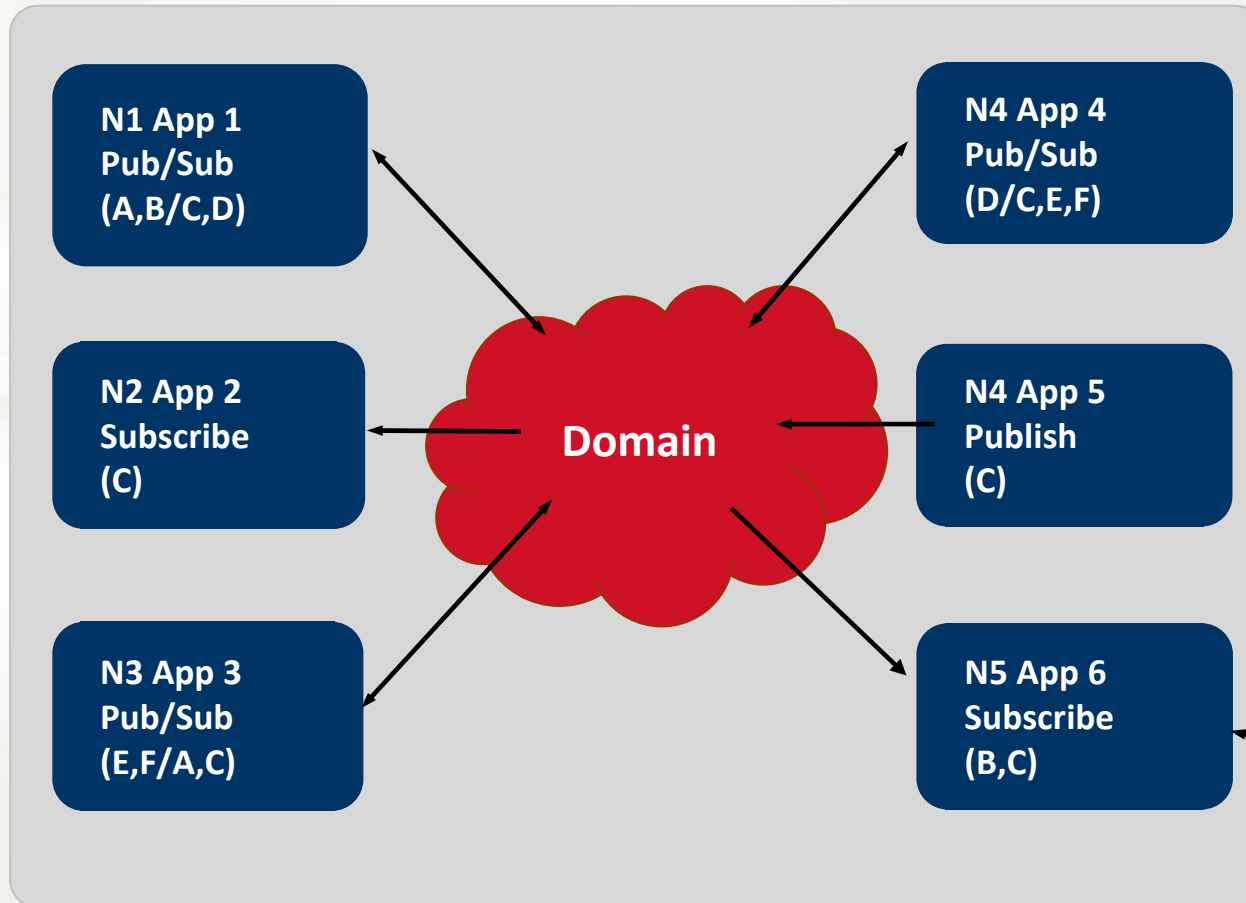
Using DDS

Common Use-Cases

Common use cases

1. Isolating Subsystems
2. Detecting presence of applications
3. Discovering who is publishing/subscribing what
4. Publishing data that outlives its source
5. Keeping a “last-value” cache of objects
6. Monitoring and detecting the health of application elements
7. Building a highly-available system
8. Limiting data-rates
9. Controlling data received by interest set

1. Isolating Subsystems: Domain and Domain Participants

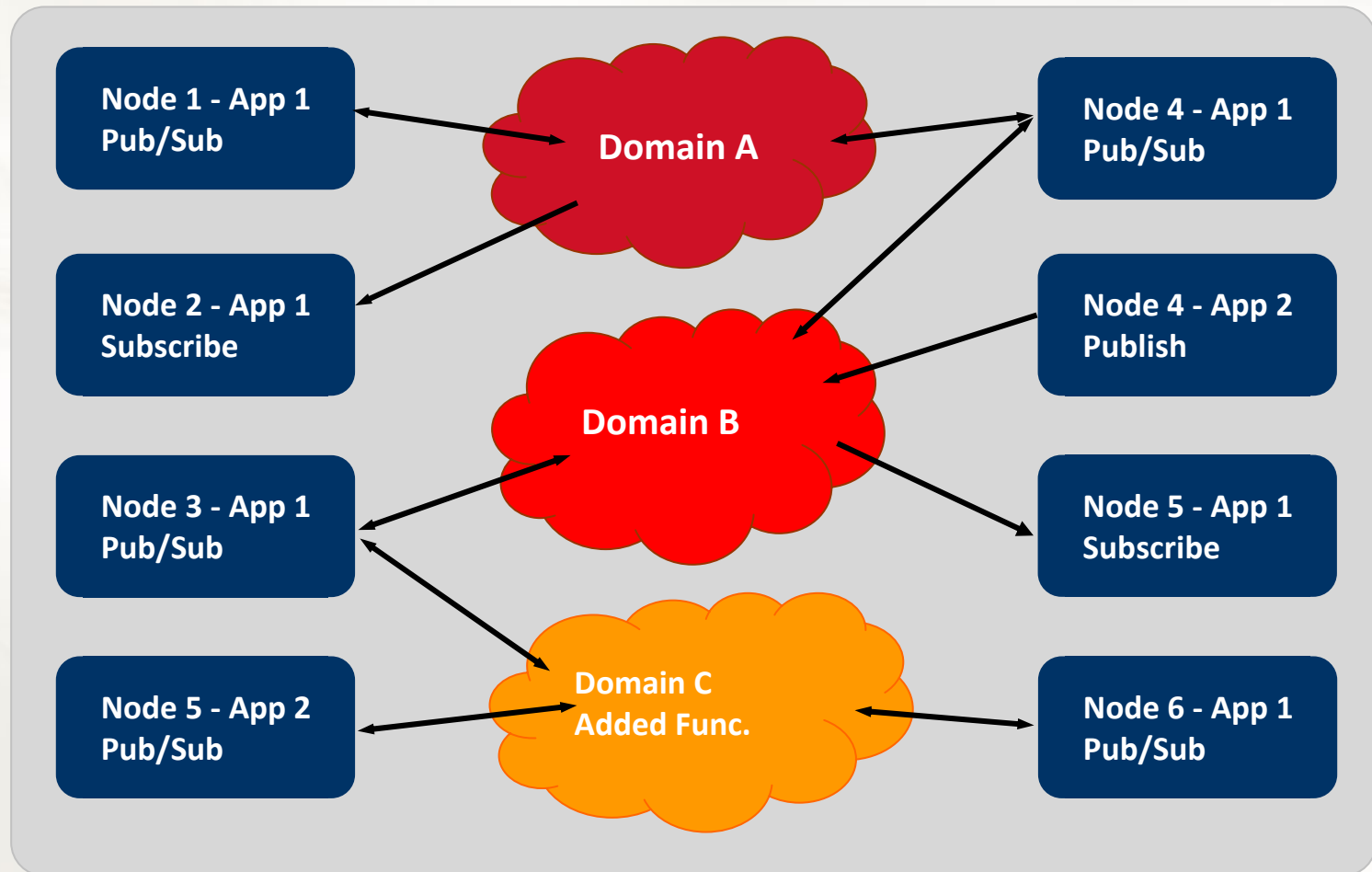


Single 'Domain' System

- Container for applications that want to communicate
- Applications can join or leave a domain in any order
- New Applications are "Auto-Discovered"
- An application that has joined a domain is also called a "Domain Participant"

1. Isolating Subsystems: Domain and Domain Participants

Using Multiple domains for Scalability, Modularity & Isolation



[demo domain 0](#)

Domain System

[demo domain 1](#)

2. Detecting presence of applications DDS builtin Discovery Service

- DDS provides the means for an application to discover the presence of other participants on the Domain
 - The Topic “DCPSParticipants” can be read as a regular Topic to see when DomainParticipants join and leave the network
- Applications can also include meta-data that is sent along by DDS discovery

[shapes demo](#)

[discovery in excel](#)

3. Discovering who is publishing/subscribing

DDS builtin Discovery Service

- DDS provides the means for an application to discover all the other DDS Entities in the Domain
 - The Topics “DCPSPublications”, “DCPSSubscriptions”, “DCPSTopics”, and “DCPSParticipants” be read to observe the other entities in the domain

[shapes demo](#)

[discovery in excel](#)

Example: Accessing discovery information

reader = participant

->**get_builtin_subscriber()**

->**lookup_datareader("DCPSSubscription");**

reader_listener = **new DiscoveryListener();**

reader->**set_listener**(reader_listener);

Example: Displaying discovery information



```
SubscriptionBuiltinTopicData *subscriptionData =  
    new SubscriptionBuiltinTopicData();  
SampleInfo *info = new SampleInfo();  
  
do {  
    retcode =  
        subscriptionReader->take_next_sample( *subscriptionData, *info);  
  
    SubscriptionBuiltinTopicDataTypeSupport  
        ::print_data (subscriptionData);  
  
} while ( retcode != RETCODE_NO_DATA );
```

4. Publishing data that outlives its source:

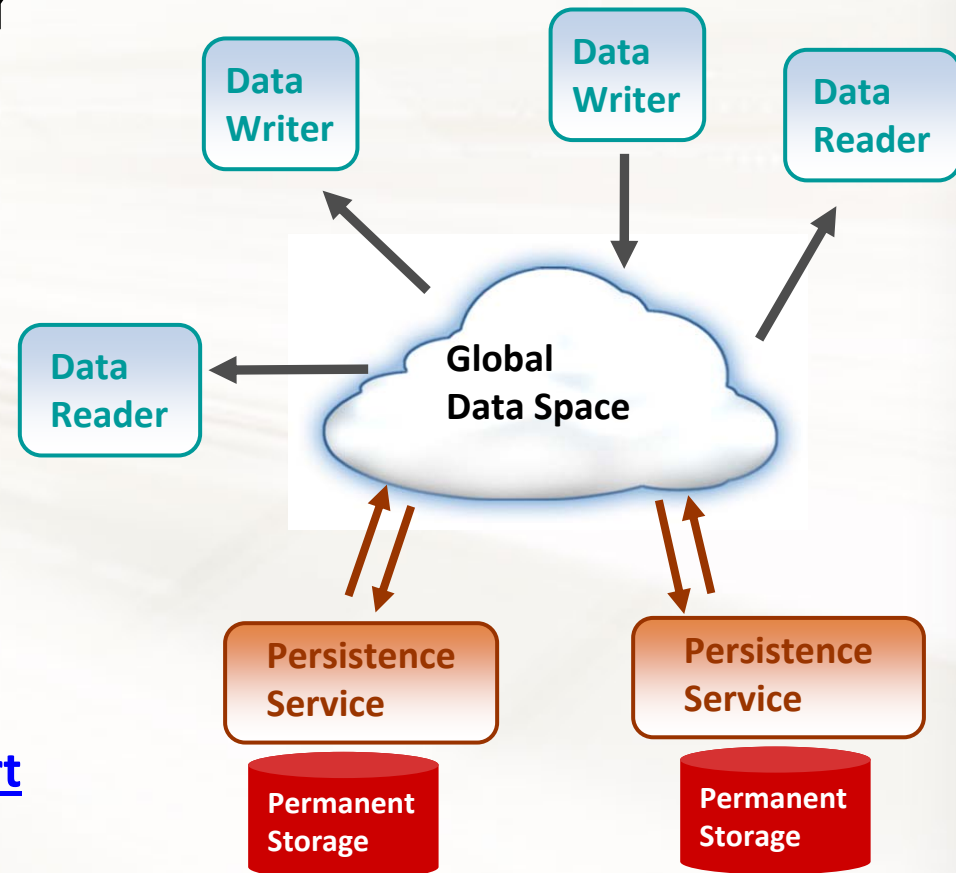
DDS DURABILITY QoS

DURABILITY QoS can be set to:

- VOLATILE -- No durability (default)
- TRANSIENT_LOCAL
 - Durability provided by the DataWriter
 - Late joiners will get data as long as writer is still present
- TRANSIENT
 - Durability provided by external “persistence” service
 - Late joiners will get data as long as persistence is still present
- PERSISTENT
 - Durability provided by external “persistence” service
 - Persistence service must store/sync state to permanent storage
 - Persistence service recover state on re-start
 - Late joiners will get data even if persistence service crashes and re-starts

4. Publishing data that outlives its source: Persistence Service

A service that persists data outside of the context of a DataWriter



Demo:

1. [PersistenceService](#)
2. [ShapesDemo](#)
3. [Application failure](#)
4. [Application \(ShapesDemo\) re-start](#)

5. Keeping a “Last value” cache

- A last-value cache is already built-in into every Writer in the system
 - Can used in combination with a Durable Writer
- A late joiner will automatically initialize to the last value
- Last value cache can be configure with history depth greater than 1
- The Persistence Service can be used to provide a last value cache for durable data

QoS: History – Last x or All

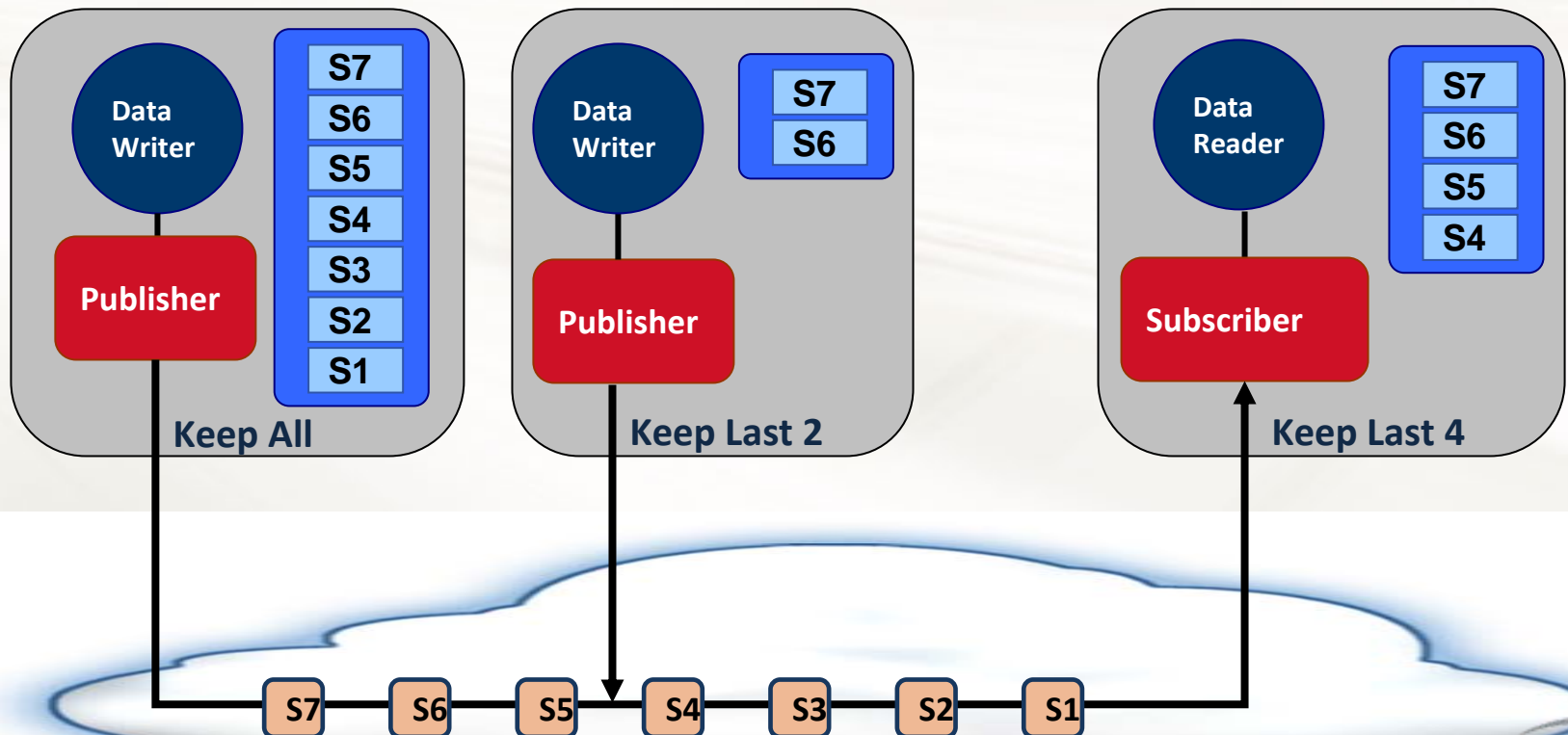
KEEP_ALL:

Publisher: keep all until delivered

Subscriber: keep each sample until the application processes that instance

KEEP_LAST: “depth” integer for the number of samples to keep at any one time

demo history



5. Monitoring the health of applications: Liveliness QoS – Classic watchdog/ deadman switch

- DDS can monitor the presence, health and activity of DDS Entities (Participant, Reader, Writer)
- Use Liveliness QoS with settings
 - AUTOMATIC
 - MANUAL_BY_PARTICIPANT
 - MANUAL_BY_TOPIC
- This is a request-offered QoS
- Answers the question: “Is no news good news?”

QoS: Liveliness: Type and Duration

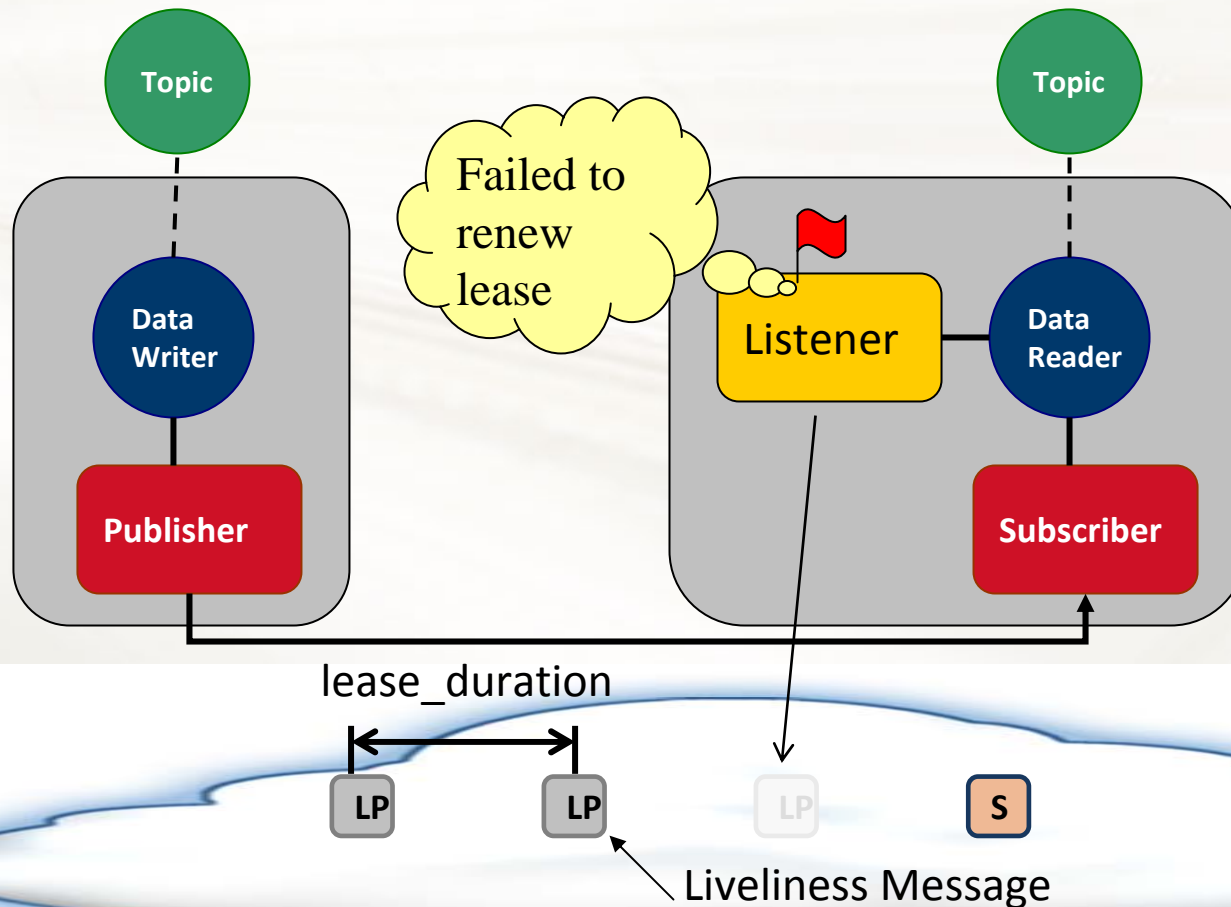
[liveliness example](#)

Type: Controls who is responsible for issues of 'liveliness packets'

AUTOMATIC = Infrastructure Managed

MANUAL = Application Managed

[kill apps](#)

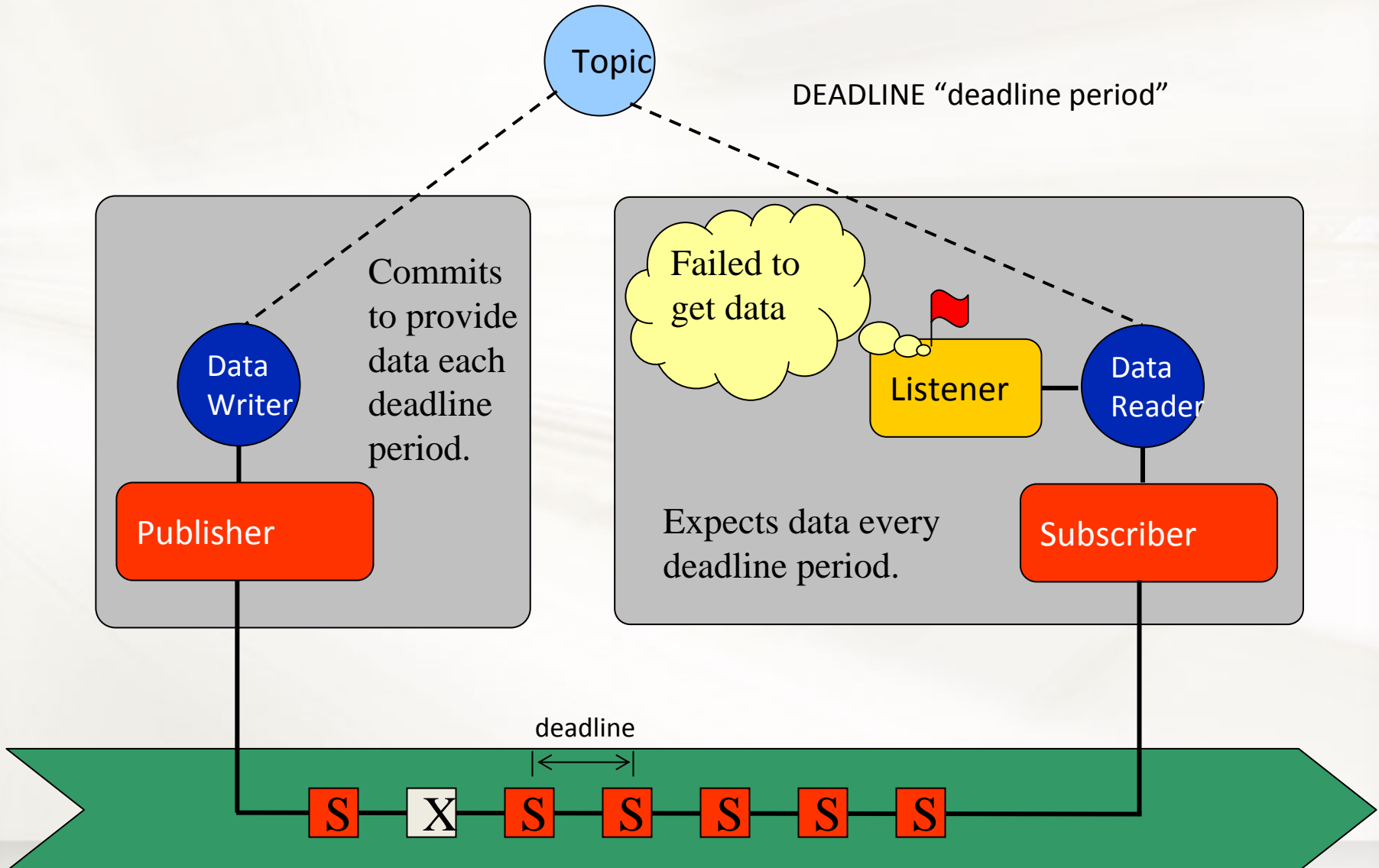


5. Monitoring the health of data-objects: Deadline QoS

- DDS can monitor activity of each individual data-instance in the system
- This is a request-offered QoS
- If an instance is not updated according to the contract the application is notified.
- Failover is automatically tied to this QoS

QoS: Deadline

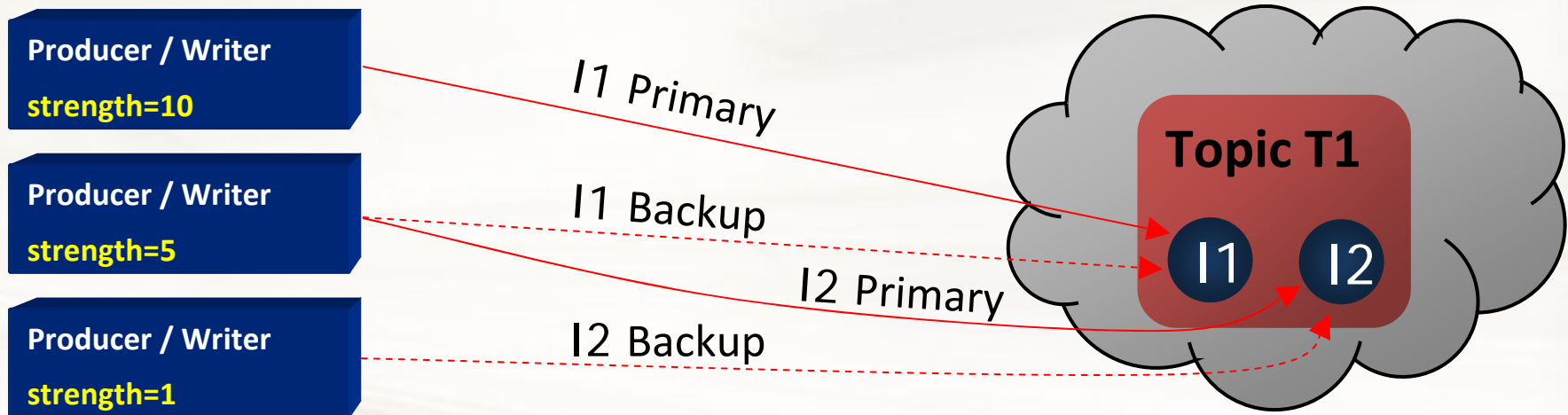
deadline example



5. Building a highly-available system

- HA systems require combining multiple patterns, many directly supported by DDS:
 - Detection of presence -> DDS Discovery
 - Detection of Health and activity -> DDS LIVELINESS
 - > DDS DEADLINE
 - Making data survive application & system failures
 - > DDS DURABILITY
 - Handling redundant data sources and failover
 - > DDS OWNERSHIP

Ownership and High Availability



- Owner determined per subject
- Only extant writer with highest strength can publish a subject (or topic for non-keyed topics)
- Automatic failover when highest strength writer:
 - Loses liveliness
 - Misses a deadline
 - Stops writing the subject
- Shared Ownership allows any writer to update the subject

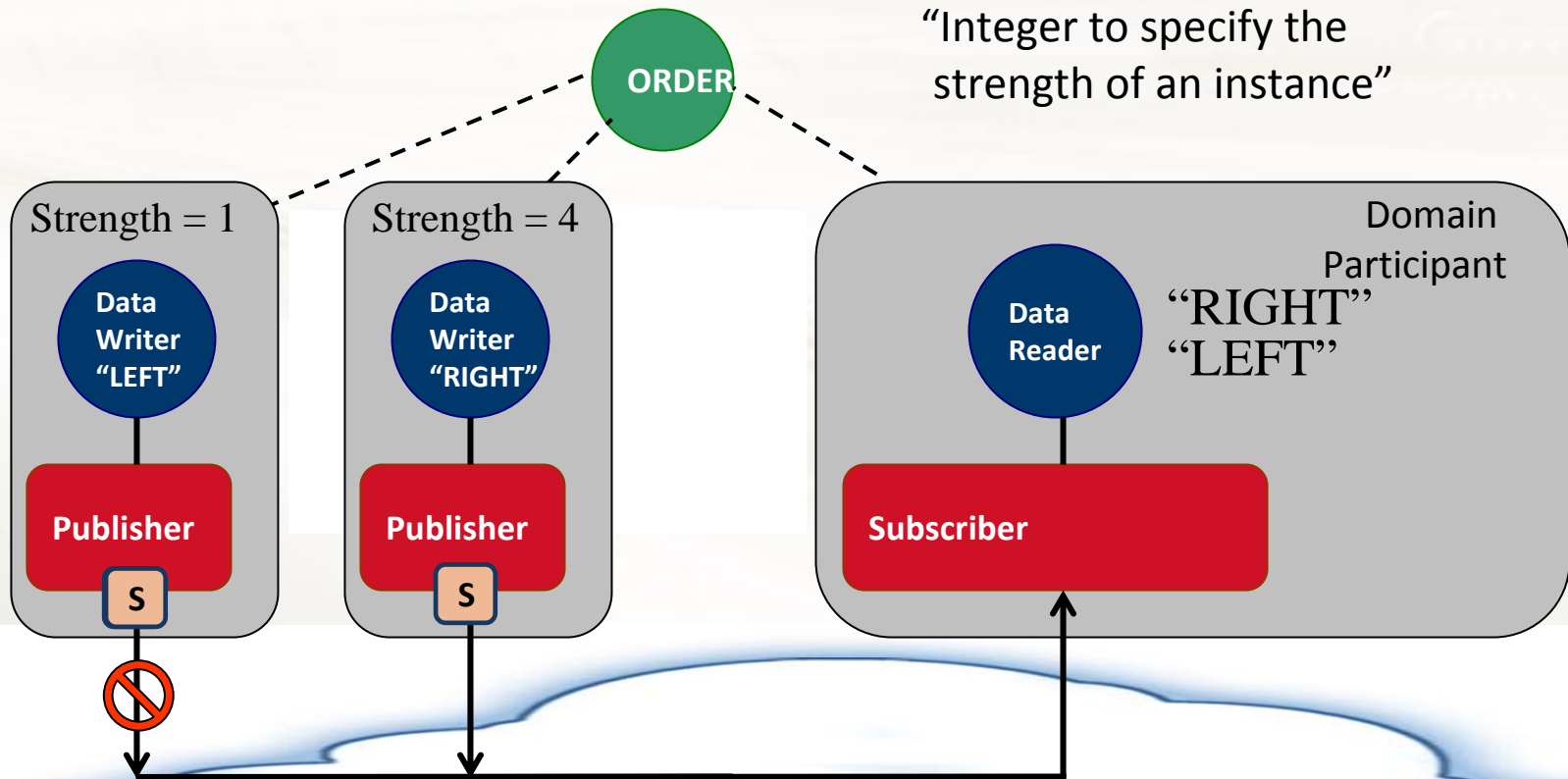
[Start demo](#)

QoS: Ownership Strength

Specifies which DataWriter is allowed to update the values of data-objects

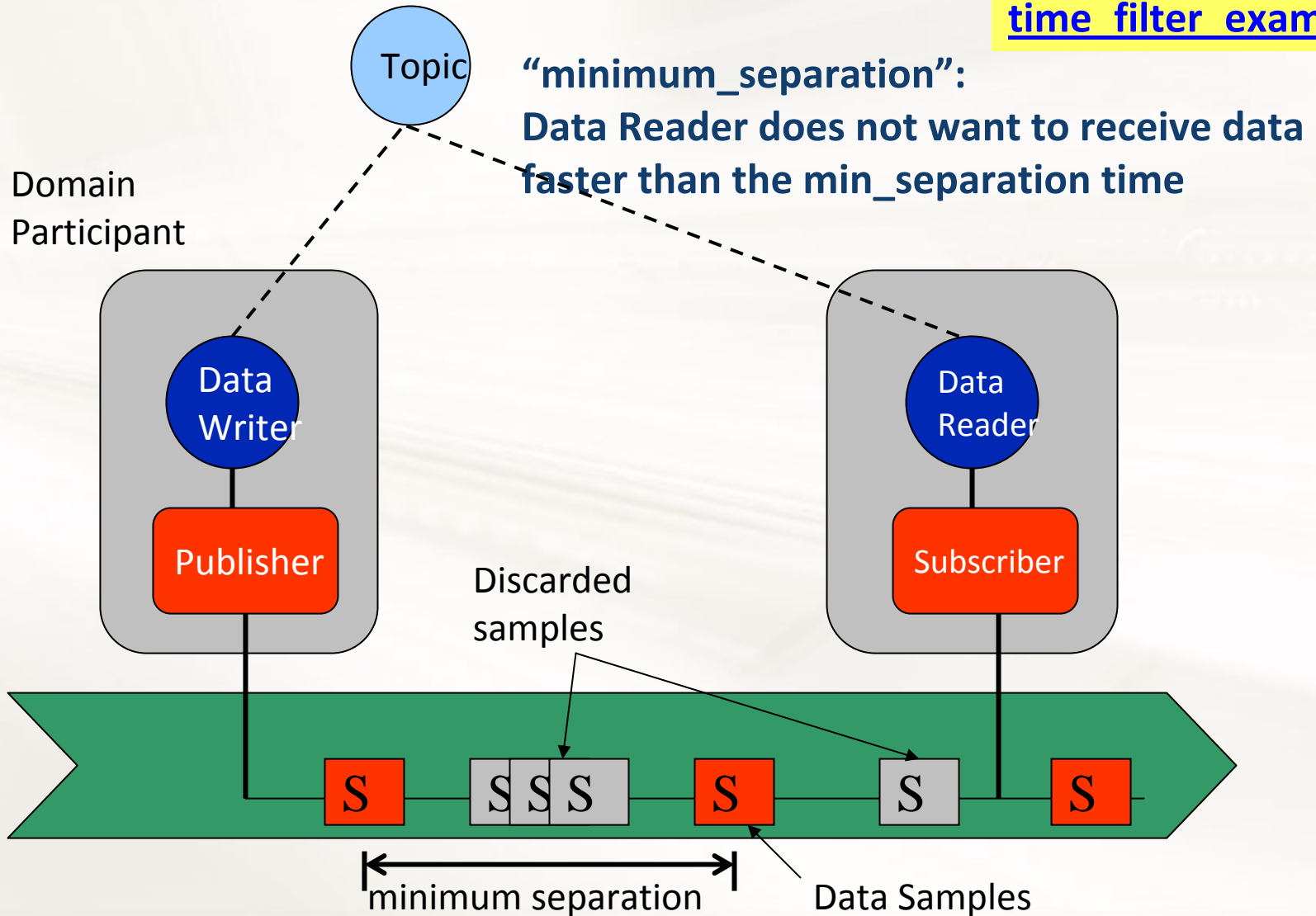
OWNERSHIP_STRENGTH

“Integer to specify the strength of an instance”



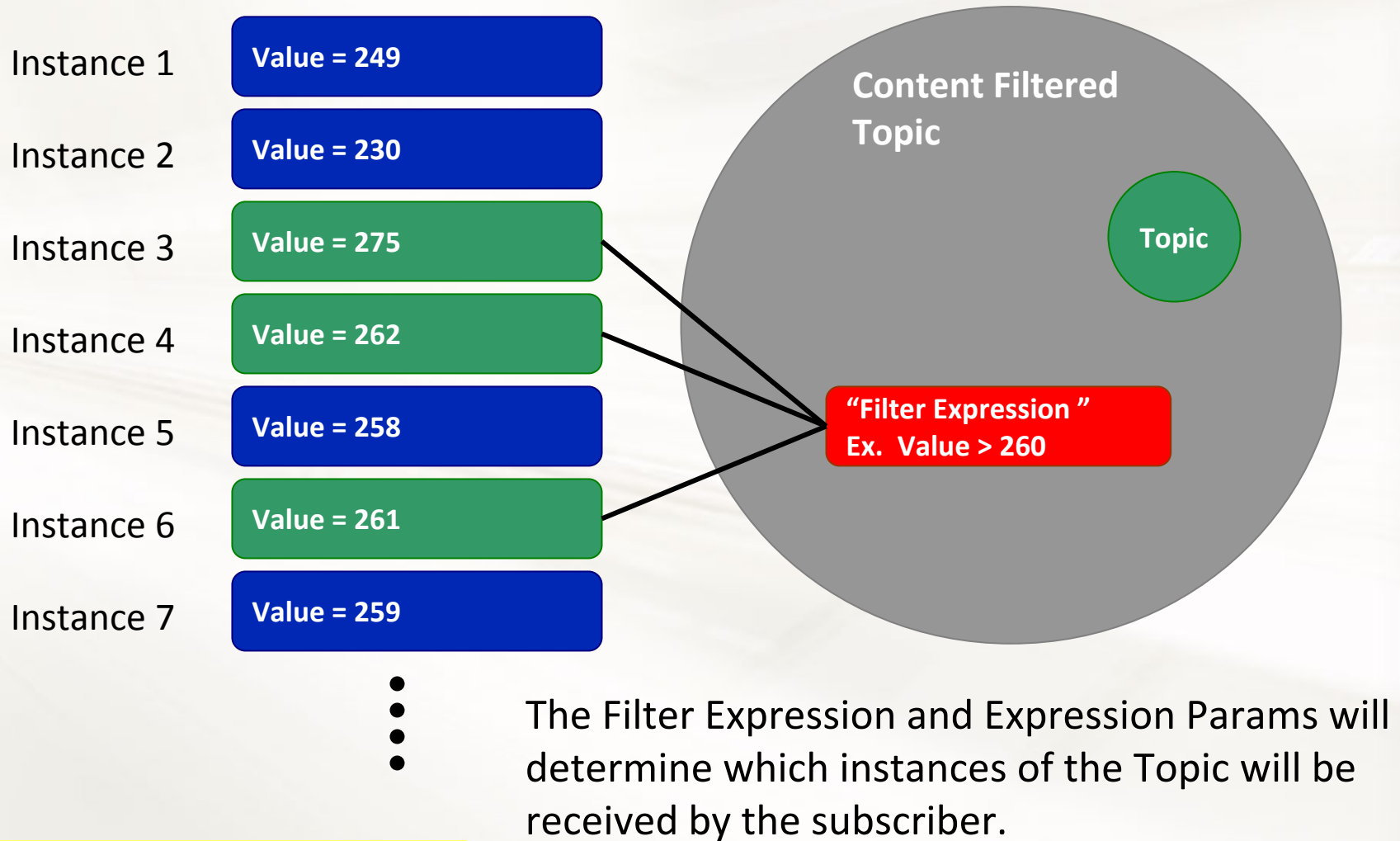
8. Limiting data-rates: QoS: TIME_BASED_FILTER

time filter example



9. Controlling data received by interest set

Content-Based Filtering



content filter example

Using DDS

Best Practices

Best Practices Summary

1. Start by defining a data model, then map the data-model to DDS domains, data types and Topics.
2. Fully define your DDS Types; do not rely on opaque bytes or other custom encapsulations.
3. Isolate subsystems into DDS Domains.
4. Use keyed Topics. For each data type, indicate the fields that uniquely identify the data object.
5. Large teams should create a targeted application platform with system-wide QoS settings.

See http://www.rti.com/docs/DDS_Best_Practices_WP.pdf

Why defining the proper keys for your data types is important

Many advanced features in DDS depend on the use of keys

- History cache.
- Ensuring regular data-object updates.
- Ownership arbitration and failover management.
- Integration with other data-centric technologies (e.g. relational databases)
- Integration with visualization tools (e.g. Excel)
- Smart management of slow consumers and applications that become temporarily disconnected.
- Achieving consistency among observers of the Global Data Space

Find out more...



www.rti.com



community.rti.com



demo.rti.com



www.youtube.com/realtimeinnovations



blogs.rti.com



www.twitter.com/RealTimeInnov



www.facebook.com/RTIsoftware



www.slideshare.net/GerardoPardo

About RTI

Global Leader in DDS

RTI: Global leader in DDS

- Over 70% worldwide embedded messaging middleware market share
- First with...
 - DDS API (2004)
 - RTPS interoperability protocol (2007)
- Active in OMG standardization
 - Board of Directors member
 - Co-chair DDS SIG
 - Chair DDS standard revision committees
- Most mature solution
 - 12+ years of commercial availability
 - Diverse range of industries: defense, finance, medical, industrial control, power generation, communications
 - 350+ commercial customers, 100+ research projects
 - 350,000+ licensed copies



rti
nters

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(RTI Connex) DDS Application Examples



Full-immersion simulation

National Highway
Transportation Safety
Authority
Migrated from CORBA,
DCOM for performance



Air-Traffic Management

INDRA.
Deployed in
UK, Germany, Spain
Standards, Performance,
Scalability



Industrial Control

Schneider Electric
VxWorks-based PLCs
communicate via RTI-DDS



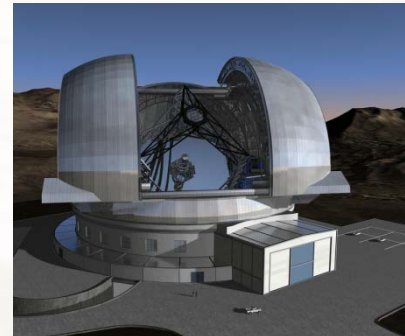
Signal Processing

PLATH GMBH
RTI supports modular
programming across
product line



Large Telescopes

European Southern
Observatory
Performance &
Scalability
1000 mirrors, 1sec loop



Radar Systems

AWACS upgrade
Evolvability,
Maintainability, and
supportability



RTI Connex DDS Application Examples



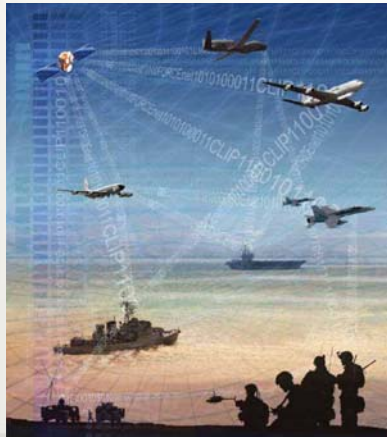
Aegis Weapon System

Lockheed Martin
Radar, weapons, displays, C2



B-1B Bomber

Boeing
C2, communications, weapons



Common Link Integration Processing (CLIP)

Northrop Grumman
Standards-compliant interface
to legacy and new tactical
data links
Air Force, Navy, B-1B and B-52

ScanEagle UAV

Boeing
Sensors, ground station



Advanced Cockpit Ground Control Station

Predator and SkyWarrior UAS
General Atomics
Telemetry data, multiple
workstations



RoboScout

Base10
Internal data bus and link to
communications center



(RTI Connex) DDS Application Examples



Multi-ship simulator

FORCE Technology
Controls, simulation
display

Driver safety

Volkswagen
vision systems, analysis, driver
information systems

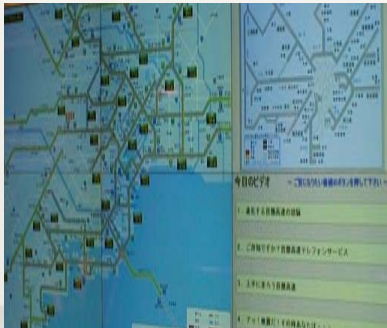


Mobile asset tracking

Wi-Tronix
GPS, operational status
over wireless links

Medical imaging

NMR and MRI
Sensors, RF generators, user
interface, control
computers



Highway traffic monitoring

City of Tokyo
Roadway sensors, roadside
kiosks, control center

Automated trading

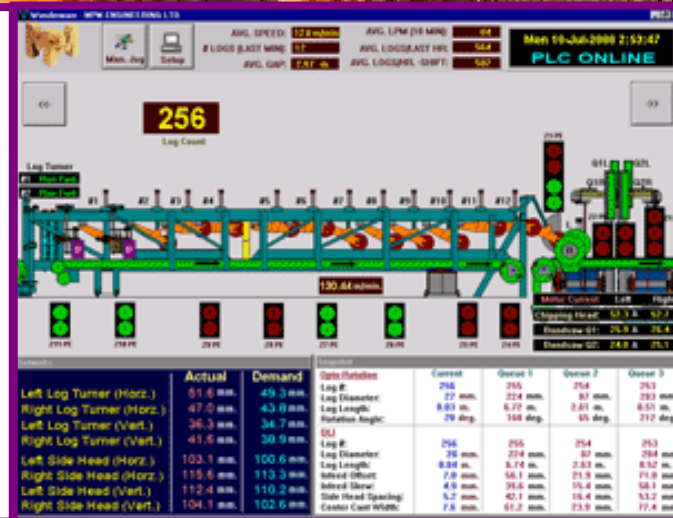
Automated Trading Desk (ATD,
now Citigroup)
Market data feed handlers,
pricing engines, algorithmic
trading applications



Schneider Programmable Logic Controllers



- Modern factories require the exchange of up-to-the-minute data on manufacturing processes, even with resource-constrained devices
- Challenge to incorporate devices with limited memory or processing power
- RTI with Schneider created a compact real-time publish-subscribe service – resides & executes in under 100 kb!



NASA KSC Launch Control



The Constellation program will be the next generation of American manned spacecraft.

RTI delivered 300k instances, at 400k msgs/sec with 5x the required throughput, at 1/5 the needed latency

NASA used RTI's Architecture Study to lower risk.

RTI connects thousands of sensors and actuators

Automotive Safety



The VW Driver Assistance & Integrated Safety system

Provides steering assistance when swerving to avoid obstacles

Detects when the lane narrows or passing wide loads

Helps drivers to safely negotiate bends



RTI Connex integrates diverse legacy buses in the Car



“RTI delivered great functionality at a low cost. Using RTI middleware saved us a lot of money, time, and effort compared to our previous in-house developed solution.”

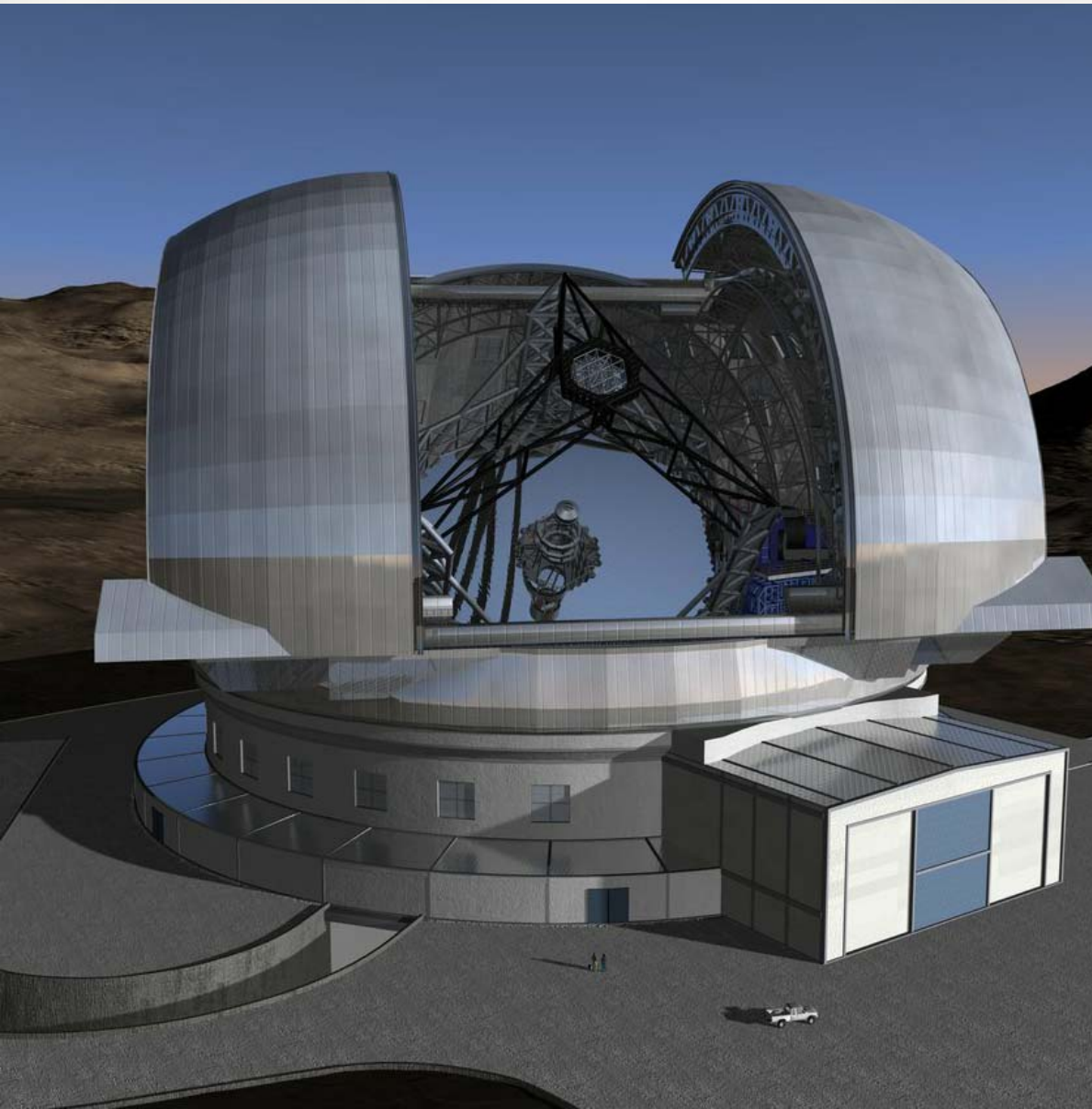
RTI powers Varian’s entire NMR and MRI product lines

A single MRI receiver can saturate a 1Gbit network. An instrument may have 16...

RTI Connex DDS flexible and powerful QoS optimizes network use

RTI Connex handles megabytes of data

European Southern Observatory



**ESO's Very Large Telescope array
has over 900 mirrors**

Each mirror can be separately
controlled in position and
orientation (6 DOF)

Each second all mirrors are
reposition to compensate for
atmospheric disturbances

RTI coordinates thousands of
servo mirrors and operational
parameters.

**RTI middleware coordinates
control and measurement**

Lockheed Martin US Navy Aegis Open Architecture Weapon System



Next-generation of the U.S. Navy Aegis Weapon System

- Challenge to share time-critical data across highly distributed system including radar, weapons, displays and controls
- Need to maximize future scalability and flexibility
- RTI provides real-time communication infrastructure. Standards-based & extensible for future system enhancements

Thank you