



Defining a Fault Tolerant CORBA Component Model

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Background



In the beginning...

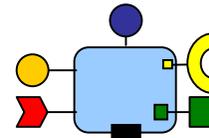
OOP let us encapsulate related data and operations

CORBA linked distributed objects, hid platform dependencies

FT CORBA added fault tolerant support for distributed objects

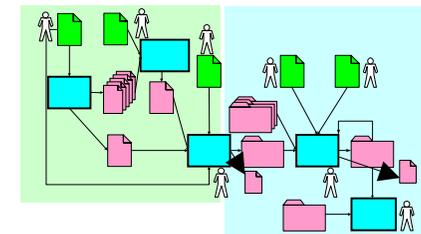
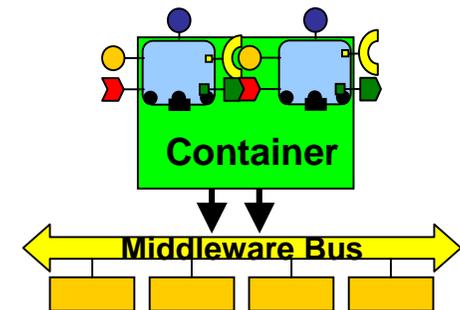
Then came...

Components - assemble/deploy objects into larger applications



CORBA Component Model (CCM)
distributed component model

Model Integrated Computing (MIC) - tools & process to implement/package/assemble/deploy distributed components



How can we add fault tolerant support for distributed components ?

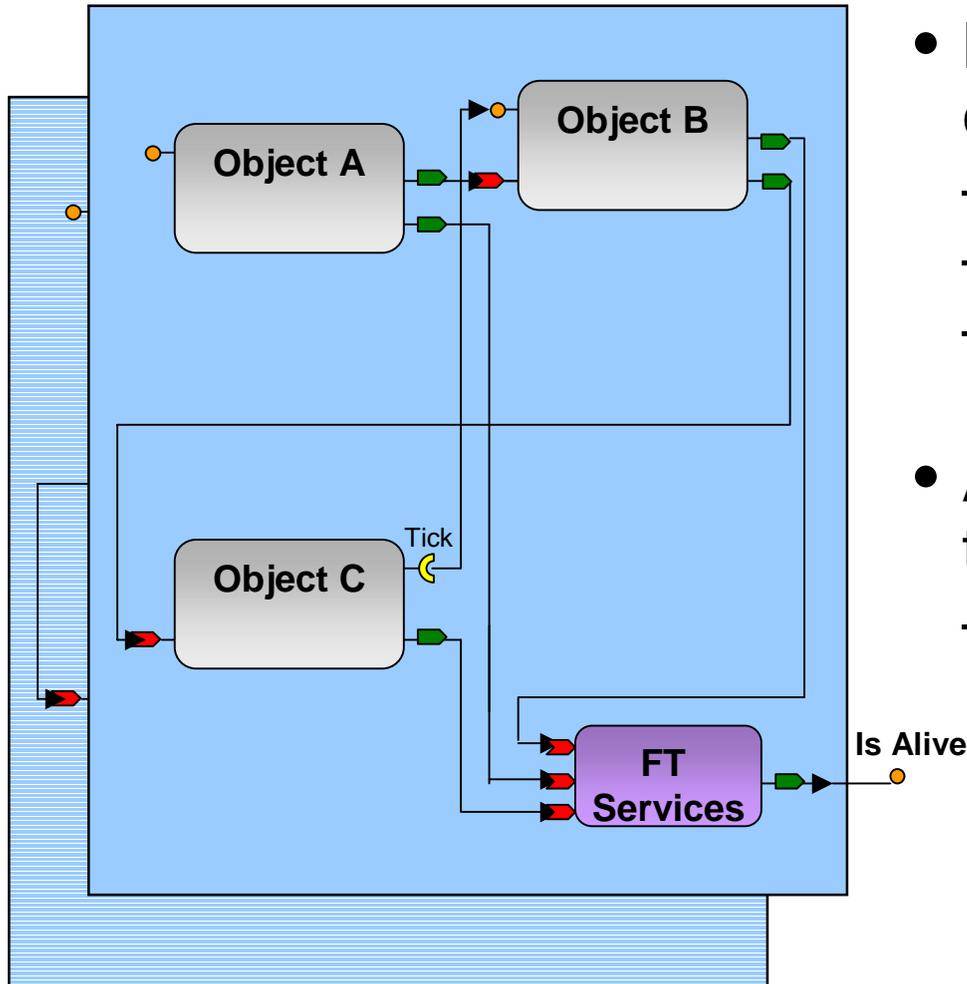
Why Have a FT CCM ?

- **CCM and MIC can support fault tolerant (FT) systems**
- **Weave fault tolerance into component-based designs**
- **Leverage benefits of component model in FT designs**
 - **separation of concerns at the right levels**
 - e.g. component, container, server level
 - run-time configurations, connections
 - **composition-based FT assembly and deployment**
 - build fault tolerant configurations and connections
 - separate logical from physical deployment
 - automate fault tolerant assembly and deployment
 - **metadata captures FT properties/policies**
- **First step towards a Real-Time Fault Tolerant CCM**

FT CCM Goals

- Application-transparent fault tolerance
- Fault tolerant design by composition
- Apply MDA principles
 - One fact in one place
 - Separate design from platform
- Automate fault tolerant component assembly & deployment
 - Hide the details of FT assembly and deployment
- Minimize edits to FT components
- Minimize impact to existing standards

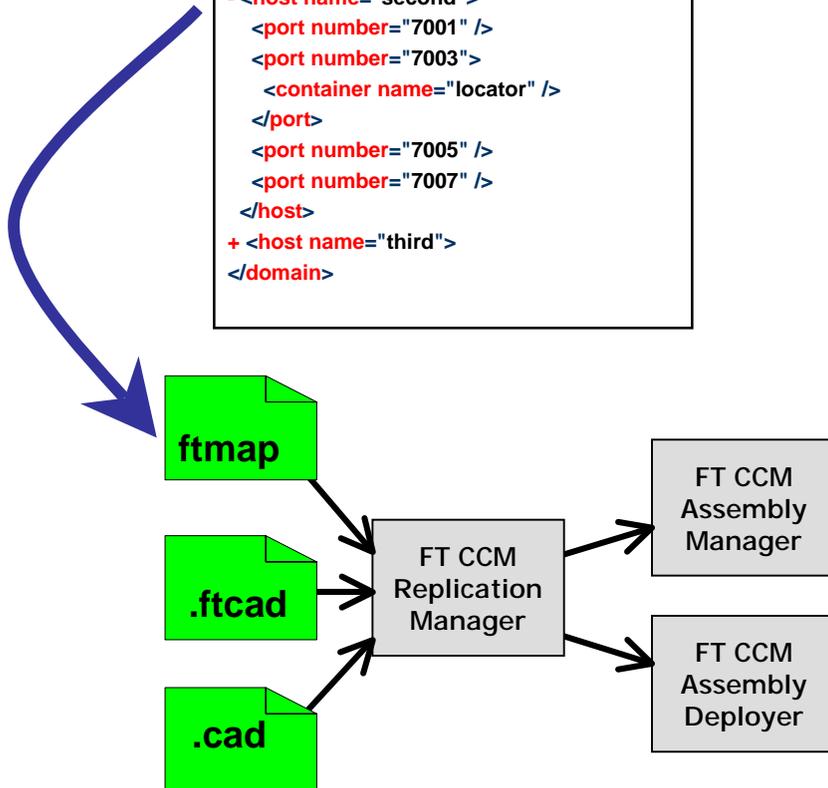
Approach to FT CCM



- Make container (not object) entity of redundancy
 - proper separation of concerns
 - handle container state
 - affects FT CORBA
- Add FT services component to containers
 - link components to FT services at the container level
 - fault monitoring
 - checkpoint (log) components
 - log container state
 - implement in CIAO daemon

Approach to FT CCM

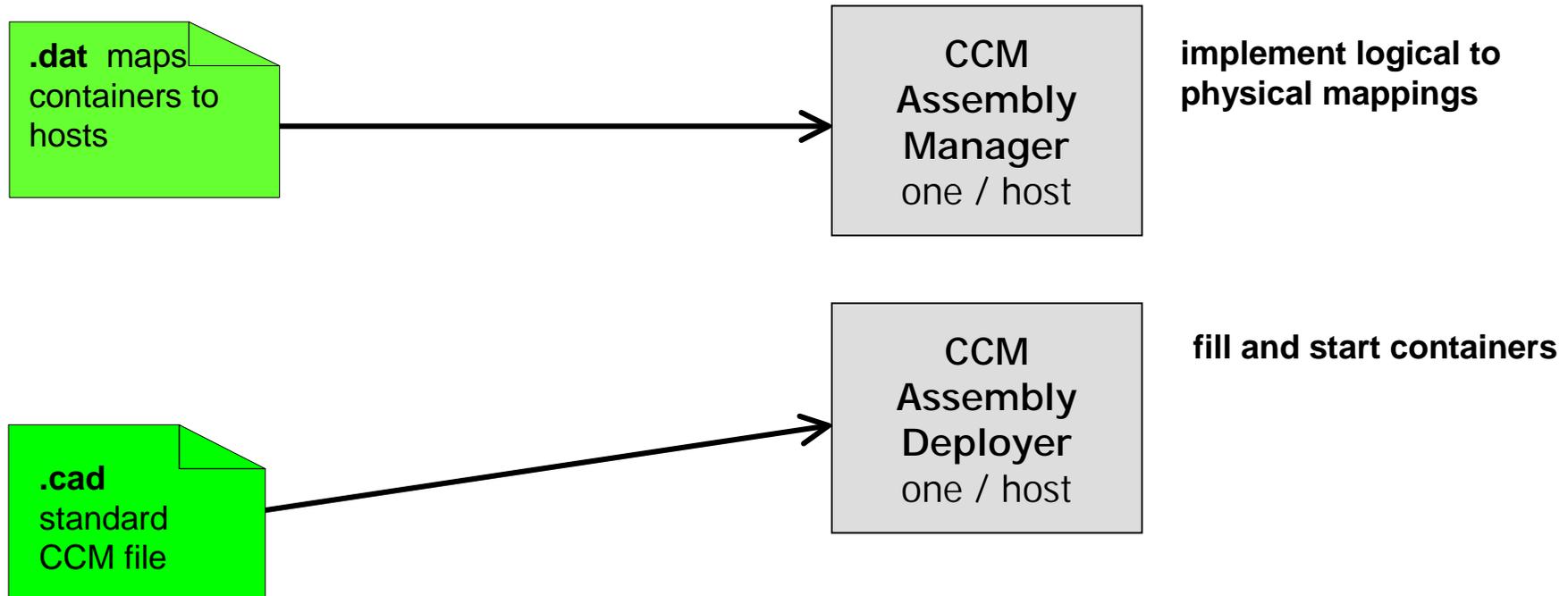
```
- <domain name="basicSP">
- <host name="first">
- <port number="7001">
  <container name="locator" />
  </port>
  <portrange low="7501" high="7599" />
</host>
- <host name="second">
  <port number="7001" />
  <port number="7003">
    <container name="locator" />
  </port>
  <port number="7005" />
  <port number="7007" />
</host>
+ <host name="third">
</domain>
```



- Express FT properties and policies in metadata
 - e.g. replication
- Separate logical assembly from physical assembly
 - Replica count is logical
 - Replica placement is physical
 - FT CCM Replication Manager deploys replicas at runtime
 - deployment rules (.ftmap)
 - resource declarations (.ftcad)
 - container definitions (.cad)

Traditional assembly/deployment process

- physical and logical assembly are combined

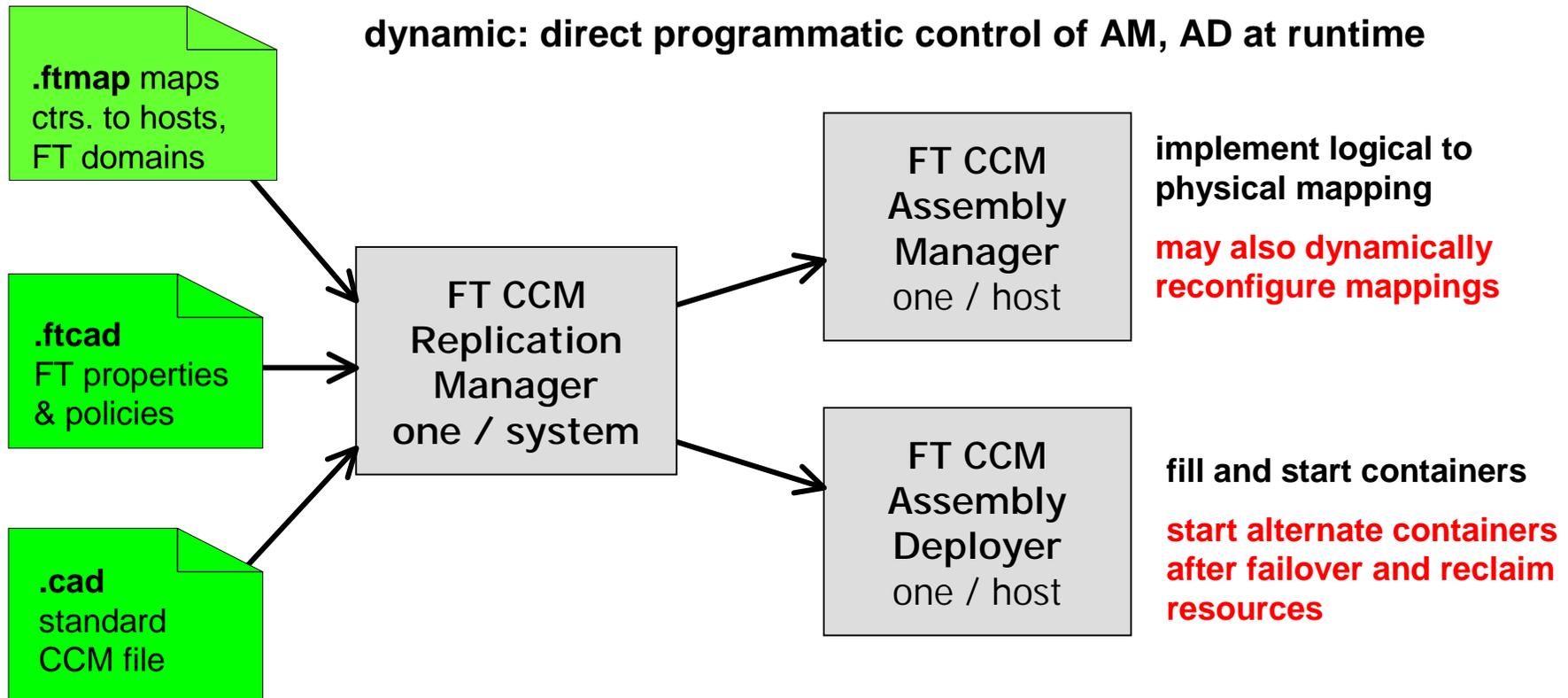


FT CCM assembly/deployment process

- decouple logical and physical assembly
- Replication Manager output can be static or dynamic

static: a post-processed .cad file with all replicas assigned

dynamic: direct programmatic control of AM, AD at runtime



XML Schemas: FT MAP file

FT MAP file maps containers to FT Domains, host ports

```
- <domain name="basicSP">
  - <host name="first">
    - <port number="7001">
      <container name="locator" />
    </port>
    <portrange low="7501" high="7599" />
  </host>
  - <host name="second">
    <port number="7001" />
    <port number="7003">
      <container name="locator" />
    </port>
    <port number="7005" />
    <port number="7007" />
  </host>
+ <host name="third">
</domain>
```

- Logical to physical mapping
- Replication Manager (RM) assigns container replicas to daemons running on host ports
- If a container name is mapped to a port, the RM may only allocate a replica of that container to that port
- If only a port is specified, RM is free to use that port for any container replica
- One FT MAP file per system replaces one **.dat** file per host

XML Schemas: FT CAD file

FT CAD file defines FT container & component properties

- Applies FT marks atop Component Assembly Descriptor (.cad) files

```
- <ftproperties>
  - <!-- Properties defined at the container level are defaults for the components in the container and the general
    container behavior -->
  • <container name="locator" replication-style="active" initial-no-of-replicas="3" min-no-of-replicas="2"
    membership-style="memb_inf_ctrl" consistency-style="cons_inf_ctrl" fault-monitoring-style="push" fault-
    monitoring-interval="100" fault-monitoring-timeout="500" fault-monitoring-granularity="container" heartbeat-
    policy="48" heartbeat-enabled-policy="49" request-duration-policy="47" checkpoint-interval="200" />
    <container name="viewer" replication-style="stateless" initial-no-of-replicas="1" min-no-of-replicas="1"
    membership-style="memb_inf_ctrl" consistency-style="cons_inf_ctrl" fault-monitoring-style="pull" fault-
    monitoring-interval="10000" fault-monitoring-timeout="20000" fault-monitoring-granularity="container"
    heartbeat-policy="48" heartbeat-enabled-policy="49" />
  - <!-- Properties defined at the component level override defaults set at the container level -->
    <component name="display" />
    <component name="rategen" />
    <component name="gps" />
</ftproperties>
```

Applying FT properties and policies

FT properties and policies	may be applied to	
	Components	Container Groups
replication style		X
initial no of replicas		X
min no of replicas		X
membership style		X
consistency style		X
fault monitoring style	X	X
fault monitoring interval	X	X
fault monitoring timeout	X	X
fault monitoring granularity	X	X
heartbeat policy	X	X
heartbeat enabled policy	X	X
checkpoint interval (logging)	X	X
factories	homes	
FT domain ID		X
obj container group ID	n/a	X
obj container group ref version	n/a	X
request duration policy	X	
metapolicy mode_ID (mode driven FT)	X	X
metapolicy knob settings (various)	X	X

Requirements

- **FT CCM Services Component**

- provides FT services to its container
- provides FT services to application components in its own container
 - fault detection, logging
- requires an FT ORB that supports container-level redundancy

- **FT CCM Replication Manager**

- redeploys and reconnects container applications
- no single point of failure
 - must be able to replicate / reconfigure itself
- handles container-level property management, groups, factories

Redeploying container applications

- **Replication Manager must support dynamic reconnections after fault detection**
 - try to restore the failed replica; or
 - reclaim failed replica's resources and create a new physical replica somewhere else;
 - update the IOGR version with the new replica.
 - CCM-level FT CORBA would use FT CCM Assembly Deployer and FT CCM Assembly Manager

- ***Aspects* make us refactor what's CORBA, what's CCM**
 - e.g. a new CORBA standard would use a new CCM standard

Plain FT CORBA under a CCM won't do

- **FT CORBA must treat containers as entity of redundancy**
- **Container & CCM issues**
 - Container-level IOGR is needed
 - supports transparent client redirection at the container level
 - Container state must be logged
 - even stateless components have stateful containers
 - Containers are OS-version-specific and language-specific design
 - hard to move containers to arbitrary hosts
 - which part of container must be replicated
 - what to checkpoint and restore
 - Container thread scheduling
 - Container quiescence
 - Lifecycle issues - e.g. FT cookies

In Summary

- **FT CCM provides FT support to distributed components**
- **FT CCM doesn't come for free**
 - FT CORBA must support containers as entity of redundancy
 - “aspects” lead us to refactor what's CORBA, what's CCM
- **FT CCM offers real payback**
 - FT systems will be able to use components, CCM and MIC tools
 - FT assembly and deployment will be easier
 - FT properties/policies will be managed at appropriate levels