

# OMG-DDS “Exploiting the Potential”

*[ Proven suitability in the Naval Combat System Domain ]*



OMG Real-time & Embedded Systems Workshop

July 2005

Hans van 't Hag

[hans.vanthag@nl.thalesgroup.com](mailto:hans.vanthag@nl.thalesgroup.com)

© THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS

THIS INFORMATION CARRIER CONTAINS PROPRIETARY INFORMATION WHICH SHALL NOT BE USED, REPRODUCED OR DISCLOSED TO THIRD PARTIES WITHOUT PRIOR WRITTEN AUTHORIZATION BY THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS, AS APPLICABLE.



- (1) Architecture Trends:** *‘Is there life after client-server ...’*
- (2) Combat systems:** *‘If your life depends on it ...’*
- (3) Architecture requirements:** *‘Challenge your middleware ...’*
- (4) CMS Use-Case:** *‘DDS by example ...’*
- (5) Conclusion:** *‘SPLICE-DDS: Proven suitability ...’*

# (1) ARCHITECTURE TRENDS

*“Is there life after client-server ...”*



© THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page

Real-time & Embedded Systems Workshop July'05

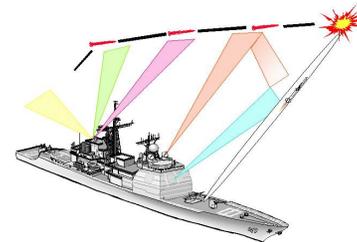
# DARPA - Open Architecture Focus

## Key Trend

- DoD system requirements are increasingly more dynamic, diverse, & demanding

## Problems

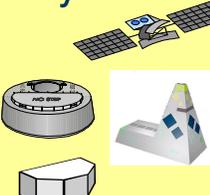
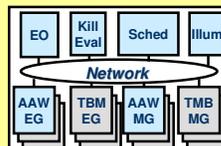
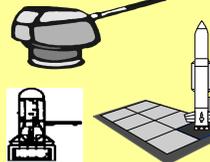
- Existing architectures
- Existing COTS
- Existing multiple technology bases
  - brittle & configured statically
  - too big, slow, buggy, incapable, & inflexible
  - proprietary & limit effectiveness by impeding
    - Assurability (of QoS),
    - Adaptability &
    - Affordability



Today, each system brings its own:  
**networks**  
**computers**  
**displays**  
**software**  
**people**

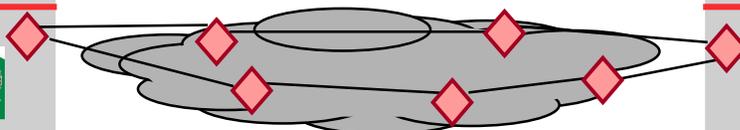
## Applications

## Applications

|  |  |  |   |   |
|--|--|--|---|---|
| <p><b>Sensor Systems</b></p>  <p>Technology base:<br/>Proprietary MW<br/>Mercury<br/>Link16/11/4</p> | <p><b>Command &amp; Control System</b></p>  <p>Technology base:<br/>DII-COE<br/>POSIX<br/>ATM/Ethernet</p> | <p><b>Engagement System</b></p>  <p>Technology base:<br/>Proprietary MW<br/>POSIX<br/>NTDS</p> | <p><b>Weapon Control Systems</b></p>  <p>Technology base:<br/>Proprietary MW<br/>VxWorks<br/>FDDI/LANS</p> | <p><b>Weapon Systems</b></p>  <p>Technology base:<br/>Proprietary MW<br/>POSIX<br/>VME/1553</p> |
|--|--|--|---|---|

Operating System 

Operating System 



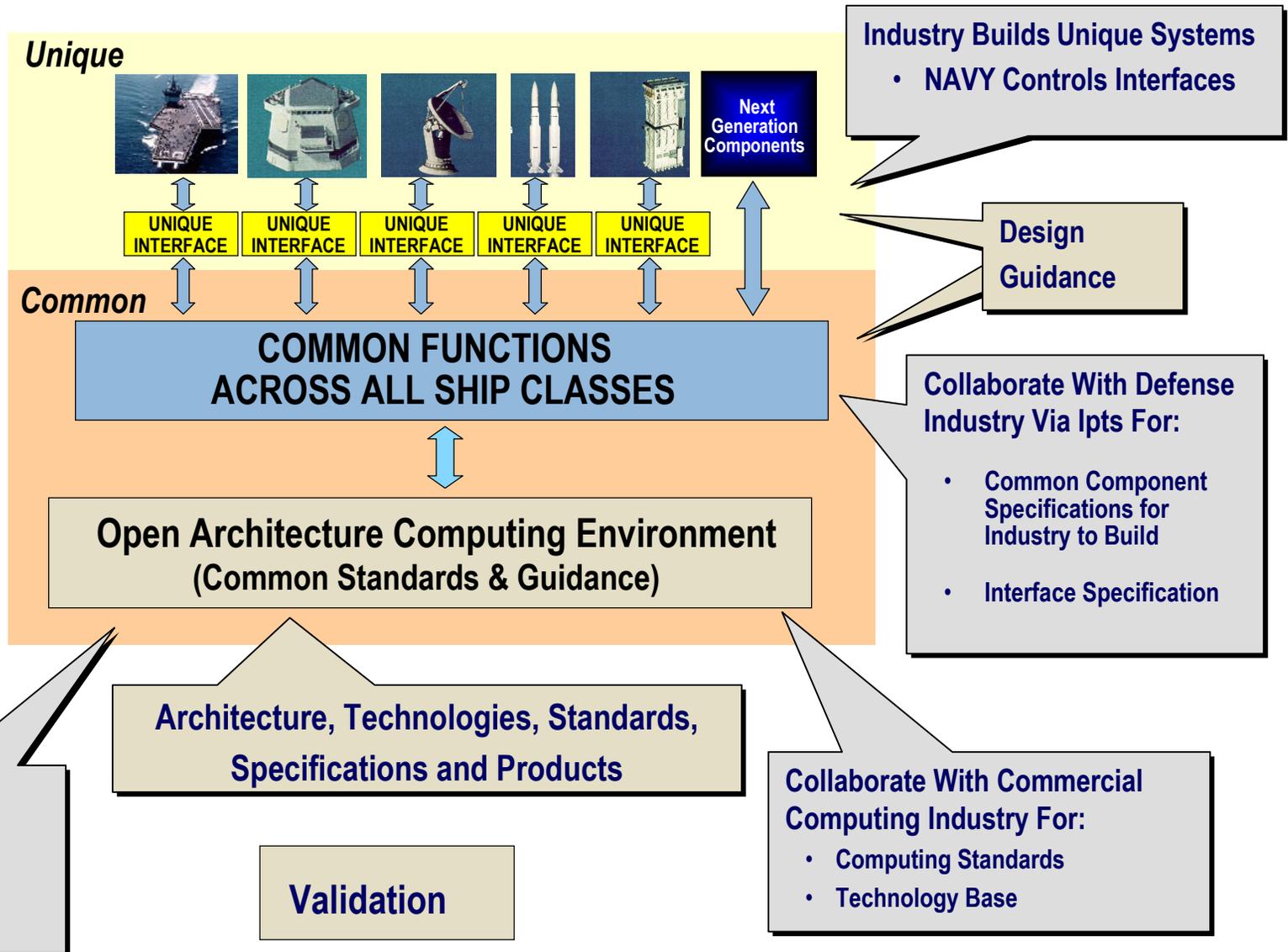
## Consequences

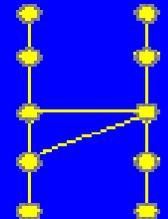
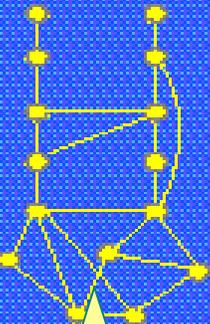
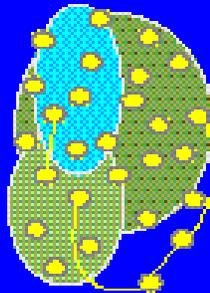
- *Hard to meet required performance levels*
- *Hard to control distributed resources*
- *High software lifecycle costs*
  - e.g., many “accidental complexities” & low-level platform dependencies

# Open Architecture Computing Environment (OACE)

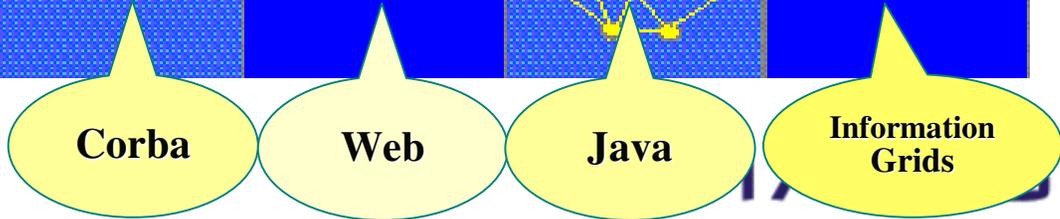
© THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page

Real-time & Embedded Systems Workshop July'05



|                    | Client Server   | 3/N-Tier  | Net Apps  | Net Services  | Next  | After that  |
|--------------------|---|---|---|---|---|---|
| Catch Phrase       | The Network Is the computer   | Objects   | Legacy to the Web   | The Computer Is the Network   | Network of embedded things  | Network of Things   |
| System Collections |   |   |   |   |   |   |
| Components         |   |   |   |   |   |   |
| Scale              | 100s  | 1000s   | 1000000s  | 10000000s   | 100000000s  | 1000000000s   |
| When/Peak          | 1984/1987   | 1990/1993   | 1996/1999   | 2001/2003   | 1998/2004   | 2004/2007   |
| Leaf Protocol(s)   | X   | X   | +HTTP (+JVM)  | +XML  |   | Unknown   |
| Directory(s)       | NIS, NIS+   | + CDS   | + LDAP (*)  |   |   | + ?   |
| Session            | RPC, XDR  | +CORBA  | +CORBA, RMI   | + SOAP, XML   | + RMI/Jini  | + ?   |
| Schematic          |  |  |  |  |  |  |

*"OMG-DDS ??!!"*



## (2) Combat Management Systems

*“If your live depends on it ...”*



© THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page

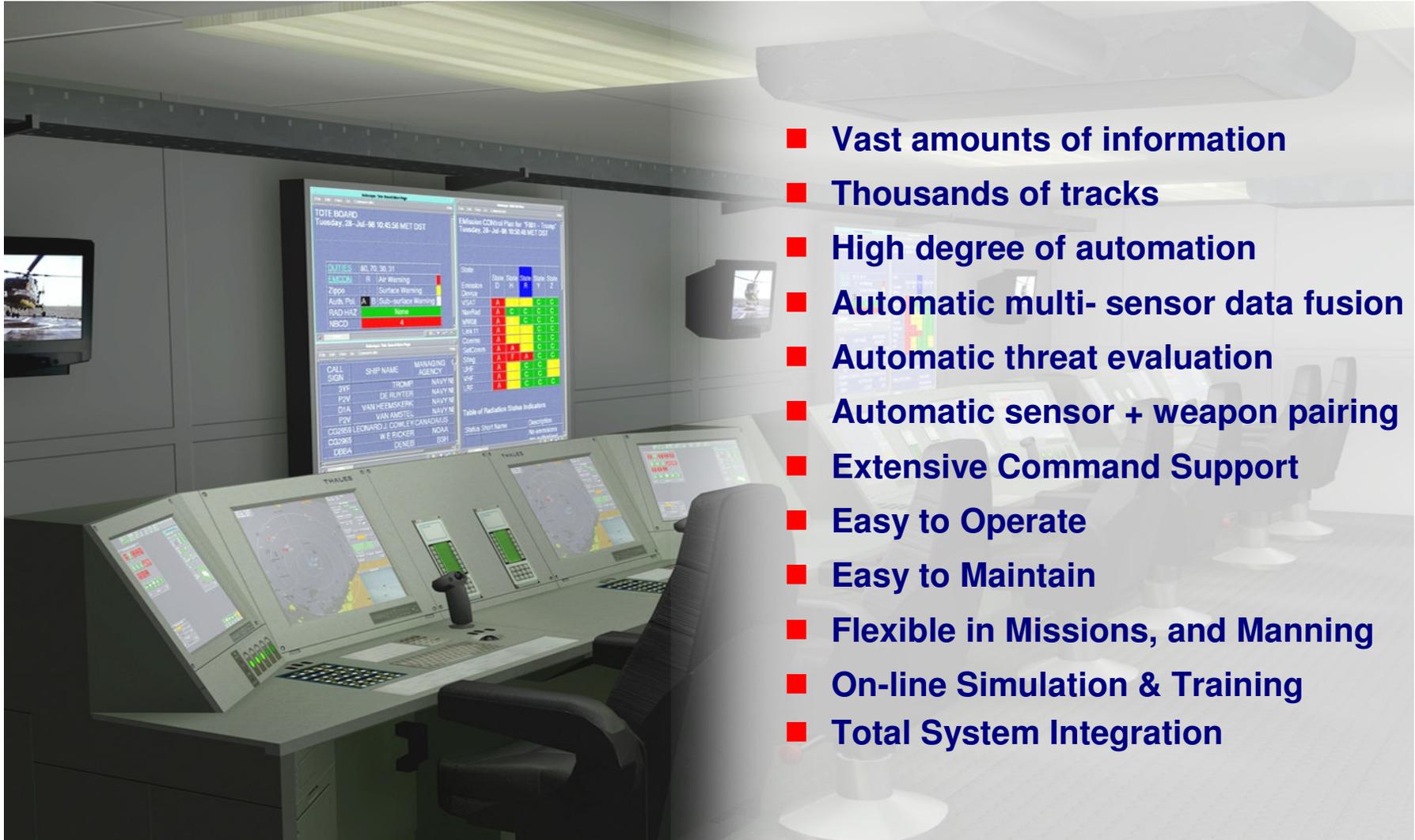
Real-time & Embedded Systems Workshop July'05

# Metrics: F124 Frigate

Real-time & Embedded Systems Workshop July'05 © THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page



# OPERATIONAL REQUIREMENTS

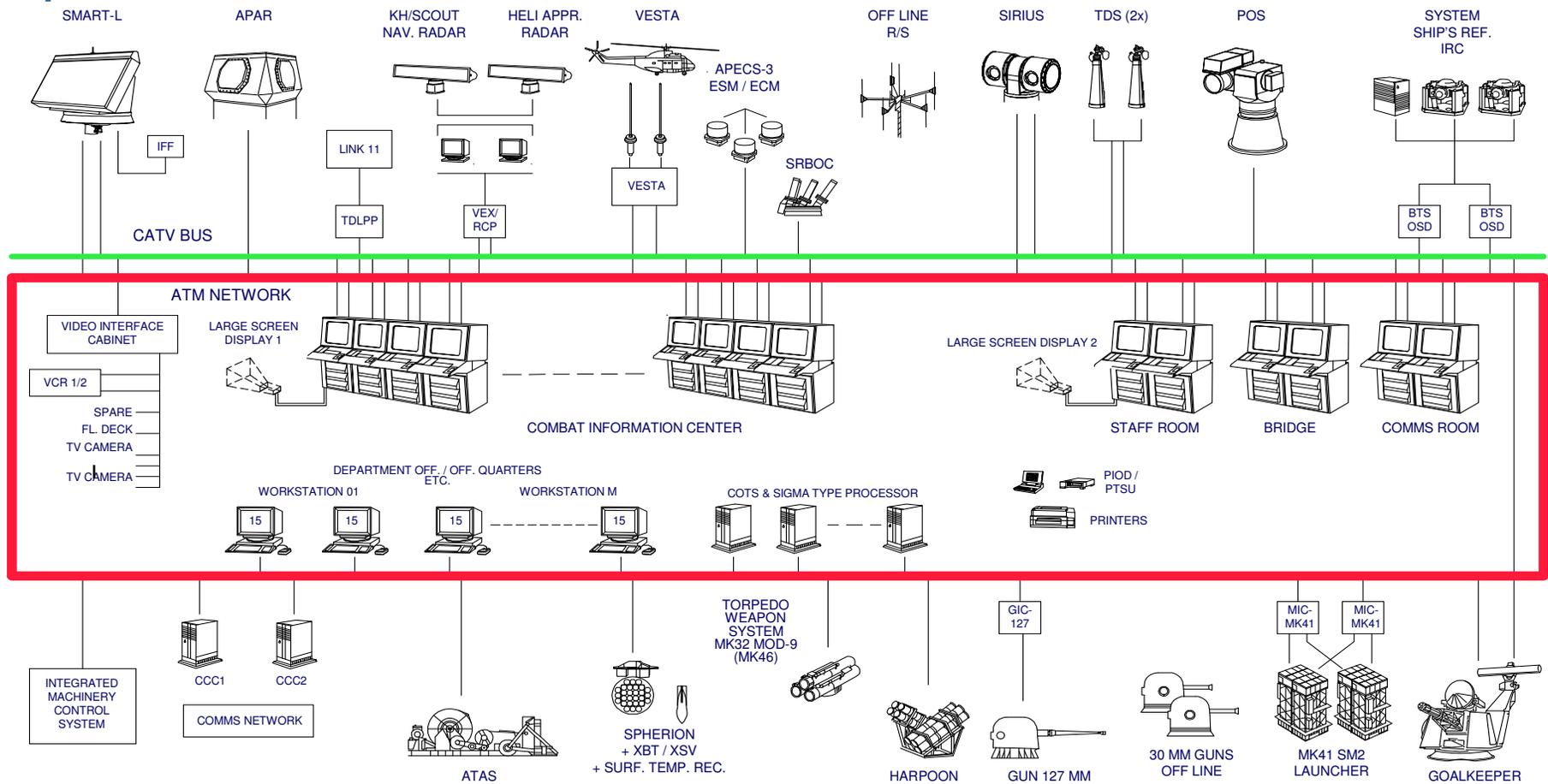


- **Vast amounts of information**
- **Thousands of tracks**
- **High degree of automation**
- **Automatic multi- sensor data fusion**
- **Automatic threat evaluation**
- **Automatic sensor + weapon pairing**
- **Extensive Command Support**
- **Easy to Operate**
- **Easy to Maintain**
- **Flexible in Missions, and Manning**
- **On-line Simulation & Training**
- **Total System Integration**

# Metrics F124 Frigate: Overview

© THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page

Real-time & Embedded Systems Workshop July'05

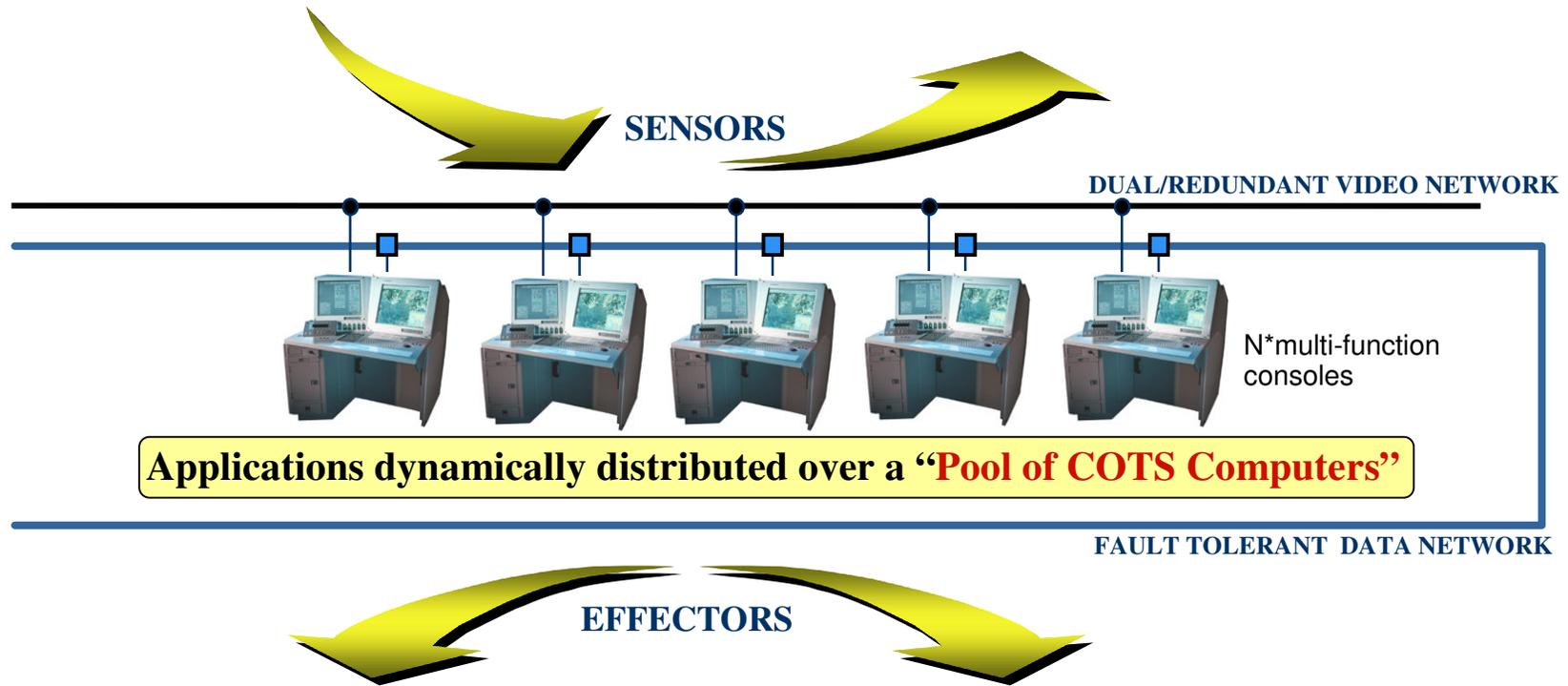


**Data-traffic:** 4.000 publications per second over the system-data bus  
**Programs:** 2.200 programs allocated over 150 processors  
**Accuracy:** 100 us. time-alignment accuracy within the distributed system

# CMS ARCHITECTURE: Starting points

© THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page

Real-time & Embedded Systems Workshop July'05



- Fault-tolerant:** *High combat survivability & maintainability (no single-point-of-failure)*
- Flexible:** *Mission-based configuration, on-board training & simulation*
- Evolvable:** *Evolutionary upgrading based on COTS & Open Standards*
- Scalable:** *From patrol-boats up to destroyers*

# CMS: Dynamic Resource Management

| Program name                 | Memory | CPU power | OS      | SigMA | Scheduling priority group .. | Dispersion group .. | Preference allocation .. |
|------------------------------|--------|-----------|---------|-------|------------------------------|---------------------|--------------------------|
| pa_wipe_tactical_track_manag | 2048   | 3.0       | Solaris | Yes   | Ts_medium_priority           | <none>              | <none>                   |
| sai_osd_reporting            | 2048   | 3.0       | Solaris | Yes   | Rt_medium_priority           | <none>              | <none>                   |
| sm_basic_gmt_provider        | 1024   | 1.0       | Solaris | Yes   | Ts_high_priority             | <none>              | <none>                   |
| sm_directory_management      | 2048   | 3.0       | Solaris | Yes   | Ts_high_priority             | <none>              | <none>                   |
| sm_file_distribution         | 2048   | 3.0       | Solaris | Yes   | Ts_high_priority             | <none>              | <none>                   |
| sm_lss_conf_definition       | 2048   | 3.0       | Solaris | Yes   | Ts_high_priority             | <none>              | <none>                   |
| sm_notary                    | 2048   | 3.0       | Solaris | Yes   | Ts_high_priority             | <none>              | <none>                   |

|  |                  |                       |
|--|------------------|-----------------------|
| Scheduling priority group  | Dispersion group | Preference allocation |
| <ul style="list-style-type: none"> <li>Non_high_priority</li> <li>Non_low_priority</li> <li>Non_medium_priority</li> <li>Nrt_high_priority</li> <li>Nrt_low_priority</li> <li>Nrt_medium_priority</li> <li>Rt_high_priority</li> </ul> | <none>           | <none>                |

Buttons: Print, Add, Modify, Delete, Quit, Help

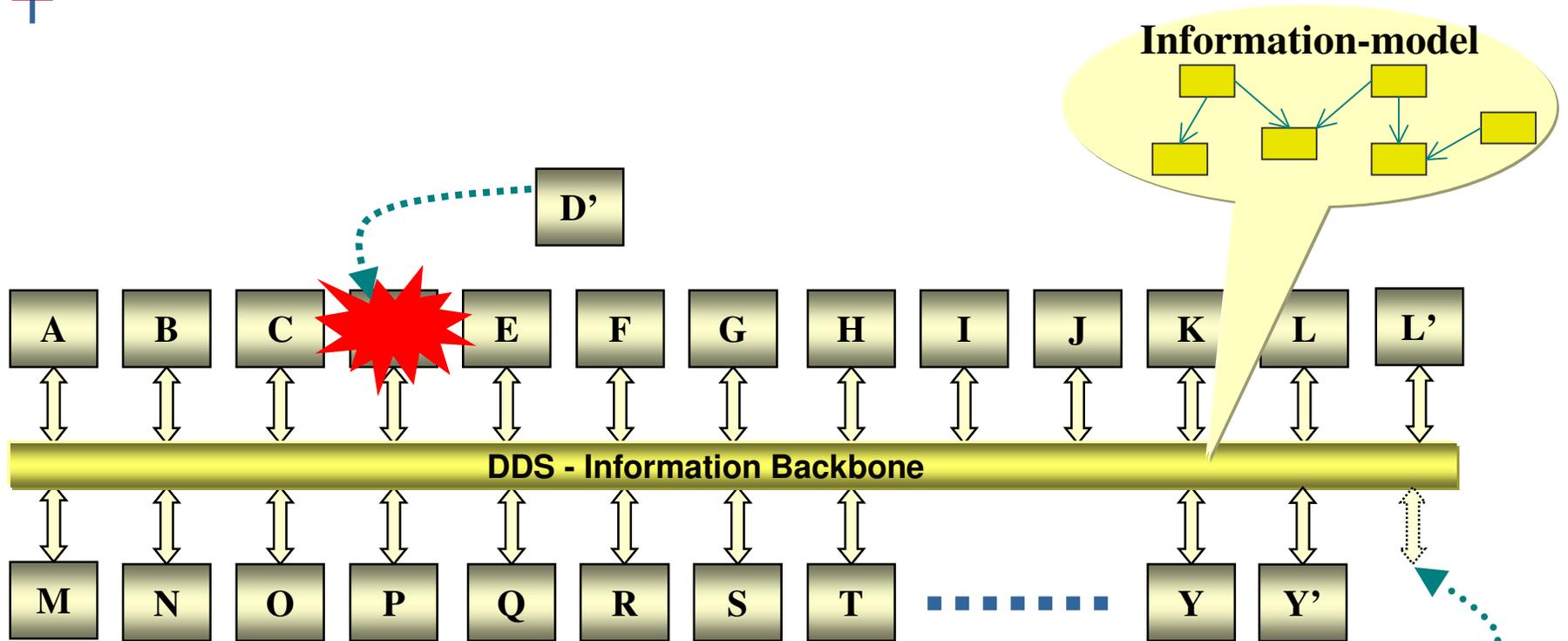
- **'pool-of-computers' utilization (Allocation schemes)**
  - Allocation driven by resource-needs and availability (CPU-power, Memory)
  - 'Dispersion groups' to force geographical separation (battle-damage resistance)
  - 'Preference allocation groups' to advice co-location (efficiency)
  - Degradation driven by 'Functional Priorities' (importance)

| Scheduling priority group name | Priority |
|--------------------------------|----------|
| Non_high_priority              | 20       |
| Non_low_priority               | 5        |
| Non_medium_priority            | 12       |
| Nrt_high_priority              | 4        |
| Nrt_low_priority               | 0        |
| Nrt_medium_priority            | 2        |
| Rt_high_priority               | 24       |

Buttons: Print, Add, Modify, Delete, Quit, Help

# INFORMATION-CENTRIC ARCHITECTURE

Real-time & Embedded Systems Workshop July'05 © THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page



**Autonomous components**

**Interacting only with the information-bus**

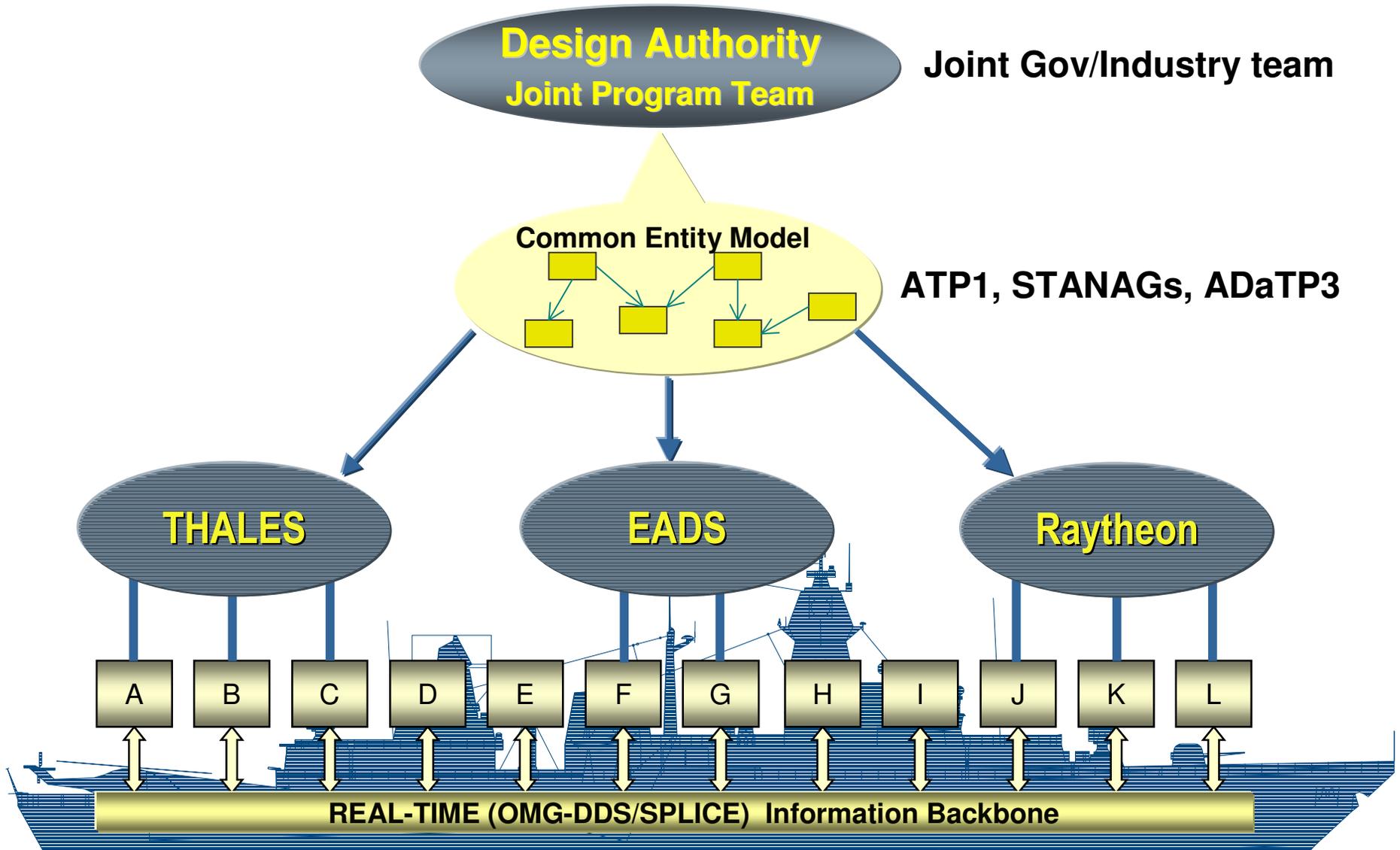
**Spontaneous: [Z], Self-healing: [D']**

**Redundant & Replicated: [L'], [Y']**

**QOS-driven Data Distribution Service (reliability, persistency, latency): [DDS]**

# COMMON ENTITY MODEL : Deployment – F124

Real-time & Embedded Systems Workshop July'05 © THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page



# COMMON ENTITY MODEL : The “CMS Glossary”

title page

The screenshot displays the Rational Rose software interface. The main window shows a project tree on the left with various system entities. The central pane displays the 'Class Specification for SystemTrack' dialog, which includes a table of attributes and their properties. A secondary dialog, 'Class Attribute Specification for systemTrackP...', is open in the foreground, showing detailed configuration for the 'systemTrackPhase' attribute, including its name, type, and documentation.

| Stere... | Name                        | Par |
|----------|-----------------------------|-----|
|          | systemTrackPhase            | Sys |
|          | timeOfInitiation            | Sys |
|          | simulated                   | Sys |
|          | systemTrackNumber           | Sys |
| optional | link1NatoTrackNumber        | Sys |
|          | realtime                    | Sys |
|          | trackQuality                | Sys |
|          | linkState                   | Sys |
|          | tacticalEnvironment         | Sys |
|          | identity                    | Sys |
|          | exerciselIndication         | Sys |
| optional | exerciselIdentity           | Sys |
| optional | specialInterestIndication   | Sys |
| optional | specialInterestIdentity     | Sys |
|          | identituManualSetIndication | Sus |

**Class Attribute Specification for systemTrackP...**

General | Detail | MSVC

Name:  Class: SystemTrack

Type:   Show classes

Stereotype:

Initial value:

Export Control:  Public  Protected  Private  Implementation

Documentation:  
This attribute specifies the current state of the lifecycle of the system track, namely operatorMaintained, systemMaintained, or automaticTrackingLost.

Real

# Business Demands: *re-use, flexibility, scalability*

## CHARACTERISTICS

**Many different customers:**

*12 Navies world-wide use 1 CMS product-line*

**Many different ships/missions:**

*20 Ships classes (from FPB's up to Destroyers)*



# (3) ARCHITECTURE REQUIREMENTS

*“Challenge your middleware ...”*



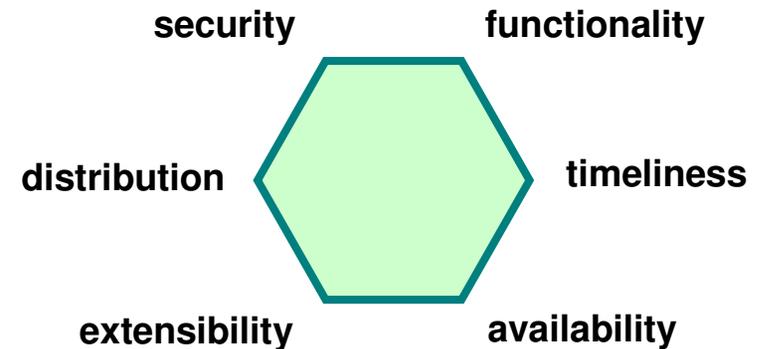
© THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page

Real-time & Embedded Systems Workshop July'05



Problem: *engineering (-cost) of distributed systems*

- too complex
- not reactive
- not future-proof
- not fault tolerant



Because '*multi-dimensional engineering*' is needed:

What about *the current 'state-of-the-art'*?

- architectures: message-passing, client/server, OO
- most efforts fall short in a number of dimensions:
- typically:
  - *limited performance* (high-volume & low-latency balance)
  - *exploding complexity* (dependencies in many dimensions)
  - *costly evolution* (impact of changes & extensions)

# Architectural Requirements: Lifecycle focus

## System design

- provide a **stable basis** to operate upon by applications
- enhance component **autonomy**
- allow transparent and global **QoS assurance**

## System development

- reduce **complexity** and enhance **re-usability**
- provide **shared/guaranteed** properties
- **small** learning effort and flat learning curve

## System integration

- support effortless component **integration**
- provide easy **monitor & control**
- **shift ratio** between design and integration effort

## System deployment

- **guaranty QoS** for reliability, latency and persistency
- allow **runtime migration** of applications
- allow applications to **join** the system at **any time**

## System maintenance & evolution

- allow runtime replacement and **evolutionary upgrading**
- support for **logging & replay** of information
- provide **future-proof, re-usable, robust** and **scalable** system

# Proposal: An Information-Centric Approach

## Towards a solution:

- make development effort more **simple**
- develop **less**
- develop solutions **only once**

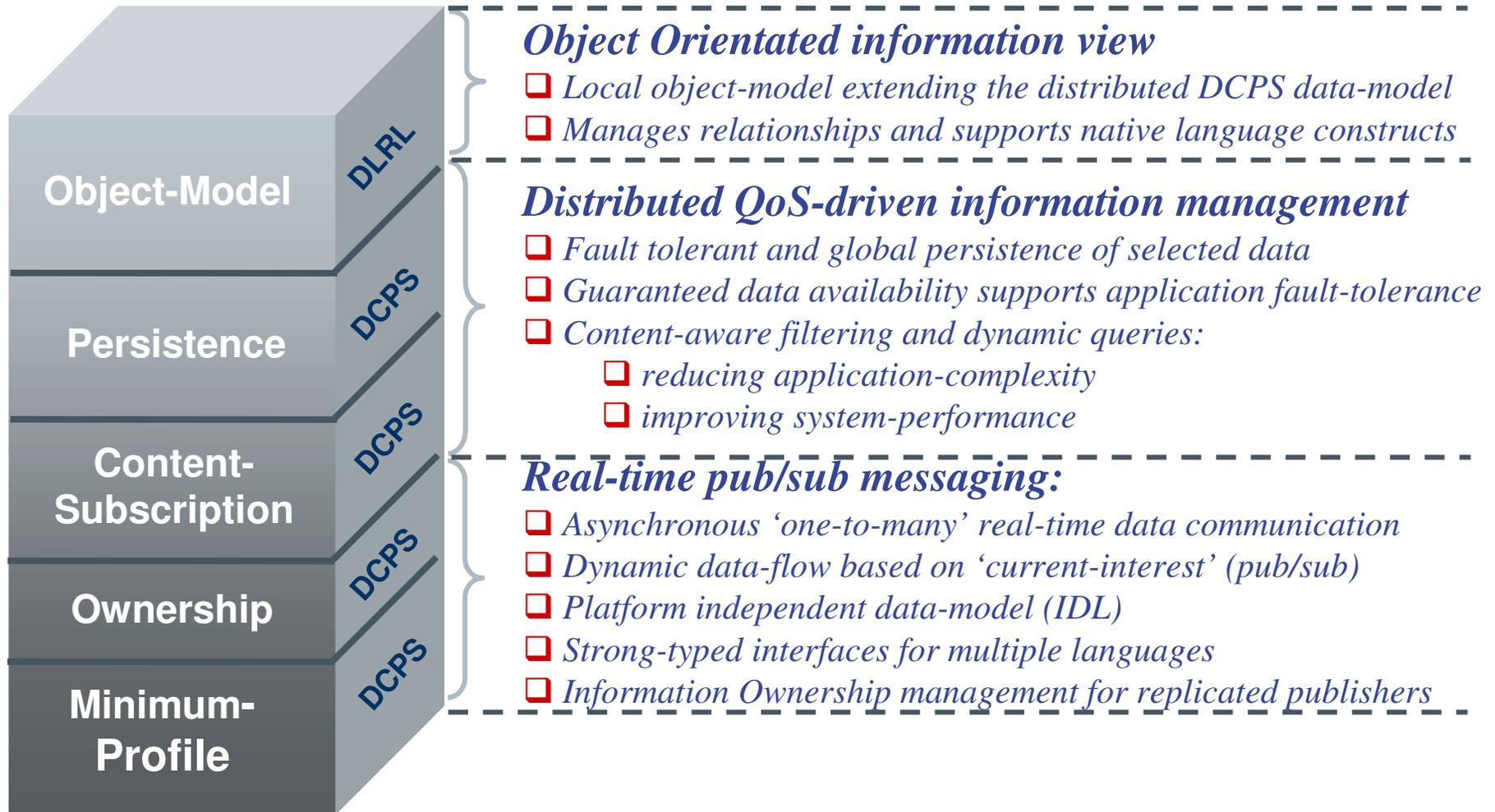
## How:

- minimize component dependencies (*'simple'*)
- maximize component autonomy (*'re-use'*)
- normalize component interactions (*'only once'*)

## The clue:

- **share** the stable properties, **localize** the unstable ones
- **information** is what matters most, not how it is processed
- properly modeled data is **stable**, processing often is not
- so **focus on data** first and then on the processing of it

# OMG-DDS: A Data-Centric Solution



# (4) CMS USE-CASE

*“DDS by example ...”*



© THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page

Real-time & Embedded Systems Workshop July'05

# INTRODUCING: THE EXAMPLE

© THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page

Real-time & Embedded Systems Workshop July'05



## SENSOR PROCESS

- ▶ Optical sensor
- ▶ Scans the environment
- ▶ Produces 'Tracks'
- ▶ Position of 'objects'
- ▶ Reports '*pointTrack*'



## CLASSIFICATION PROCESS

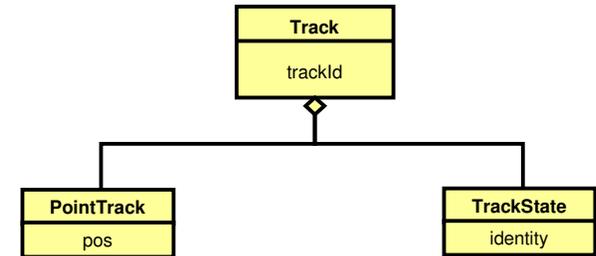
- ▶ Classifies tracks
- ▶ Determines their identity
- ▶ Analyses the trajectories
- ▶ Determines hostility
- ▶ Reports '*trackState*'



## DISPLAY PROCESS

- ▶ Displays track info
- ▶ Both position & identity
- ▶ Raises alerts
- ▶ Requires '*pointTrack*'
- ▶ Requires '*trackState*'

- ▶ Information modeled as “**TOPICS**”
  - Basic units of information
  - Individually produced and/or consumed
  - Support autonomous & decoupled programs
  
- ▶ Each **TOPIC** has an associated name and data type
  - Data-definition in IDL
  - ‘Key’ fields for unique identification
  - Relational Data Model (keys)
  
- ▶ Our example:



### *Topic “PointTrack”*

```

Struct PointTrackType {
    long trackId;          // key

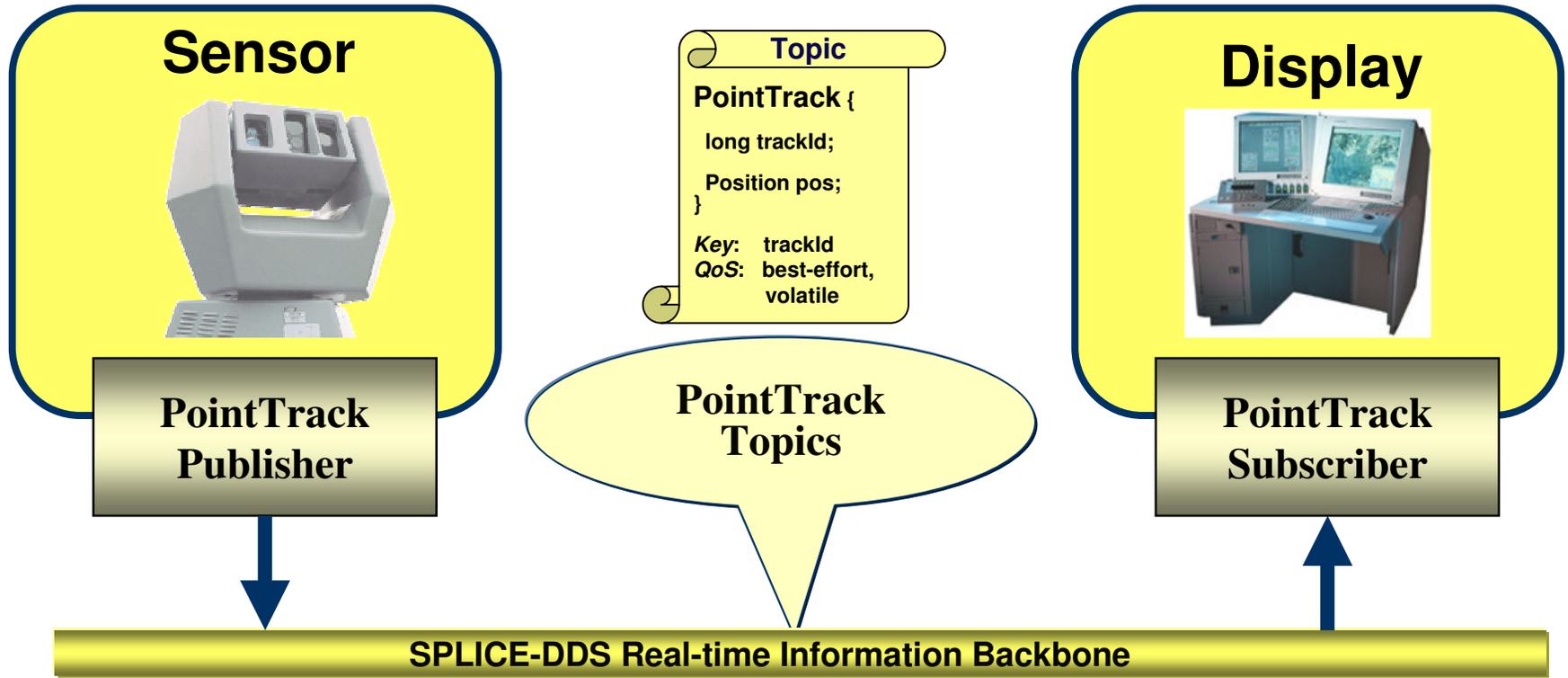
    Position pos;
}
  
```

### *Topic “TrackState”*

```

Struct TrackStateType {
    long trackId;          // key

    Id identity;
}
  
```



### Characteristics

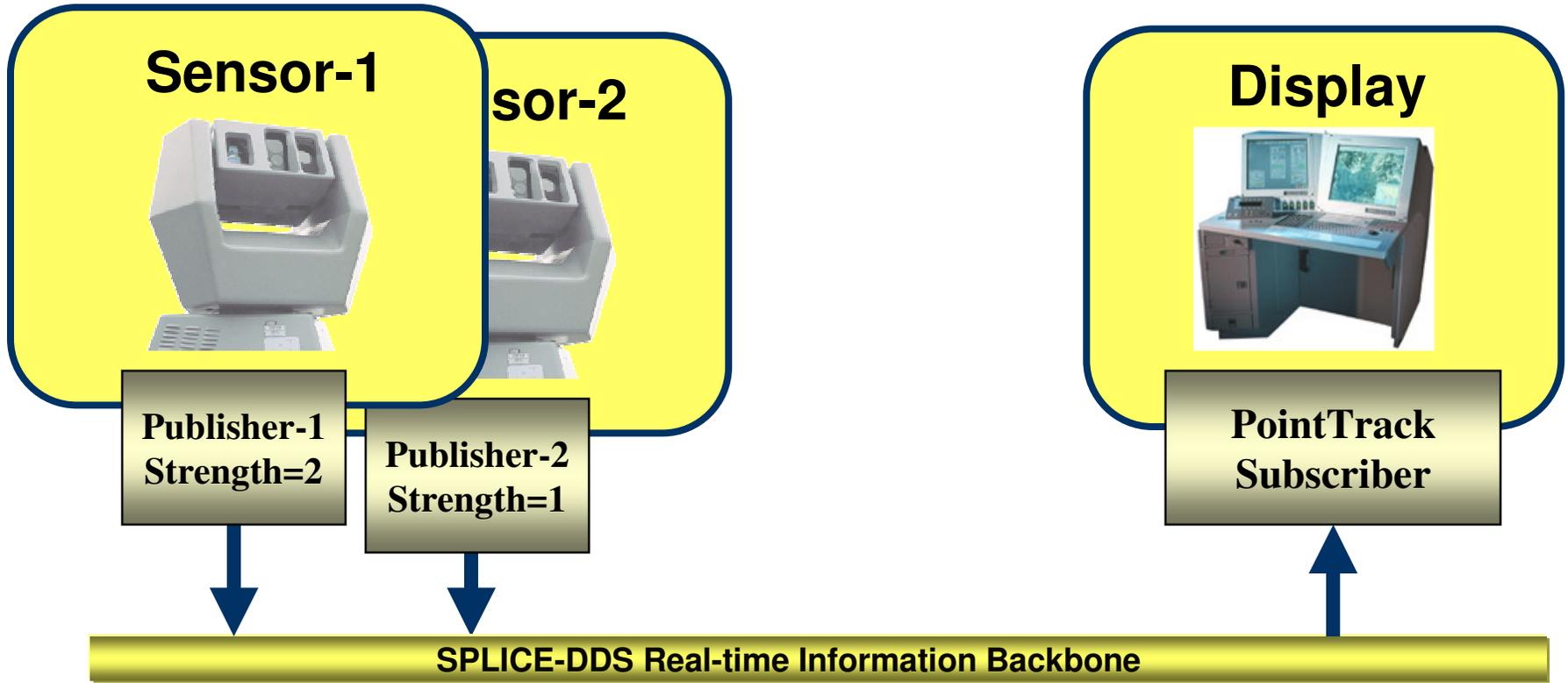
- ▶ Basic publish/subscribe data distribution
- ▶ Topics (types) specified in IDL
- ▶ QoS regarding: reliability, urgency & liveness

### Features / Advantages

- ▶ Autonomous & loosely coupled applications
- ▶ Pub/Sub & QoS driven communication
- ▶ Strong-typed interfaces
- ▶ Smart networking based on priority & latency-budget

# THE OWNERSHIP PROFILE

Real-time & Embedded Systems Workshop July'05 © THALES NEDERLAND B.V. / AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page



### Characteristics

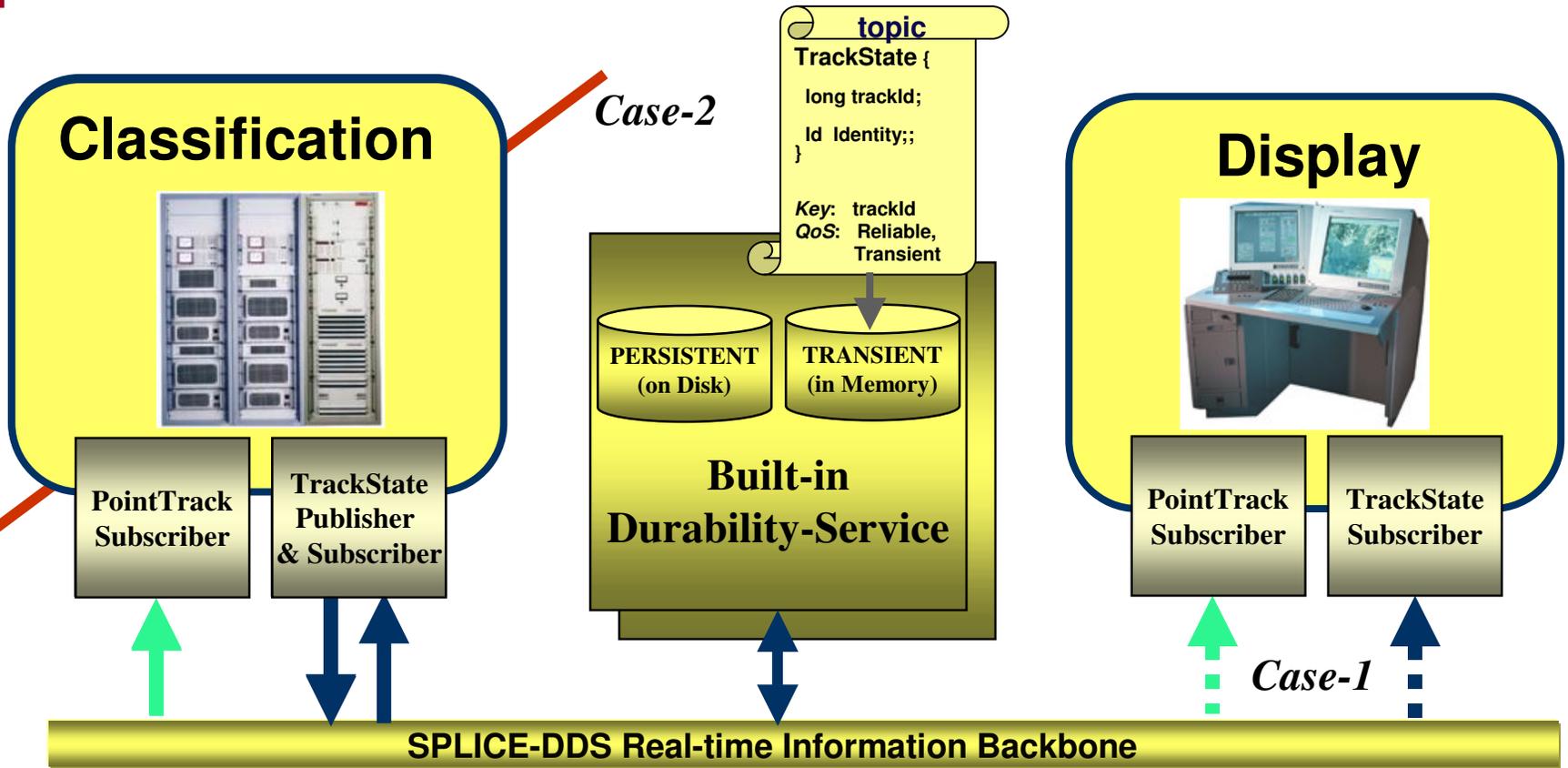
- ▶ Replicated publishers of data (with own 'strength')
- ▶ Only highest-strength will be received
- ▶ On failure, next highest-strength will 'take-over'

### Features / Advantages

- ▶ Fault-tolerance by replication
- ▶ Notes:
  - ▶ Requires a lot of resources
  - ▶ Quality must be expressible as an 'integer'

# THE PERSISTENCE PROFILE

Real-time & Embedded Systems Workshop July'05 © THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page



### Characteristics

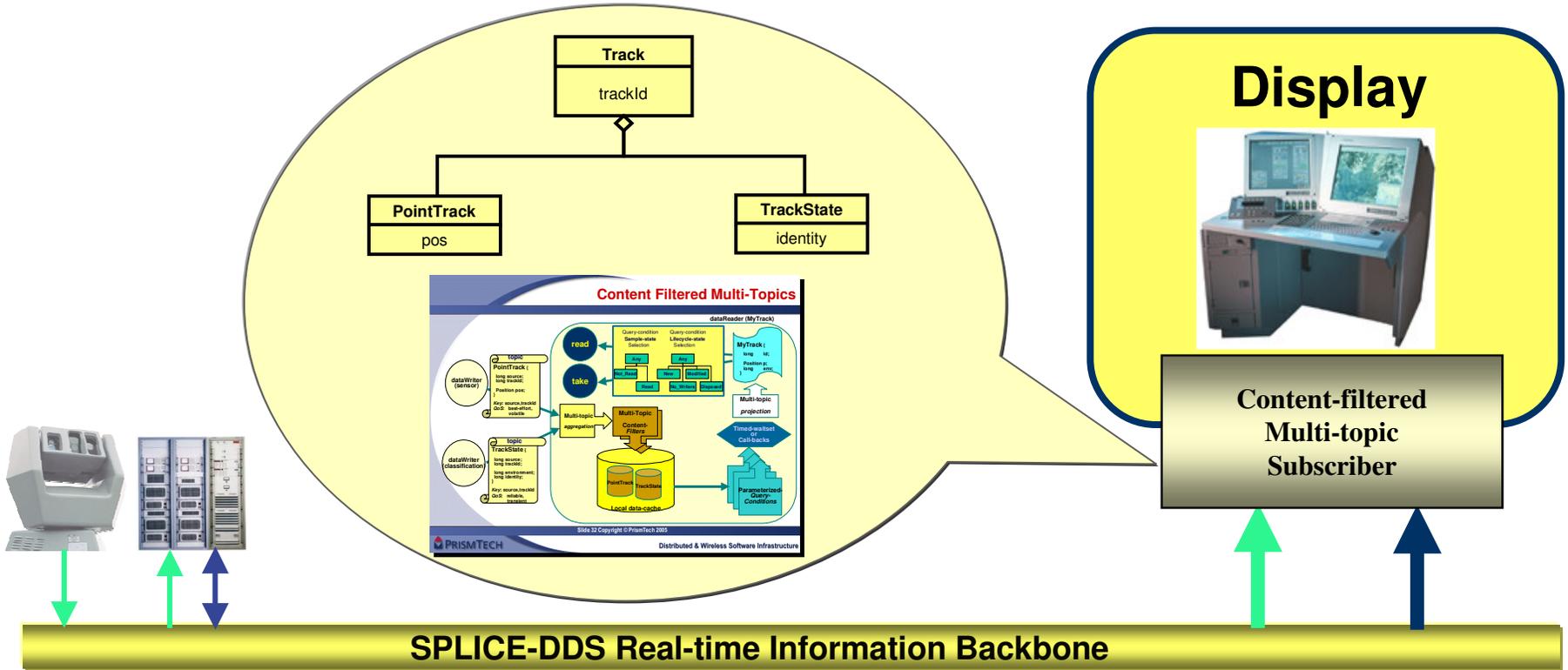
- ▶ Built-in persistence for non-volatile data
  - ▶ State preservation for transient publishers
  - ▶ Settings persistence surviving system downtime
- ▶ Replicated durability service for maximal fault-tolerance

### Features / Advantages

- ▶ **Case-1:** late-joining of Display process
  - ▶ Previously produced TrackStates readily available
- ▶ **Case-2:** restart of failed Classification process
  - ▶ Internal state (already classified tracks) regained

# THE CONTENT-SUBSCRIPTION PROFILE (1)

Real-time & Embedded Systems Workshop July'05 © THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page



### Characteristics

- ▶ Adds 'content awareness'
  - ▶ Content-filtered Topics & query-conditions
- ▶ Supports 'compound interest'
  - ▶ Multi-topics (combine/filter/re-arrange topics)

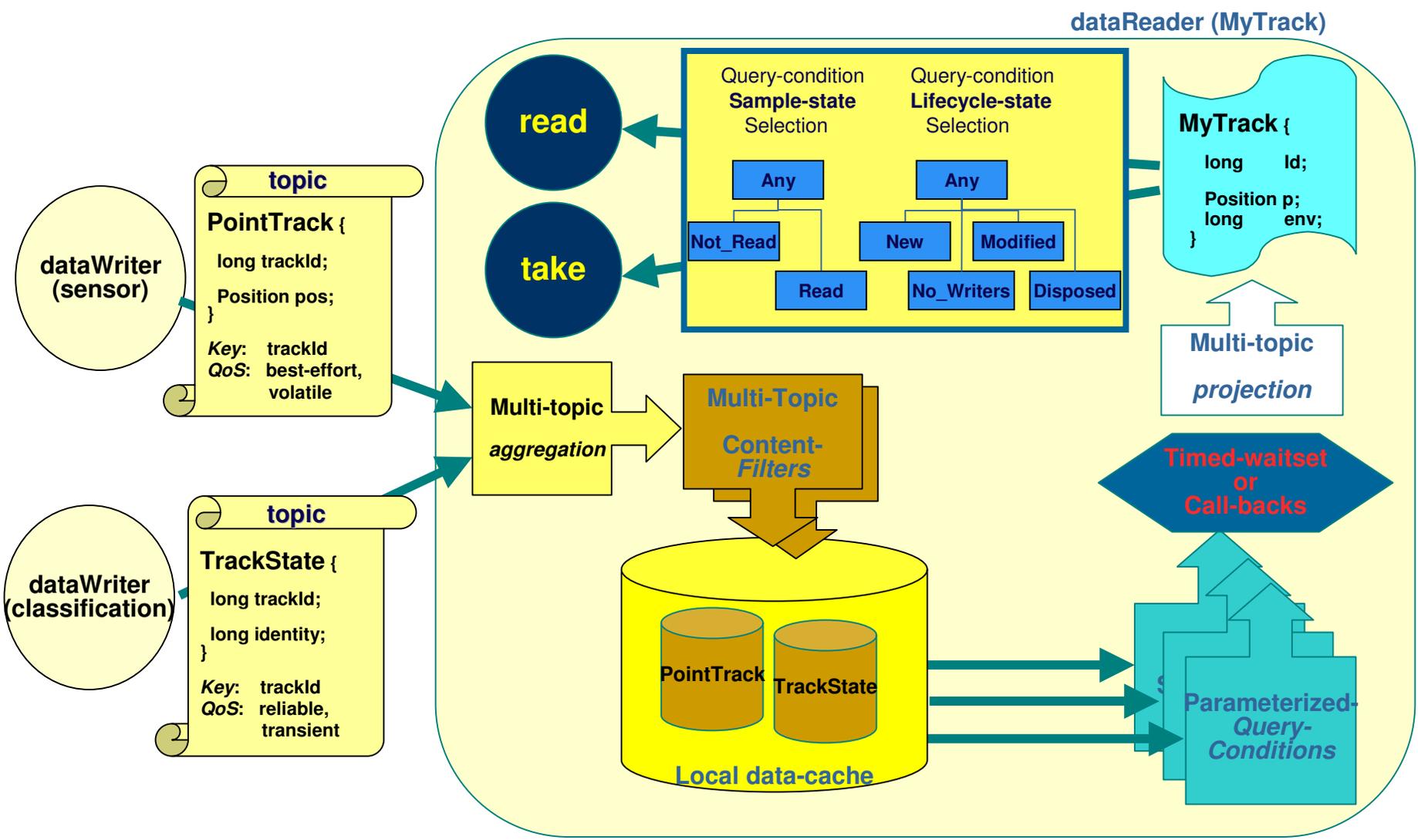
### Features / Advantages

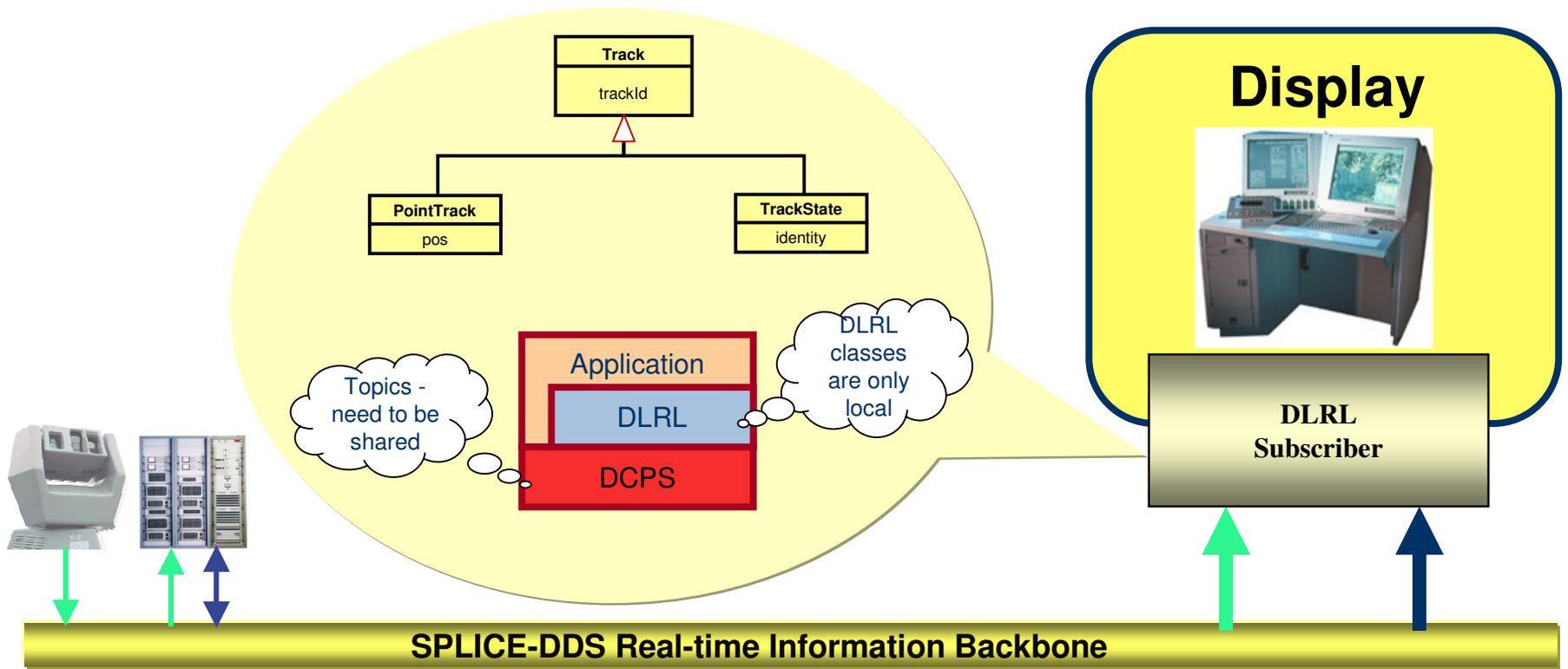
- ▶ Reduced application complexity
  - ▶ Automatic 'reconstitution' (join) of related data
- ▶ Improved system performance
  - ▶ Only receive/process what is of interest

# THE CONTENT-SUBSCRIPTION PROFILE (2)

## Content Filtered Multi-Topics

Real-time & Embedded Systems Workshop July'05 © THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page





- ### Characteristics
- ▶ **Local** Object Oriented Data-Access Layer
  - ▶ Supports 'OO' features:
    - ▶ Inheritance, aggregation, composition
  - ▶ Uses DCPS to distribute **state** by 'mapped topics'

- ### Features / Advantages
- ▶ Ease of Management of (related) data
    - ▶ Object oriented 'graphs of objects' (value-types)
  - ▶ Supports 'native language constructs' (I.e. navigation)
    - ▶ Automatic 'change-management' of objects

# (5) CONCLUSION

*“Proven suitability...”*



© THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page

Real-time & Embedded Systems Workshop July'05

# SUMMARY: Requirements & Realization



## Requirement:

## Realized by:

### System design

- provide a **stable basis** to operate upon by applications
- enhance component **autonomy**
- allow transparent and global **QoS** assurance

- *shared Information Model*
- *state-based information-centric system*
- *Information classification (QoS topic-defaults)*

### System development

- reduce **complexity** and enhance **re-usability**
- provide shared/**guaranteed** properties
- **small** learning effort and flat learning curve

- *minimized component dependencies*
- *standardized (DDS-) interaction-environment*
- *intuitive concept, simple/powerful features*

### System integration

- support effortless component **integration**
- provide **easy** monitor & control
- **shift** ratio between design and integration effort

- *maximized component autonomy*
- *globally accessible information (data+metadata)*
- *focus on info-model & decoupled applications*

### System deployment

- **guaranty QoS** for reliability, latency and persistency
- allow **runtime migration** of applications
- allow applications to join the system at **any time**

- *realtime “DDS” information backbone*
- *global & FT availability of transient state data*
- *dynamic discovery and data persistence*

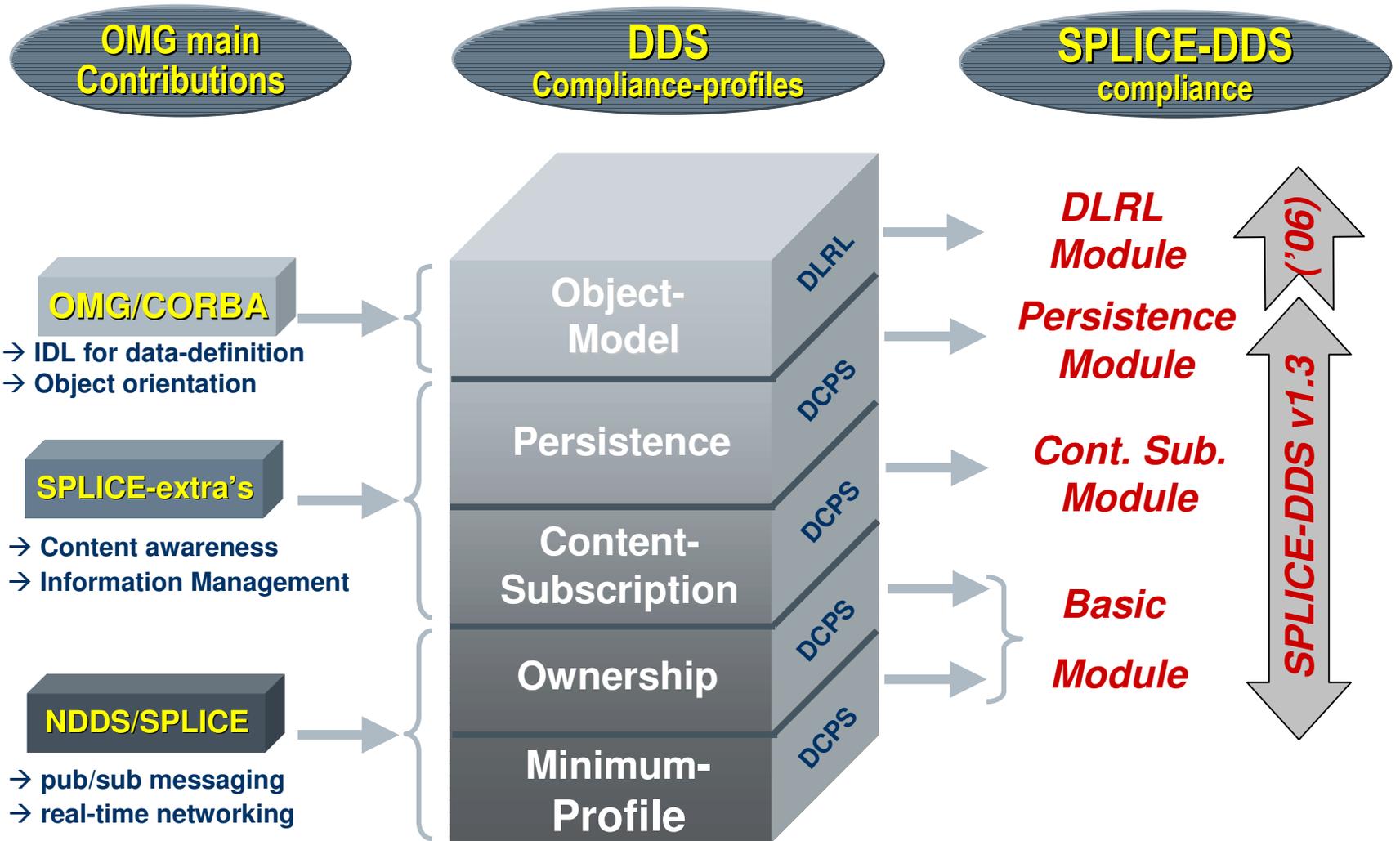
### System maintenance & evolution

- allow runtime replacement and **evolutionary upgrading**
- support for **logging & replay** of information
- provide **future-proof, re-usable, robust** and **scalable** system

- *de-coupled & autonomous components*
- *global availability of all (time-stamped) data*
- *highly adaptive associative data-model*

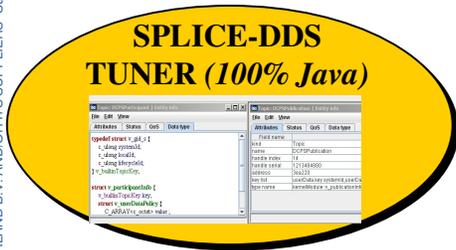
# SPLICE-DDS "Proven & Complete DDS implementation"

Real-time & Embedded Systems Workshop July'05 © THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page

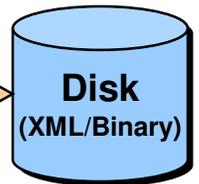
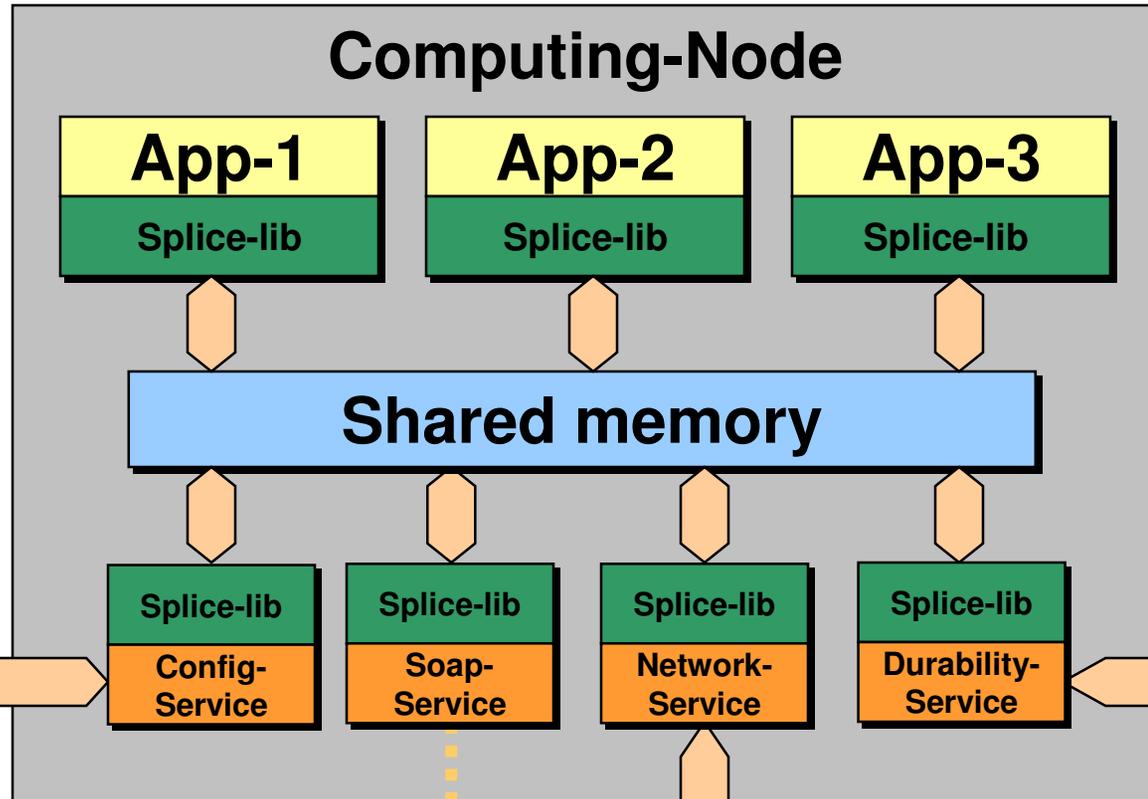


# SPLICE-DDS: *Pluggable Service Architecture*

Real-time & Embedded Systems Workshop July'05 © THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page



SOAP



network

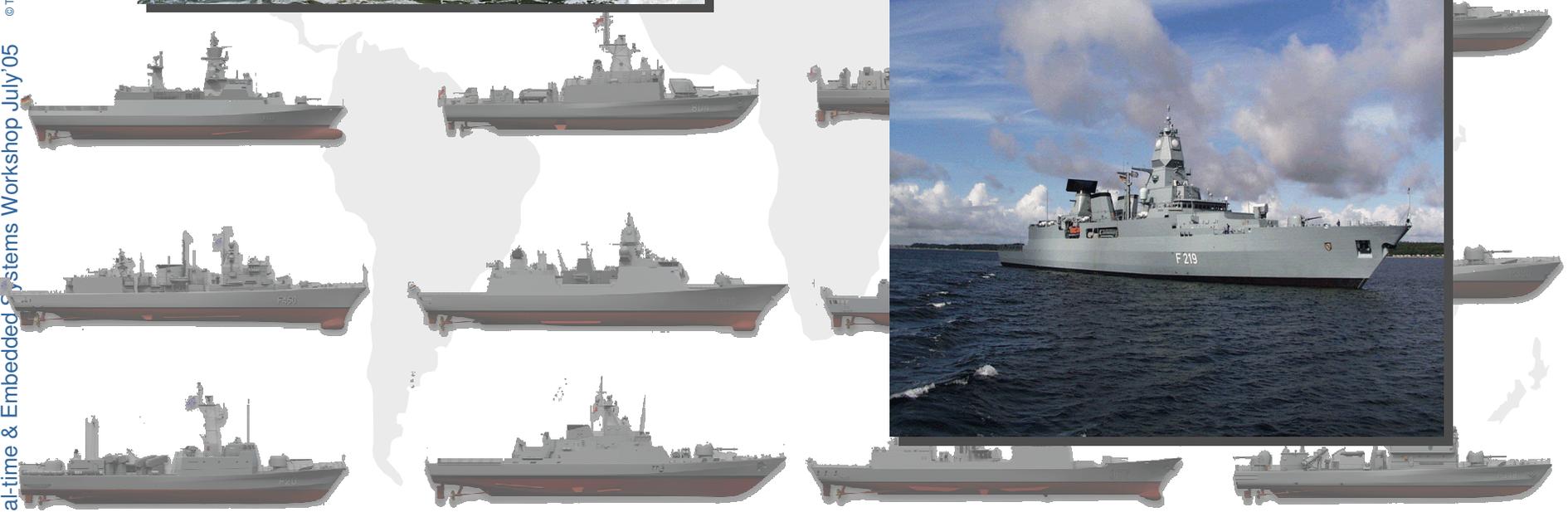
# SPLICE-DDS, a FULL OMG-DDS Implementation

- **SPLICE-DDS**, developed by **TNL**, Marketed & Supported by **PrismTech**
  - SPLICE-DDS v1.3 supports **ALL** DCPS profiles
  - Check <http://www.prismtech.com> for product-details and SPLICE-DDS webcast
  
- **PrismTech** brings its wide experience as a middleware ISV for the marketing and support SPLICE-DDS worldwide:
  - Product evaluation
  - Ports and customisations to customer's special environments
  - Support & training
  
- **Thales Netherlands (TNL)** is in charge of product evolutions, with a dedicated team of over 15 experienced engineers and a long term commitment to:
  - Continued contribution to OMG DDS specification process
  - Committed road map for full implementation of the DDS standard
  - Expert level consulting

# “DDS SAILS THE SEVEN SEAS”

Real-time & Embedded Systems Workshop July'05

© THALES NEDERLAND B.V. AND/OR ITS SUPPLIERS. Subject to restrictive legend on title page



# *QUESTIONS ??????*