

# Meta-Programming Techniques to Configure Open Standard RT CORBA Middleware Declaratively

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# Problem: Applications Depend on Middleware Products

## Dependency:

If middleware product changes, then application source code must change

## Primary Dependency:

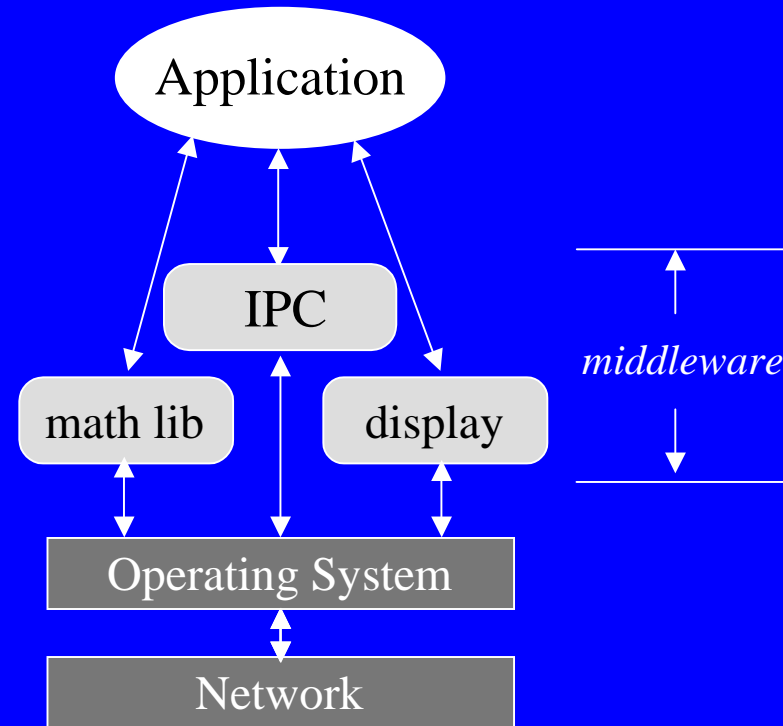
Application depends on product-peculiar functions

## Secondary Dependency:

Application depends on product-peculiar qualities or configuration operations

*Avoided by use of standard interfaces*

*Subject of this talk*



# Examples of Secondary Dependencies

Applies to: a Real-time ORB

## Qualities

- Transports and protocols supported
- Reliability, or reliabilities available
- Efficiency of marshalling and de-marshalling event parameters
- Efficiency of de-multiplexing incoming method calls
- Buffer sizes, flow control, and buffer overflow handling
- Thread and thread priority utilization

## Configuration Operations

- ORB initialization options
- ORB compilation options
- Implementation-provided configuration objects

# Two Ways to Avoid Secondary Dependencies

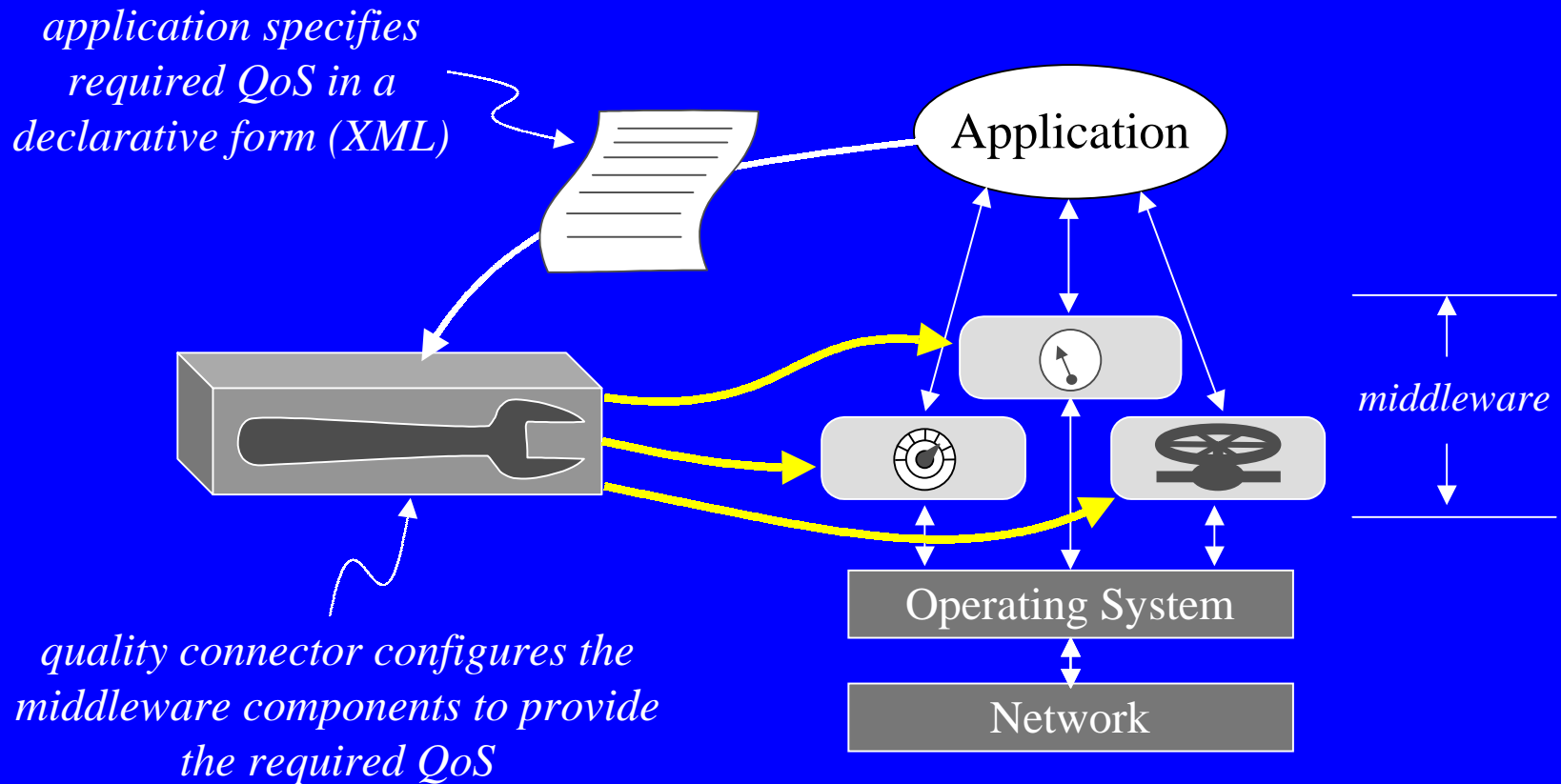
## Standardize

- Standardize available configuration operations *not likely*
- Standardize offered qualities *generally not possible, not desirable*

## Adapt

- Provide a software component, a quality connector, that
  - selects available qualities pursuant to application direction
  - performs required configuration operations
- Implementation of a quality connector is product-peculiar
- Interface to a quality connector could be standardized

# A Quality Connector Acts on QoS Requirements Declarations



# Data from Application to Quality Connector

The (declarative) data that the application passes to the quality connector consist of:

- Mode: a boolean combination of statements about the states of system components; the remaining data apply only when it's true
- Load: one or more constraints on the load that the application will impose
- QoS: one or more requirements on the QoSs that the application demands

```
<proposal>
  <mode> ← proposal applies in this mode
    <or>
      <ci name="portSlingshot" state="onLine" />
      <ci name="starboardSlingshot" state="onLine" />
    </or>
  </mode>
  <QoS type="latency">
    <upperPoint secs="1.0" prob="0.99" />
    <upperPoint secs="4.0" prob="0.9999" />
  </QoS>
  <load type="interMessageTime"> ← this flow is periodic
    <upperPoint secs="1.0" prob="0.0001" />
    <lowerPoint secs="1.0" prob="0.9999" />
  </load>
  <load type="messageSize">
    <upperPoint bytes="256" prob="1.0" />
    <upperPoint bytes="32" prob="0.5" />
  </load>
  <load type="priority">
    <urgency val="10" />
    <importance val="2" />
  </load>
</proposal>
```

*there are QoS types other than latency -- e.g., jitter*

*priority determines how this request will compete with others for resources*

# Quality Connector Implementation

- In general, a quality connector may act at several points in the system life cycle:
  - when middleware is developed (e.g., options to the compiler that compiles the ORB)
  - when the application is written (weaver-style)
  - when the system is linked
  - when the system is initialized
  - during system execution
- We have built a prototype
  - acts only at run time
  - selects which of several physical channels will propagate events
- We will build a TAO-RT-event-configuring prototype

# The Beautiful Vision

- Suppose the community of middleware users could agree on a core set of qualities of service and how to specify their values.

E.g., a QoS for an event service is latency, and it is measured from the time any supplier's `push()` call begins until all consumers have received their `push()` calls. The 'latency' XML schema is at ....

- Vendors might be moved to supply quality connectors for their products. Users would be appreciative.
- Vendors might be moved to optimize their products using the standard QoS's as metrics.



**BACKUP**