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Remote Procedure Call over DDS

Version Beta 1

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Normative reference: http://www.omg.org/spec/DDS-RPC

Machine Readable Files:

C++: http://www.omg.org/spec/DDS-RPC/20141120/mars-14-11-03.zip

Java: http://www.omg.org/spec/DDS-RPC/20141120/mars-14-11-04.zip

Non-normative:

IDL http://www.omg.org/spec/DDS-RPC/20141120/mars-14-11-05.zip

This OMG document replaces the earlier document (ptc/2015-05-01, Beta 1). This is an OMG Adopted Beta Specification and is currently in the finalization phase. Comments on the content of this document are welcome, and should be directed to issues@omg.org by August 24, 2015.

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The FTF Recommendation and Report for this specification will be published on December 18, 2015. If you are reading this after that date, please download the available specification from the OMG Specifications web page http://www.omg.org/spec/.

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Preface

OMG

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 - o UML Profile
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Times/Times New Roman - 10 pt.: Standard body text

Helvetica/Arial - 10 pt. Bold: OMG Interface Definition Language (OMG IDL) and syntax elements.

Courier - 10 pt. Bold: Programming language elements.

Helvetica/Arial - 10 pt: Exceptions

NOTE: Terms that appear in italics are defined in the glossary. Italic text also represents the name of a document, specification, or other publication.

Issues The reader is encouraged to report any technical or editing issues/problems with this specification to http://www.omg.org/report_issue.htm.

1 Scope

The Data Distribution Service is widely used for data-centric publish/subscribe communication in real-time distributed systems. Large distributed systems often need more than one style of communication. For instance, data distribution works great for one-to-many dissemination of information. However, certain other styles of communication namely request/reply and remote method invocation are cumbersome to express using the basic building blocks of DDS. Using two or more middleware frameworks is often not practical due to complexity, cost, and maintenance overhead reasons. As a consequence, developing a standard mechanism for request/reply style bidirectional communication on top of DDS is highly desirable for portability and interoperability. Such facility would allow commands to be naturally represented as remote method invocations. This s presents a solution to this problem.

This specification defines a Remote Procedure Calls (RPC) framework using the basic building blocks of DDS, such as topics, types, DataReaders, and DataWriters to provide request/reply semantics. It defines distributed services, described using a service interface, which serves as a shareable contract between service provider and a service consumer. It supports synchronous and asynchronous method invocation. Despite its similarity, it is not intended to be a replacement for CORBA.

2 Conformance

This specification defines two conformance points: Basic and Enhanced.

- [1] Basic conformance (mandatory).
- [2] Enhanced conformance (optional).

The basic conformance point includes support for the Basic service mapping and both the functional and the request-reply language binding styles.

The enhanced conformance point includes the basic conformance and adds support for the Enhanced Service mapping.

The table below summarizes what is included in each of the conformance points.

Conformance	Service Mapping		Language Binding Style	
point	Basic	Enhanced	Function-call	Request/Reply
Basic	Included		Included	Included
Enhanced	Included	Included	Included	Included

3 Normative References

The following normative documents contain provisions which, through reference in this text, constitute provisions of this specification. For dated references, subsequent amendments to, or

revisions of, any of these publications do not apply.

- [DDS] Data Distribution Service for Real-Time Systems Specification, version 1.2 (OMG document formal/2007-01-01).
- [RTPS] The Real-Time Publish-Subscribe Wire Protocol DDS Interoperability Wire Protocol (DDSI-RTPS) (OMG document formal/2010-11-01)
- **[DDS-XTypes]** *Extensible and Dynamic Topic Types for DDS*, version 1.0 Beta 1 (OMG document ptc/2010-05-12).
- [CORBA] Common Object Request Broker Architecture (CORBA/IIOP). formal/2011-11-01, formal/2011-11-02, and formal/2011-11-03
- **[IDL]** Common Object Request Broker Architecture (CORBA) Specification, Version 3.1, Part 1 (OMG document formal/2008-01-04), section 7: "OMG IDL Syntax and Semantics"
- [EBNF] ISO/IEC 14977 Information Technology Syntactic Metalanguage Extended BNF (first edition)
- **[Java-Grammar]** The Java Language Specification, Third Edition. Chapter 8 http://docs.oracle.com/javase/specs/jls/se5.0/html/syntax.html
- [DDS-Cxx-PSM] C++ Language PSM for DDS (OMG document ptc/2012-10-01)
- [DDS-Java-PSM] Java 5 Language PSM for DDS (OMG document ptc/2012-12-02)
- [DDS-LWCCM] DDS for lightweight CCM
- [IDL2Java] IDL to Java Language Mapping, version 1.3 http://www.omg.org/spec/I2JAV/1.3/
- [DDS-RPC-CXX-Github] C++ API for RPC over DDS, https://github.com/rticommunity/dds-rpc-cxx (request_reply.h, function_call.h, and sample.h)
- [DDS-RPC-Java-Github] Java API for RPC over DDS, https://github.com/rticommunity/dds-rpc-java

4 Terms and Definitions

For the purposes of this specification, the following terms and definitions apply.

Service

A Service is a mechanism to enable access to one or more capabilities, where the access is provided using a prescribed interface and is exercised consistent with constraints and policies as specified by the service description. (Source: OASIS SOA Reference Model)

Remote Procedure Call

Remote Procedure Call is an inter-process communication that allows a computer program to cause a subroutine or procedure to execute in another address space

5 Symbols

DDS Data-Distribution Service

GUID Global Unique Identifier

RPC Remote Procedure Call

RTPS Real-Time Publish-Subscribe Protocol

SN Sequence Number

6 Additional Information

6.1 Changes to Adopted OMG Specifications

None

6.2 Acknowledgements

The following companies submitted this specification:

- Real-Time Innovations, Inc.
- eProsima
- PrismTech

The following companies support this specification:

- Real-Time Innovations, Inc.
- eProsima
- PrismTech
- Twin Oaks Computing, Inc.

7 Remote Procedure Call over Data Distribution Service

7.1 Overview

Large distributed systems often require different communication patterns depending upon the problem at hand. For instance, distribution of sensor data is best achieved using unidirectional *one-to-many* pattern whereas sending commands to a specific device or retrieving configuration of a remote service is best done using bidirectional request/reply communication. Using a single middleware that supports multiple communication styles is a very cost-effective way of developing and maintaining large distributed systems. Data Distribution Service (DDS) is a well-known standard for data-centric publish-subscribe communication for real-time distributed systems. DDS excels at providing an abstraction of global data space where applications can publish real-world data and also subscribe to it without temporal or spatial coupling.

DDS, however, is cumbersome to use for bidirectional communication in the sense of request-reply pattern. The pattern can be expressed using the basic building blocks of DDS, however, substantial plumbing must be created manually to achieve the desired effect. As a consequence, it is fair to say that request/reply style communication is not *first-class* in DDS. The intent of this submission is to specify higher-level abstractions built on top of DDS to achieve *first-class* request/reply communication. It is also the intent of this submission to facilitate portability, interoperability, and promote data-centric view for request/reply communication so that the architectural benefits of using DDS can be leveraged in request/reply communication.

7.2 General Concepts

7.2.1 Architecture

Remote Procedure Call necessarily has two participants: a *client* and a *service*. Structurally, every client uses a data writer for sending requests and a data reader for receiving replies. Symmetrically, every *service* uses a data reader for receiving the requests and a data writer for sending the replies.

Figure 1 shows the high-level architecture of the remote procedure call over DDS. The client consists of a data writer to publish the sample that represents remote procedure call on the *call* topic. Correspondingly, the service implementation contains a data reader to read the method name and the parameters (i.e., Foo). The service computes the return values (i.e., Bar) to be sent back to the client on the *Return* topic. (The service implementation details are not shown.)

The data reader at the client side receives the response, which is delivered to the application. To ensure that the client receives a response to a previous call made by itself, a content-based filter is used by the reader at the client-side. This ensures that responses for remote invocations of other clients are filtered.

It is possible for a client to have more than one outstanding request, particularly when asynchronous invocations are used. In such cases, it is critical to correlate requests with responses. As a consequence, each individual request must be correlated with the corresponding reply. Requests, like all samples in the DDS data space, are identified using a unique SampleIdentity defined as a struct composed of GUID_t and a SequenceNumber_t defined in sub clause 7.5.1.1.1. When a service implementation sends a reply to a specific remote invocation, it is necessary to identify the

original request by providing the *sample-identity* of the request. Note that a reply data sample has its own unique message-id (sample identity), which represents the reply message itself and is independent of the request sample-identity.

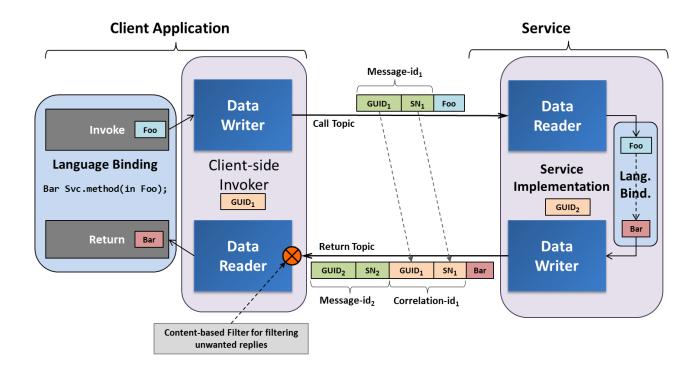


Figure 1: Conceptual View of Remote Procedure Call over DDS

7.2.2 Language Binding Styles for RPC over DDS

Language binding style determines how the client API is exposed to the programmer and how the service implementation receives notification of the arriving requests. This specification includes a higher-level language binding with *function-call* style and a lower-level language binding with *request/reply* style.

7.2.2.1 Function-call Style

The function-call style is conceptually analogous to Java RMI, .NET WFC Service Contracts, or CORBA. To provide function-call style, a common approach is to generate *stubs* that serve as client-side proxies for remote operations and *skeletons* to support service-side implementations. The look-and-feel is like a local function invocation. A code generator generates *stub* and *skeleton* classes from an interface specification. The generated code is used by the client and service implementation. An advantage of such a mapping is that the look and feel of the client-side program and the service implementation is just like a native method call.

7.2.2.2 Request/Reply Style

The request/reply style makes no effort to make the remote invocation look like a function call. Instead, it provides a general-purpose API to send and receive messages. The programmer is responsible for populating the request messages (a.k.a. samples) at the client side and the reply messages on the service side. In that sense it is lower-level language binding compared to the function-call semantics.

The request/reply style provides a flat interface, such as *send_request*, *receive_request*, and *send_reply*, *receive_reply*, which substantially simplifies language binding as no code generation is necessary beyond the request/reply types. However, remote procedure call does not appear *first-class* to the programmer.

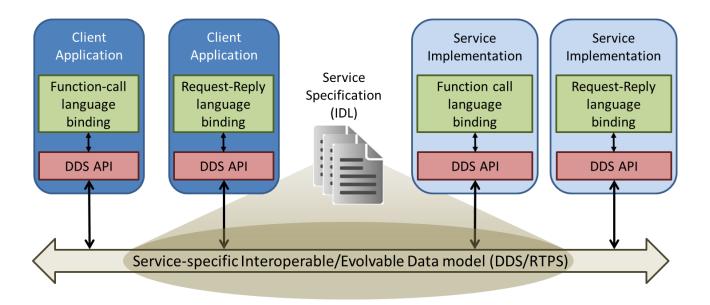


Figure 2: Strong decoupling of language binding (function-call and request/reply) from the service-specific data model

7.2.2.3 Pros and Cons of each Language Binding Styles

The function-call style is natural to programmers due to its familiar look-and-feel. Sending of the request message and reception of the corresponding reply is abstracted away using *proxy* objects on the client side. Request-reply style, on the other hand, is more explicit about exchanging messages and therefore can be used to implement complex interactions between the client and the server. For example, the *command-response* pattern typically involves multiple replies to the same request. (e.g., completion percentage status). Request-reply style can easily implement such a pattern without polling. For a given request, a service may simply produce multiple replies with the same request-id as that of the original request. The client correlates the replies with the original request using the request-id. The function-call style must use application-level polling or asynchronous callbacks if multiple replies are expected by the client. This is because the *single-entry-single-return* semantics restrict underlying messaging.

Furthermore, request-reply style is inherently asynchronous because invocation of the service is separated from reception of replies. Multiple replies (for a single request) may be consumed one at a time or in a batch. The API for request-reply style often simplifies code-generation requirements because stubs and skeletons are not required. Finally, the request-reply style is strongly typed and this specification uses templates in case of C++ and generics in case of Java to provide service-specific type-rich language bindings.

It is important to note that the client and service sides are not coupled with respect to the language binding styles. Thanks to the strong separation imposed by the mapping of interfaces to topic types. It is possible for a client to use function-call style language binding to invoke remote operations on a server that uses request/reply style language binding to implement the service. The converse is also true. Furthermore, it is also possible for the stubs and skeletons of the functional style to use the request/reply language binding under the hood.

In light of the above observation, a conforming implementation to this specification shall support both styles of language binding.

7.2.3 Request-Reply Correlation

Request-reply correlation requires an ability to retrieve the sample identity (GUID, SN) at both the requester and service side. The requester needs to know the sample identity because it needs to correlate the reply with the original request. The service implementation also needs to retrieve the sample identity of the request so that it can use it to relate the reply sample to the request that triggered it.

This specification makes important distinction in how the information necessary for correlation is propagated. The sample-identity can be propagated either *implicitly* or *explicitly*. Explicit sample-identity implies that the request-id is visible in the top-level data type for the DDS topic. Implicit sample-identity, on the other hand, implies that the request sample-identity is communicated via extensibility mechanisms supported by the DDS-RTPS protocol. Specifically using the *inlineQoS* sub-message element. See sub clause 8.3.7.2 of the DDS-RTPS specification [RTPS].

In both cases, the specification provides APIs to get the request-id at the client side and get/set the request-id at the service side.

7.2.4 Basic and Enhanced Service Mapping for RPC over DDS

This specification includes two mappings for interfaces to DDS topics and types called "Basic" and "Enhanced".

- The Basic service mapping enables RPC over DDS functionality without any extensions to the [DDS] and [DDS-RTPS] specifications. It uses explicit request-id for correlation
- The Enhanced service mapping uses implicit request-id for correlation, allows use of the additional data-types defined in DDS-XTypes, uses DDS-XTypes for type-compatibility checking, and provides more robust service discovery.

The following table summarizes the key aspects of the Basic and Enhanced service mapping profiles

Mapping Aspect	Basic Service Mapping Profile	Enhanced Service Mapping Profile
Correlation Information (request-id)	Explicitly added to the datatype	Implicit. Correlation Information appears on the Sample meta-data.
Topic Mapping	One request topic and one reply topic per interface. 2*N for a hierarchy of N interfaces.	One request and one reply topic per interface independent of interface hierarchies.
Type Mapping	Synthesized types compatible with DDS 1.3 compliant implementations.	Use facilities of DDS-XTypes for type descriptions, annotations, and type-compatibility checks.
Discovery	No special extensions.	Robust service discovery as described in sub clause 8.6

7.2.5 Interoperability

Client and service interoperability requires both sides to use the same service mapping. Basic and Enhanced Service Mappings can be mixed in an application but for any given service both client and the service side must use the same service mapping. It is therefore considered part of the service interface contract.

The Basic and Enhanced Service mappings are independent of the language binding style. I.e., It is possible for clients and service implementations to communicate using different language binding styles as long as their service mappings match.

7.3 **Service Definition**

A service definition is provided using the following two alternatives.

- a. **Interface:** An interface is a description of the methods/operations and attributes the service implements. It is a *provided* interface. A service may implement one or more interfaces related by inheritance (single or multiple).
- b. **A Pair of Types:** A service specification may simply include a pair of request and reply types. The request and reply types may be the same. The pair of types may not correspond to an interface. However, all service descriptions correspond to a pair of types. In that sense the pair-of-types mechanism of defining a service is strictly more general than interfaces.

This specification uses OMG Interface Definition Language (IDL) or Java 1.5 as a concrete syntax to define services with either of the mechanisms above.

7.3.1 Service Definition in IDL

This specification uses the interface definition syntax specified in [IDL]. Additionally, annotations are supported to provide extra information. Service definition in IDL does not specify whether an operation is synchronous or asynchronous, which is a run-time concern and not intrinsic to the interface contract. Therefore, this specification provides synchronous and asynchronous invocation capabilities only at the language binding level.

Non-normative: The definition of the IDL syntax as part of this specification is a transient situation. Once IDL 4.0 is adopted this specification will be able to simply reference the appropriate IDL syntax building blocks defined in IDL 4.0.

7.3.1.1 Service Definition in IDL for the Basic Service Mapping

The BNF grammar used to define the IDL syntax uses the same production rules as in sub clause 7.4 (IDL Grammar) in the [IDL] specification and sub clause 7.3.1.12.1 (New Productions) of the [DDS-XTypes] specification.

The IDL 3.5 grammar shall be modified with the productions shown below. These productions are numbered using the same numbers as in the IDL 3.5 document.

Note, [] represents optional.

```
(1) <specification> ::= <definition>+
```

```
(7) <interface_header> ::= [ <annotation> ] "interface" <identifier> [ <interface_inheritance_spec> ]
```

```
(9) <export> ::= <attr_dcl> ";" 
| <op_dcl> ";"
```

```
(42) <type_dcl> ::= [ <annotation> ] "typedef" <type_declarator> | [ <annotation> ] <struct_type>
```

```
| <union_type>
| <enum_type>
| "native" <simple_declarator>
| <constr_forward_decl>
```

- (91) <param_dcl> ::= [<annotation>] <param_attribute> <param_type_spec> <simple_declarator>
- (106) <attr_spec> ::= [<annotation>] "attribute" <param_type_spec> <attr_declarator>

The <annotations> production used above is defined in sub clause 7.3.1.12.1 of the [DDS-XTypes] specification.

Design Rationale (non-normative)

The table below provides the justification for the modified production rules:

Reference	Origin	Explanation
(1)	IDL 3.5	This is the root production rule. Modified to remove the CORBA-specific import statement.
(2)	IDL 3.5	Modified to remove the productions for related to CORBA Repository Identity and CCM. Specifically <type_id_dcl>, <type_prefix_dcl>, <event>, <component>, and <home_dcl></home_dcl></component></event></type_prefix_dcl></type_id_dcl>
		The modified rule also adds support for annotation declarations.
		The <annotation> and <ann_appl_post> productions are defined in sub clause 7.3.1.12.1 of the [DDS-XTypes] specification.</ann_appl_post></annotation>
(7)	IDL 3.5	Modified to add support for interface annotations
		The <annotation> production is defined in sub clause 7.3.1.12.1 of the [DDS-XTypes] specification</annotation>
$\perp /(1)$		Modified to remove productions related to CORBA Repository Identity. Specifically <type_id_dcl> and <type_prefix_dcl></type_prefix_dcl></type_id_dcl>
		This production also removes the rules that allow embedding declarations of types, constants, and exceptions within an interface. Specifically the <type_dcl>, <const_dcl>, and <except_dcl></except_dcl></const_dcl></type_dcl>
(42)	IDL 3.5	Added <annotation> production at the beginning of struct and typedef declarators. This allows a structured type to be a request or reply type.</annotation>
(87)	IDL 3.5	Modified to add support for annotations on operations. Removed the CORBA-specific "oneway" modifier and the "context" expressions.
(91)	IDL 3.5	Modified to add support for annotations on the operation parameters
(104)	IDL 3.5	Modified to add support for annotations on read-only attributes
(106)	IDL 3.5	Modified to add support for annotations on attributes
DDS- XTypes	[DDS-XTypes] sub clause 7.3.1.12.2	These productions add support for annotating types and the new IDL types defined in the [DDS-XTypes] specification.

The use of the <annotations> production from DDS-XTypes does not mean that the underlying DDS implementation needs to support DDS-XTypes. The Basic Service Mapping uses annotations only for interface declarations and not on regular type declarations. These interface annotations are resolved in the mapping such that the resulting IDL used by DDS does not have annotations.

7.3.1.2 Service Definition in IDL for the Enhanced Service Mapping

The Enhanced Service Mapping allows use of the full type-system defined in the DDS-XTypes specification in the declaration of interface attributes, operation parameters and return values.

The Enhanced Service Mapping extends the IDL productions defined in the Basic Service Mapping with all the productions (i.e., not just related to annotations) in sub clause 7.3.1.12.1 (New Productions) of the DDS-XTypes specification.

In addition, the Enhanced Service Mapping also uses all the modified productions defined in sub clause 7.3.1.12.2 (Modified Productions) of the [DDS-Xtypes] specification with the exception of the production for <definition>, which shall remain, as defined for the Basic Service Mapping.

7.3.1.3 Example of an Interface in IDL (Non-normative)

```
module robot {
  exception TooFast {};
  enum Command { START_COMMAND, STOP_COMMAND };
  struct Status {
    string msg;
  };
  @DDSService
  interface RobotControl {
    void command(Command com);
    float setSpeed(float speed) raises (TooFast);
    float getSpeed();
    void getStatus(out Status status);
  };
}; //module robot
```

7.3.1.4 Service Definition in IDL Using a Pair of Types

A service definition may simply include a pair of types, which may be the same. The request and reply types shall be marked as such using the <code>@RPCRequestType</code> and <code>@RPCReplyType</code> annotations. Only <code>struct</code> types shall be marked as request/reply types.

In the Basic Service Mapping, the types annotated as <code>@RPCRequestType</code> shall have a member named header of type <code>dds::rpc::RequestHeader</code> and the types annotated as <code>@RPCReplyType</code> shall have a member named header of type <code>dds::rpc::RequestHeader</code>. See sub clause 7.5.1.1.1 for the request and reply header types.

When using the Enhanced Service Mapping, the annotations are not necessary and the special data members must not be defined.

7.3.2 Service Definition in Java

The BNF grammar used to define the Java syntax used in [Java-Grammar]. Conforming implementations shall support the syntax generated by the following modified productions from the Java grammar.

Note, [] represents optional and {} represents zero or more occurrences.

```
InterfaceDeclaration:
      NormalInterfaceDeclaration
NormalInterfaceDeclaration:
     interface Identifier [extends TypeList] InterfaceBody
InterfaceBody:
        { InterfaceBodyDeclaration {InterfaceBodyDeclaration} }
InterfaceMemberDecl:
        InterfaceMethodOrFieldDecl
        void Identifier VoidInterfaceMethodDeclaratorRest
        InterfaceDeclaration
        ClassDeclaration
NormalClassDeclaration:
     class Identifier [extends Type] [implements TypeList] ClassBody
ClassBody:
        { ClassBodyDeclaration {ClassBodyDeclaration} }
ClassBodyDeclaration:
        {Modifier} MemberDecl
MemberDecl:
        MethodOrFieldDecl
MethodOrFieldRest:
        VariableDeclaratorRest
```

Design Rationale (non-normative)

The table below provides the justification for the modified production rules:

Name	Origin	Explanation
InterfaceDeclaration Java 1.5		Removed annotation type declaration.
NormalInterfaceDeclaration	Java 1.5	Removed generic type parameters.
InterfaceBody	Java 1.5	At least one method must be present in an interface. Note, Java allows empty (marker) interfaces.
InterfaceMemberDecl	Java 1.5	Removed generic method declaration.
NormalClassDeclaration	Java 1.5	Removed generic type parameters.
ClassBody Java 1.5		At least one data member must be defined in the class body. Note, Java allows empty classes.
ClassBodyDeclaration	Java 1.5	Removed Java's static block support.
MemberDecl	Java 1.5	Removed method (generic or otherwise) declarator, constructor declarator, nested interface and class declarators. This specification shall support data member declarations inside a Java class.
MethodOrFieldRest Java 1.5		Removed method declarator. This specification shall support data member declarations inside a Java class.

In, *out*, and *inout* parameters are specified using the @in, @out and @inout annotations. By default the parameters are read only, and the use of @in is optional. One or more operations may be marked oneway using the @oneway annotation.

7.3.2.1 Example of an interface in Java (Non-normative)

```
public class TooFast extends Exception
{
}
@DDSService
public interface RobotControl
{
   void command(Command com);
   float setSpeed(float speed) throws TooFast;
```

```
float getSpeed();
  void getStatus(@out Status status);
};
```

7.3.2.2 Service Definition in Java Using a Pair of Types

A service definition may simply include a pair of types, which may be the same. The request and reply types shall be marked as such using the <code>@RPCRequestType</code> and <code>@RPCReplyType</code> annotations. Only <code>class</code> types shall be marked as request/reply types.

In the Basic Service Mapping, the types annotated as @RPCRequestType shall have a member named header of type dds.rpc.RequestHeader and the types annotated as @RPCReplyType shall have a member named header of type dds.rpc.RequestHeader. See sub clause 7.5.1.1.1 for the request and reply header types.

When using the Enhanced Service Mapping, the annotations are not necessary and the special data members must not be defined.

7.4 Mapping Service Specification to DDS Topics

7.4.1 Rules for Synthesizing DDS Topic Names

Request and reply topic names use the following BNF grammar.

Topic name is either a user-defined string literal or a composite string consisting <interface_name> and <service_name>. The <interface_name> non-terminal represents the unqualified name of the interface, which is captured automatically for interface-based service definitions. The <service_name> non-terminal may be user-supplied. When it is not, it defaults to "Service". If the <service_name> is specified by the user, "Request" and "Reply" topic suffixes are used automatically. When <service_name> and user-defined topic names are both provided by the used, the user-defined topic names take precedence.

For the request-reply style language binding, **<interface_name>** and the following underscore shall not be captured automatically.

Note that the **<user_def_alpha_num>** non-terminal is a regular expression that includes alphanumeric characters (a-zA-Z0-9), underscore and space.

7.4.2 Basic Service Mapping

The Basic Service mapping maps every interface to a request topic and a reply topic. It provides three alternative mechanisms to specify the names of the topics. It is possible to use different

mechanism at the client and server sides. However, to ensure successful end-point matching, the topic names must match.

In case of an interface inheritance hierarchy, including multiple inheritance, each interface in the hierarchy shall be mapped to its own pair of request and reply topics.

7.4.2.1 Default Topic Names

The default topic names are synthesized using the rules defined in sub clause 7.4.1.

7.4.2.2 Specifying Topic Names using Annotations

Interfaces and the request/reply types may be annotated to specify the names of the request and reply topics. @DDSRequestTopic and @DDSReplyTopic annotations are pre-defined for this purpose. They are defined using the [DDS-XTypes] notation as follows:

```
module dds {
  module rpc {

   @Annotation
  local interface DDSRequestTopic {
    attribute string name;
  };

  @Annotation
  local interface DDSReplyTopic {
    attribute string name;
  };
  };
};
```

Note that support for [DDS-XTypes] in the underlying DDS implementation is not required to interpret the annotations. These annotations simply control the generated DDS wrapper code.

Non-Normative Example: The RobotControl interface may use one or both of the annotations shown below.

```
@DDSService

@DDSRequestTopic(name="RobotRequestTopic")

@DDSReplyTopic(name="RobotReplyTopic")

interface RobotControl
```

```
void command(Command com);
...
}
```

7.4.2.3 Specifying Topic Names at Run-time

DDS Topic names may also be specified at run-time. The ServiceParams, ClientParams, RequesterParams, and ReplierParams classes (sub clause 7.11.1.4) provide functions to specify the service name and the topic name suffix. When used as such, the rules defined in sub clause 7.4.1 apply.

When more than one method of specifying topic names is used, the run-time specification shall take precedence over the IDL annotations and the default mechanism in that order.

7.4.3 The Enhanced Service Mapping

To support single and multiple inheritance of interfaces, the Enhanced Service mapping introduces a notion called "topic aliases". A topic-alias is an alternative name for a topic. A topic may have one or more topic aliases. A topic-alias does not introduce a new topic. It simply indicates the fact that a given topic may be known by different names. Topic aliases are announced during the endpoint discovery protocol using either of the PublicationBuiltinTopicDataExt and SubscriptionBuiltinTopicDataExt structures described in in sub clause 7.6.2.1.

The Enhanced Service Mapping shall map an interface to exactly one request topic and a reply topic. The names of the topics are obtained using the rules defined in sub clause 7.4.1. In case of single and multiple inheritance, the request and reply topics shall additionally have topic-aliases, which are obtained using the rules in sub clause 7.4.1 for each parent interface.

Non-normative example: The following example shows the topic names and topic-aliases for the Calculator hierarchy while using the function-call style language binding. Depending upon whether the user has supplied the service name and/or topic-suffixes, different outcomes are produced.

```
interface Adder { ... };
interface Subtractor { ... };
interface Calculator : Adder, Subtractor { ... }
```

		Topic name	Topic aliases	
Everything Default	Request	Calculator_Service_Request	Adder_Service_Request, Subtractor_Service_Request	
	Reply	Calculator_Service_Reply	Adder_Service_Reply, Subtractor_Service_Reply	
User- defined service	Request	Calculator_\${servicename}_Reque st	Adder_\${servicename}_Request, Subtractor_\${servicename}_Reques t	
name	Reply	Calculator_\${servicename}_Reply	Adder_\${servicename}_Reply, Subtractor_\${servicename}_Reply	
User- defined topic	Request	Calculator_\${topic-suffix-request}	Adder_\${topic-suffix-request}, Subtractor_\${topic-suffix-request}	
suffixes	Reply	Calculator_\${topic-suffix-reply}	Adder_\${topic-suffix-reply}, Subtractor_\${topic-suffix-reply}	

For the request-reply style language binding, the interfaces name shall not be annexed automatically.

7.4.3.1 Default Topic Names

The default topic names are synthesized as described above.

7.4.3.2 Specifying Topic Names Using Annotations

Interfaces and the request/reply types may be annotated to specify the names of the request and reply topics. The same built-in @DDSRequestTopic and @DDSReplyTopic annotations defined in the Basic Service Mapping may be used for this purpose.

7.4.3.3 Specifying Topic Names at Run-time

DDS Topic names may also be specified at run-time. The ServiceParams, ClientParams, RequesterParams, and ReplierParams classes (sub clause 7.11.1.4) provide functions to

specify the service name and the topic name suffix. When used as such, the rules defined in sub clause 7.4.1 apply.

When more than one method of specifying topic names is used, the run-time specification shall take precedence over the IDL annotations and the default mechanism in that order.

7.5 Mapping Service Specification to DDS Topics Types

The *request* and *reply* DDS Topic types shall be synthesized from the interface definition. To accurately capture the semantics of the method call invocation and return, this specification defines additional built-in annotations. The following annotations are applicable for the Enhanced Service Mapping only.

7.5.1 Interface Mapping

7.5.1.1 Basic Service Mapping of Interfaces

The Basic Service Mapping maps interfaces to data-types that can be used by DDS version 1.3 compliant implementations, which may lack support for the [DDS-XTypes] specification.

7.5.1.1.1 **Common Types**

All the generated types as per the Basic Service Mapping use a set of common types.

```
module dds {
    // The following DDS related types are
    // borrowed from the RTPS v1.2 specification
    typedef octet GuidPrefix_t[12];

struct EntityId_t {
    octet entityKey[3];
    octet entityKind;
};

struct GUID_t {
    GuidPrefix_t guidPrefix;
    EntityId_t entityId;
};

struct SequenceNumber_t {
    long high;
```

```
unsigned long low;
  };
  struct SampleIdentity {
    GUID t
                     writer guid;
    SequenceNumber t sequence number;
  };
module rpc {
typedef octet UnknownOperation;
typedef octet UnknownException;
typedef octet UnusedMember;
enum RemoteExceptionCode t; // defined in sub clause 8.5.2
struct RequestHeader {
  SampleIndentity t requestId;
  string<255> instanceName;
};
struct ReplyHeader {
  dds::SampleIdentity relatedRequestId;
  dds::rpc::RemoteExceptionCode t remoteEx;
};
} // module rpc
} // module dds
```

7.5.1.1.2 Mapping of Operations to the Request Topic Types

The mapping of an interface operation to a request type is defined according to the following rules. In these rules the token \${interfaceName} shall be replaced with the name of the interface and the token \${operationName}_shall be replaced with the name of the operation. The substituted names are not fully qualified. I.e., any module prefixes shall be removed.

1. Each operation in the interface shall map to an In structure with name "\${interfaceName}_\${operationName}_In".

- 2. The *In* structure shall be defined within the same module as the original interface.
- 3. The *In* structure shall contain as members the *in* and *inout* parameters defined in the operation signature.
 - a. The members shall appear in the same order as the parameters in the operation, starting from the left.
 - b. The names of the members shall be the same as the formal parameter names.
 - c. If an operation has no *in* and *inout* parameters the resulting structure shall contain a single member of type UnusedMember and name "dummy".

Non-normative Example: The operations in the RobotControl interface defined in sub clause 7.3.1.3 shall map to the following *In* structures.

```
module robot {

struct RobotControl_command_In {
   Command com;
};

struct RobotControl_setSpeed_In {
   float speed;
};

struct RobotControl_getSpeed_In {
   dds::rpc::UnusedMember dummy;
};

struct RobotControl_getStatus_In {
   dds::rpc::UnusedMember dummy;
};
```

7.5.1.1.3 Mapping of Operations to the Reply Topic Types

Each operation in the interface shall map to an *Out* structure and a *Result* union. The following rules define the *Out* structure.

- 1. The name of the *Out* structure shall be "\${interfaceName}_\${operationName}_Out".
- 2. The *Out* structure shall be defined within the same module as the original interface.

- 3. The *Out* structure shall contain as members the *out* and *inout* parameters defined in the operation signature. In addition it may contain a member named "return".
 - a. The *Out* structure shall include one member for each *out* and *inout* parameter in the operation signature.
 - i. The members shall appear in the same order as the parameters in the operation, starting from the left.
 - ii. The name of the members shall be the same as the formal parameter names.
 - b. If the operation defines a non-void return value the *Out* structure shall have its last member named "return_". The type of the "return_" member shall be the return type of the operation. In the case where the function does not define a return value this member shall not be present.
 - c. If the operation has no return value, no *out/inout* parameters, the *Out* structure shall contain a single member named "dummy" of type dds::rpc::UnusedMember.

Non-normative Example: The operations defined in the RobotControl interface defined in sub clause 7.3.1.3 map to the following *Out* structures.

```
module robot {
struct RobotControl_command_Out {
   dds::rpc::UnusedMember dummy;
};
struct RobotControl_setSpeed_Out {
   float return_;
};
struct RobotControl_getSpeed_Out {
   float return_;
};
struct RobotControl_getStatus_Out {
   Status status;
};
```

The following rules define the *Result* union.

- 1. The *Result* union name shall be "\${interfaceName}}_\${operationName}_Result".
- 2. The *Result* union discriminator type shall be long.
- 3. The *Result* union shall have a default case label containing a member named "unknownEx" of type dds::rpc::UnknownException.

- 4. The *Result* union shall have a case with label dds::RETCODE_OK which is used to represent a successful return.
 - a. This case label shall contain a single member with name "result" and type \$\{\text{interfaceName}_\$\{\text{operationName}_\text{Out.}}\]
- 5. For each exception type raised by the operation,
 - a. A constant of type long and with name "\${exceptionType}_Ex_Hash" shall be available in the same namespace as the interface is defined in.
 - b. The value of the constant shall be the HASH of the fully qualified name of the exception type where module separator to be used is "::" (2 colons).
- 6. The union shall have a case label for each exception declared as a possible outcome of the operation.
 - a. The integral value of the case label shall be \${exceptionType}_Ex_Hash.
 - b. The case label shall contain a single member with name synthetized as the lower-case of the exception name with the suffix "_ex" added.
 - c. The type associated with the case member shall be the exception type.

Non-normative Example: The operations defined in the RobotControl interface defined in sub clause 7.3.1.3 map to the following *Result* unions.

```
module robot {
  const long TooFast_Ex_Hash = HASH("TooFast");
  union RobotControl_command_Result switch(long)
  {
    default:
        dds::rpc::UnknownException unknownEx;
    case dds::RETCODE_OK:
        RobotControl_command_Out result;
};

union RobotControl_setSpeed_Result switch(long)
  {
    default:
        dds::rpc::UnknownException unknownEx;
```

```
case dds::RETCODE OK:
    RobotControl setSpeed Out result;
  case TooFast Ex Hash:
    TooFast toofast ex;
};
union RobotControl getSpeed Result switch(long)
  default:
    dds::rpc::UnknownException unknownEx;
  case dds::RETCODE OK:
    RobotControl getSpeed Out result;
};
union RobotControl getStatus Result switch(long)
  default:
    dds::rpc::UnknownException unknownEx;
  case dds::RETCODE OK:
    RobotControl getStatus Out result;
};
} // module robot
```

In the above IDL the short-hand HASH (arg) is used for clarity. In the actual IDL it shall be substituted with the actual value computed according to the formula:

```
long HASH(string arg)
{
  octet md5_hash[16];
```

7.5.1.1.4 Mapping of Interfaces to the Request Topic Types

Each interface shall map to a *Call* union and a *Request* structure. The following rules define the *Call* union.

- 1. The *Call* union name shall be "\${interfaceName} Call" in the same module as the interface.
- 2. The *Call* union discriminator type shall be of type long.
- 3. The *Call* union shall have a default case label containing a member named "unknownOp" of type dds::rpc::UnknownOperation. [Non-normative design rationale: Due to interface evolution a client that uses new interface may end up calling a service that implements a previous version of the interface. In that case, the discriminator value will not match any of the existing cases and hence will default to unknown, which should be recognized by the service implementation.]
- 4. For each operation in the interface, an integral constant of type long and name "\$(interfaceName)_\${operationName}_Hash" shall be present in the same module as the interface. The value of this constant is the HASH of unqualified \${operationName}.
- 5. The *Call* union shall have a case label for each operation in the interface.
 - a. The integral value of the case label shall be the HASH of \${operationName}.
 - b. The member name for the case label shall be the operation name.
 - c. The type for the case label member shall be \${interfaceName}_\${operationName}_In as defined in sub clause 7.5.1.1.2.

Non-normative Example: The RobotControl interface defined in sub clause 7.3.1.3 shall map to the following union RobotControl Call.

```
module robot {

const long RobotControl_command_Hash = HASH("command");

const long RobotControl_setSpeed_Hash = HASH("setSpeed");

const long RobotControl_getSpeed_Hash = HASH("getSpeed");
```

```
const long RobotControl_getStatus_Hash = HASH("getStatus");
union RobotControl_Call switch(long)
{
    default:
        dds::rpc::UnknownOperation unknownOp;

    case RobotControl_command_Hash:
        RobotControl_command_In command;

    case RobotControl_setSpeed_Hash:
        RobotControl_setSpeed_Hash:
        RobotControl_getSpeed_Hash:
        RobotControl_getSpeed_Hash:
        RobotControl_getSpeed_In getSpeed;

    case RobotControl_getStatus_Hash:
        RobotControl_getStatus_Hash:
        RobotControl_getStatus_In getStatus;
};
};
```

The following rules define the *Request* structure.

- 1. The name of *Request* structure shall be "\${interfaceName}_*Request*" in the same module as the interface.
- 2. The *Request* structure shall have two members:
 - a. The first member of the *Request* structure shall be named "header" and be of type dds::rpc::RequestHeader.
 - b. The second member of the *Request* structure shall be named "data" and be of type \${interfaceName}_Call.

Non-normative Example: The RobotControl interface defined in sub clause 7.3.1.3 shall map to RobotControl Request defined below.

```
module robot {

struct RobotControl_Request {
   dds::rpc::RequestHeader header;
   RobotControl_Call data;
};
}
```

7.5.1.1.5 Mapping of Interfaces to the Reply Topic Types

Each interface shall map to a *Return* union and a *Reply* structure.

The following rules define the *Return* union.

- 1. The *Return* union name shall be "\${interfaceName} Return" in the same module as the interface.
- 2. The *Return* union discriminator type shall be of type long.
- 3. The *Return* union shall have a default case label containing a member named "unknownOp" of type dds::rpc::UnknownOperation. [Non-normative rationale: Unknown operation errors should not be reported back using this member. The ReplyHeader.remoteEx member should be used for that. The only reason the unknownOp member is used because it is a good practice to define a default for a union.]
- 4. For each operation,
 - a. A constant of type long and with name "\${interfaceName}_\${operationName}_Hash" shall be available in the same namespace as the interface is defined in.
 - b. The value of the constant shall be the HASH of the name of the operation (not qualified).
- 5. The *Return* union shall have a case label for each operation in the interface:
 - a. The integral value of the case label shall be \${interfaceName}_\${operationName}_Hash as computed using the HASH algorithm of the unqualified name of the operation.
 - b. The member name for the case label shall be the operation name and the type shall be \$\{interfaceName}_\$\{operationName}_Result.

Non-normative Example: The RobotControl interface defined in sub clause 7.3.1.3 shall map to the union RobotControl_Return defined below:

```
union RobotControl_Return switch(long)
{
   default:
```

```
case RobotControl_command_Hash:
   RobotControl_command_Result command;

case RobotControl_setSpeed_Hash:
   RobotControl_setSpeed_Result setSpeed;

case RobotControl_getSpeed_Hash:
   RobotControl_getSpeed_Result getSpeed;

case RobotControl_getSpeed_Result getSpeed;

case RobotControl_getStatus_Hash:
   RobotControl_getStatus_Result getStatus;
};
```

The following rules define the *Reply* structure.

- 1. The *Reply* structure name shall be "\${interfaceName}_*Reply*,".
- 2. The *Reply* structure shall be defined within the same module as the original interface.
- 3. The *Reply* structure shall have two members:
 - a. The first member of the Reply structure shall be named "header" and be of type dds::rpc::ReplyHeader.
 - b. The second member of the *Reply* type shall be named "data" and be of type \${interfaceName} Return.

Non-noramtive Example: The RobotControl interface defined in sub clause 7.3.1.3 shall map to the structure RobotControl_Reply defined below:

```
struct RobotControl_Reply {
   dds::rpc::ReplyHeader header;
   RobotControl_Return reply;
};
```

7.5.1.1.6 Mapping of inherited Interfaces to the Request and Reply Topic Types

Inheritance has no effect on the generated structures and unions. A DDS service that implements a derived interface uses two topics for every interface in the hierarchy. As a result, a service implementing a hierarchy of N interfaces, shall have N request topics and N reply topics.

Consequently, it will necessitate N DataWriters and N DataReaders. The types and the topic names are obtained as specified in sub clause 7.4.2. The *Request* and *Reply* types for a derived interface includes operations defined only in the derived interface.

Non-normative Example: The Basic Service Mapping for the Calculator interface is shown below.

```
interface Adder {
  long add(long a, long b);
};
interface Subtractor {
  long sub(long a, long b);
};
interface Calculator : Adder, Subtractor {
  void on();
  void off();
};
```

```
struct Adder_add_In {
  long a;
  long b;
};

struct Adder_add_Out {
  long return_;
};

union Adder_add_Result switch (long) {
  default:
    dds::rpc::UnknownException unknownEx;

case dds::rpc::REMOTE_EX_OK:
    Adder_add_Out result;
};
```

```
const long Adder add Hash = HASH("add");
union Adder Call switch (long) {
  default:
    dds::rpc::UnknownOperation unknownOp;
 case Adder add Hash:
    Adder add In add;
};
struct Adder Request {
  dds::rpc::RequestHeader header;
 Adder Call data;
};
union Adder Return switch(long) {
  default:
    UnknownOperation unknownOp;
  case Adder_add_Hash:
    Adder add Result add;
};
struct Adder Reply {
  dds::rpc::ReplyHeader header;
 Adder Return data;
};
struct Subtractor sub In {
 long a;
  long b;
};
struct Subtractor sub Out {
```

```
long return ;
};
union Subtractor sub Result switch (long) {
  default:
    dds::rpc::UnknownException unknownEx;
  case dds::rpc::REMOTE EX OK:
    Subtractor sub Out result;
};
const long Subtractor sub Hash = HASH("sub");
union Subtractor Call switch (long) {
  default:
    dds::rpc::UnknownOperation unknownOp;
  case Subtractor sub Hash:
    Subtractro sub In sub;
};
struct Subtractor Request {
    dds::rpc::RequestHeader header;
    Subtractor Call data;
};
union Subtractor Return switch(long) {
  default:
    dds::rpc::UnknownOperation unknownOp;
  case Subtractor sub Hash:
    Subtractor sub Result sub;
} ;
struct Subtractor Reply {
  dds::rpc::ReplyHeader header;
  Subtractor Return data;
};
```

```
struct Calculator on In {
 dds::rpc::UnusedMember dummy;
};
struct Calculator off In {
  dds::rpc::UnusedMember dummy;
};
struct Calculator on Out {
  dds::rpc::UnusedMember dummy;
};
union Calculator on Result switch(long) {
  default:
    dds::rpc::UnknownException unknownEx;
  case dds::rpc::REMOTE_EX_OK:
    Calculator on Out result;
};
struct Calculator off Out {
  dds::rpc::UnusedMember dummy;
};
union Calculator off Result switch(long) {
  default:
    dds::rpc::UnknownException unknownEx;
  case dds::rpc::REMOTE EX OK:
    Calculator off Out result;
};
```

```
const long Calculator on Hash = HASH("on");
const long Calculator off Hash = HASH("off");
union Calculator Call switch (long) {
  default:
    dds::rpc::UnknownOperation unknownOp;
  case Calculator on Hash:
    Calculator_on In on;
 case Calculator off Hash:
    Calculator off In off;
};
struct Calculator Request {
  dds::rpc::RequestHeader header;
  Calculator Call
                         data;
};
union Calculator Return switch(long) {
  default:
    dds::rpc::UnknownOperation unknownOp;
  case Calculator on Hash:
    Calculator on Result on;
  case Calculator off Hash:
    Calculator off Result off;
} ;
struct Calculator Reply {
  dds::rpc::ReplyHeader header;
  Calculator Return
};
```

7.5.1.2 Enhanced Service Mapping of Interfaces

The Enhanced Service Mapping uses the [DDS-XTypes] type system in addition to the annotations defined in sub clause 7.5.1.2.1.

7.5.1.2.1 Annotations for the Enhanced Service Mapping

All annotations below are defined in the dds::rpc module.

7.5.1.2.1.1 @Choice Annotation

This specification defines an @Choice annotation to capture the semantics of a union without using a discriminator. Using unions to indicate which operation is being invoked is brittle. Operations in an interface have set semantics and have no ordering constraints. Union, however, enforces strict association with discriminator values, which are too strict for set semantics. Further, use of unions leads to ambiguities in case of multiple inheritance of interfaces.

The @Choice annotation is a placeholder annotation defined as follows.

```
@Annotation local interface Choice { };
```

The @Choice annotation is allowed on structures only. When present, the structure shall be interpreted as if the structure had the @Extensibility (MUTABLE_EXTENSIBILITY) annotation and all the members of the structure had the @Optional annotation. Furthermore, exactly one member shall be present at any given time.

This specification uses the semantics of <code>@Choice</code> for the *return* topic type and to differentiate between normal and exceptional return from a remote method call.

7.5.1.2.1.2 @Autoid Annotation

The @Autoid annotation shall be allowed on structures and data members. The structures of the topic types synthesized from the interface shall be annotated as @Autoid.

The @Autoid annotation indicates that the member-id of each member shall be computed using the HASH algorithm (defined in sub clause) applied to the name of the member. As IDL does not support overloading, no two members will have the same name. Consequently, the member ids of two members will be different, unless a hash-collision occurs, which shall be detected by the code generator that processes the IDL interface. Using the MD5 hash for the member id also ensures that the topic types synthesized from the interface definitions are not subject to the order of operation declaration or interface inheritance. Note that the order of interface inheritance is irrelevant to the semantics of an interface. Further, it supports interface evolution (including new operations, operation reorder and new base interfaces) without changing the member ids.

7.5.1.2.1.3 @Empty Annotation

This specification uses empty IDL structures to capture operations that do not accept any parameters. IDL does not support empty structures. @Empty annotation has been introduced to simplify the mapping rules and support operations that take no arguments. Empty structures, however, are used to maintain consistency between the *call* and *return* structures. Furthermore, eliminating empty structures in the synthesized topic types is undesirable because two or more operations may be empty in which case it becomes ambiguous. The <code>@Empty</code> annotation allows a structure to be empty. The code synthesized from an empty structure is implementation dependent.

7.5.1.2.1.4 @Mutable Annotation

This annotation shall be allowed on interface operations. It controls the type-mapping for the operation parameters and return value. By default, adding and removing operation parameters would break compatibility with the previous interface. The use of the @Mutable operation changes the type declaration of the synthesized call and return structures so that they are declared with the @Extensibility (MUTABLE EXTENSIBILITY) annotation.

7.5.1.2.2 Mapping of Operations to the Request Topic Types

The mapping for interface operations is same as defined in sub clause 7.5.1.1.2 with the following additional rules.

If the operation has the @Mutable annotation, then the synthesized In structure shall have the annotation @Extensibility(MUTABLE EXTENSIBILITY)

For example, please see sub clause 7.5.1.1.2.

7.5.1.2.3 Mapping of Operations to the Reply Topic Types

Each operation in the interface shall map to an *Out* structure and a *Result* structure. The rules for mapping the *Out* structure is identical to that defined in sub clause 7.5.1.1.3 with the following additional rule.

1. If the operation has the @Mutable annotation, then the synthesized *Out* structure shall have the annotation @Extensibility (MUTABLE EXTENSIBILITY)

The mapping rules for the *Result* structure are as follows.

- 2. The *Result* structure name shall be "\{interfaceName}_\{operationName}_Result".
- 3. The *Result* structure shall have the annotation @Choice.
- 4. The *Result* structure shall have the annotation @Autoid.
- 5. The *Result* structure shall have a first member with name "result" and with type \$\{\text{interfaceName}_\$\{\text{operationName}_\text{Out.}}\]
- 6. The *Result* structure name shall have members for each exception an operation may raise.
 - a. The member name shall be synthetized as the lower-case version of the exception name with the suffix "ex" added.
 - b. The type associated with the member shall be the exception type.
- 7. If the operation has the @Mutable annotation, then the synthesized *Result* structure shall have the annotation @Extensibility (MUTABLE EXTENSIBILITY)

Non-normative example: The operations defined in the RobotControl interface defined earlier map to the following *Result* structures.

```
@Choice @Autoid
struct RobotControl command Result {
   RobotControl command Out result;
} ;
@Choice @Autoid
struct RobotControl stop Result {
    RobotControl getSpeed Out result;
};
@Choice @Autoid
struct RobotControl setSpeed Result {
    RobotControl setSpeed Out result;
    TooFast toofast ex;
};
@Choice @Autoid
struct RobotControl getSpeed Result {
    RobotControl getStatus Out result;
};
```

7.5.1.2.4 Interface Mapping for the Request Topic Types

Each interface shall map to a *Request* structure.

The following rules define the *Request* structure.

- 1. The *Request* structure name shall be "\${interfaceName} Request".
- 2. The *Request* structure shall have the @Choice annotation.
- 3. The *Request* structure shall have the @Autoid annotation.
- 4. The *Request* structure shall contain a member for each operation in the interface.
 - a. The member name shall be the operation name.
 - b. The member type shall be \${interfaceName}_\${operationName}_In.

Non-normative example: The Robotcontrol interface defined earlier shall result in the RobotControl_Call structure defined below.

```
@Choice @Autoid
struct RobotControl_Request {
    RobotControl_command_In command;
    RobotControl_setSpeed_In setSpeed;
    RobotControl_getSpeed_In getSpeed;
```

```
RobotControl_getStatus_In getStatus;
};
```

7.5.1.2.5 Interface Mapping for the Reply Type

Each interface shall map to a *Reply* structure.

The following rules define the *Reply* structure. In these rules the token \${interfaceName} shall be replaced with the name of the interface:

- 1. The *Reply* structure name shall be "\${interfaceName}_Reply".
- 2. The *Reply* structure shall have the @Choice annotation.
- 3. The *Reply* structure shall have the @Autoid annotation.
- 4. The *Reply* structure shall contain a member for each operation in the interface.
 - a. The member name shall be the operation name.
 - b. The member type shall be \${interfaceName}_\${operationName}_Result.
- 5. The *Reply* structure shall contain a member named "remoteEx" of type dds::rpc::RemoteException t.

Non-normative example: The RobotService interface defined earlier maps to the following structure.

```
@Choice @Autoid
struct RobotControl_Reply {
    RobotControl_command_Result command;
    RobotControl_setSpeed_Result setSpeed;
    RobotControl_getSpeed_Result getSpeed;
    RobotControl_getStatus_Result getStatus;
    dds::rpc::RemoteException_t remoteEx;
};
```

7.5.1.2.6 Mapping of Inherited Interfaces to Request and Reply Topic Types

A derived interface is interpreted as if all the inherited operations are declared in-place in the derived interface. That is, the inheritance structure is *flattened*.

Non-normative Example: The Enhanced Service Mapping rules applied to the Calculator interface hierarchy results in the following request and reply Topic types.

```
@Autoid
struct Adder_add_In {
  long a;
```

```
long b;
};
@Autoid
struct Adder add Out {
  long return ;
};
@Choice @Autoid
struct Adder add Result {
 Adder add Out result;
};
@Choice @Autoid
struct Adder Request {
 Adder_add_Result add;
};
@Autoid
struct Subtractor_sub_In {
 long a;
 long b;
};
@Autoid
struct Subtractor sub Out {
  long return ;
};
@Choice @Autoid
struct Subtractor_sub_Result {
   Subtractor sub Out result;
};
@Choice @Autoid
struct Subtractor sub Reply {
   Subtractor sub Result sub;
   dds::rpc::RemoteException t remoteEx;
```

```
};
@Autoid
struct Calculator on In {
  long dummy;
};
@Autoid
struct Calculator_off_In {
  long dummy;
};
@Autoid
struct Calculator on Out {
  long dummy;
};
@Choice @Autoid
struct Calculator_on_Result {
  Calculator_on_Out result;
};
@Autoid
struct Calculator_off_Out {
 long dummy;
};
@Choice @Autoid
struct Calculator_off_Result {
   Calculator_off_Out result;
};
@Choice @Autoid
struct Calculator Request {
```

```
add;
  Adder add In
  Adder sub In
                     sub;
  Calculator on In
                     on;
  Calculator off In off;
};
@Choice @Autoid
struct Calculator Reply {
                               add;
  Adder add Result
  Subtractor sub Result
                                sub;
  Calculator on Result
                                on;
  Calculator off Result
                                off;
  dds::rpc::RemoteException t remoteEx;
};
```

The Enhanced Service Mapping leverages the assignability rules defined in the [DDS-XTypes] specification to ensure that the topic types remain compatible in case of inheritance. A client using the base interface can invoke an operation in a service that implements a derived interface as long as the same topic names are used.

7.5.2 Mapping of Remote Exceptions for Basic and Enhanced Profiles

Erroneous conditions are reported using exception codes. All return codes defined in the DDS PIM are mapped to exceptions as per the [DDS-Cxx-PSM] and [DDS-Java-PSM] specifications. Additionally, the following remote exception codes are used to report *remote* errors. The language bindings for the remote exception codes is defined in sub clause 7.11.

```
module dds { module rpc {
  enum RemoteExceptionCode_t
  {
     REMOTE_EX_OK,
     REMOTE_EX_UNSUPPORTED,
     REMOTE_EX_INVALID_ARGUMENT,
     REMOTE_EX_OUT_OF_RESOURCES,
     REMOTE_EX_UNKNOWN_OPERATION,
     REMOTE_EX_UNKNOWN_EXCEPTION
  };
```

```
} // module rpc
} // module dds
```

The remote exception codes have the following meanings.

Remote Exception Code	Meaning
REMOTE_EX_OK	The request was executed successfully.
REMOTE_EX_UNSUPPORTED	Operation is valid but it is unsupported (a.k.a. not implemented)
REMOTE_EX_INVALID_ARGUMENT	The value of the parameter that is passed in has an illegal value. (e.g., two options active in a @Choice)
REMOTE_EX_OUT_OF_RESOURCES	The remote service ran out of resources while processing the request
REMOTE_EX_UNKNOWN_OPERATION	The operation called is unknown.
REMOTE_EX_UNKNOWN_EXCEPTION	A generic, unspecified exception was raised by the service implementation.

7.6 Discovering and Matching RPC Services

7.6.1 Client and Service Discovery for the Basic Service Mapping

The Basic Service Mapping relies on the built-in discovery provided by the underlying [DDS] compliant implementation. It does not use any extensions to the DDS discovery built-in topics.

A client comprises one (or more) DataWriter to send requests and one (or more) DataReader to receive replies. Similarly, a service implementation comprises one (or more) DataReader to receive requests and one (or more) DataWriter to send replies. The built-in publication and subscription topics are used to discover the DataWriter and DataReader at both sides.

Non-normative Note: Service discovery for the Basic Service Mapping is not robust because discovery race conditions can cause the service replies to be lost. The request-topic and reply-topic are two different RTPS sessions that are matched independently by the DDS discovery process. For this reason it is possible for the entities on the request topic to discover each other before the entities on the reply topic discover each other. If such a situation, if a client makes a request before the entities over the reply topic are fully discovered, the client may lose the corresponding replies.

7.6.2 Client and Service Discovery for the Enhanced Service Mapping

The Enhanced Service Mapping relies on the built-in discovery service provided by DDS. However, it extends the built-in publication and subscription topic data to avoid the discovery race conditions.

Non-normative Design Rationale: The discovery race condition is avoided by announcing the pair of DataReader and DataWriter endpoints (both client-side and service-side) atomically and ensuring that the discovery of entities over the reply topic is complete before a request is sent or received.

A client must ensure that the client-side DataReader has discovered the service-side DataWriter before writing a request to the service-side DataReader. This ensures that the replies received by the client-side DataReader are not discarded.

A service must ensure that service-side DataWriter has discovered the client-side DataReader before a request is accepted by the service-side DataReader. This ensures that the replies in response to a request are not discarded by the service-side DataWriter.

7.6.2.1 Extensions to the DDS Discovery Builtin Topics

The [DDS] specification includes the *DCPSPublication* and *DCPSSubscription* builtin topics and corresponding built-in data writers and readers. The data type associated with the *DCPSPublication* built-in Topic is PublicationBuiltinTopicData. The data type associated with the *DCPSSubscription* built-in topic is SubscriptionBuiltinTopicData. Both are defined in sub clause 2.1.5 of the [DDS] specification. This specification extends both PublicationBuiltinTopicData and SubscriptionBuiltinTopicData.

Non-normative Design Rationale: The extensions specified here are backwards compatible. The [RTPS] specification, which defines the serialization format of

PublicationBuiltinTopicData and SubscriptionBuiltinTopicData, defines what's called a *ParameterList* where each member in the built-in topic data is serialized using CDR but preceded by a *ParameterID* and *Length* of the serialized member. See sub clause 8.3.5.9 of the [RTPS] specification. This serialization format allows the PublicationBuiltinTopicData and SubscriptionBuiltinTopicData to be extended without breaking interoperability.

7.6.2.1.1 Extended PublicationBuiltinTopicData

This specification defines an extension to the PublicationBuiltinTopicData structure. The member types and the ParameterID used for the serialization are described below.

Member name	Member type	Parameter ID name	Paramete r ID value
service_instance_name	string<256>	PID_SERVICE_INSTANCE_NAME	0x0080
related_datareader_key	GUID_t	PID_RELATED_ENTITY_GUID	0x0081
topic_aliases	sequence <string<256>></string<256>	PID_TOPIC_ALIASES	0x0082

```
@extensibility(MUTABLE_EXTENSIBILITY)
struct PublicationBuiltinTopicDataExt : PublicationBuiltinTopicData {
   @ID(0x0054) string<256> service_instance_name;
   @ID(0x0055) GUID t related datareader key;
```

```
@ID(0x0056) sequence<string<256>> topic_aliases;
};
```

The service_instance_name is the instance name specified by the user at the service-side. If none is specified, there is no default value. Likewise, the client-side DataWriter shall not include service_instance_name.

The topic aliases are as per defined in sub clause 7.4.3. There is no default value.

The related datareader key shall be set and interpreted according to the following rules:

- When not present the default value for the related_datareader_key shall be interpreted as GUID_UNKNOWN as defined by sub clause 9.3.1.5 of the [RTPS] specification.
- The PublicationBuiltinTopicDataExt that corresponds to the client-side DataWriter used for sending requests for a service shall have the related_datareader_key set to the BuiltinTopicKey_t of the client-side DataReader used for receiving the replies.
- The PublicationBuiltinTopicDataExt that corresponds to the service-side DataWriter used for sending replies shall have the related_datareader_key set to the BuiltinTopicKey t of the service-side DataReader used to receive the requests.

7.6.2.1.2 Extended SubscriptionBuiltinTopicData

This specification defines an extension to the SubscriptionBuiltinTopicData structure. The member types and the ParameterID used for the serialization are described below:

Member name	Member type	Parameter ID name	Paramete r ID value
service_instance_name	string<256>	PID_SERVICE_INSTANCE_NAME	0x0054
related_datawriter_key	GUID_t	PID_RELATED_ENTITY_GUID	0x0055
topic_aliases	sequence <string<256>></string<256>	PID_TOPIC_ALIASES	0x0056

```
@extensibility(MUTABLE_EXTENSIBILITY)
struct SubscriptionBuiltinTopicDataExt : SubscriptionBuiltinTopicData {
    @ID(0x0054) string<256> service_instance_name;
    @ID(0x0055) GUID_t related_datawriter_key;
    @ID(0x0056) sequence<string<256>> topic_aliases;
};
```

The service_instance_name is the instance name specified by the user at the service-side. If none is specified, there is no default value. Likewise, the client-side DataReader shall not include service instance name.

The topic aliases are as per defined in sub clause 7.4.3. There is no default value.

The related datawriter key shall be set and interpreted according to the following rules:

- When not present the default value for the related datawriter_key shall be interpreted as GUID_UNKNOWN as defined by sub clause 9.3.1.5 of the RTPS specification.
- The SubscriptionBuiltinTopicDataExt that corresponds to the client-side DataReader used to receive replies shall have the related_datawriter_key set to the BuiltinTopicKey_t of the client-side DataWriter used to send the requests to the DDS-RPC Service.
- The SubscriptionBuiltinTopicDataExt that corresponds to the service-side DataReader used to write replies shall have the related_datawriter_key set to the BuiltinTopicKey t of the service-side DataWriter used to receive requests.

7.6.2.2 Enhanced algorithm for Service Discovery

The built-in DDS discovery mechanism ensures that DataWriters discover the matching DataReaders and vice versa. However to ensure robustness, service discovery must ensure that no replies are lost due to race conditions in the discovery process of the underlying DDS entities. Additional rules shall be used at the client-side DataWriter and service-side DataReader:

- The client-side DataWriter (request DataWriter) shall not send out any request to a service DataReader unless the client-side DataReader (reply DataReader) has discovered and matched the corresponding service DataWriter (reply DataWriter).
- The service-side DataReader (request DataReader) shall reject requests from a client DataWriter (request DataWriter) as long as the service-side DataWriter (reply DataWriter) has not discovered and matched the corresponding client-side DataReader (reply DataReader).

The above rules may be implemented outside "DDS layer" because no discovery algorithm modifications are required in the underlying DDS implementation to achieve "service discovery" beyond the extensions to the built-in topic data described in sub clause 7.6.2.1.

7.6.2.2.1 Client Matching

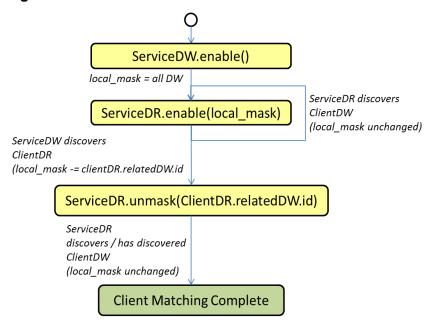


Figure 4: The service-side client matching algorithm

Figure 4 shows the client-matching algorithm executed at the service side. Client DataWriter and DataReader are discovered on the service-side using regular DDS discovery but "client matching" does not complete unless the service-side has discovered both client entities (DataReader and DataWriter). While "client matching" is still in progress, service-side does not process requests from the client. This behavior is illustrated in Figure 4 using a notional local state called <code>local_mask</code>. At the beginning, the service-side DataReader is enabled with <code>local_mask=All_DW</code> so that it does not process any the incoming requests. When the service-side DataWriter completes the discovery of a client DataReader, the service DataReader is ready to accept requests from that specific client. Therefore, it unmasks the related client DataWriter. The "client matching" algorithm completes when the service-side has discovered both client DDS Entities.

7.6.2.2.2 Service Matching

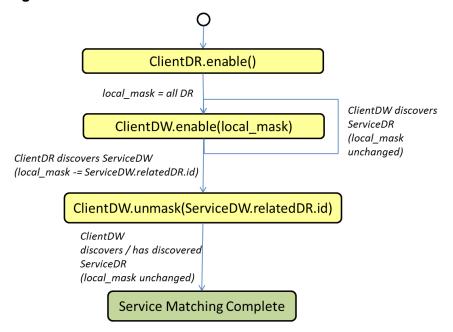


Figure 5: The client-side service matching algorithm

Figure 5 shows the service-matching algorithm executed at the client side. Service DataWriter and DataReader are discovered using regular DDS discovery but "service matching" does not complete unless the client-side has discovered both service DDS Entities (DataReader and DataWriter) and it does not send requests to the service until "service matching" completes. This behavior is illustrated in Figure 5 using a notional local state called <code>local_mask</code>. At the beginning, the client-side DataWriter is enabled <code>local_mask=All_DR</code> such that it does not send any request at all. Attempts to send requests would be queued. When the client-side DataReader completes the discovery of a service DataWriter, the client DataWriter updates the local mask so that it can send requests to the service DataReader as long as it has been discovered. The "service matching" algorithm completes when the client-side has discovered both the service end-points.

7.7 Interface Evolution

7.7.1 Interface Evolution in the Basic Service Mapping

The Basic Service Profile has limited support for interface Evolution. I.e., the interfaces used by the client and the service may not match exactly. Interface evolution is constrained by the rules described herein.

7.7.1.1 Adding/Removing an Operation

A client may use an interface that has fewer or more operations than what the service has implemented. If a client uses an interface that has fewer methods than that of the service, it is simply oblivious of the fact that the service has more capabilities than the client can use. If the client uses an interface with more operations than that of the service, invocation of an unimplemented operation shall result in REMOTE_EX_UNSUPPORTED remote exception code.

7.7.1.2 Reordering Operations and Base Interfaces

Reordering operations has no impact on the semantics of the interface because every interface has set semantics. The order in which operations are listed in an interface is irrelevant to the caller. Reordering base interfaces has no impact on the semantics of the interface.

7.7.1.3 Changing Operation Signature

The Basic Service Profile shall not support any modifications to the operation signatures.

7.7.2 Interface Evolution in the Enhanced Service Mapping

The Enhanced Service Profile supports flexible interface evolution. It is possible for a client/service pair to use different interfaces where one interface is an evolution of the other. The client may be using an old interface and the service might be using the new interface or vice versa. Interface evolution is constrained by the rules described herein.

In sub clauses that follow, I_{old} represents the old interface whereas I_{new} represents the evolved interface. The interface mapping rules in the previous sub clause are designed such that the assignability rules defined in [DDS-XTypes] will ensure seamless evolution from I_{old} to I_{new} .

Each entity is in one of the four possible roles: C_{old} , C_{new} , S_{old} , S_{new} . C_{old} is a client instance using an older version of the interface. C_{new} is a client instance using the new version of the interface. Likewise, S_{old} is the old version of service implementing the old interface whereas S_{new} is the new instance of the service implementing the new interface.

 C_{old} and S_{old} use the topic types synthesized from I_{old} whereas C_{new} and S_{new} use the topic types synthesized from I_{new} . Request_{old} and Reply_{old} are the types synthesized from I_{old} whereas Request_{new} and Reply_{new} are the types synthesized from I_{new} .

7.7.2.1 Adding a new Operation

Adding an operation to an interface will result in additional members in the synthesized topic types. C_{old} can invoke S_{new} because the additional member in Request_{new} is never populated by C_{old} . S_{new} responds with Reply_{new}, which remains assignable to Reply_{old} because the ids of members are based on md5 hash and therefore uniquely assignable to the target structure.

When C_{new} invokes S_{old} , S_{old} receives a sample with no active member because the additional member in Request_{\text{new}} has no equivalent in Request_{\text{old}}. In such cases, the service (S_{old}) returns Reply_{\text{old}} with remoteEx = REMOTE_EX_UNKNOWN_OPERATION. As the ids of the remoteEx member match in Reply_{\text{old}} and Reply_{\text{new}}, the sample is assignable and the C_{new} receives the correct remote exception code.

7.7.2.2 Removing an Operation

The case of removing an operation from an interface is quite analogous to adding an operation to an interface. When C_{old} calls S_{new} , C_{old} receives REMOTE_EX_UNKNOWN_OPERATION RemoteExceptionCode. Likewise, When C_{new} invokes S_{old} , C_{new} uses only a subset of operations supported by S_{old} .

7.7.2.3 Reordering Operations and Base Interfaces

Reordering operations has no impact on the semantics of the interface because every interface has set semantics. The order in which operations are listed in an interface is irrelevant to the caller. Due to the use of md5 hash algorithm to compute the member ids, this specification considers two interfaces equivalent as long they contain the same operations. Reordering base interfaces has no impact on the semantics of the interface.

7.7.2.4 Duck Typing Interface Evolution

Enhanced Service Profile supports "duck typing" evolution of an interface.

[Non-Normative Note: Duck typing is a style of dynamic typing in which an object's operations and properties determine the valid semantics, rather than its inheritance from a particular class or implementation of a specific interface. When two interfaces with the same name have the identical set of operations but in one interface all the operations are defined in-place whereas in the other interface one or more operations are inherited, the two (derived-most) interfaces are identical for the purpose of this specification. It is possible to specify the same topic name for two different interfaces. Therefore, as long as the topic names and type names match, the two interfaces are compatible.]

7.7.2.5 Changing Operation Signature

7.7.2.5.1 Adding and Removing Parameters

Adding and removing parameters in an operation shall break compatibility with the older interface. The <code>@final</code> annotation on the *In* and *Out* structures enforce this restriction. It is, however, possible to mark an operation <code>@mutable</code> to allow the *In* and *Out* structures to be mutable and thereby supporting extensions.

7.7.2.5.2 Reordering Parameters

Reordering parameters in an operation shall break compatibility with the older interface. The <code>@final</code> annotation on the *In* and *Out* structures enforce this restriction. It is, however, possible to mark an operation <code>@mutable</code> to allow reordering of parameters. In that case the synthesized structures (*In* and *Out*) shall be annotated <code>@mutable</code>.

7.7.2.5.3 Changing the Type of a Parameters

Changing the type of the parameters is allowed by this specification. The type assignability rules shall be as described in [DDS-XTypes].

7.7.2.5.4 Adding and Removing Return Type

Adding and removing return type shall break compatibility with the older interface. The <code>@final</code> annotation on the *In* and *Out* structures enforce this restriction. It is, however, possible to annotate an operation <code>@Mutable</code> to allow the *In* and *Out* structures to be mutable and consequently support addition or removal of return type and the interface level.

7.7.2.5.5 Changing the Return Type

Changing the type of the return value is allowed by this specification. The type assignability rules shall be as described in [DDS-XTypes].

7.7.2.5.6 Adding and Removing an Exception

This specification supports adding and removing one or more exceptions on an operation. The <code>@mutable</code> annotation on the return structure will support this interface evolution. The language binding that provides function call/return semantics may throw

REMOTE_EX_UNKNOWN_EXCEPTION if the RPC call results into an exception that client does not understand.

7.8 Request and Reply Correlation

7.8.1 Request and Reply Correlation in the Basic Service Profile

The Basic service profile uses the RequestHeader and ReplyHeader described in sub clause 7.5.1.1.1.

7.8.2 Request and Reply Correlation in the Enhanced Service Profile

To support propagation of the sample identity of a related request this specification extends the [RTPS] specification adding a new parameter id *PID_RELATED_SAMPLE_IDENTITY* with value 0x0083. This parameter may appear in the inlineQos sub-message element of the DATA sub-message (see sub clause 9.4.5.3 in [RTPS]).

The *PID_RELATED_SAMPLE_IDENTITY* shall be used for data samples sent as reply to a request. When present, it shall contain the CDR serialization of the SampleIdentity structure defined below. The RELATED_SAMPLE_IDENTITY_INVALID constant is used to indicate an invalid/non-existing sample identity.

The value of the *PID_RELATED_SAMPLE_IDENTITY* in a reply message shall be identical to the sample identity (GUID, SN) of the request sample that triggered the reply.

```
struct SampleIdentity {
    struct GUID_t writer_guid;
    struct SequenceNumber_t sequence_number;
}
```

RELATED_SAMPLE_IDENTITY_INVALID is defined as { GUID_UNKNOWN , SEQUENCENUMBER_UNKNOWN } both of which are defined in the [RTPS] specification.

7.8.2.1 Retrieve the Request Identity at the Service Side

This specification provides language bindings to retrieve the sample identity of the request in the form of a SampleIdentity object.

7.8.2.2 Retrieve the Request Identity at the Client Side

This specification provides language bindings to retrieve the related sample identity of the reply from the reply SampleInfo in the form of a SampleIdentity object.

7.8.2.3 Propagating Request Sample Identity to the Client

Before sending a reply, the service implementation needs to set the related sample identity of the reply sample. The related sample identity is the same as the identity of the request sample. This specification provides language bindings to set the related sample identity when sending the reply to a request.

7.9 Service Lifecycle

7.9.1 Activating Services

In Basic and Enhanced Service Mappings, when using the function-call style language binding, creating an instance of the Service type activates the service. Likewise, when using the request/reply style language binding, creating an instance of a Replier activates the service.

Service activation shall result in creation of the underlying DataReader and DataWriter entities and they shall be enabled. An activated service shall be discoverable.

7.9.2 Processing Requests

7.9.2.1 Processing Requests using Function-Call Style Language Binding

The function-call style language binding provides a synchronous way to receive requests and return replies. Concrete implementations of the interface operations shall be invoked as a consequence of receiving requests. The operations must return a reply consistent with the language binding.

7.9.2.2 Processing Requests using Request/Reply Style Language Binding

The request/reply style language binding provides three mutually exclusive ways to process requests.

- 1. A synchronous service listener callback can be installed during service activation. The synchronous callback must return the reply before the callback returns. It is invoked for each received request.
- 2. An asynchronous service listener callback can be installed during service activation. The asynchronous callback does not return the reply. The callback receives a handle to the Replier instance and the Replier API can be used to retrieve the requests and send the replies. Unlike synchronous Replier listener callback, the asynchronous Replier listener allows decoupling of request reception from request processing.
- 3. The Replier API may be used to retrieve the requests and send replies.

7.9.3 Deactivating Services

Deleting (subject to language binding) the service instance deactivates the service. In Java language binding, Closeable.Close() deactivates the service. In C++ language binding, the destructor of the service implementation shall deactivate the service. Deactivation shall delete the underlying DDS entities (i.e., DataReader and DataWriter only).

7.10 Service QoS

Both Basic and Enhanced Service Mappings allow QoS annotation with an interface.

7.10.1 Interface Qos Annotation

To set the specific Qos for an interface, the annotation @Qos shall be used. It is defined as follows.

```
@Annotation
local interface Qos
{
   attribute string RequestProfile;
   attribute string ReplyProfile;
};
```

The profile attributes are string URLs of the form: col>://path/resource where
protocol, ":", "//" and path are optional. Support for the file:// protocol is mandatory. If the
protocol:// is omitted, the string attributes are interpreted as if the protocol is file://

The QoS profiles are XML QoS Profiles as defined in the [DDS-LWCCM] specification.

7.10.2 Default QoS

When no QoS is specified, default QoS are in effect. The default QoS for the endpoints (DataReaders and DataWriters) are specified as follows. The users may modify the mutable QoS policies at runtime.

QoS Policy	Value
Reliability	DDS_RELIABLE_RELIABILITY_QOS
History	DDS_KEEP_ALL_HISTORY_QOS
Durability	DDS_VOLATILE_DURABILITY_QOS

7.11 Language Bindings

Figure 6 shows the relationship of select RPC entities defined by the language bindings.

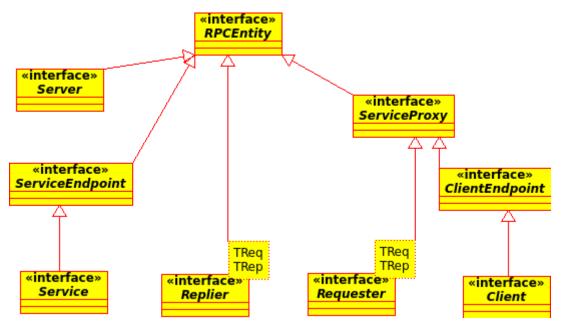


Figure 6: Inheritance Hierarchy of RPC Entities (TReq., TRep are type parameters)

7.11.1 C++ Language Binding

The normative language bindings for C++ is defined in [DDS-RPC-CXX-Github]. Alternatively, and equivalently, the machine readable files associated with this specification represent the normative language bindings for C++. The following sub clause summarizes the normative reference.

7.11.1.1 General C++ Language Binding Rules for Basic Service Mappings

7.11.1.1.1 Request-Reply Style Language Binding

The request-reply style language binding for the Basic Service Mapping shall use either the user-defined IDL structs directly or the structs synthesized from an IDL interface. The IDL shall be mapped to C++ types as defined in [IDL] (including the vendor-specific mappings for DDS v1.3). The Requester, Replier, Sample, SampleRef, WriteSample, and WriteSampleRef templates provide a uniform interface to send, receive, allocate, initialize, and destroy data.

7.11.1.1.2 Function-Call Style Language Binding

The function-call style language binding for the Basic Service Mapping shall use the structs (and unions) synthesized from the user-defined IDL interface as specified in sub clause 7.5. The topic-types shall be mapped to C++ types as per defined in [DDS-Cxx-PSM] with the following additional rules.

- 1. Each IDL interface shall maps to an abstract class named "\${interface}" and an abstract class named "\${interface}Async" in the same namespace corresponding to the module of the interface. If there is no module, no C++ namespace is generated.
- 2. Both "\${interface}" and "\${interface}Async" abstract classes shall have a public virtual destructor.

- 3. Both "\${interface}" and "\${interface}Async" abstract classes shall have public SupportType, RequestType, and ReplyType typedefs for "\${interface}Support", "\${interface}_Request", and "\${interface}_Reply" types.
- 4. The "\$ {interface}" abstract class shall contain a public AsyncInterfaceType typedef for "\$ {interface} Async".
- 5. The "\${interface}Async" abstract class shall contain a public InterfaceType typedef for "\${interface}".
- 6. The "\${interface}" abstract class shall contain public pure virtual functions for all the operations and attributes defined in the IDL using the following rules
 - a. The name of the function shall be same as the name of the IDL operation.
 - b. The number and the order of the arguments shall be as defined in the IDL.
 - c. The functions shall not have any exception specification even if the IDL operation has an exception specification. The implementation may still throw the exceptions specified by the IDL operation.
 - d. The mapping of IDL primitive and container types to C++ types is provided in sub clause 7.4.2 in [DDS-Cxx-PSM].
 - e. The mapping of *In*, *Out*, and *InOut* primitive and constructed types (e.g.,struct) is provided in in sub clause 7.4.5 in [DDS-Cxx-PSM].
 - f. Getter/Setter functions for attributes in an interface is specified in sub clause 7.4.6 in [DDS-Cxx-PSM].
 - g. IDL operations that return primitive types and enumeration types the corresponding C++ function shall return the C++ type by value as per the mapping specified in sub clause 7.4.2. in [DDS-Cxx-PSM].
 - h. IDL operations that return constructed type (e.g., struct) shall map to the first parameter with name "cxx_return" of type a T& to the function and the function shall return void.
- 7. The "\${interface}Async" abstract class shall contain asynchronous public pure virtual functions for all the operations and attributes defined in the IDL using the following rules
 - a. The name of the function shall be "\${operation} async".
 - b. The function shall accept only *In* and *InOut* parameters and shall have no *Out* parameters.
 - c. The functions shall not have any exception specification even if the IDL operation has an exception specification.
 - d. The mapping of IDL primitive and container types to C++ types is provided in sub clause 7.4.2 in [DDS-Cxx-PSM]. All the arguments shall be const.

- e. The mapping of *In* and *InOut* primitive and constructed types (e.g.,struct) is provided in in sub clause 7.4.5 in [DDs-Cxx-PSM]. All the arguments shall be const.
- f. Attribute getter functions shall take no parameters and shall return dds::rpc::future of the same type as the attribute.
- g. Attribute setter functions shall take a parameter as per specified in sub clause 7.4.6 in [DDS-Cxx-PSM]. It shall return a dds::rpc::future<void>.
- h. Operation that produce a return value in the form of a regular return (primitive or constructed type) shall return a value of dds::rpc::future of that type.
- i. Operation that produce return values with one or more Out/InOut parameters shall return a value of dds::rpc::future of "\${interface}_\${operation}_Out" type. Otherwise, it will return dds::rpc::future<void>.
- 8. Any identifier (e.g., parameter, operation name, exception, interface, module) in an IDL file that is a reserved word in C++ shall be prefixed by "cxx_".

7.11.1.2 General C++ Language Binding Rules for Enhanced Service Mappings

The request-reply style language binding for the Enhanced Service Mapping shall use either the user-defined IDL structs directly or the structs synthesized from an IDL interface. The IDL shall be mapped to C++ types as defined in [DDS-Cxx-PSM].

The function-call style language binding for the Enhanced Service Mapping shall use the mapping rules defined in sub clause 7.11.1.1.2.

7.11.1.3 Mapping of Exceptions

The C++ language binding may throw locally generated and remotely generated exceptions. As such, all DDS exceptions defined in sub clause 7.5.5 in [DDS-Cxx-PSM] are valid exceptions. Additionally, remote exception codes defined in sub clause 7.5.2 are mapped to C++ exceptions as follows.

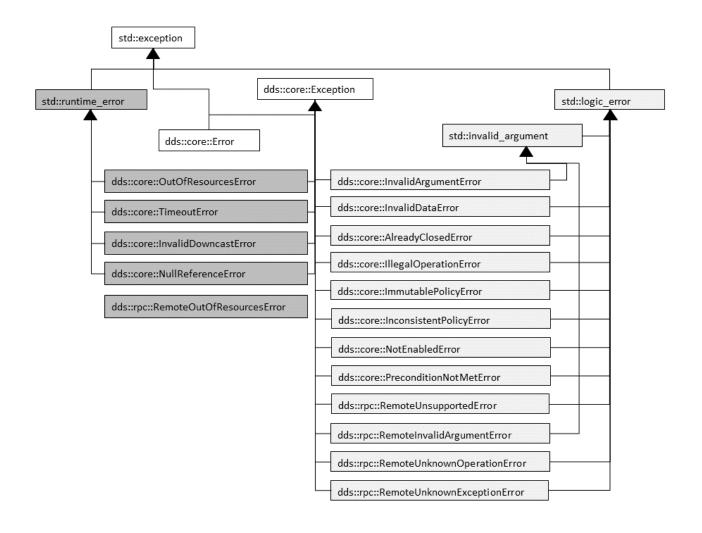


Figure 7: Inheritance Hierarchy of Local and Remote Exceptions

Specifically, the remote exception codes map to C++ exceptions as per the following table.

Remote Exception Code	RPC Exception
REMOTE_EX_OK	No exception
REMOTE_EX_UNSUPPORTED	dds::rpc::RemoteUnsupportedError
REMOTE_EX_INVALID_ARGUMENT	dds::rpc::RemoteInvalidArgumentError
REMOTE_EX_OUT_OF_RESOURCES	dds::rpc::RemoteOutOfResourcesError
REMOTE_EX_UNKNOWN_OPERATION	dds::rpc::RemoteUnknownOperationError
REMOTE_EX_UNKNOWN_EXCEPTION	dds::rpc::RemoteUnknownExceptionError

7.11.1.4 Summary of C++ Request-Reply Style Language Binding

7.11.1.4.1 **Namespaces**

The dds, and dds::rpc namespaces define the classes and functions for the request-reply style language bindings. Specifically, the language binding includes RPCEntity, Requester, Replier, ServiceProxy, ListenerBase, SimpleReplierListener, ReplierListener, SimpleRequesterListener, RequesterListener, RequesterParams, ReplierParams, future, shared_future, Sample, SampleRef, WriteSample, WriteSampleRef, LoanedSamples, SharedSamples, SampleIterator, dds_type_traits, and dds_entity_traits.

C++ request-reply language binding uses templates. Unless otherwise stated in the following sub clause, TReq represents the top-level request type and the TRep represents the top-level reply type. Depending upon the profile in use (Basic/Enhanced), the actual structure of the TReq and TRep types will vary. However, the request-reply language binding is independent of the profile in use.

7.11.1.4.2 **RPCEntity**

RPCEntity is the base abstract class extended by all the active RPC entities. It supports close() and is null() operations.

7.11.1.4.3 Requester<TReq, TRep>

A requester sends requests and receives replies. Requester is a reference type and when copied it makes a shallow copy. An instance of a Requester is configured at the time of construction using RequesterParams, which is a container of configuration parameters, such as domain participant, QoS, listeners and more.

Requester is inherently asynchronous as sending a request and receiving its corresponding reply (or replies) are separated. Requester allows listener-based, polling-based, and future-based reception of replies. SimpleRequesterListener and RequesterListener interfaces enable callback-based notification when a reply is available. On the other hand, Requester provides functions to allow polling reception of replies. Future-based notification of replies is analogous to callback-based notification, however, no request-reply correlation is necessary because every future represents a reply to a unique request.

A requester reference may be bound to a specific service instance. Requests sent through a bound requester reference shall be sent to the bound service instance only.

7.11.1.4.4 ServiceProxy

ServiceProxy class defines type-independent operations for Requester and the Client. For example, binding to a specific instance, waiting for an instance to discover, closing the service, and more. ServiceProxy shall not be instantiated directly.

7.11.1.4.5 Replier<TReq, TRep>

A replier receives requests and send replies. Replier is a reference type and it is inexpensive to copy (comparable to a pointer assignment). An instance of Replier is configured at the time of

construction using ReplierParams, which is a container of configuration parameters such as domain participant, QoS, listeners and more.

Replier allows listener-based and polling-based reception of requests.

SimpleReplierListener and ReplierListener interfaces enable call-back based notification when a request is available. On the other hand, Replier provides functions to allow polling reception of requests.

7.11.1.4.6 ListenerBase

ListenerBase is a "marker" abstract base class, which all generic listener abstract classes inherit from. It defines no member functions.

7.11.1.4.7 SimpleReplierListener<TReg, TRep>

SimpleReplierListener<TReq, TRep> is used to provide a synchronous request listener for a Replier. ReplierParams is used to pass an instance of

SimpleReplierListener<TReq, TRep>. It extends the ListenerBase abstract class and enables synchronous processing of the requests. I.e., the callback provides the request object and expects the reply as the return value.

7.11.1.4.8 ReplierListener<TReq, TRep>

ReplierListener<TReq, TRep> interface is used to provide an asynchronous request listener for a Replier. It is passed to the Replier constructor through ReplierParams. It extends ListenerBase interface and enables asynchronous processing of the requests. I.e., the callback provides the Replier object and returns void.

7.11.1.4.9 SimpleRequesterListener<TRep>

SimpleRequesterListener<TRep> abstract class is used to receive notifications of arrival of replies. It is used to configure a Requester through RequesterParams. It extends ListenerBase and enables processing of replies. I.e., the callback provides access to the reply sample and returns void.

7.11.1.4.10 RequesterListener<TReq, TRep>

RequesterListener<TReq, TRep> interface is used to receive notification of reply arrival. It is used to configure a Requester through RequesterParams. It extends ListenerBase and enables processing of replies. I.e., the callback provides the replier object and returns void.

7.11.1.4.11 RequesterParams

RequesterParams is a valuetype that serves as a container of configuration parameters of a Requester. It is designed to mimic the named-parameters feature available in some programming languages, which improves readability.

7.11.1.4.12 ReplierParams

ReplierParams is a valuetype that serves as a container of configuration parameters of a Replier. It is designed to mimic the named-parameters feature available in some programming languages, which improves readability.

7.11.1.4.13 future<T>

future<T> provides a mechanism to access the result of an asynchronous operation. It transports results (including exceptions) across an asynchronous boundary. In C++11 and C++14 environments, dds::rpc::future<T> is a typedef for std::future<T>. Compiler prior to C++11, dds::rpc::future<T> shall provide the same API as std::future<T> in C++11. Future is not copyable but it is movable.

7.11.1.4.14 shared_future<T>

shared_future<T> is closely related to future<T> and the only difference is that shared future<T> is copyable and movable.

7.11.1.4.15 **Sample<T>**

Sample<T> is a valetype that combines a value of type T and a value of type SampleInfo. Sample is conceptually immutable.

7.11.1.4.16 **SampleRef<T>**

SampleRef<T> is a reference type that combines a value of type T and a value of type SampleInfo. Copying SampleRef<T> makes a shall copy.

7.11.1.4.17 WriteSample<T>

WriteSample<T> is a valuetype that combines a value of type T and a value of type dds::SampleIdentity. The user populates the value of T and the middleware populates the value of dds::SampleIdentity. When a request is sent as a WriteSample, upon function return, the WriteSample.identity() uniquely identifies the request sent.

7.11.1.4.18 WriteSampleRef<T>

WriteSampleRef<T> is a reference type, which groups a reference to T and a value of type dds::SampleIdentity. The user populates the value of T and the middleware populates the value of dds::SampleIdentity. When a request is sent as a WriteSampleRef<T>, upon function return, the WriteSample.identity() uniquely identifies the request sent.

7.11.1.4.19 LoanedSamples<T>

LoanedSamples<T> is conceptually a container of loaned Sample<T> from the middleware. LoanedSamples<T> is not copyable but it is movable. LoanedSamples<T>::value_type is SampleRef<T>. Upon destruction, LoanedSamples<T> returns the loaned samples to the middleware.

7.11.1.4.20 SharedSamples<T>

SharedSamples<T> is container that contains loaned samples from the middleware but the SharedSamples<T> object may be copied in the application space. All copies of a SharedSamples<T> refer to the same set of loaned samples. SharedSamples<T>::value type is SampleRef<T>. Upon destruction of the last

SharedSamples<T>, the underlying loaned samples are returned to the middleware. Note that SharedSamples<T> can be obtained from LoanedSample<T> but not vice versa.

7.11.1.4.21 SampleIterator<T>

SampleIterator<T> is a random-access iterator over LoanedSamples<T> and SharedSamples<T>. SampleIterator<T>::value_type is a SampleRef<T>.

7.11.1.4.22 dds_type_traits<T>

dds_type_traits<T> is a collection of meta-functions that given a type T, provides commonly needed dependent types, such as a DataReader for T, DataWriter for T, Sample<T>, LoanedSamples<T>, etc. The primary use of dds_type_traits is to provide a consistent syntax to refer to the dependent types irrespective of the DDS C++ language binding.

7.11.1.4.23 dds_entity_traits

dds_entity_traits abstracts over the DDS entity types and provides consistent syntax to get DDS entity types irrespective of the DDS C++ language bindings. (e.g., DomainParticipant, Publisher, Subscriber, DataReaderQos, and DataWriterQos)

7.11.1.5 Summary of C++ Function-Call Style Language Binding

Service, ServiceEndpoint, Server, Client, and ClientEndpoint classes are specific to the function-call style language binding and are described below.

7.11.1.5.1 **Service**

Service is a reference type and accepts a reference to the service implementation. A Service instantiates the underlying DDS entities and makes the service discoverable. Every Service inherits from ServiceEndpoint. A Service may belong to only one Server.

7.11.1.5.2 **ServiceEndpoint**

A ServiceEndpoint provides type-independent functions to manage a service (e.g., pause, resume, close, etc.) A ServiceEndpoint shall not be instantiated directly; it can be obtained from a Service object. ServiceEndpoint is a reference type.

7.11.1.5.3 **Server**

A Server is a container of one or more Services. Server.run() function begins dispatching the requests to the Service implementation. Server is a reference type.

7.11.1.5.4 Client

Client is a reference type and provides functions to invoke operations on a remote service synchronously and asynchronously. A Client instantiates the underlying DDS entities and makes them discoverable. Every Client inherits publicly from "\${interface}", "\${interface}Async", and ClientEndpoint (public virtual).

7.11.1.5.5 ClientEndpoint

A ClientEndpoint provides functions to obtain the underlying DDS entities at the client side. ClientEndpoint inherits from ServiceProxy. A ClientEndpoint shall not be instantiated directly; it can be obtained from a Client object.

7.11.2 Java Language Binding

The normative language bindings for Java is defined in [DDS-RPC-Java-Github]. Alternatively, and equivalently, the machine readable files associated with this specification represent the normative language bindings for Java. The Java language binding shall use IDL type mapping as per [DDS-Java-PSM].

The following sub clauses describe the entities that are either different or not described in the C++ language bindings.

7.11.2.1 Mapping of Exceptions

7.11.2.2 Summary of Java Request-Reply Style Language Binding

7.11.2.2.1 Packages

The org.omg.dds, and org.omg.dds.rpc packages define the interfaces for the request-reply style language binding. Specifically, the language binding includes Requester, Replier, ServiceProxy, RPCEntity, RPCRuntime, SimpleReplierListener, ReplierListener, SimpleRequesterListener, RequesterParams, ReplierParams, Future, FutureCompletionListener, Sample, and Sample.Iterator.

7.11.2.2.2 **RPCEntity**

RPCEntity is the base interface extended by all the active entities. It inherits from the DDSObject interface defined in [DDS-Java-PSM] and java.io.Closeable. Its purpose is to provide quick access to the RPCRuntime object.

7.11.2.2.3 **RPCRuntime**

RPCRuntime is the only abstract class with placeholder implementation in the Java language binding. It extends ServiceEnvironment abstract class defined in [DDS-Java-PSM]. Its purpose is to provide access to the RPCRuntime singleton, which serves as a factory for all other entities.

7.11.2.2.4 Future<T>

The rpc.Future<T> interface extends the java.util.concurrent.Future<T> interface and adds a single operation to specify a FutureCompletionListener.

7.11.2.2.5 FutureCompletionListener<T>

The FutureCompletionListener allows callback notification when the corresponding future becomes ready.

7.11.2.2.6 **Sample<T>**

The rpc.Sample<T> interface extends dds.sub.Sample<T> interface and defines two additional operations to retrieve the SampleIdentity and the related sample identity, if any.

7.11.2.2.7 Sample.Iterator

The Sample.Iterator interface is the same as in [DDS-Java-PSM].

7.11.2.3 Summary of Java Function-Call Style Language Binding

Function-Call style language binding in Java shall define the same entities as that of C++. See sub clause 7.11.1.5.

7.11.3 Non-normative Examples

See robot_reqrep.cxx and robot_func.cxx in [DDS-RPC-CXX-Github] for C++. See test_robot.java in [DDS-RPC-Java-Github] for Java.