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**RAAML**

OMG RISK ANALYSIS  
AND ASSESSMENT  
MODELING LANGUAGE

# Risk Analysis and Assessment Modeling Language (RAAML) Libraries and Profiles

Version 1.~~1~~ *Beta 2*

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## Preface

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# 1. Scope

## 1.1 Introduction

There are two parts to this specification, one being normative and another informative. The normative part is:

- The Risk Analysis and Assessment Modeling Language (RAAML) Library and Profile (this document) defines concepts and relationships for capturing safety and reliability aspects of a system in the library and profile form.

The informative part is:

- The RAAML Example Model, Annex A (see document ad/2020-11-01), which illustrates practical usages of RAAML.

## 1.2 RAAML Background

Model-Based Systems Engineering (MBSE) is gaining popularity in organizations creating complex systems where it is crucial to collaborate in a multi-disciplinary environment. SysML, being one of the key MBSE components, has a good foundation for capturing requirements, architecture, constraints, views, and viewpoints. However, SysML does not provide the constructs to capture safety, reliability or security information in the system model. A group of industry experts at the OMG has been working since 2016 to define a new specification providing the necessary capabilities.

The need for a standardized UML profile/library for addressing safety, reliability and security aspects emerged long ago. Working group members have seen multiple commercial-grade model-based safety, reliability and security solution implementations being developed during the recent years and successfully used in practice. While the various safety, reliability and security implementations may fit the needs for a specific purpose, there are many instances where information needs to be traced and shared across multiple organizations. These inconsistent model-based solutions prohibit direct model sharing between organizations and across the various tools. One of the key goals for the working group is to reconcile these different approaches to alleviate the industry from repeatedly formulating safety, reliability and security constructs in their tools. The specification provides the modeling capabilities for tool vendors to build safety, reliability and security modeling tools that provide traditional representations (e.g., trees, tables, etc.) while using a modern model-based approach.

This RAAML 1.1 specification defines extensions to SysML needed to support safety, reliability and security analysis. It describes:

- the core concepts and shows how the simple concepts are powerful enough to unite all safety, reliability and security information across a variety of analysis methods
- the approach to automating several safety and reliability analyses, which is built on leveraging existing SysML functionalities to ensure that the profile and library is usable with existing tooling
- specific safety and reliability analysis methods and application domains that are supported
  - Failure Mode and Effect Analysis (FMEA)
  - Fault Tree Analysis (FTA)
  - Systems Theoretic Process Analysis (STPA)
  - Goal Structuring Notation (GSN)
  - ISO 26262 Road Vehicles - Functional Safety
  - Reliability Block Diagrams (RBD)
- extension mechanisms that are typically needed by the industry to apply the specification in practice

## 1.3 Intended Usage

The RAAML specification provides the foundation for conducting various safety and quality engineering activities including safety and reliability analysis methods. Besides the method support, linkages to the SysML model-of-interest

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are provided, enabling integration with and traceability to the analyses. The specification can be used for modeling safety, reliability and security aspects directly in the model or as a standard language to import and export from external safety and reliability tools.

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The organization of RAAML facilitates tailoring the methodologies to specific engineering domains and industries to support the various assessment and certification agencies.

### 1.4 Related Documents

The specification is delivered as a set of related documents. The primary normative document is this document, while a set of additional machine-readable documents is provided to specify the UML profiles and model libraries, specified by this standard.

For each safety/reliability domain, supported by this standard (FMEA, FTA, ISO-26262, STPA and RBD) there is a pair of profile and library.

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In addition to that there is a pair of profile and library for the concepts used in multiple domains – General and General Security; and a pair of profile and library for the very core concepts that might be useful for the implementers of other standards in the safety/reliability/security domain.

GSN stands separately, as it is an add-on, which can be used with any of the aforementioned domains for additional substantiation of the safety models. It consists of just the profile; no library is necessary. The GSN profile only covers the GSN version 2 standard core notation.

Non-normative examples document is also provided, illustrating how to apply RAAML for capturing safety and reliability data.

**Table 1.1 – Table of Related Documents**

Document Number	Description	File Name	Nor-mative	Machine Readable
<del>ptc/24-03-04</del>	Core portion of the RAAML.	CoreRAAML.xmi	Y	Y
<del>ptc/24-03-05</del>	Library portion of the RAAML.	CoreRAAMLLib.xmi	Y	Y
<del>ptc/24-03-06</del>	General portion, shared across domains of the RAAML.	GeneralRAAML.xmi	Y	Y
<del>ptc/24-03-07</del>	General Library portion, shared across domains of the RAAML.	GeneralRAAMLLib.xmi	Y	Y
<del>ptc/24-03-08</del>	Goal Structuring Notation profile.	GSN.xmi	Y	Y
<del>ptc/24-03-09</del>	FMEA portion of the RAAML.	FMEA.xmi	Y	Y
<del>ptc/24-03-10</del>	FMEA Library portion of the RAAML.	FMEALib.xmi	Y	Y
<del>ptc/24-03-11</del>	FTA (Fault Tree Analysis) portion of the RAAML.	FTA.xmi	Y	Y
<del>ptc/24-03-12</del>	FTA (Fault Tree Analysis) Library portion of the RAAML.	FTALib.xmi	Y	Y
<del>ptc/24-03-13</del>	ISO26262 Functional Safety Standard portion of the RAAML.	ISO26262.xmi	Y	Y
<del>ptc/24-03-14</del>	ISO26262 Functional Safety Standard Library portion of the RAAML.	ISO26262Lib.xmi	Y	Y
<del>ptc/24-03-15</del>	STPA (Systems Theoretic Process Analysis) portion of the RAAML.	STPA.xmi	Y	Y
<del>ptc/24-03-16</del>	STPA (Systems Theoretic Process Analysis) Library portion of the RAAML.	STPALib.xmi	Y	Y
<del>ptc/24-03-17</del>	Security profile portion of the RAAML.	GeneralRAAMLSecurity.xmi	Y	Y
<del>ptc/24-03-18</del>	Security library portion of the RAAML.	GeneralRAAMLSecurityLib.xmi	Y	Y

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ptc/24-03-19	RBD (Reliability Block Diagram) profile portion of the RAAML	RBD.xmi	Y	Y
ptc/24-03-20	RBD (Reliability Block Diagram) library portion of the RAAML	RBDLib.xmi	Y	Y
ptc/24-03-21	MagicDraw model from which all XMIs and images were produced	Safety and Reliability Library and Profile.583.mdzip	N	Y
ptc/21-11-22	Risk Analysis and Assessment Modeling Language 1.1 Examples	OMG RAAML Examples 1.1.docx	N	N

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## 2. Conformance

RAAML specifies two types of conformance.

- Type 1 Conformance: RAAML model interchange conformance. A tool demonstrating model interchange conformance can import and export conformant XMI for all valid RAAML models.
- Type 2 Conformance: RAAML View specification conformance. A tool demonstrating view specification conformance shall implement the views specified in RAAML specification.

A tool vendor may choose to implement one method supported by the specification (FMEA, FTA, STPA, GSN, ~~ISO 26262~~ or RBD) and claim conformance to it.

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## 3. References

### 3.1 Normative References

The following normative documents contain provisions which, through reference in this text, constitute provisions of this specification. For dated references, subsequent amendments to, or revisions of, any of these publications do not apply.

### 3.2 OMG Documents (Normative References)

- Unified Modeling Language (UML), 2.5.1, December 2017, <https://www.omg.org/spec/UML>
- Object Constraint Language (OCL), 2.4, February 2014, <https://www.omg.org/spec/OCL>
- System Modeling Language (SysML), 1.6, December 2019, <https://www.omg.org/spec/SysML>
- XMI Metadata Interchange (XMI), 2.5.1, June 2015, <https://www.omg.org/spec/XMI>

### 3.3 Other Normative References

- IEC 60812 for FMEA, <https://webstore.iec.ch/publication/26359> [accessed on October 28, 2020]
- IEC 61025 for FTA, <https://webstore.iec.ch/publication/4311> [accessed on October 28, 2020]
- IEC 61508:2010 for Functional safety of electrical/electronic/programmable electronic safety-related systems, <https://webstore.iec.ch/publication/22273> [accessed on October 28, 2020]
- International Standardization Organization. ISO PAS 21448:2019(en) Road vehicles – Safety of the intended functionality, <https://www.iso.org/standard/70939.html> [accessed on October 28, 2020]
- ~~International Standardization Organization. ISO 26262-1:2018 Road vehicles Functional safety - Part 1, Part 3. <https://www.iso.org/standard/68383.html> [accessed on June 19, 2023]~~
- N. Leveson and J. Thomas, STPA Handbook, Boston, MA: MIT, March 2018, [https://psas.scripts.mit.edu/home/get\\_file.php?name=STPA\\_handbook.pdf](https://psas.scripts.mit.edu/home/get_file.php?name=STPA_handbook.pdf) [accessed on October 28, 2020]
- GSN specification 2, document number SCSC-141B <https://scsc.uk/gsn?page=gsn%202standard> [accessed on September 29, 2021]
- GSN metamodel mapping to SACM, [https://scsc.uk/file/gc/GSN\\_metamodelV2-2-1210.pdf](https://scsc.uk/file/gc/GSN_metamodelV2-2-1210.pdf) [accessed on October 7, 2021]
- ~~IEC 61078:2016, Reliability Block Diagrams, <https://webstore.iec.ch/publication/25647> [accessed on October 21, 2023]~~

### 3.4 Informative References

- ISO/IEC 15288:2015, Systems Engineering - Systems Life Cycle Processes, [https://www.iso.org/iso/home/store/catalogue\\_tc/catalogue\\_detail.htm?csnumber=63711](https://www.iso.org/iso/home/store/catalogue_tc/catalogue_detail.htm?csnumber=63711) [accessed on October 28, 2020]
- International Council On Systems Engineering (INCOSE), Systems Engineering Handbook V4, 2015, <https://www.incose.org/products-and-publications/se-handbook> [accessed on October 28, 2020]
- National Institute of Standards and Technology, "NIST/Sematech Engineering Statistics Handbook", <https://www.itl.nist.gov/div898/handbook/> [accessed on October 21, 2023]

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## 4. Acknowledgements

The following companies and organizations submitted or supported parts of the original version of this standard:

### Industry

- Dassault Systemes (submitter)
- Ford Motor Company (submitter)
- The Aerospace Corporation

### Government

- NASA/Jet Propulsion Laboratory
- Commissariat à l'énergie atomique
- German Aerospace Center
- National Institute of Advanced Industrial Science and Technology (AIST)

### Vendors

- No Magic owned by Dassault Systemes

### Academia

- Massachusetts Institute of Technology

### Liaisons

- Gesellschaft für Systems Engineering (submitter)
- MACE
- Assystem

The following persons were members of the team that designed and wrote this International Standard: Achim Weiss, Andreas Knapp, Andrius Armonas, Annelisa Sturgeon, Axel Berres, Christian Lalitsch-Schneider, Christoph Barchanski, Christopher Davey, Damun Mollahassani, Dave Banham, Edith Holland, Geoffrey Biggs, George Walley, Ilse Adamek, Jean-Francois Castet, Jianlin Shi, John Thomas, Kyle Post, Laura Hart, Manfred Koethe, Mark Sampson, Matthias Nagorni, Myron Hecht, Nataliya Yakymets, Rajiv Murali, Regis Casteran, Sarra Yako, Stephan Boutenko, Thomas Krynicki, Tim Weilkiens, Tomas Juknevičius, Vanessa Sehon, Victor Arcos Barraquero, Yan Liu.

For the final edition of the standard, the following people contributed: Andrius Armonas, Axel Berres, Dave Banham, Kyle Post, George Walley, Tomas Juknevičius.

## 5. Terms and Definitions

New terms and definitions have been required to create this specification. They are listed in the table below.

**Table 5.1 – Description of terms and definitions used in this specification**

Situation	<p>A situation describes a set of situation occurrences of some type. The system, place, time, and state parameters are described by classifiers rather than individual descriptions. A situation occurrence is a system being in a given place at given time and in a given state.</p> <p>For example, “Boeing 747 with S/N 12305 is being refueled at Gate 7 of Amsterdam Schiphol at 11:45 on Monday, 30th of July 2018.”</p>
Causality	<p>Identifies cause-effect relationship between two situations. Causality could be direct (non-conditional), conditional, probabilistic or any other inter-situation relationship, defined by the user. Multiple situations can cause one situation and vice versa - one situation can cause multiple other situations.</p> <p>For example, a car in frequent contact with salt, causing safety-critical parts to corrode, which causes leaks in the brake line, causing the brakes to fail, causing a car accident, causing a passenger injury.</p>
Relevant To	<p>The Relevant To relationship is used to link situations to system model elements to provide context and relevance for the Situation.</p> <p>For example, in an insulin pump, a Situation where the insulin pump cannot be charged would be related to the main battery element in the system model.</p>
Controlling Measure	<p>A measure taken to address (mitigate severity, reduce probability of occurrence, increase probability of detection) a potential or real adverse situation.</p>

## 6. Acronyms and Abbreviations

For the purposes of this specification, the following List of acronyms and abbreviations apply.

**Table 6.1 – Description of acronyms used in this specification**

ASIL	Automotive Safety Integrity Level
<u>CDF</u>	<u>Cumulative Distribution Function</u>
DET	Detectability
FMEA	Failure Mode and Effect Analysis
FTA	Fault Tree Analysis
GSN	Goal Structuring Notation
HARA	Hazard Analysis and Risk Assessment
HAZOP	A hazard and operability study
MBSE	Model-Based Systems Engineering
<u>MTBF</u>	<u>Mean Time Between Failures</u>
<u>MTTF</u>	<u>Mean Time to Failure</u>
<u>MTRR</u>	<u>Mean Time to Restore</u>
ISO	International Standardization Organization
OCC	Occurrence
OMG	Object Management Group
<u>PDF</u>	<u>Probability Density Function</u>
RAAML	Risk Analysis and Assessment Modeling Language
<u>RBD</u>	<u>Reliability Block Diagram</u>
RPN	Risk priority number
SEV	Severity
STPA	Systems Theoretic Process Analysis
SysML	Systems Modeling Language
UAF	Universal Architecture Framework
UML	Unified Modeling Language

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## 7. Additional Information (non-normative)

### 7.1 Language Architecture

The RAAML specification reuses a subset of UML 2.5.1 and SysML 1.6 and provides additional extensions needed to address the Safety and Reliability for UML RFP (ad/2017-03-05) requirements. Those requirements form the basis for this specification. This document specifies the language architecture in terms of UML 2.5.1 and SysML 1.6. It explains the design principles and how they are applied to implement RAAML.

### 7.2 Philosophy

The RAAML working group uses a library approach heavily with a light UML profile support. Using model libraries has several significant benefits compared with implementing everything in a profile:

- It makes use of the full UML structural modeling capabilities instead of just using metamodeling, which are further limited by the UML prescriptions for stereotyping. The tools with good support for UML/SysML class and composite structure diagrams can make use of their existing generic functionality for modeling safety and reliability aspects of a system.
- It enables end users to extend the libraries and profiles provided by the specification because safety and reliability practices vary across domains (automotive, aerospace, nuclear, etc.) and organizations.
- Finally, it is typically easier to make modifications and extensions to model libraries than to profiles, as extensions occur at lower metalevels.

The RAAML development uses a model-driven approach. A simple description of the work process is:

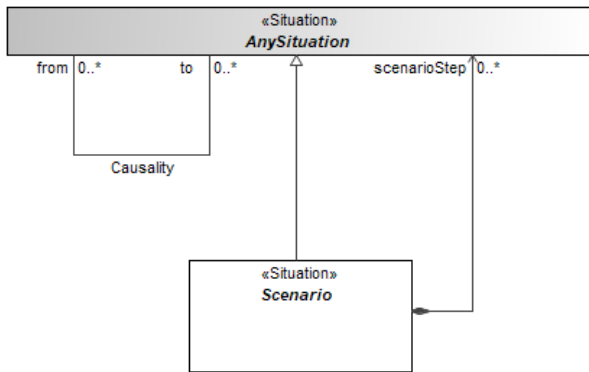
- The specification is generated from the UML model used to describe RAAML. This approach allows the working group members to concentrate on architecture issues rather than documentation production. The UML tool automatically maintains consistency.

### 7.3 Principles of Creating, Editing, and Displaying of Composite Situations in Diagrammatic and Tabular Views

This standard uses UML/SysML structural modeling capabilities to capture safety and reliability data. The safety and reliability data are captured by a collection of scenarios and situations as shown in

Figure 7.1.





**Figure 7.1 – Fundamental situation modeling principles**

Complex scenarios can be built by inheriting from other scenarios and composing other situations as parts. Scenarios defined in libraries of this standard provide template scenarios from which to be inherited from. This way multilevel composite situations can be built.

- Situations are UML Classes, SysML Blocks.
- Scenario steps are captured using SysML parts - UML Properties with aggregation set to composite, and type set to sub-situation (which is UML Class, SysML Block); usually an association is also created for this property.
- Situation attribute values are captured using value properties - UML properties with type describing possible values (which is UML DataType, SysML ValueType) with the value specified in the defaultValue field.

When inheriting from library situations the properties of the user defined situations redefine or subset the properties of the library situation.

Note that user’s model can have additional properties (including sub situations, and attributes and other kinds of properties), beyond those defined in the library. However, from the viewpoint of this standard, they carry user-specific extensions and are not relevant.

Situation in the user model can be inherited from the situation in the standard library indirectly through intermediate situations. This can be used to capture generality/specificity between the real-world situations being described and introduce user-specific library extensions.

Creation and Displaying of situation and scenario models can be done in diagrams, usual for UML/SysML tools, e.g., Class or Block Definition and Composite Structure or Internal Block diagrams. This suits rather well for the safety and reliability domains, which are used to graphical information input such as Fault Tree Analysis and Reliability Block Diagrams. However, users of many safety and reliability domains such as FMEA, STPA or ISO26262 are accustomed to tabular information input. Therefore, the principles of how these models can be described in a tabular format are explained in section §7.3.2.

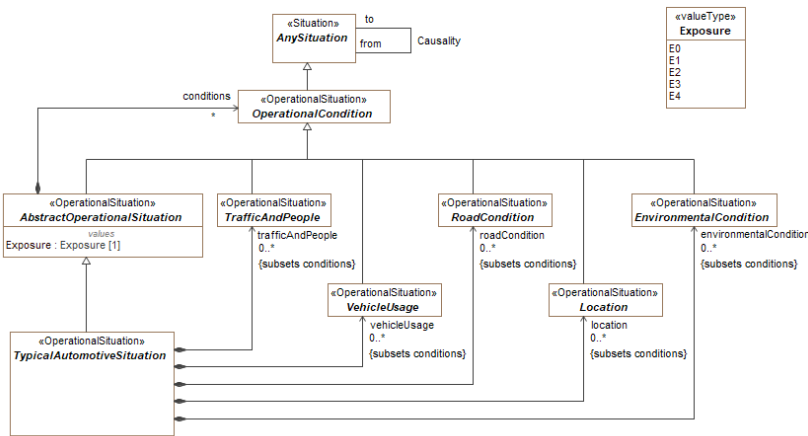
**Commented [AA11]:** RAAML11-17

**Deleted:** This suits rather well for the safety and reliability domains, which are used to graphical information input such as Fault Tree Analysis.

### 7.3.1 Diagrammatic Situation Specification

Taking the operational situation TypicalAutomotiveSituation from ISO26262 library as an example, here is how the situation “Highway Driving Straight as Speed” would be defined in a diagram.

The ISO26262 library shown in (Figure 7.2) stipulates, that TypicalAutomotiveSituation is described by specifying trafficAndPeople, vehicleUsage, roadCondition, location, and environmentalCondition sub-situations and an Exposure attribute.



**Figure 7.2 – Typical Automotive Situation definition in the ISO26262 Library**

The “Highway Driving Straight at Speed” situation, in the user model (Figure 7.3) specifies, that Exposure level is E4 (chosen from the level enumeration defined in the library), trafficAndPeople is “Traffic Free Flow” (another situation defined by the user or coming from a library of operational conditions), the vehicleUsage is “Driving at Speed”, location is “City Roads” and “Highway” (two values), while roadCondition and environmentalCondition are left unspecified.

Note that:

- a) The scenario and sub-situations are inherited from the situations defined in the library.
- b) Exposure, which is a value attribute (i.e., an attribute, whose type is not a situation, but some data type instead a numeric or enumerated value) is specified by redefining a library attribute and specifying a default value.
- c) The trafficAndPeople and vehicleUsage attributes, which specify sub-situations, are redefining corresponding library attributes, and specifying a different type. The normal rules for UML attribute redefinition apply, i.e., redefined attribute type must be narrower than the parent attribute type.
- d) The roadCondition and environmentalCondition are not redefined, therefore they are left unspecified. The attributes type remains the maximally wide, library type (“RoadCondition” and “EnvironmentalCondition” library types).
- e) Two values are being specified for location attribute. Therefore, two attributes location1 and location2 are defined in the situation. These attributes are sub-setting the parent location attribute instead of redefining, as in case 3 above. Note that, according to UML rules, names of the sub-setting attributes are not regulated and therefore they can be anything. However, it is strongly recommended that the tool vendor adopt some intuitive, user-friendly naming scheme like parent\_attribute\_name+number.

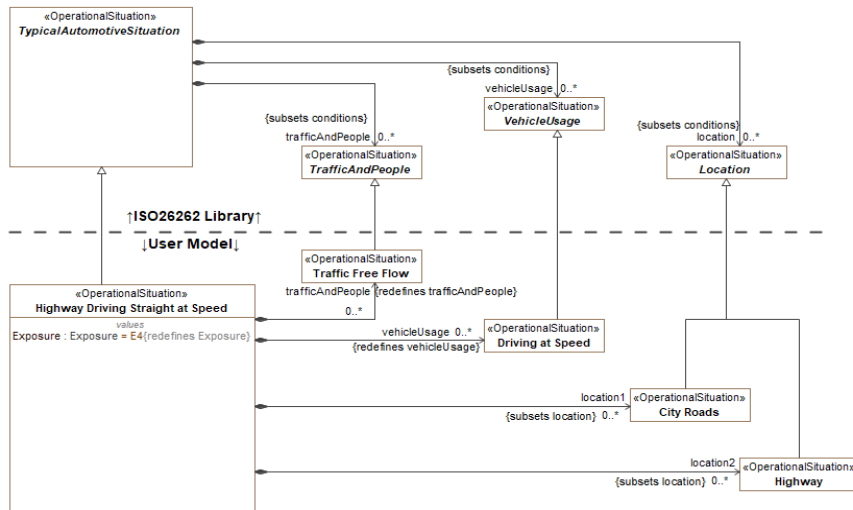


Figure 7.3 – User Model Defining Operational Situation “Highway Driving Straight at Speed”

### 7.3.2 Tabular Situation Specification

The same TypicalAutomotiveSituation, defined by the ISO26262 library and again shown in Figure 7.2, can also define a table format for entering automotive situation user model data in a tabular format.

The table for specifying typical automotive situations comprises the main Name column for defining the situation itself, plus one column per each attribute. A table for typical automotive situations, as defined by TypicalAutomotiveSituation library situation class would then have columns for Exposure, vehicleUsage, trafficAndPeople, location, roadCondition, and environmentalCondition. The column’s name does not need to follow library attributes strictly. They can be beautified, for the sake of user-friendliness. It is important that when the user adds or edits rows in this table, the underlying model data must be created in accordance with the chapters above.

The table below (Table 7.1) shows the same “Highway Driving Straight as Speed” situation defined in tabular format as in the previous chapter. Therefore, the underlying UML model structures must be the same as those shown in diagrammatic format (Figure 7.1).

Table 7.1 – Table for Specifying Operational Situations with Situation “Highway Driving Straight at Speed” Defined

#	Name	Exposure	Vehicle Usage	Traffic and People	Location	Road Condition	Environmental Condition
1	Highway Driving Straight at Speed	E4	Driving at Speed	Traffic Free Flow	Highway, City Roads		
1.1	Highway Driving Straight at Speed, Dangerous Conditions	E3	Driving at Speed	Traffic Free Flow	Highway, City Roads	Wet, Ice	Reduced Visibility

A typical safety and reliability domain such as ISO26262 will then use multiple tables, one for each of the structures defined in the library for that domain.

The tables can have additional columns, at the vendor’s discretion, for specifying additional data about the situation, being described in a row. An example of such data could be a description (realized by e.g., UML Comment) of the situation.

Sub-classing by using a generalization relationship between situations can be expressed in tabular format, using hierarchical indented text in table row. In the above table, the “Highway Driving Straight at Speed, Dangerous Conditions” situation is a subclass of the “Highway Driving Straight at Speed” situation. Therefore, a generalization relationship is created between the two in the model. Note that the more specific situation can narrow down the field types of the parent. In this example, the sub-classing situation provides additional data for road and environmental conditions by using attributes and redefining attributes from the library. Using UML redefinition overrides the parent exposure to E3. The vehicle use, traffic and people, and location settings are inherited from the parent and do not require additional model elements.

In case of multiple composition levels between the situations defined in the library, it is possible to show multi-level composite situation data in a single table instead of the multiple interrelated tables by using hierarchical grouped column approach.

An example of using this hierarchical approach is shown for the main situation - HazardousEvent - in the library for ISO26262 standard (Figure 7.4):

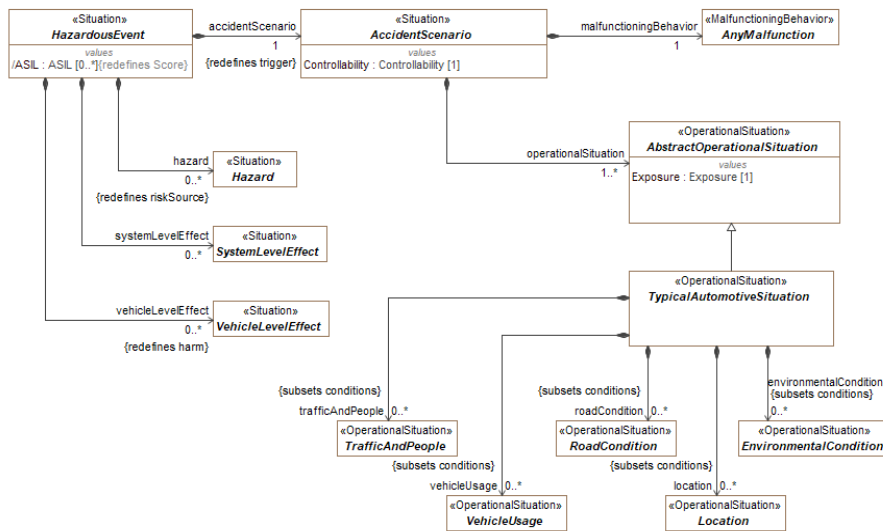


Figure 7.4 – HazardousEvent Definition in the ISO26262 Library

The HazardousEvent comprises sub-situations hazard, systemLevelEffect, vehicleLevelEffect which are elementary and an accidentScenario which is a composite sub-situation. AccidentScenario is composed of the elementary malfunctioningBehavior and operationalSituation. OperationalSituation is composed of a multitude of operational condition sub-situations vehicleUsage, trafficAndPeople, location, roadCondition, and environmentalCondition.

If tabular format is used for entering this information, there could be 3 simple tables:

1. Table for operational situations, having columns for vehicleUsage, trafficAndPeople, location, roadCondition, and environmentalCondition.
2. Table for accident scenarios, having columns for malfunctioningBehavior and operationalSituation.

- 3. Table for hazardous events, having columns for hazard, systemLevelEffect, vehicleLevelEffect, and accidentScenario.

Alternatively, all this data can be entered in a single table, as shown in Table 7.2:

- 1. Table for hazardous events, having columns for **hazard**, **systemLevelEffect**, **vehicleLevelEffect**, and an **accidentScenario**.

- 1.1. Accident scenario is a column group, comprising of columns **malfunctioningBehavior** and **operationalSituation**.

- 1.1.1. Operational situation is a column group comprising of columns **vehicleUsage**, **trafficAndPeople**, **location**, **roadCondition**, and **environmentalCondition**.

**Table 7.2 – Hazardous Event Table with Grouped Columns**

Name	Hazard	Accident Scenario							System Level Effect	Vehicle Level Effect
		Malfunctioning Behavior	Operational Situation					Controllability		
			Vehicle Usage	Traffic and People	Location	Road Condition	Environmental Condition			

Note – some columns (like ASIL level, or names of accident scenario, operational situation) have been skipped in the table for compactness reasons; in the actual tool that is not limited by page width they would be present.

## 8. Diagram Legend (non-normative)

The section 9 is comprised of diagrams that represent elements from the RAAML 1.0 specification. The diagrams are color-coded to help the reader to understand the model easier. Please refer to the legend in Figure 8.1 to understand the diagrams.



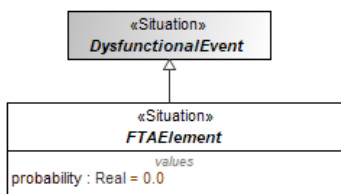
Diagram shapes color-coded using gray color represent elements belonging to other packages than the one being specified in the current diagram.



Diagram shapes color-coded using white color represent elements belonging to packages that are being specified in the current diagram.

**Figure 8.1 – Legend of color codes**

An example in Figure 8.2 demonstrates how legends are used. Elements that belong to FTA (Fault Tree Analysis) library will be represented in white color in diagrams which belong to FTA method specification. Other elements like DysfunctionalEvent will be represented in gray since they belong to the General part of the specification.



**Figure 8.2 – An example of using a legend**

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## 9. Risk Analysis and Assessment Modeling Language (RAAML) Library and Profile

The RAAML library and profile imports the entire SysML profile. The use of this import is intended to provide more seamless integration with system modeling using SysML and to be able to fully leverage the capabilities of SysML.

### 9.1 Core

The core concepts domain model is depicted in Figure 9.1. The submission team uses this domain model to derive the CoreLibrary and CoreProfile packages (specified in sections 9.1.1 and 9.1.2 respectively). The other libraries and profiles of the specification are based on the CoreLibrary and CoreProfile packages and contain elements and relationships representing concepts common across safety and reliability analysis methods.

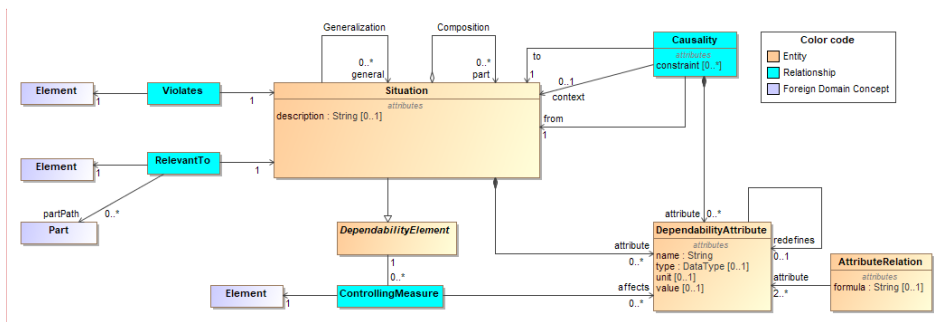


Figure 9.1 – Core concepts domain model

The central element in the core concepts domain model is the “Situation” concept. A situation occurrence is defined as a system being in a given place at given time and in a given state. For example, “Boeing 747 with S/N 12305 is being refueled at Gate 7 of Amsterdam Schiphol at 11:45 on Monday, 30th of July 2018.” An elementary situation is a classifier. It describes a set of situation occurrences of some type. The system, place, time, and state parameters are described by classifiers rather than individual descriptions.

When describing a situation, some of its parameters may be omitted if the situation does not need to be specific with respect to that parameter. For example:

- Fire in the engine compartment of the ship.
- Finger injury of the circular saw operator.

Different Situations can have generalization/specialization relationships between them. Generalization between two situations expresses the subset/superset relationship between the sets of occurrences that these situations represent. For example, “bone fracture” may be defined as a subtype of “Injury”.

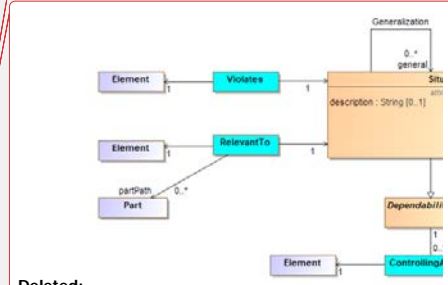
Situations can have quantitative attributes, such as probability of occurrence. These are defined using the DependabilityAttribute class. Quantitative attributes can be related to each other and to attributes of the system by formulae using the AttributeRelation class. Formulae can be expressed in any language that the modeling tool can compute, including OCL and other executable languages. For example:

$$\text{FMEAItem.RiskPriorityNumber} = \text{Cause.Occurrence} \times \text{FailureMode.Detectability} \times$$

$\text{Effect.Severity}$

Different Situations can be associated with each other using the Causality class, expressing semantic relationships between situations such as simple causality, conditional causality, and probabilistic connections. These relations may also have quantitative attributes, such as the probability of occurrence of the “to” situation if the “from” situation occurs.

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For example, a car in frequent contact with salt, causing safety-critical parts to corrode, which causes leaks in the brake line, causing the brakes to fail, causing a car accident, causing a passenger injury.

A non-elementary situation (the “Composition” relationship in Figure 9.1) is a concept encompassing multiple elementary situations: a single system or combination of several systems in a mutable layout, flowing in time through a sequence of states. The choice of whether to use a composite situation with parts described by subsituations, or to use a single situation, is at the discretion of the modeler. It depends on the modeler’s needs, such as the depth of analysis required.

Situations can violate requirements, constraints defined/prescribed for the system, or other specifications describing how the system should operate. For example, a Situation where the system can-not detect glucose level violates the requirement that “the insulin pump must work for 1 week without the need to replace batteries”.

The RelevantTo relationship is used to link situations to system model elements to provide context and relevance for the Situation. For example, in the aforementioned insulin pump, a Situation where the insulin pump cannot be charged would be related to the main battery element in the system model.

Situations can be mitigated, detected, and prevented via the **ControllingMeasure**. The use of this relationship introduces new safety requirements.

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It was decided early on to reuse as many concepts from the SysML language as possible and only add concepts that are missing in SysML to address safety and reliability aspects of systems. This avoids duplication between two languages that will typically be used together. It also enables tool vendors to implement the new profile and library without requiring new tool capabilities, assuming SysML is supported. This leads to a very small library and profile on top of SysML/UML being sufficient to cover all core concepts. The core domain model is covered by SysML/UML concepts as shown in Table 1. The CoreLibrary package is specified in section 9.1.1. The CoreProfile package is shown in 9.1.2. The Core profile and library are used by all domain-specific methods in the specification.

**Table 9.1 – Mapping of core concepts to the SysML/UML language**

Core concept	SysML/UML concept
Situation	A specialization of a Block in SysML and a new stereotype «Situation»
DependabilityAttribute	SysML Value Property
AttributeRelation	SysML Constraint Block
Generalization	UML Generalization relationship
Composition	UML Composition relationship
Violates	A stereotyped UML dependency
RelevantTo	A stereotyped UML dependency
Causality	An association/connector combination
<b>ControllingMeasure</b>	A stereotyped UML dependency

Commented [AA14]: RAAML11-11  
 Deleted: ControllingAction

### 9.1.1 Core::Core Library

AnySituation

**Package:** Core Library

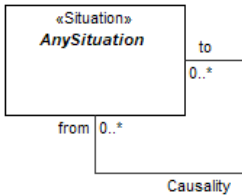
**isAbstract:** Yes

**Applied Stereotype:** «Situation»

Description

AnySituation is the universal root of all situations. All situations inherit from AnySituation. A situation describes a set of situation occurrences of some type. The system, place, time, and state parameters are described by classifiers rather than individual descriptions. A situation occurrence is a system being in a given place at given time and in a given state.

For example, “Boeing 747 with S/N 12305 is being refueled at Gate 7 of Amsterdam Schiphol at 11:45 on Monday, 30th of July 2018.”



**Figure 9.2 – AnySituation**

**Attributes**

- from : AnySituation[0..\*] (member end of [Causality](#) association) A situation which precedes the one at the other end of the [Causality](#) relationship.
- to : AnySituation[0..\*] (member end of [Causality](#) association) A situation which follows the one at the other end of the [Causality](#) relationship.

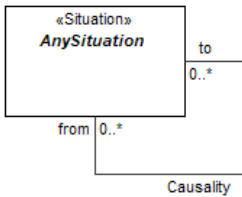
**Causality**

**Package:** Core Library

**Description**

Universal root relationship between situations. All situation relationships inherit from this relationship. Identifies cause and effect relationship between two situations. Causality could be direct (non-conditional), conditional or probabilistic or any other inter-situation relationship, defined by the user. Multiple situations can cause one situation and vice versa - one situation can cause multiple other situations.

For example, a car in frequent contact with salt, causing safety-critical parts to corrode, which causes leaks in the brake line, causing the brakes to fail, causing a car accident, causing a passenger injury.



**Figure 9.3 – Causality**

**Association ends**

- to : AnySituation[0..\*] (member end of [Causality](#) association) A situation which follows the one at the other end of the [Causality](#) relationship.
- from : AnySituation[0..\*] (member end of [Causality](#) association) A situation which precedes the one at the other end of the [Causality](#) relationship.

### 9.1.2 Core::Core Profile

Situation

**Package:** Core Profile  
**isAbstract:** No  
**Generalization:** Block  
**Extension:** Class

Description

A situation is a SysML v1.6 Block. The situation reuses the following functionality from the Block concept: generalizations, parts, value properties, and Parametrics. The situation stereotype is only needed to distinguish situations from other types of blocks. See [AnySituation](#) for the definition of a situation concept.

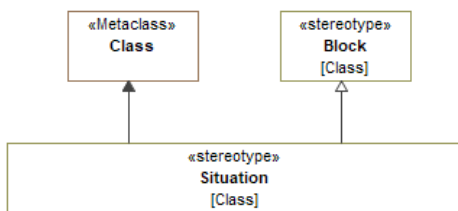


Figure 9.4 – Situation

RelevantTo

**Package:** Core Profile  
**isAbstract:** No  
**Generalization:** DirectedRelationshipPropertyPath  
**Extension:** Dependency

Description

The RelevantTo relationship is used to link situations to system model elements to provide context and relevance for the Situation. For example, in an insulin pump, a Situation where the insulin pump cannot be charged would be related to the main battery element in the system model. The RelevantTo relationship reuses the following functionality from the DirectedRelationshipPropertyPath concept: targetContext and targetPropertyPath.

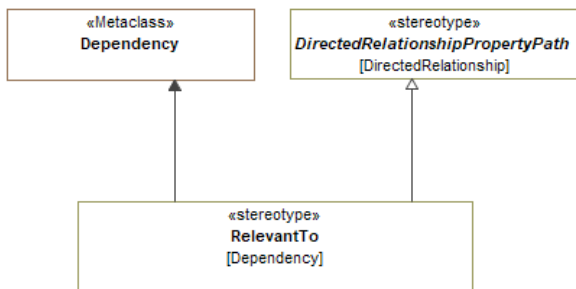


Figure 9.5 – RelevantTo

Constraints

[1] ClientIsSituation -- client of the RelevantTo must be a Situation  
Situation.allInstances().base\_Class->includesAll(self.base\_Dependency.client)

ControllingMeasure

**Package:** Core Profile  
**isAbstract:** Yes  
**Generalization:** DirectedRelationshipPropertyPath  
**Extension:** Dependency

Description

A measure taken to address (mitigate severity, reduce probability of occurrence, increase probability of detection) a potential or real adverse situation.

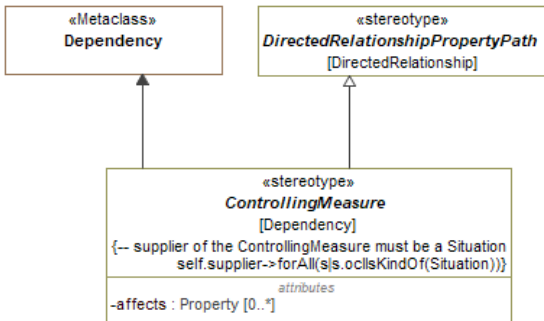


Figure 9.6 – ControllingMeasure

Attributes

affects : Property[0..\*] Indicates that this controlling measure influences (typically improves) a particular quantitative attribute of the situation.

Constraints

[1] SupplierIsSituation -- supplier of the ControllingMeasure must be a Situation  
Situation.allInstances().base\_Class->includesAll(self.base\_Dependency.supplier)

Violates

**Package:** Core Profile  
**isAbstract:** No  
**Extension:** Dependency

Description

The violates relationship indicates a situation where a system is violating a prescription (requirement, constraint, etc.). It is used to connect situations to requirements, design constraints and any other elements of system models which prescribe a characteristic of the system.

For example, a Situation where the insulin pump drains the battery in 3 days violates the requirement that “The system must work for 1 week without the need to replace batteries”.

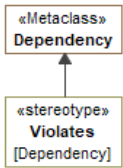


Figure 9.7 – Violates

Constraints

```

[1] ClientIsSituation -- client of the Violates must be a Situation
Situation.allInstances().base_Class->includesAll(self.base_Dependency.client)
  
```

IDCarrier

**Package:** ISO 26262 Profile  
**isAbstract:** No  
**Extension:** Element

Description

Additional stereotype for carrying human-readable identification data.

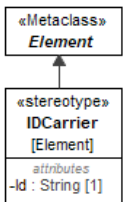


Figure 9.8 – IDCarrier

Attributes

Id : String[1] Human readable identifier.

## 9.2 General

The specification includes a general safety and reliability package that extends the core package. It defines common concepts that are used or extended in the method- and domain-specific reliability and safety packages. The package provides a model library, specified in section 9.2.1, and a profile, specified in section 9.2.2.

The general concepts contained in this package can be used as-is to model the safety and reliability related aspects of a system. However, the intended purposes of the package are as follows:

1. Provide a common base for the method- and domain-specific reliability and safety modeling packages. The same concepts are used in a number of safety and reliability techniques (such as FMEA and FTA), so the role of this package is to prevent duplication of common concepts in other packages. This also enables movement of information between domains for cross-domain issues. This is particularly important as different domains may use the same concepts with different vocabulary. A common foundation provides a way to translate between these.

2. Provide traceability links between safety and reliability artefacts across the system life cycle. For example, the failure modes defined during Hazard Analysis and Risk Assessment (HARA, defined in the ISO 26262 package) and in an FMEA could be traced and considered during an FTA.
3. Provide a foundation on which additional methods, techniques and domains with safety and reliability concerns not currently included in the profile can be built by users. For example, a tool vendor could build an additional package for the railway domain by building on the general safety and reliability foundation. This both reduces effort to introduce an additional domain and allows additional domain packages to be compatible with the existing specification content.

### 9.2.1 General::General Concepts Library

AbstractEvent

**Package:** General Concepts Library

**isAbstract:** Yes

**Generalization:** [AnySituation](#)

**Applied Stereotype:** «Situation»

Description

Anything that causes a change in a system under analysis or environment. Event has an identifiable starting point in time.

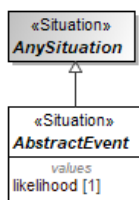


Figure 9.9 – AbstractEvent

Attributes

likelihood : [1]

A placeholder attribute for indicating likelihood of occurrence of an event. It is intentionally left without a type. Method developers can derive more specialized ways to characterize likelihood.

AbstractCause

**Package:** General Concepts Library

**isAbstract:** Yes

**Generalization:** [AbstractEvent](#), [Factor](#)

**Applied Stereotype:** «Situation»

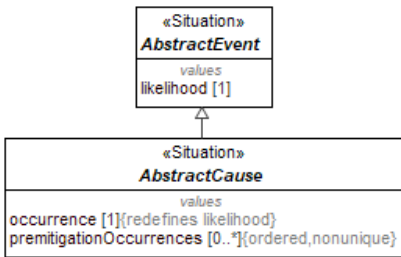
Description

An AbstractCause is a precursor [event](#) that activates other [events](#). The AbstractCause is a root class for all kinds of causes; method developers should derive from it more specific kinds of causes with specific types for [occurrence](#) property. One case is demonstrated in the [Cause](#) element that redefines the occurrence property of the AbstractCause with the type Real.

See the diagram [GeneralConceptsLibrary](#).

Commented [AA15]: RAAML11-28

See also: [fault](#) association end of the [Activation](#) association.



**Figure 9.10 – AbstractCause**

**Attributes**

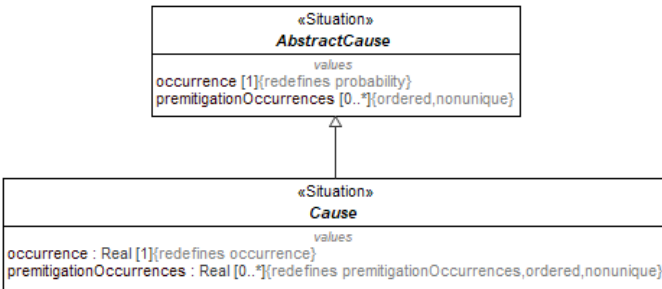
occurrence : [1], redefines <a href="#">likelihood</a>	A placeholder attribute without a type declared, for indicating how often this situation occurs. It is a redefinition of <a href="#">likelihood</a> .
premitigationOccurrences : [0..*]	A placeholder attribute for indicating how often this situation occurred prior to mitigation. This property can have more than one value.

**Cause**

**Package:** General Concepts Library  
**isAbstract:** Yes  
**Generalization:** [AbstractCause](#)  
**Applied Stereotype:** [«Situation»](#)

**Description**

A Cause is a specific implementation of [AbstractCause](#) that defines [occurrence](#) property with the type Real.



**Figure 9.11 – Cause**

**Attributes**

occurrence : Real[1], redefines <a href="#">occurrence</a>	An attribute with the type Real, for indicating how often this situation occurs.
premitigationOccurrences : Real[0..*], redefines <a href="#">premitigationOccurrences</a>	An attribute for indicating how often this situation occurred prior to mitigation. This property can have more than one value.

DysfunctionalEvent

**Package:** General Concepts Library  
**isAbstract:** Yes  
**Generalization:** [AbstractEvent](#)  
**Applied Stereotype:** «Situation»

Description

An event whose occurrence can cause a dysfunctional behavior of a system or a part of the system. The DysfunctionalEvent concept is a generalization of such concepts as failure, feared event, etc. that are considered in the domain-specific safety standards. It might be extended for introducing new safety and reliability methods and techniques.

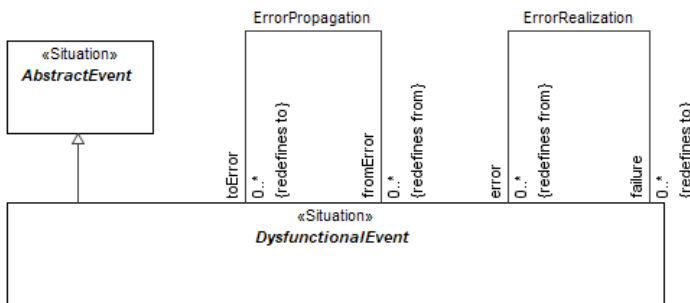


Figure 9.12 – DysfunctionalEvent

AbstractFailureMode

**Package:** General Concepts Library  
**isAbstract:** Yes  
**Generalization:** [UndesiredState](#)  
**Applied Stereotype:** «FailureMode»

Description

The manner in which a system or part of a system (e.g., functions, components, hardware, software, hardware parts, software units), can fail (ISO 26262-1:2018, definition 3.51, modified). The AbstractFailureMode is a root class for all failure modes; method developers should derive more specific kinds of failure modes with specific types for the [detectability](#) property. One case is demonstrated in the [FailureMode](#) element that redefines the detectability property of the AbstractFailureMode with the type Real.

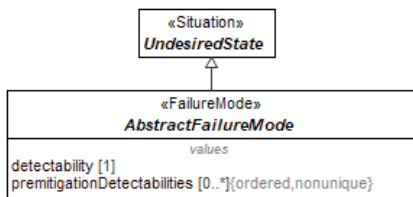


Figure 9.13 – AbstractFailureMode



Attributes

detectability : [1]                      A placeholder attribute without a type declared, for indicating how easy it is to detect this failure mode.

premitigationDetectabilities : [0..\*]                      A placeholder attribute for indicating how easy it would have been to detect the situation with the previous design iteration. This property can have more than one value.

FailureMode

**Package:** General Concepts Library  
**isAbstract:** Yes  
**Generalization:** [AbstractFailureMode](#)  
**Applied Stereotype:** [«FailureMode»](#)

Description

FailureMode is a specific implementation of [AbstractFailureMode](#) that defines the [detectability](#) property with the type Real.  
 A failure is an instance of a FailureMode.

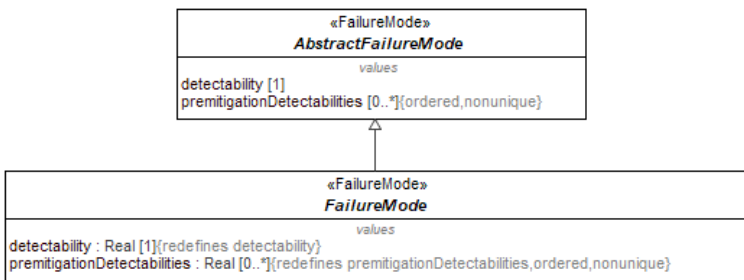


Figure 9.14 – FailureMode

Attributes

detectability : Real[1], redefines [detectability](#)                      An attribute with the type Real, for indicating how easy it is to detect the situation.

premitigationDetectabilities : Real[0..\*], redefines [premitigationDetectabilities](#)                      An attribute for indicating how easy it would have been to detect the situation with the previous design iteration. This property can have more than one value.

AbstractEffect

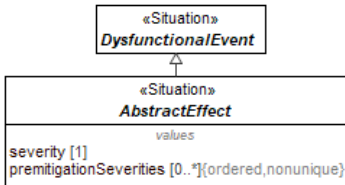
**Package:** General Concepts Library  
**isAbstract:** Yes  
**Generalization:** [DysfunctionalEvent](#)  
**Applied Stereotype:** [«Situation»](#)

Description

An AbstractEffect is a [DysfunctionalEvent](#) that is a result or a consequence of another [Situation](#). The AbstractEffect is a root class for all effects; method developers should derive more specific kinds of effects with specific types for the [severity](#) property.  
 One case is demonstrated in the [Effect](#) element that redefines the severity property of the AbstractEffect with the type Real.

See the diagram [GeneralConceptsLibrary](#).

See also: [ErrorPropagation](#), [ErrorRealization](#) associations.



**Figure 9.15 – AbstractEffect**

**Attributes**

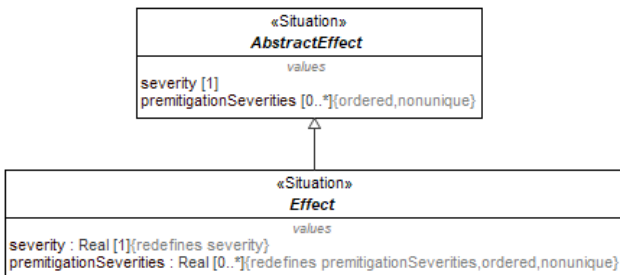
severity : [1]	A placeholder attribute without a type declared, for indicating the estimate of the extent of harm.
premitigationSeverities : [0..*]	A placeholder attribute for indicating the estimate of the extent of harm that would have resulted from the previous design iterations. This property can have more than one value.

**Effect**

**Package:** General Concepts Library  
**isAbstract:** Yes  
**Generalization:** [AbstractEffect](#)  
**Applied Stereotype:** [«Situation»](#)

**Description**

An Effect is a specific implementation of [AbstractEffect](#) that defines the [severity](#) property with the type Real.



**Figure 9.16 – Effect**

**Attributes**

severity : Real[1], redefines <a href="#">severity</a>	An attribute with the type Real, for indicating the estimate of the extent of harm.
premitigationSeverities : Real[0..*], redefines <a href="#">premitigationSeverities</a>	An attribute for indicating the estimate of the extent of harm that would have resulted from the previous design iterations. This property stores more than one value.

Activation

Package: General Concepts Library  
Generalization: [Causality](#)

Description

A [causal](#) relationship describing the propagation of the initial [AbstractCause](#) situation to the [DysfunctionalEvent](#) situation in the system.

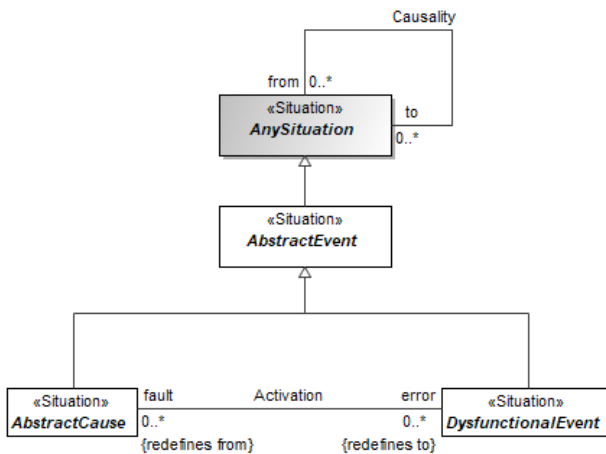


Figure 9.17 – Activation

Association ends

error : DysfunctionalEvent[0..\*] The dysfunctional situation (error) of the system.  
(member end of [Activation](#) association, redefines [to](#))

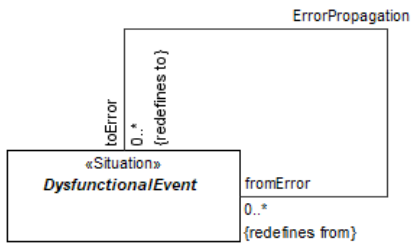
fault : AbstractCause[0..\*] (member end of [Activation](#) association, redefines [from](#)) The causal fault.

ErrorPropagation

Package: General Concepts Library  
Generalization: [Causality](#)

Description

A [causal](#) relationship describing the propagation of [errors](#) (one error leading to another) throughout the system.



**Figure 9.18 – ErrorPropagation**

Association ends

toError : DysfunctionalEvent[0..\*]      The successor error.  
 (member end of [ErrorPropagation](#)  
 association, redefines [to](#))

fromError : DysfunctionalEvent[0..\*]      The predecessor error.  
 (member end of [ErrorPropagation](#)  
 association, redefines [from](#))

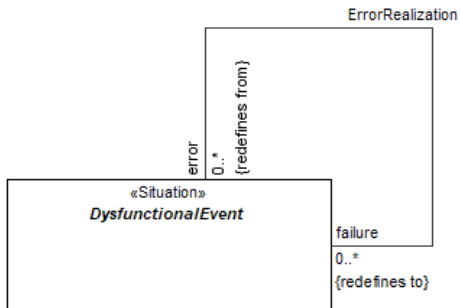
ErrorRealization

**Package:** General Concepts Library

**Generalization:** [Causality](#)

Description

A [causal](#) relationship describing the propagation of an [error](#) to a [failure](#).



**Figure 9.19 – ErrorRealization**

Association ends

failure : DysfunctionalEvent[0..\*]      The resulting failure.  
 (member end of [ErrorRealization](#)  
 association, redefines [to](#))

error : DysfunctionalEvent[0..\*]      The predecessor error.  
 (member end of [ErrorRealization](#)  
 association, redefines [from](#))

## HarmPotential

**Package:** General Concepts Library  
**isAbstract:** Yes  
**Generalization:** [AnySituation](#)  
**Applied Stereotype:** [«Situation»](#)

### Description

A state where there is the potential of [harm](#). This includes all types of harm arising from malicious or non-malicious causes.

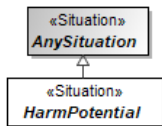


Figure 9.20 – HarmPotential

## Hazard

**Package:** General Concepts Library  
**isAbstract:** Yes  
**Generalization:** [HarmPotential](#)  
**Applied Stereotype:** [«Situation»](#)

### Description

A potential source of [harm](#) (IEC 61508-4, 3.1.2). Source of harm is non-malicious.

The term includes danger to persons arising within a short time scale (for example, fire and explosion) and also those that have a long-term effect on a person's health (for example, release of a toxic substance).

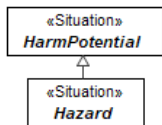


Figure 9.21 – Hazard

## Scenario

**Package:** General Concepts Library  
**isAbstract:** Yes  
**Generalization:** [AnySituation](#)  
**Applied Stereotype:** [«Situation»](#)

### Description

A composite [situation](#), consisting of multiple steps (that are themselves [situations](#)). Steps should have causal ordering, indicated by [Causality](#) relationships or sub-types thereof.

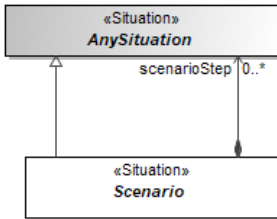


Figure 9.22 – Scenario

Attributes

scenarioStep : AnySituation[0..\*] (member end of association) A situation which is a part of a bigger situation - scenario.

AbstractRisk

Package: General Concepts Library

isAbstract: Yes

Generalization: Scenario

Applied Stereotype: «Situation»

Description

An AbstractRisk is a Scenario - combination of harm potential (Hazard or Vulnerability), triggering event (AbstractEvent), and resulting harm (AbstractEffect).

The AbstractRisk is a placeholder to enable modelers to specify methodology-specific kinds of risks.

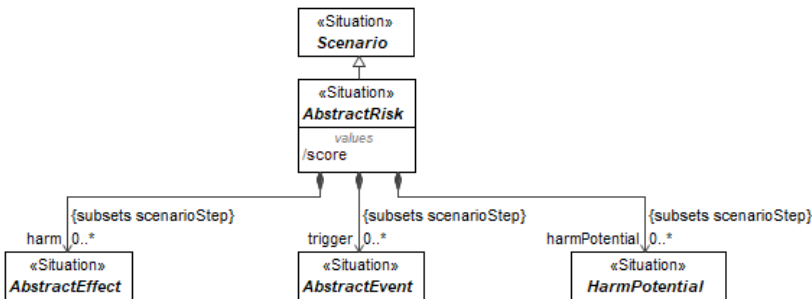


Figure 9.23 – AbstractRisk

Attributes

score : Combination of the probability of occurrence of abstract event resulting from abstract harm and the severity of that harm (IEC 61508-4, 3.1.5, modified).

An example could be risk priority number (RPN) in FMEA analysis.

trigger : AbstractEvent[0..\*] (member end of association, subsets scenarioStep) Triggering event (AbstractEvent) which causes harm to materialize.

harm : AbstractEffect[0..\*] (member end of association, subsets scenarioStep) Resulting harm (AbstractEffect).

harmPotential : HarmPotential[0..\*]  
 (member end of association, subsets  
[scenarioStep](#))

Pre-existing risk ([HarmPotential](#)).

**UndesiredState**  
**Package:** General Concepts Library  
**isAbstract:** Yes  
**Generalization:** [DysfunctionalEvent](#)  
**Applied Stereotype:** «[Situation](#)»

Description  
 An element's condition as a specific time which represents an unintended situation.

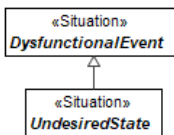


Figure 9.24 – UndesiredState

**Limitation**  
**Package:** General Concepts Library  
**isAbstract:** Yes  
**Generalization:** [Factor](#)  
**Applied Stereotype:** «[Situation](#)»

Description  
 A limiting condition; restrictive weakness; lack of capacity; inability or handicap.  
 Limitation is a restriction of Capability.

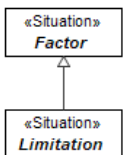


Figure 9.25 – Limitation

**Loss**  
**Package:** General Concepts Library  
**isAbstract:** Yes  
**Generalization:** [AbstractEffect](#)  
**Applied Stereotype:** «[Situation](#)»

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Description

In STPA, is any effect that is unacceptable and should be prevented. Some factors such as environmental conditions may contribute to a loss but are outside our control. Examples for losses are:

- Loss of human life or injury
- Vehicle/property damage
- Mission loss (inadequate transportation)
- Loss of customer satisfaction
- Financial loss
- Loss of public image
- Environmental pollution

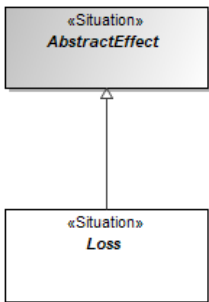


Figure 9.26 – Loss

Factor

Package: General Concepts Library  
isAbstract: Yes

Generalization: AnySituation

Applied Stereotype: «Situation»

Description

A situation that contributes to a result or outcome

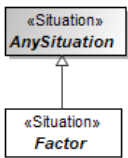


Figure 9.27 – Factor

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## 9.2.2 General::General Concepts Profile

FailureMode

**Package:** General Concepts Profile

**isAbstract:** No

**Generalization:** [Situation](#)

**Extension:** Class

Description

See [FailureMode](#) library class for the definition of a situation concept.

The [FailureMode](#) stereotype is only needed to distinguish FailureModes from other types of situations.

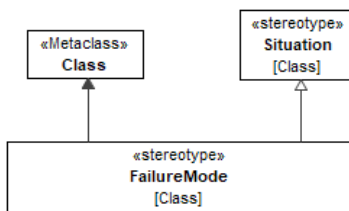


Figure 9.28 – FailureMode

Error

**Package:** General Concepts Profile

**isAbstract:** No

**Generalization:** [Situation](#)

**Extension:** Class

Description

The discrepancy between a computed, observed, or measured value or condition and the true, specified or theoretically correct value or condition. [IEC 61508-4, 3.6.11].

The [Error](#) stereotype is needed to distinguish this type of situations.

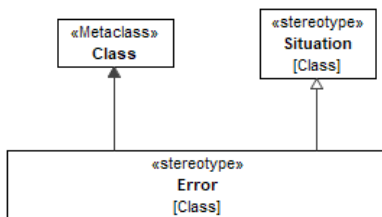


Figure 9.29 – Error

Fault

**Package:** General Concepts Profile

**isAbstract:** No

**Generalization:** [Situation](#)

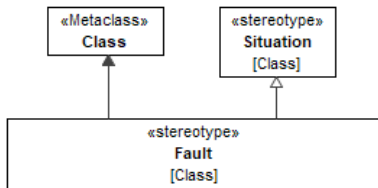
**Extension:** Class

Description

Abnormal condition that may cause a reduction in, or loss of, the capability of a functional unit to perform a required function. [IEC 61508-4, 3.6.1].

Abnormal or undesired condition that can cause an element or a system to fail. [ISO 26262-1:2018, 3.54, modified]

The [Fault](#) stereotype is needed to distinguish this type of situations.



**Figure 9.30 – Fault**

Detection

**Package:** General Concepts Profile

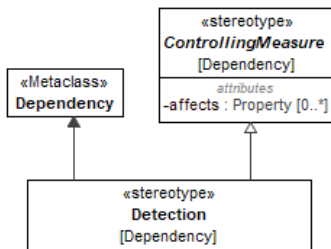
**isAbstract:** No

**Generalization:** [ControllingMeasure](#)

**Extension:** Dependency

Description

A kind of [ControllingMeasure](#) taken to increase probability of detecting the situation under analysis. In hardware these measures may include built-in diagnostic tests, or physical inspection and manual tests.



**Figure 9.31 – Detection**

Prevention

**Package:** General Concepts Profile

**isAbstract:** No

**Generalization:** [ControllingMeasure](#)

**Extension:** Dependency

Description

A kind of [ControllingMeasure](#) taken to reduce probability of occurrence of the situation under analysis.

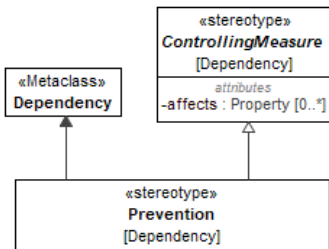


Figure 9.32 – Prevention

Mitigation

**Package:** General Concepts Profile

**isAbstract:** No

**Generalization:** [ControllingMeasure](#)

**Extension:** Dependency

Description

A kind of [ControllingMeasure](#) taken to reduce severity of the situation under analysis.

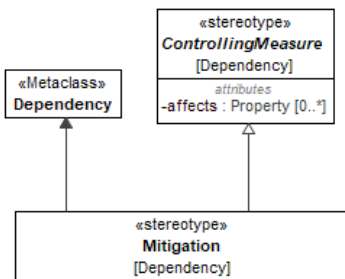


Figure 9.33 – Mitigation

Recommendation

**Package:** General Concepts Profile

**isAbstract:** No

**Generalization:** [ControllingMeasure](#)

**Extension:** Dependency

Description

Recommendation is used to connect the situation to an action item.

An action item is normally a Requirement, but it can be a less "strong" type of advice - comment, rationale, etc.

The requirement is further managed by the requirements management system - it can have responsible persons, due date, verification properties etc.

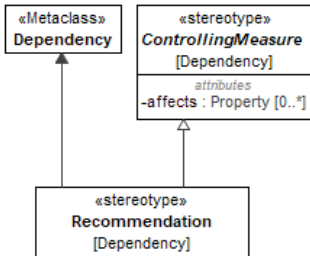


Figure 9.34 – Recommendation

FailureState

**Package:** General Concepts Profile

**isAbstract:** No

**Extension:** State

Description

State, which the system or a part of the system enters after occurrence of [FailureMode](#) (failure).

The Failure state concept might be used in various formal safety and reliability analysis methods based on the state machine notation. Failure states could be tied to [FailureModes](#) via the [RelevantTo](#) dependency.

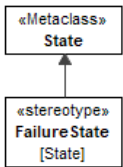


Figure 9.35 – FailureState

Undeveloped

**Package:** General Concepts Profile

**isAbstract:** No

**Extension:** Element

Description

Undeveloped stereotype is meant to identify incomplete concepts.

This stereotype can be applied in combination with Goal or Strategy stereotype to express the fact that the goal or strategy is not fully developed, and therefore may lack crucial details.

This stereotype can also be applied to basic event in fault trees to express the fact that it is not fully developed.

**Hazard**

**Package:** General Concepts Profile

**isAbstract:** No

**Generalization:** Situation

**Extension:** Class

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Description

A marker stereotype for hazards (see the Hazard library element for definition).

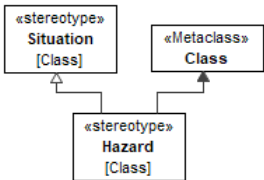


Figure 9.36 – Hazard

Item

**Package:** General Concepts Profile  
**isAbstract:** Yes

**Extension:** Element

Description

An item defines a notional boundary for a risk analysis.

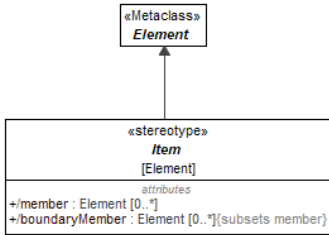


Figure 9.37 – Item

Attributes

member : Element[0..\*]

Elements that are inside the boundary of an item.

boundaryMember : Element[0..\*], subsets member

Elements that are on the boundary of an item. They act as interaction points between inside and outside of the item.

PresentIn

**Package:** General Concepts Profile  
**isAbstract:** No

**Generalization:** RelevantTo

**Extension:** Dependency

Description

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Declares that a specific situation (e.g. weakness, vulnerability) is persistent when the part/block is included in the system.

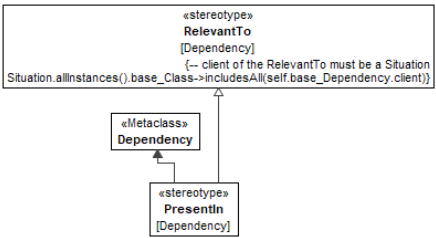


Figure 9.38 – PresentIn

SingleElementItem

Package: General Concepts Profile

isAbstract: No

Generalization: Item

Extension: Class

Description

An item that is defined by an individual block.

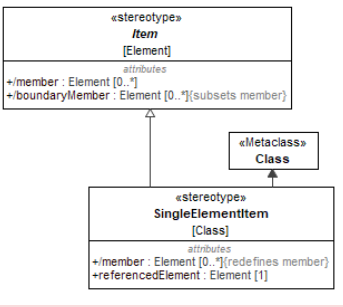


Figure 9.39 – SingleElementItem

Attributes

member : Element[0..\*], redefines member

This is a redefinition of Item::member. When the item is defined by an individual block, this property collects features of this block.

referencedElement : Element[1]

A reference to a block defining the item.

ElementGroupBasedItem

Package: General Concepts Profile

isAbstract: No

Generalization: ElementGroup, Item

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**Extension: Comment**

**Description**

An item that is defined by a set of elements using the SysML element group mechanism.

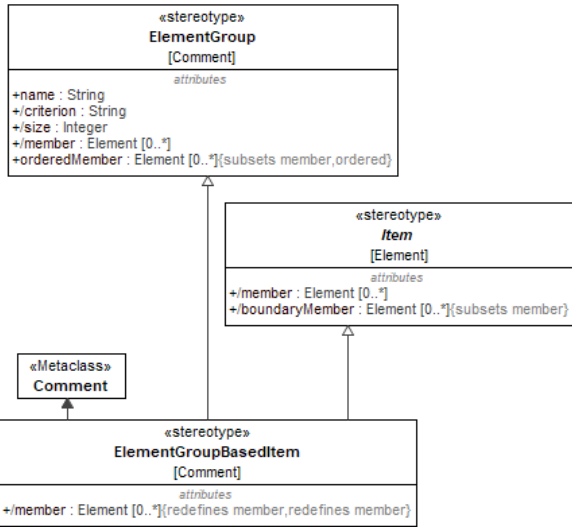


Figure 9.40 – ElementGroupBasedItem

**Attributes**

member : Element[0..\*], redefines member, member The members of the group are specified by SysML. ElementGroup::member.

**9.3 General Security**

**9.3.1 General Security::General Security Concepts Library**

**Threat**

Package: General Security Concepts Library isAbstract: Yes

Generalization: HarmPotential

Applied Stereotype: «Situation»

**Description**

A Threat is any circumstance or event (Situation in RAAML) with the potential to adversely impact Assets.

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A Threat is the potential cause of unacceptable asset loss and the undesirable consequences or impact of such a loss.

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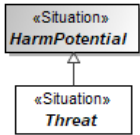


Figure 1.41 - Threat

Weakness

Package: General Security Concepts Library  
isAbstract: No

Generalization: Limitation

Applied Stereotype: «Situation»

Description

A "weakness" is a condition under certain circumstances, could contribute to the introduction of Vulnerabilities.

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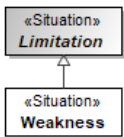


Figure 1.42 - Weakness

Vulnerability

Package: General Security Concepts Library  
isAbstract: No

Generalization: Limitation

Applied Stereotype: «Situation»

Description

A Weakness that can be exploited or triggered by a SecurityActor to produce an undesirable behavior (DysfunctionalEvent).

Vulnerability can then be used as a (exploit)scenario step.

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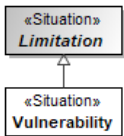


Figure 1.43 - Vulnerability



### 9.3.2 General Security::General Security Concepts Profile

#### Threat

**Package:** General Security Concepts Profile

**isAbstract:** No

**Generalization:** Situation

**Extension:** Class

#### Description

A marker stereotype for Threat.

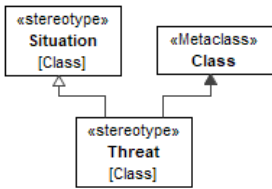


Figure 1.44 - Threat

#### Impacts

**Package:** General Security Concepts Profile

**isAbstract:** No

**Generalization:** RelevantTo

**Extension:** Dependency

#### Description

How a particular Situation affects the properties of an Asset.

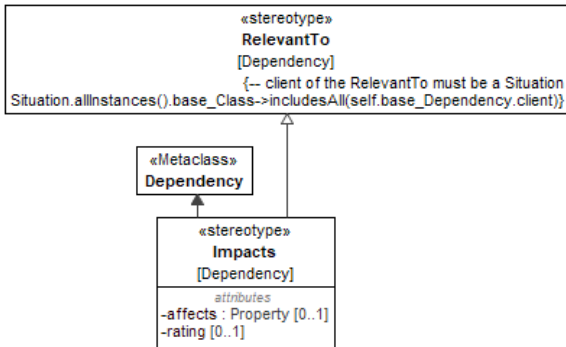


Figure 1.45 - Impacts

#### Attributes

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affects : Property[0..1]

Indicates which aspect of the asset (e.g. financial, or operational etc.) is being impacted.

rating : [0..1]

Rating of the Impact on the Asset

**Asset**

**Package:** General Security Concepts Profile

**isAbstract:** No

**Extension:** Class

**Description**

An Asset represents anything that has value to a person or organization.

Asset can be contextualized by the Item.

For that, the recommended way is to create Asset-typed property in the appropriate Item.

Note: this only works for the Item flavors that are based on UML Class. If there are methodologies that have custom kinds of items, not based on UML Class, those methodologies need to specify their own mechanisms to contextualize the Asset

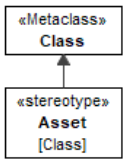


Figure 1.46 - Asset

**Valuates**

**Package:** General Security Concepts Profile

**isAbstract:** No

**Generalization:** DirectedRelationshipPropertyPath

**Extension:** Dependency

**Description**

Relationship connecting Asset description with the underlying system model element.

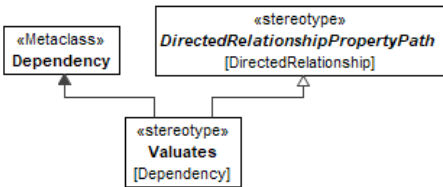


Figure 1.47 - Valuates

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SecurityActor

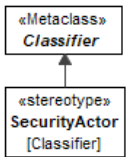
Package: General Security Concepts Profile

isAbstract: No

Extension: Classifier

Description

A SecurityActor represents an entity that has the potential to affect a Risk - typically a threat actor.



**Figure 1.48 - SecurityActor**

PresentedBy

Package: General Security Concepts Profile

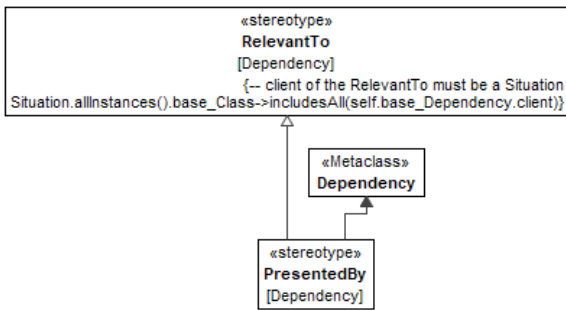
isAbstract: No

Generalization: RelevantTo

Extension: Dependency

Description

Presentation/Initiation of a Situation by a SecurityActor.



**Figure 1.49 - PresentedBy**

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## 9.4 Methods::FMEA

The Failure Mode and Effects Analysis (FMEA) is a method of inspecting a system to analyze potential failures. Therefore, as many components, assemblies, and subsystems as possible are examined in order to identify these failure modes in a system and their causes and effects.

### 9.4.1 Methods::FMEA::FMEALibrary

AbstractFMEAItem

Package: FMEALibrary

isAbstract: Yes

Generalization: [AbstractRisk](#)

Applied Stereotype: [«FMEAItem»](#)

Description

An AbstractFMEAItem is a scenario (more specifically - [AbstractRisk](#) scenario) composed of a failure mode, (potentially multiple) cause(s) and effect(s). It stores assessed and mitigated risk priority numbers.

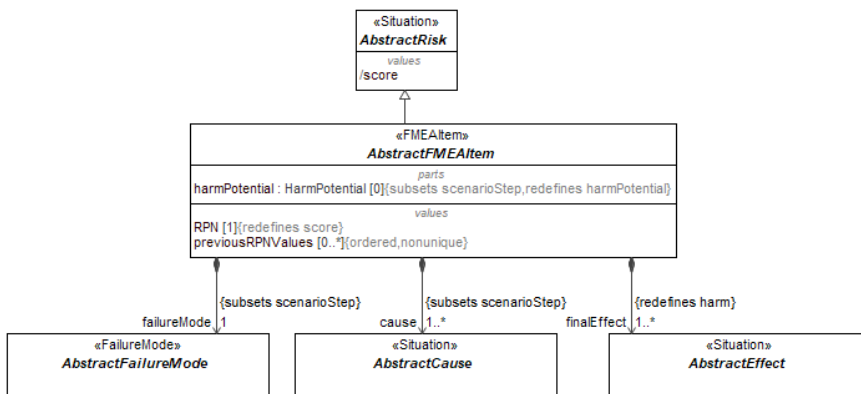


Figure 9.50 – AbstractFMEAItem

Attributes

RPN : [1], redefines [score](#)

The risk priority number ranks the risk of the FMEA item. It is a specialization of [AbstractRisk::score](#).

failureMode : AbstractFailureMode[1] (member end of association, subsets [scenarioStep](#))

Represents the failure mode which is reached if a system element fails.

cause : AbstractCause[1..\*] (member end of association, subsets [scenarioStep](#))

Represents the cause of the failure of a system element.

finalEffect : AbstractEffect[1..\*] (member end of association, redefines [harm](#))

Represents the effect which occurs on the system border.

previousRPNValues : [0..\*]

Represents the assessed risk priority number before mitigating the risk of a failure.

harmPotential : HarmPotential[0] (member end of association, redefines [harmPotential](#), subsets [scenarioStep](#))

Pre-existing risk. Not used in FMEA method, therefore redefined in this library with multiplicity [0]

## FMEItem

**Package:** FMEALibrary

**isAbstract:** Yes

**Generalization:** [AbstractFMEItem](#)

**Applied Stereotype:** «FMEItem»

### Description

A FMEItem is a specialization of [AbstractFMEItem](#) with the Real implementation of quantitative attributes.

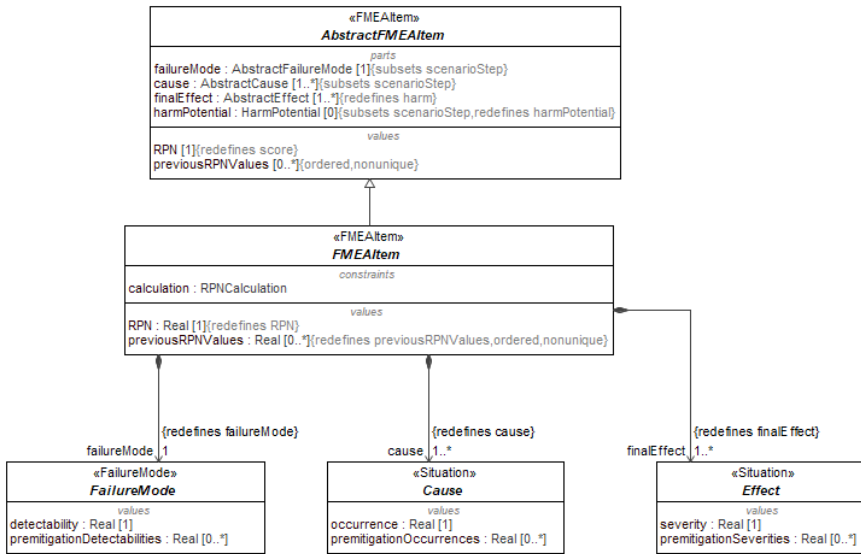


Figure 9.51 – FMEItem

### Attributes

finalEffect : Effect[1..\*] (member end of association, redefines [finalEffect](#))

cause : Cause[1..\*] (member end of association, redefines [cause](#))

RPN : Real[1], redefines [RPN](#)

failureMode : FailureMode[1] (member end of association, redefines [failureMode](#))

calculation : RPNCalculation

previousRPNValues : Real[0..\*], redefines [previousRPNValues](#)

The specialization of [AbstractFMEItem](#) :: [finalEffect](#) with the implementation of [Effect](#) with Real severity.

The specialization of [AbstractFMEItem](#) :: [cause](#) with the implementation of [Cause](#) with Real occurrence.

The specialization of [AbstractFMEItem](#) :: [RPN](#) with the type Real.

The specialization of [AbstractFMEItem](#) :: [failureMode](#) with the implementation of [FailureMode](#) with Real detectability.

Link to a formula for [RPN](#) calculation.

The specialization of [AbstractFMEItem](#) :: [previousRPNValues](#) with the type Real.

### RPNCalculation

**Package:** FMEALibrary

**isAbstract:** No

**Applied Stereotype:** «ConstraintBlock»

Description

A formula for [RPN](#) calculation. This implementation uses multiplication of Occurrence x Detectability x Severity to calculate RPN.

Attributes

RPN :	Risk priority number
SEV :	Severity
OCC : Real	Occurrence
DET :	Detectability

Constraints

[1] Reduced priority number is calculated by simple multiplication of Severity, Detectability and Occurrence.

LossOfFunction

**Package:** FMEALibrary  
**isAbstract:** Yes  
**Generalization:** [FailureMode](#)  
**Applied Stereotype:** [«FailureMode»](#)

Description

A failure mode representing loss of function e.g., the function is inoperable, or suddenly fails.

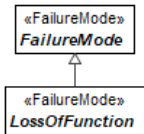


Figure 9.52 – LossOfFunction

DegradationOfFunction

**Package:** FMEALibrary  
**isAbstract:** Yes  
**Generalization:** [FailureMode](#)  
**Applied Stereotype:** [«FailureMode»](#)

Description

A failure mode representing a degradation of function or loss of function over time.

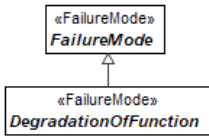


Figure 9.53 – DegradationOfFunction

IntermittentFunction

**Package:** FMEALibrary

**isAbstract:** Yes

**Generalization:** [FailureMode](#)

**Applied Stereotype:** [«FailureMode»](#)

Description

A failure mode representing an intermittent function or the random stops and starts of a function.

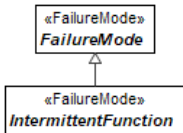


Figure 9.54 – IntermittentFunction

PartialFunction

**Package:** FMEALibrary

**isAbstract:** Yes

**Generalization:** [FailureMode](#)

**Applied Stereotype:** [«FailureMode»](#)

Description

A failure mode representing a partial function or loss of performance.

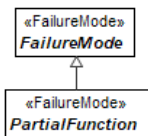


Figure 9.55 – PartialFunction

UnintendedFunction

**Package:** FMEALibrary

**isAbstract:** Yes

**Generalization:** [FailureMode](#)

**Applied Stereotype:** [«FailureMode»](#)

Description

A failure mode representing an unintended function, function operating at the wrong time, with unintended direction, or unequal performance.

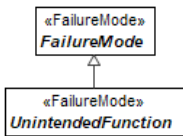


Figure 9.56 – UnintendedFunction

ExceedingFunction

Package: FMEALibrary

isAbstract: Yes

Generalization: [FailureMode](#)

Applied Stereotype: [«FailureMode»](#)

Description

A failure mode representing a function exceeding the acceptable operational performance.

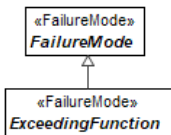


Figure 9.57 – ExceedingFunction

DelayedFunction

Package: FMEALibrary

isAbstract: Yes

Generalization: [FailureMode](#)

Applied Stereotype: [«FailureMode»](#)

Description

A failure mode representing a delayed function or function operating after an unintended time interval.

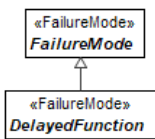


Figure 9.58 – DelayedFunction

## 9.4.2 Methods::FMEA::FMEAProfile

FMEAItem

Package: FMEAProfile

isAbstract: No



**Generalization:** Block  
**Extension:** Class

Description

See [AbstractFMEAItem](#) library class for the definition of a FMEA Item concept.

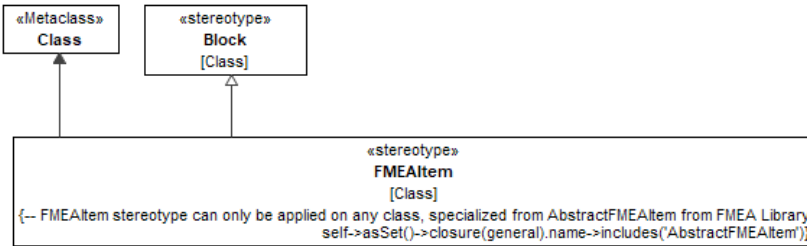


Figure 9.59 – FMEAItem

Constraints

```

[1] -- FMEAItem stereotype can only be applied on any class, specialized from
FMEAItemIsAbstractFMEAItem AbstractFMEAItem from FMEA Library
self.base_Class->asSet()->closure(general).name->includes('AbstractFMEAItem')
  
```

## 9.5 Methods::FTA

Fault Tree Analysis (FTA) is a top-down failure analysis in which an undesired state of a system is analyzed using Boolean logic to combine a series of lower-level (basic) events. This analysis method is used to understand how systems can fail, to identify the best ways to reduce risk and to determine event rates of a safety accident or a functional failure.

The FTA package contains all required elements to implement this analysis. Support for Fault Tree Analysis (FTA) modeling is based on the IEC 61025:2006 standard. Using this standard ensures that the specification offers a form of FTA that is based on best practices and accepted by practitioners. It is also possible for a user to extend the capabilities of the FTA package to enable, for example, dynamic fault tree analysis and component fault tree modeling while still remaining compatible with other information modeled using the specification.

In order to combine FMEA and FTA analysis, a connection between a failure mode and a fault tree event needs to be made. Therefore, the Cause of an FMEAItem can be interpreted as the event which leads to a failure of a system item. By combining FMEAs and FTAs, both analyses can be used to verify the analysis results. This may lead to a better understanding of the behavior of a system during erroneous behavior.

### 9.5.1 Methods::FTA::FTALibrary

FTAElement

**Package:** FTALibrary

**isAbstract:** Yes

**Generalization:** [DysfunctionalEvent](#)

**Applied Stereotype:** «Situation»

Description

Any of the [Events](#) and [Gates](#) needed for the evaluation of the [TopEvent](#) probability.

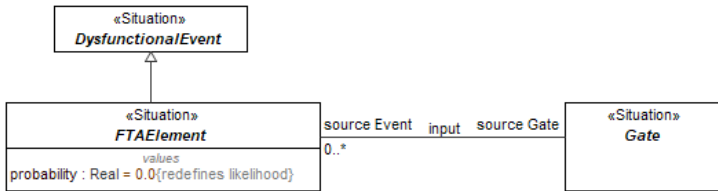


Figure 9.60 – FTAElement

Attributes

probability : Real, redefines [likelihood](#)

The probability that the event represented by the owning FTA element occurs. Probability is a Real value between 0 and 1.

source Gate : Gate (member end of input association)

FTATree

Package: FTALibrary

isAbstract: No

Generalization: [FTAElement](#), [Scenario](#)

Applied Stereotype: «Tree»

Description

A collection of FTAElements and their interrelationships for the evaluation of the top event probability.

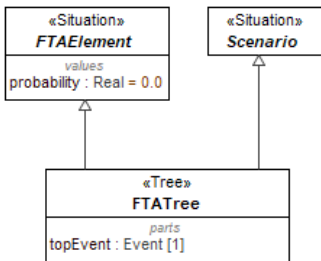


Figure 9.61 – FTATree

Attributes

topEvent : Event[1] (member end of association)

Undesired event which lead to the failure of the system.

Methods::FTA::FTALibrary::Events

Package of events for building fault trees.

Event

Package: Events

isAbstract: Yes

Generalization: [FTAElement](#)

Applied Stereotype: «Situation»

Description

The Event is a base class for all types of fault tree events. It is a kind of [DysfunctionalEvent](#).

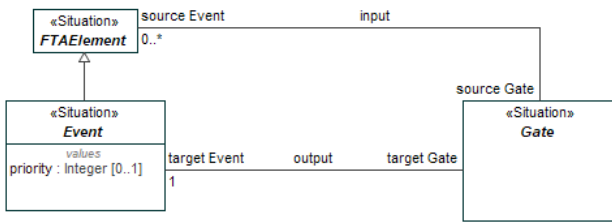


Figure 9.62 – Event

Attributes

priority : Integer[0..1]

The priority field is only used to indicate the order of this event when multiple events are inputs of Priority AND (SEQ) gate.

target Gate : Gate (member end of output association)

BasicEvent

Package: Events

isAbstract: No

Generalization: [Event](#)

Applied Stereotype: «BasicEvent»

Description

A basic initiating failure requiring no further development.

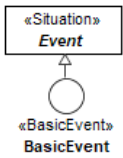


Figure 9.63 – BasicEvent

IntermediateEvent

Package: Events

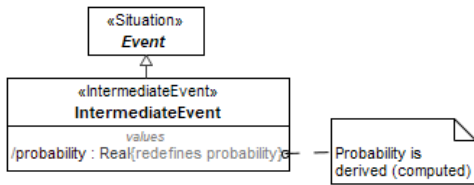
isAbstract: No

Generalization: [Event](#)

Applied Stereotype: «IntermediateEvent»

Description

An intermediate event is a failure which occurs because of one or more antecedent events acting through logic gates.



**Figure 9.64 – IntermediateEvent**

**Attributes**

probability : Real, redefines [probability](#)

Probability of the intermediate event is derived. It is calculated by the gate from the probabilities of the more basic events.

**TopEvent**

Package: Events

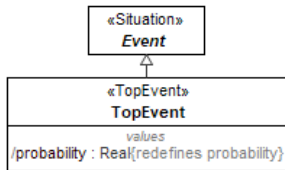
isAbstract: No

Generalization: [Event](#)

Applied Stereotype: «TopEvent»

**Description**

Undesired event - failure or effect - at the top of the fault tree.



**Figure 9.65 – TopEvent**

**Attributes**

probability : Real, redefines [probability](#)

The (derived) probability of the top event is the result of the fault tree calculation.

**ConditionalEvent**

Package: Events

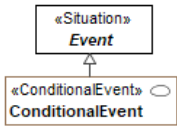
isAbstract: No

Generalization: [Event](#)

Applied Stereotype: «ConditionalEvent»

**Description**

Specific conditions or restrictions that apply to any logic gate (used primarily with PRIORITY AND and INHIBIT gates).



**Figure 9.66 – ConditionalEvent**

DormantEvent

Package: Events

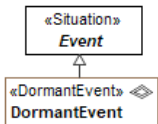
isAbstract: No

Generalization: [Event](#)

Applied Stereotype: [«DormantEvent»](#)

Description

The dormant event is similar to [BasicEvent](#) but indicates the latent failure which is discovered by periodical tests.



**Figure 9.67 – DormantEvent**

UndevelopedEvent

Package: Events

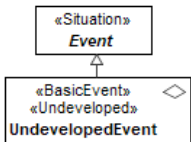
isAbstract: No

Generalization: [Event](#)

Applied Stereotype: [«BasicEvent»](#), [«Undeveloped»](#)

Description

An event which is not further developed either because it is of insufficient consequence or because information is unavailable.



**Figure 9.68 – UndevelopedEvent**

HouseEvent

Package: Events

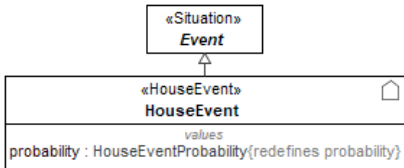
isAbstract: No

Generalization: [Event](#)

Applied Stereotype: [«HouseEvent»](#)

Description

An event which can be set to occur or not occur.



**Figure 9.69 – HouseEvent**

**Attributes**

probability : HouseEventProbability, Probability of the house event is 0 or 1. It is set before doing a fault tree redefines [probability](#) evaluation.

**ZeroEvent**

Package: Events

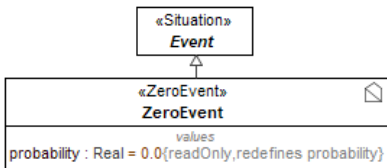
isAbstract: No

Generalization: [Event](#)

Applied Stereotype: [«ZeroEvent»](#)

**Description**

An event which represents a condition or an event that will never occur.



**Figure 9.70 – ZeroEvent**

**Attributes**

probability : Real, redefines [probability](#) The probability of zero event is always 0.

**Methods::FTA::FTALibrary::Gates**

Package of logical conditions for building fault trees.

**Gate**

Package: Gates

isAbstract: Yes

Applied Stereotype: [«Situation»](#)

**Description**

An [FTAElement](#) that combines input [Event](#) probabilities in a prescribed manner to determine output [Event](#) probability. The output event occurs if the combination of input events is satisfied. The gate subtypes specify the necessary combination.

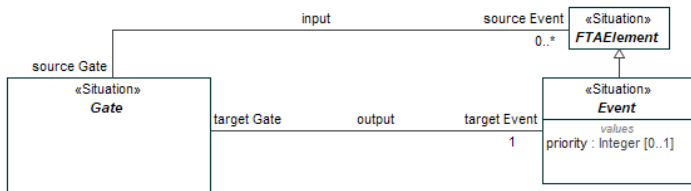


Figure 9.71 – Gate

Attributes

source Event : Event[0..\*] (member end of input association)

target Event : Event[1] (member end of output association)

AND

Package: Gates

isAbstract: No

Generalization: [Gate](#)

Applied Stereotype: «Block», «AND»

Description

The output event occurs only if all input events occur.

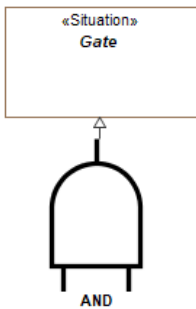


Figure 9.72 – AND

OR

Package: Gates

isAbstract: No

Generalization: [Gate](#)

Applied Stereotype: «Block», «OR»

Description

The output event occurs if at least one of input event occurs.

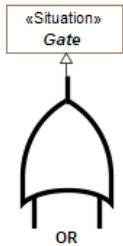


Figure 9.73 – OR

NOT

Package: Gates

isAbstract: No

Generalization: [Gate](#)

Applied Stereotype: «Block», «NOT»

Description

The output event occurs if the input event does not occur.

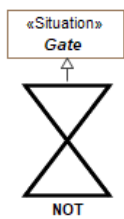


Figure 9.74 – NOT

XOR

Package: Gates

isAbstract: No

Generalization: [Gate](#)

Applied Stereotype: «Block», «XOR»

Description

The output event occurs if exactly one of the input events occurs.



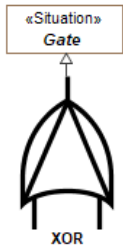


Figure 9.75 – XOR

SEQ

Package: Gates

isAbstract: No

Generalization: [Gate](#)

Applied Stereotype: «Block», [«SEQ»](#)

Description

The output event occurs if all the input events occur in a specific sequence.

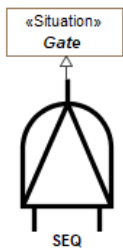


Figure 9.76 – SEQ

INHIBIT

Package: Gates

isAbstract: No

Generalization: [Gate](#)

Applied Stereotype: [«INHIBIT»](#), «Block»

Description

The output event occurs if the (single) input event occurs in the presence of an enabling condition.

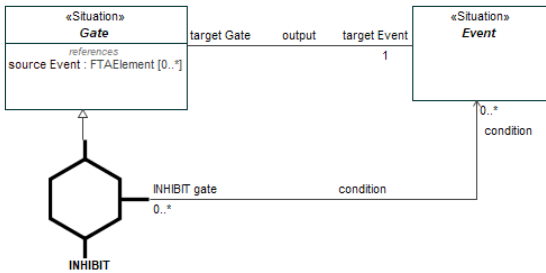


Figure 9.77 – INHIBIT

Attributes

condition : Event[0..\*] (member end of condition association)

MAJORITY\_VOTE

Package: Gates

isAbstract: No

Generalization: [Gate](#)

Applied Stereotype: «Block», [«MAJORITY\\_VOTE»](#)

Description

The output event occurs if the majority of the input events occurs. It has a threshold parameter m.

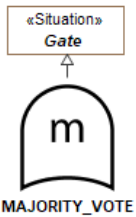


Figure 9.78 – MAJORITY\_VOTE

Attributes

m : Integer

The m parameter defines the number of input events that form a majority. It is not necessarily  $\text{ceil}(\text{number\_of\_inputs} / 2)$ . It is possible to stipulate that e.g., 5 (or 2) input events have to occur out of total of 7 events for majority gate to fire.

Methods::FTA::FTALibrary::Gates::ConstraintBlocks

Reference implementation for the FTA gates.

ANDConstraintBlock

Package: ConstraintBlocks

isAbstract: No

Applied Stereotype: «ConstraintBlock»

#### Description

Reference implementation for the [AND](#) gate.

#### Attributes

output :

input : [0..\*]

#### Constraints

- [1] Probability of AND node is simply a multiplication of probabilities of incoming nodes.  
Note - this simplistic calculation assumes that incoming node events are mutually independent.

#### ORConstraintBlock

**Package:** ConstraintBlocks

**isAbstract:** No

**Applied Stereotype:** «ConstraintBlock»

#### Description

Reference implementation for the [OR](#) gate.

#### Attributes

output :

input : [0..\*]

#### Constraints

- [1] Probability of OR node is calculated as opposite probability of the event where neither of the input events happen.  
This follows De Morgan's theorem -  $OR(input1, input2, input3\dots)$  is equal to  $NOT AND (NOT input1, NOT input2, NOT input3\dots)$ .  
Note - this simplistic calculation assumes that incoming node events are mutually independent.

#### SEQConstraintBlock

**Package:** ConstraintBlocks

**isAbstract:** No

**Applied Stereotype:** «ConstraintBlock»

#### Description

Reference implementation for the [SEQ](#) gate.

#### Attributes

output :

input : Real[0..\*]

#### Constraints

- [1] Probability of SEQ node is calculated the same way as AND node - it is simply a multiplication of probabilities of incoming nodes.

This simplistic calculation cannot capture time-dependency of the events; only more complex simulations can estimate this probability.

#### XORConstraintBlock

**Package:** ConstraintBlocks

**isAbstract:** No

**Applied Stereotype:** «ConstraintBlock»

#### Description

Reference implementation for the [XOR](#) gate.

#### Attributes

output :

input : [0..\*]

#### Constraints

[1]

In case of two inputs, XOR probability is calculated by ORing of two event combination probabilities - probability that first event happened and second did not ORed with probability that second event happened while first did not.

$$\text{Input1 XOR Input2} = \text{Input1 AND NOT Input2 OR Input2 AND NOT Input1}$$

Since combinations are mutually exclusive, simple (+) operation can be used for ORing them. Therefore

$$\text{Input1 XOR Input2} = \text{Input1 AND NOT Input2} + \text{Input2 AND NOT Input1}$$

Further expanding ANDs and NOTs using their corresponding formulas, we get

$$\text{Input1 XOR Input2} = \text{Input1} * (1 - \text{Input2}) + \text{Input2} * (1 - \text{Input1}) = \text{Input1} + \text{Input2} - 2 * \text{Input1} * \text{Input2}$$

This formula can be iteratively applied for the case with number of inputs greater than two.

Note - this simplistic calculation assumes that incoming node events are mutually independent.

#### INHIBITConstraintBlock

**Package:** ConstraintBlocks

**isAbstract:** No

**Applied Stereotype:** «ConstraintBlock»

#### Description

Reference implementation for the [INHIBIT](#) gate.

#### Attributes

output :

input : [0..\*]

condition : Real

#### Constraints

[1]

Probability of INHIBIT node is calculated the same way as AND node - it is simply a multiplication of probabilities of input nodes and condition nodes.

Note - this simplistic calculation assumes that incoming node events and conditions are mutually independent.

#### MAJORITY\_VOTEConstraintBlock

**Package:** ConstraintBlocks

**isAbstract:** No

**Applied Stereotype:** «ConstraintBlock»

#### Description

Reference implementation for the [MAJORITY\\_VOTE](#) gate.

#### Attributes

output :

input : [0..\*]

m :

#### Constraints

[1]

Majority Vote probability can be calculated by iteratively examining all the combinations of input events, taking those combinations that satisfy the condition that at least m input events happen, then calculating probability of each combination using AND formula (multiplying all individual event probabilities in that combination) and then calculating cumulative probability of all combinations by ORing them.

Note - this simplistic calculation assumes that incoming node events are mutually independent.

#### NOTConstraintBlock

**Package:** ConstraintBlocks

**isAbstract:** No

**Applied Stereotype:** «ConstraintBlock»

#### Description

Reference implementation for the [NOT](#) gate.

#### Attributes

output :

input : [1]

#### Constraints

[1]

Probability of NOT node is calculated as probability of the event opposite to the input event.

Thereby it is unity minus probability of input event.

### 9.5.2 Methods::FTA::FTAProfile

#### Tree

**Package:** FTAProfile

**isAbstract:** No

**Generalization:** [Situation](#)

**Extension:** Class

Description

A marker stereotype for fault trees. See [FTATree](#) library class for definition.

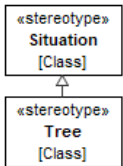


Figure 9.79 – Tree

Constraints

[1] TreeIsFTATree -- Tree stereotype can only be applied on any class specialized from FTATree from FTA Library  
 self.base\_Class->asSet()->closure(general).name->includes('FTATree')

Gate

**Package:** FTAProfile  
**isAbstract:** Yes  
**Extension:** Class, Property

Description

A marker stereotype for fault tree gates. See [Gate](#) library class for definition.

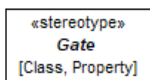


Figure 9.80 – Gate

Event

**Package:** FTAProfile  
**isAbstract:** Yes  
**Extension:** Class, Property

Description

A marker stereotype for fault tree events. See [Event](#) library class for definition.  
 If the Event stereotype is applied to a class, then that class also must have the Situation stereotype (or its descendants) applied.

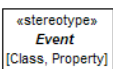


Figure 9.81 – Event

## DormantEvent

**Package:** FTAProfile

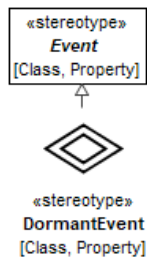
**isAbstract:** No

**Generalization:** [Event](#)

**Extension:** Class, Property

### Description

A marker stereotype, carrying icon for dormant events. See [DormantEvent](#) library class for definition.



**Figure 9.82 – DormantEvent**

### Constraints

[1]

DormantEventIsDormantEvent

```
if not self.base_Class->isEmpty() then
```

```
--DormantEvent stereotype can only be applied on any class specialized from  
DormantEvent from FTA Library
```

```
self.base_Class->asSet()->closure(general).name->includes('DormantEvent')
```

```
else
```

```
--DormantEvent stereotype can only be applied on any property whose type is  
specialized from DormantEvent from FTA Library
```

```
self.base_Property.type->asSet()->closure(general).name-
```

```
>includes('DormantEvent')
```

```
endif
```

## BasicEvent

**Package:** FTAProfile

**isAbstract:** No

**Generalization:** [Event](#)

**Extension:** Class, Property

### Description

A marker stereotype, carrying icon for basic events. See [BasicEvent](#) library class for definition.

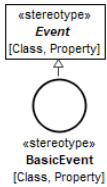


Figure 9.83 – BasicEvent

#### Constraints

[1] BasicEventIsBasicEvent

```

if not self.base_Class->isEmpty() then
  --BasicEvent stereotype can only be applied on any class specialized from
  BasicEvent from FTA Library
  self.base_Class->asSet()->closure(general).name->includes('BasicEvent')
else
  --BasicEvent stereotype can only be applied on any property whose type is
  specialized from BasicEvent from FTA Library
  self.base_Property.type->asSet()->closure(general).name-
  >includes('BasicEvent')
endif

```

[2] UndevelopedEventIsUndevelopedEvent

```

--BasicEvent + Undeveloped stereotype combination can be applied on any
class specialized from UndevelopedEvent from FTA Library
Undeveloped.allInstances().base_Element->includesAll(self.base_Class)
implies
self.base_Class->asSet()->closure(general).name-
>includes('UndevelopedEvent')

```

#### ConditionalEvent

**Package:** FTAProfile  
**isAbstract:** No  
**Generalization:** [Event](#)  
**Extension:** Class, Property

#### Description

A marker stereotype, carrying icon for conditional events. See [ConditionalEvent](#) library class for definition.



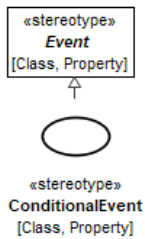


Figure 9.84 – ConditionalEvent

Constraints

```
[1]
ConditionalEventIsConditionalEvent
    if not self.base_Class->isEmpty() then
        --ConditionalEvent stereotype can only be applied on any class specialized
        from ConditionalEvent from FTA Library
        self.base_Class->asSet()->closure(general).name-
        >includes('ConditionalEvent')
    else
        --ConditionalEvent stereotype can only be applied on any property whose type
        is specialized from ConditionalEvent from FTA Library
        self.base_Property.type->asSet()->closure(general).name-
        >includes('ConditionalEvent')
    endif
```

ZeroEvent

**Package:** FTAProfile  
**isAbstract:** No  
**Generalization:** [Event](#)  
**Extension:** Class, Property

Description

A marker stereotype, carrying icon for zero events. See [ZeroEvent](#) library class for definition.

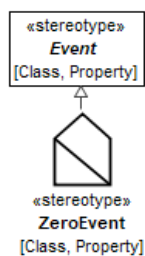


Figure 9.85 – ZeroEvent

Constraints

[1] ZeroEventIsZeroEvent

```
if not self.base_Class->isEmpty() then
  --ZeroEvent stereotype can only be applied on any class specialized from ZeroEvent
  from FTA Library
  self.base_Class->asSet()->closure(general).name->includes('ZeroEvent')
else
  --ZeroEvent stereotype can only be applied on any property whose type is
  specialized from ZeroEvent from FTA Library
  self.base_Property.type->asSet()->closure(general).name->includes('ZeroEvent')
endif
```

HouseEvent

**Package:** FTAProfile  
**isAbstract:** No  
**Generalization:** [Event](#)  
**Extension:** Class, Property

Description

A marker stereotype, carrying icon for house events. See [HouseEvent](#) library class for definition.

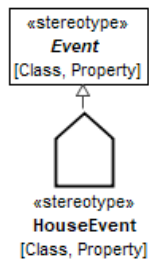


Figure 9.86 – HouseEvent

Constraints

[1] HouseEventIsHouseEvent

```
if not self.base_Class->isEmpty() then
  --HouseEvent stereotype can only be applied on any class specialized from
  HouseEvent from FTA Library
  self.base_Class->asSet()->closure(general).name->includes('HouseEvent')
else
  --HouseEvent stereotype can only be applied on any property whose type is
  specialized from HouseEvent from FTA Library
  self.base_Property.type->asSet()->closure(general).name->includes('HouseEvent')
endif
```

## AND

**Package:** FTAProfile  
**isAbstract:** No  
**Generalization:** [Gate](#)  
**Extension:** Class, Property

### Description

A marker stereotype, carrying icon for AND gates. See [AND](#) library class for definition.

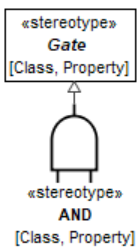


Figure 9.87 – AND

### Constraints

[1] ANDIsAND

```
if not self.base_Class->isEmpty() then
    --AND stereotype can only be applied on any class specialized from AND gate from
    FTA Library
    self.base_Class->asSet()->closure(general).name->includes('AND')
else
    --AND stereotype can only be applied on any property whose type is specialized
    from AND from FTA Library
    self.base_Property.type->asSet()->closure(general).name->includes('AND')
endif
```

## OR

**Package:** FTAProfile  
**isAbstract:** No  
**Generalization:** [Gate](#)  
**Extension:** Class, Property

### Description

A marker stereotype, carrying icon for OR gates. See [OR](#) library class for definition.

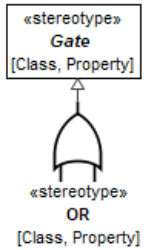


Figure 9.88 – OR

Constraints  
 [1] ORIsOR

```

if not self.base_Class->isEmpty() then
  --OR stereotype can only be applied on any class specialized from OR gate from
  FTA Library
  self.base_Class->asSet()->closure(general).name->includes('OR')
else
  --OR stereotype can only be applied on any property whose type is specialized from
  OR from FTA Library
  self.base_Property.type->asSet()->closure(general).name->includes('OR')
endif

```

SEQ

**Package:** FTAProfile  
**isAbstract:** No  
**Generalization:** [Gate](#)  
**Extension:** Class, Property

Description

A marker stereotype, carrying icon for SEQ gates. See [SEQ](#) library class for definition.

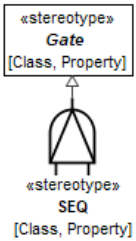


Figure 9.89 – SEQ

#### Constraints

[1] SEQIsSEQ

```
if not self.base_Class->isEmpty() then
  --SEQ stereotype can only be applied on any class specialized from SEQ gate from
  FTA Library
  self.base_Class->asSet()->closure(general).name->includes('SEQ')
else
  --SEQ stereotype can only be applied on any property whose type is specialized
  from SEQ from FTA Library
  self.base_Property.type->asSet()->closure(general).name->includes('SEQ')
endif
```

#### XOR

**Package:** FTAProfile

**isAbstract:** No

**Generalization:** [Gate](#)

**Extension:** Class, Property

#### Description

A marker stereotype, carrying icon for XOR gates. See [XOR](#) library class for definition.

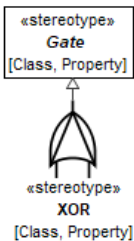


Figure 9.90 – XOR

#### Constraints

[1] XORIsXOR

```
if not self.base_Class->isEmpty() then
  --XOR stereotype can only be applied on any class specialized from XOR gate from
  FTA Library
  self.base_Class->asSet()->closure(general).name->includes('XOR')
else
  --XOR stereotype can only be applied on any property whose type is specialized
  from XOR from FTA Library
  self.base_Property.type->asSet()->closure(general).name->includes('XOR')
endif
```

## INHIBIT

**Package:** FTAProfile  
**isAbstract:** No  
**Generalization:** [Gate](#)  
**Extension:** Class, Property

### Description

A marker stereotype, carrying icon for INHIBIT gates. See [INHIBIT](#) library class for definition.

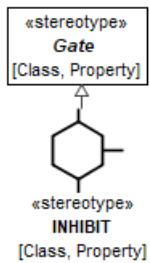


Figure 9.91 – INHIBIT

### Constraints

```
[1] INHIBITisINHIBIT
    if not self.base_Class->isEmpty() then
        --INHIBIT stereotype can only be applied on any class specialized from INHIBIT
        gate from FTA Library
        self.base_Class->asSet()->closure(general).name->includes('INHIBIT')
    else
        --INHIBIT stereotype can only be applied on any property whose type is specialized
        from INHIBIT from FTA Library
        self.base_Property.type->asSet()->closure(general).name->includes('INHIBIT')
    endif
```

## MAJORITY\_VOTE

**Package:** FTAProfile  
**isAbstract:** No  
**Generalization:** [Gate](#)  
**Extension:** Class, Property

### Description

A marker stereotype, carrying icon for MAJORITY\_VOTE gates. See [MAJORITY\\_VOTE](#) library class for definition.

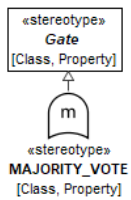


Figure 9.92 – MAJORITY\_VOTE

Constraints

```

[1] MAJORITY_VOTE is MAJORITY_VOTE
if not self.base_Class->isEmpty() then
  --MAJORITY_VOTE stereotype can only be applied on any class
  specialized from MAJORITY_VOTE gate from FTA Library
  self.base_Class->asSet()->closure(general).name-
  >includes('MAJORITY_VOTE')
else
  --MAJORITY_VOTE stereotype can only be applied on any property
  whose type is specialized from MAJORITY_VOTE from FTA Library
  self.base_Property.type->asSet()->closure(general).name-
  >includes('MAJORITY_VOTE')
endif
  
```

NOT

**Package:** FTAProfile  
**isAbstract:** No  
**Generalization:** Gate  
**Extension:** Class, Property  
 Description

A marker stereotype, carrying icon for NOT gates. See [NOT](#) library class for definition.

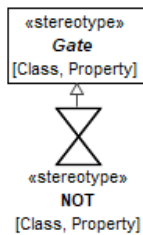


Figure 9.93 – NOT

Constraints

[1] NOTIsNOT

```
if not self.base_Class->isEmpty() then
  --NOT stereotype can only be applied on any class specialized from NOT gate from
  FTA Library
  self.base_Class->asSet()->closure(general).name->includes('NOT')
else
  --NOT stereotype can only be applied on any property whose type is specialized
  from NOT from FTA Library
  self.base_Property.type->asSet()->closure(general).name->includes('NOT')
endif
```

IntermediateEvent

**Package:** FTAProfile

**isAbstract:** No

**Generalization:** [Event](#)

**Extension:** Class, Property

Description

A marker stereotype, carrying icon for intermediate events. See [IntermediateEvent](#) library class for definition.

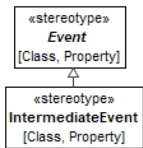


Figure 9.94 – IntermediateEvent

Constraints

[1]

IntermediateEventIsIntermediateEvent

```
if not self.base_Class->isEmpty() then
  --IntermediateEvent stereotype can only be applied on any class specialized
  from IntermediateEvent from FTA Library
  self.base_Class->asSet()->closure(general).name-
  >includes('IntermediateEvent')
else
  --IntermediateEvent stereotype can only be applied on any property whose
  type is specialized from IntermediateEvent from FTA Library
  self.base_Property.type->asSet()->closure(general).name-
  >includes('IntermediateEvent')
endif
```



## TopEvent

**Package:** FTAProfile

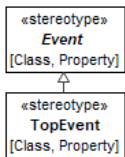
**isAbstract:** No

**Generalization:** [Event](#)

**Extension:** Class, Property

### Description

A marker stereotype, carrying icon for top events. See [TopEvent](#) library class for definition.



**Figure 9.95 – TopEvent**

### Constraints

[1] TopEventIsTopEvent

```
if not self.base_Class->isEmpty() then
```

```
--TopEvent stereotype can only be applied on any class specialized from TopEvent  
from FTA Library
```

```
self.base_Class->asSet()->closure(general).name->includes('TopEvent')
```

```
else
```

```
--TopEvent stereotype can only be applied on any property whose type is specialized  
from TopEvent from FTA Library
```

```
self.base_Property.type->asSet()->closure(general).name->includes('TopEvent')
```

```
endif
```

## TransferIn

**Package:** FTAProfile

**isAbstract:** No

**Extension:** Property

### Description

The node of the current fault tree that indicates that the tree is developed further as a separate fault tree - [TransferOut](#).



**Figure 9.96 – TransferIn**

Constraints  
 [1] TypeIsTransferOut -- type of TransferIn property must be TransferOut FTA Tree  
 TransferOut.allInstances().base\_Class->includesAll(self.base\_Property.type)

TransferOut  
**Package:** FTAProfile  
**isAbstract:** No  
**Generalization:** [Tree](#)  
**Extension:** Class

Description  
 A marker stereotype for partial fault trees. It indicates that this tree is used as a part of another fault tree through [TransferIn](#). The computed probability of the top event of the TransferOut tree is used as a probability of the [TransferIn](#) node.

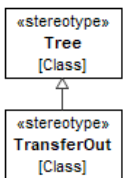


Figure 9.97 – TransferOut

## 9.6 Methods::STPA

The System Theoretical Process Analysis (STPA) is a hazard analysis technique based on control and system theory. In comparison, most existing hazard analysis techniques are based on reliability theory. In STPA, however, the easy goals are pursued as in any hazard analysis, i.e., collecting information on how hazards may occur. For further information on this approach the handbook<sup>1</sup> describes the method and show the application.

### 9.6.1 Methods::STPA::STPA Library

OutOfSequence  
**Package:** STPA Library  
**isAbstract:** Yes  
**Generalization:** [UndesiredControlAction](#)  
**Applied Stereotype:** [«UndesiredControlAction»](#)

Description  
 STPA Guideword, describing kind of control.

- Commented [AA19]: RAAML11-28
- Deleted: [UnsafeControlAction](#)
- Commented [AA20]: RAAML11-28
- Deleted: [safe](#)

<sup>1</sup> [https://psas.scripts.mit.edu/home/get\\_file.php?name=STPA\\_handbook.pdf](https://psas.scripts.mit.edu/home/get_file.php?name=STPA_handbook.pdf)

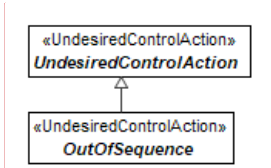


Figure 9.98 – OutOfSequence

Late

Package: STPA Library

isAbstract: Yes

Generalization: [UndesiredControlAction](#)

Applied Stereotype: «UndesiredControlAction»

Description

STPA Guideword, describing kind of control.

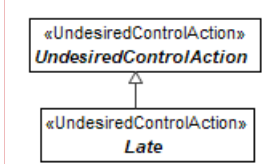


Figure 9.99 – Late

Early

Package: STPA Library

isAbstract: Yes

Generalization: [UndesiredControlAction](#)

Applied Stereotype: «UndesiredControlAction»

Description

STPA Guideword, describing kind of control.

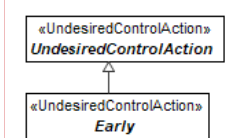


Figure 9.100 – Early

TooLong

Package: STPA Library

isAbstract: Yes

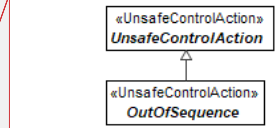
Generalization: [UndesiredControlAction](#)

Applied Stereotype: «UndesiredControlAction»

Description

STPA Guideword, describing kind of control.

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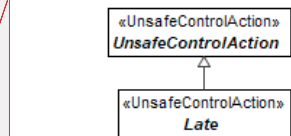
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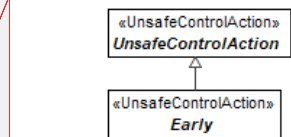
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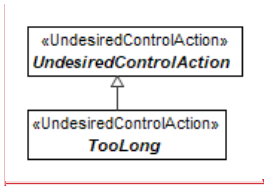


Figure 9.101 – TooLong

TooShort

Package: STPA Library

isAbstract: Yes

Generalization: [UndesiredControlAction](#)

Applied Stereotype: «UndesiredControlAction»

Description

STPA Guideword, describing kind of control.

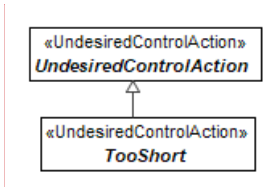


Figure 9.102 – TooShort

Provided

Package: STPA Library

isAbstract: Yes

Generalization: [UndesiredControlAction](#)

Applied Stereotype: «UndesiredControlAction»

Description

STPA Guideword, describing a kind of control.

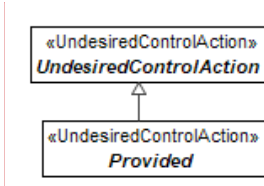


Figure 9.103 – Provided

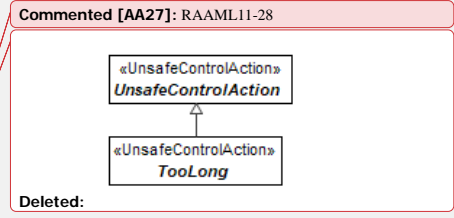
NotProvided

Package: STPA Library

isAbstract: Yes

Generalization: [UndesiredControlAction](#)

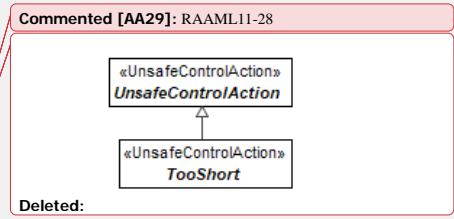
Applied Stereotype: «UndesiredControlAction»



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Commented [AA28]: RAAML11-28

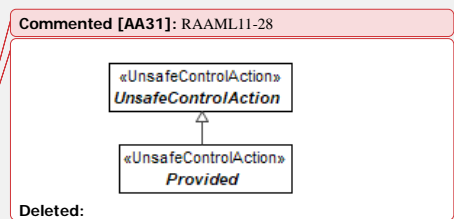
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Description

STPA Guideword, describing kind of control.



Figure 9.104 – NotProvided

LossScenario

Package: STPA Library

isAbstract: Yes

Generalization: Scenario

Applied Stereotype: «LossScenario»

Description

A sequence of situations starting from causalFactors, that (through Process Model deficiencies) leads to an UndesiredControlAction (which further leads to risks and possibly losses).

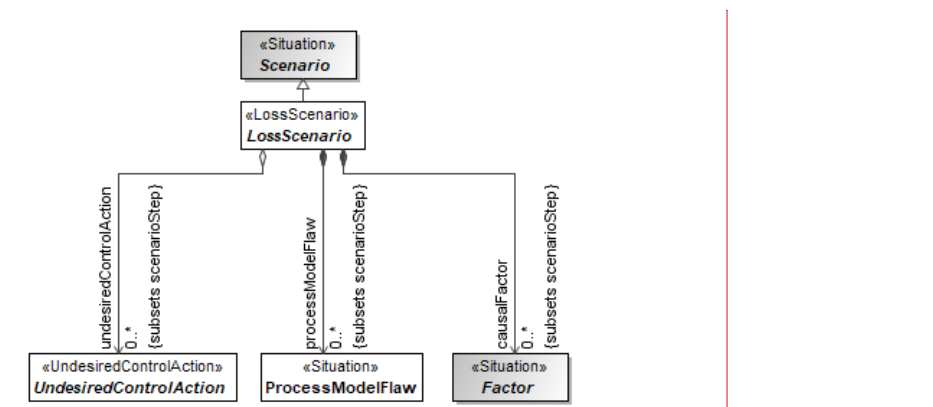


Figure 9.105 – LossScenario

Attributes

causalFactor : Factor[0..\*] (member end of association, subsets scenarioStep)

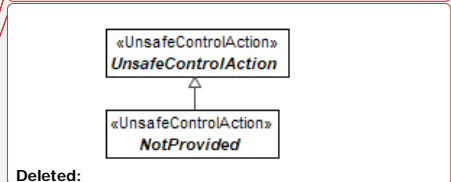
A causalFactor can be used to further refine Process Model inadequacies - specifying causes of deficiencies in the process model and/or other contributing factors.

undesiredControlAction :

Undesired control action related to the loss scenario.

UndesiredControlAction[0..\*] (member end of association, subsets scenarioStep)

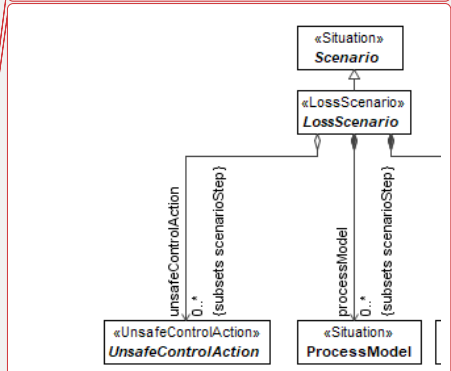
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Deleted: UnsafeControlAction

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Deleted: unsafeControlAction

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processModelFlaw : ProcessModelFlaw[0..\*]  
 (member end of association, subsets scenarioStep)

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ProcessModelFlaw

Commented [AA37]: RAAML11-28

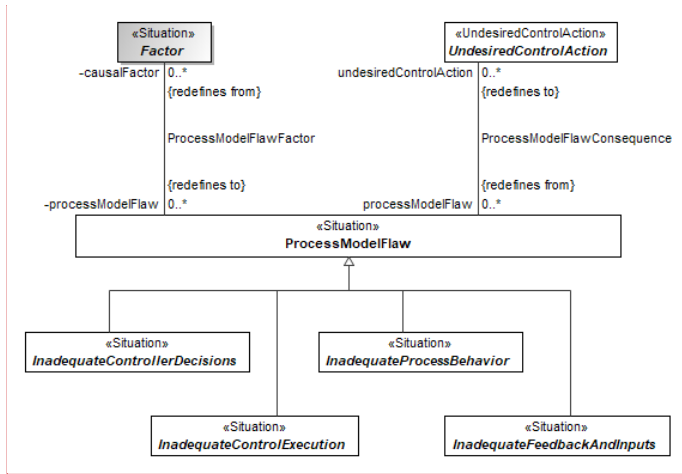
Package: STPA Library  
 isAbstract: No  
 Applied Stereotype: «Situation»

Description

A ProcessModelFlaw describes a process / control loop model that may lead to an Undesired Control Action. The four high level kinds of process model deficiencies can be used to specify the section of the control loop. Process model deficiencies are often called (high level) Scenario in STPA theory.

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Figure 9.106 – ProcessModelFlaw

Attributes

undesiredControlAction : Undesired control action related to process model flaw.  
 UndesiredControlAction[0..\*] (member end of ProcessModelFlawConsequence association, redefines to)

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Deleted: Factor : Factor[0..\*] (member end of ProcessModelFactor association, redefines from)

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InadequateControllerDecisions

Package: STPA Library  
 isAbstract: Yes  
 Generalization: ProcessModelFlaw  
 Applied Stereotype: «Situation»

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Description

A kind of ProcessFlaw.

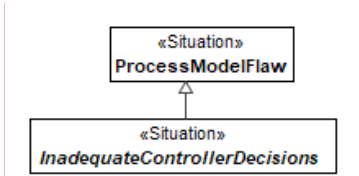
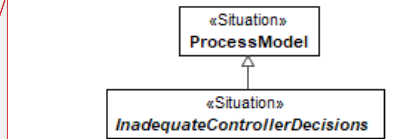


Figure 9.107 – InadequateControllerDecisions

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InadequateControlExecution

Package: STPA Library

isAbstract: Yes

Generalization: [ProcessModelFlaw](#)

Applied Stereotype: «Situation»

Description

A kind of ProcessFlaw.

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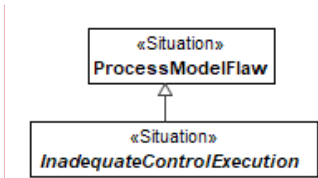
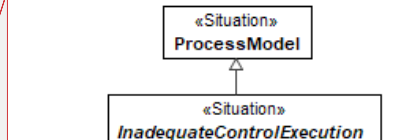


Figure 9.108 – InadequateControlExecution

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InadequateProcessBehavior

Package: STPA Library

isAbstract: Yes

Generalization: [ProcessModelFlaw](#)

Applied Stereotype: «Situation»

Description

A kind of ProcessFlaw.

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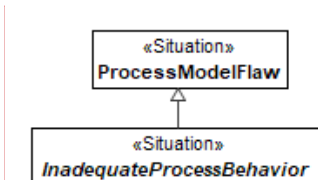
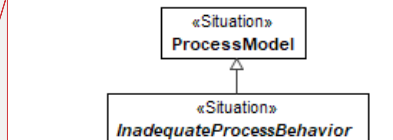


Figure 9.109 – InadequateProcessBehavior

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## InadequateFeedbackAndInputs

Package: STPA Library

isAbstract: Yes

Generalization: [ProcessModelFlaw](#)

Applied Stereotype: [«Situation»](#)

Description

A kind of ProcessFlaw.

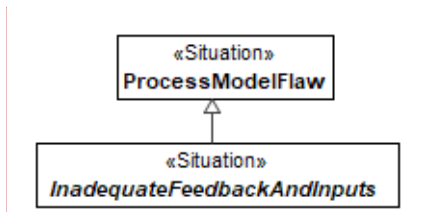


Figure 9.110 – InadequateFeedbackAndInputs

## UndesiredControlAction

Package: STPA Library

isAbstract: Yes

Generalization: [UndesiredState](#)

Applied Stereotype: [«UndesiredControlAction»](#)

Description

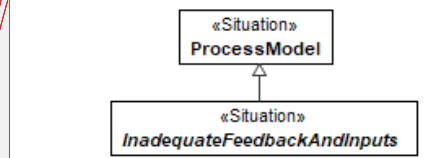
An **Undesired** Control Action (UCA), used in STPA, describes in what context providing / not providing a Control Action might lead to an undesired result.

A UCA generally consist of four parts:

- Controller (Subject) that issues the Control Action - inferred from Control Action and model of the system (block/part producing the control action).
- Guideword (provides, does not provide, etc.) - indicated using Generalization relationship
- Control Action - connected with RelevantTo relationship.
- Context in which Control Action leads to undesired outcome - sub situation of (part of) UCA situation.

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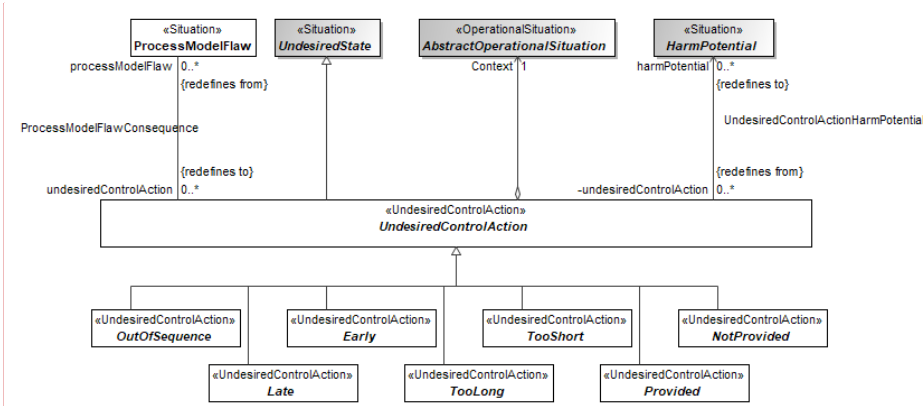


Figure 9.111 – UndesiredControlAction

Attributes

Context : AbstractOperationalSituation[1] *The context of the undesired control action.*  
 (member end of association)

processModelFlaw : *Process model flaw related to the undesired control action.*  
 ProcessModelFlaw[0..\*] (member end of [ProcessModelFlawConsequence](#) association, redefines from)

harmPotential : HarmPotential[0..\*] *Harm potential related to the undesired control action.*  
 (member end of [UndesiredControlActionHarmPotential](#) association, redefines to)

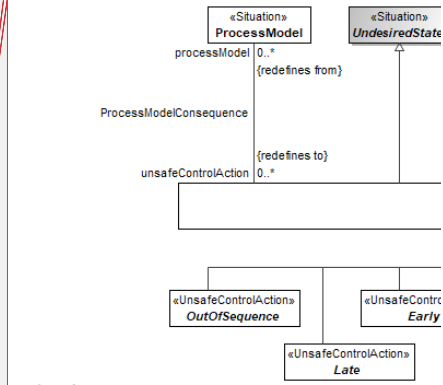
RiskRealization

Package: STPA Library  
 isAbstract: No  
 Generalization: [AbstractRisk](#), Causality  
 Applied Stereotype: «Block»

Description

Association between the Loss and Hazard (potential harm).

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Moved up [1]: Factor

Deleted: Package: STPA Library  
 isAbstract: No  
 Generalization: [AbstractCause](#)  
 Applied Stereotype: «Situation»  
 Description  
 A Factor (F) can be used to further refine Process Model inadequacies - specifying causes of deficiencies in the process model and/or other contributing factors.  
 Attributes  
 processModel : ProcessModel[0..\*] (member end of [ProcessModelFactor](#) association, redefines to)

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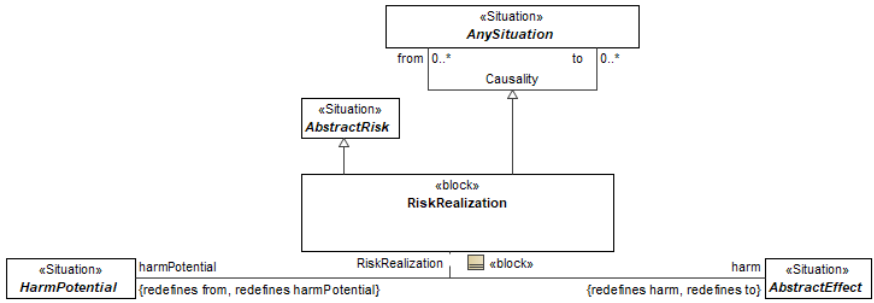


Figure 9.112 – RiskRealization

ProcessModelFlawFactor

Package: STPA Library

Generalization: Causality

Description

Causal relationship between CausalFactor and ProcessFlaw

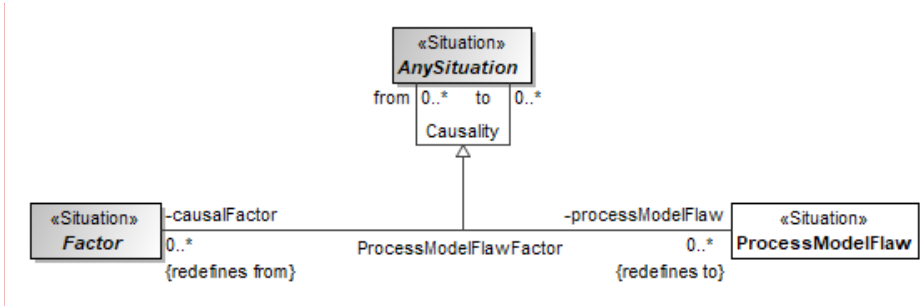


Figure 9.113 – ProcessModelFlawFactor

Association ends

processModelFlaw : Process model flaw related to the process model flaw factor.

ProcessModelFlaw[0..\*] (member end of ProcessModelFlawFactor association, redefines to)

causalFactor : Factor[0..\*] (member end of ProcessModelFlawFactor association, redefines from) A causalFactor can be used to further refine Process Model inadequacies - specifying causes of deficiencies in the process model and/or other contributing factors.

ProcessModelFawConsequence

Package: STPA Library

Generalization: Causality

Description

Causal relationship between ProcessModelFlaw and UndesiredControlAction

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Commented [AA57]: RAAML11-28

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Deleted: UnsafeControlAction

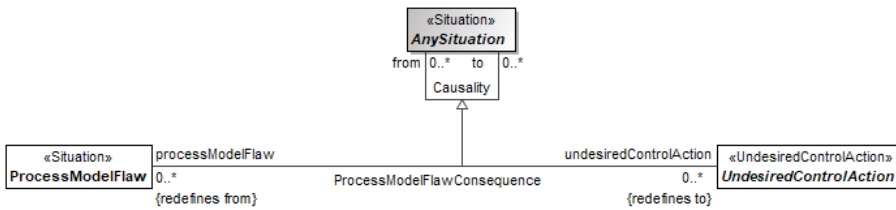


Figure 9.114 – ProcessModelFlawConsequence

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Association ends

undesiredControlAction : Undesired control action related to process model flaw.

UndesiredControlAction[0..\*] (member end of ProcessModelFlawConsequence association, redefines to)

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processModelFlaw : ProcessModelFlaw[0..\*] Process model flaw related to the undesired control action.

(member end of ProcessModelFlawConsequence association, redefines from)

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UndesiredControlActionHarmPotential

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Package: STPA Library

Generalization: Causality

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Description

Causal relationship between UndesiredControlAction and HarmPotential.

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Deleted: RiskSource

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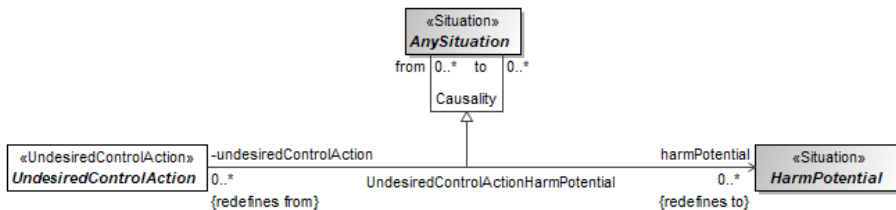


Figure 9.115 – UndesiredControlActionHarmPotential

Association ends

harmPotential : HarmPotential[0..\*] (member end of UndesiredControlActionHarmPotential association, redefines to)

Deleted: UnsafeControlActionHarmPotential

undesiredControlAction : Harm potential (or hazard, or threat) related to the undesired control action.

UndesiredControlAction[0..\*] (member end of UndesiredControlActionHarmPotential association, redefines from)

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Deleted: UnsafeControlActionHarmPotential

## 9.6.2 Methods::STPA::STPA Profile

ControlAction

**Package:** STPA Profile

**isAbstract:** No

**Extension:** Signal, Class, DataType

Description

A Control Action (CA) is an output signal from a functional / logical Controller to a ControlledProcess (via the Actuator), that determines the receiving process behaviour.

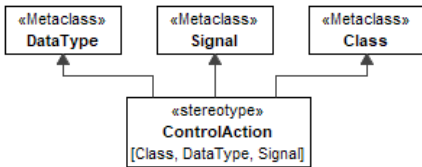


Figure 9.116 – ControlAction

Feedback

**Package:** STPA Profile

**isAbstract:** No

**Extension:** Signal, Class, DataType

Description

A Feedback is an input signal to a functional / logical Controller from a ControlledProcess (via the Sensor), that characterizes the current processes behavior (or the environment).

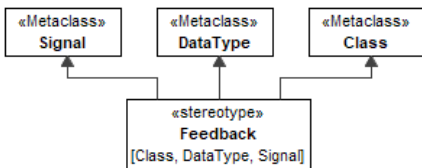


Figure 9.117 – Feedback

UndesiredControlAction

**Package:** STPA Profile

**isAbstract:** No

**Generalization:** [Situation](#)

**Extension:** Class

Description

Stereotype used to demarcate all the UndesiredControlActions.

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Commented [AA70]: RAAML11-28

Deleted: UnsafeControlActions

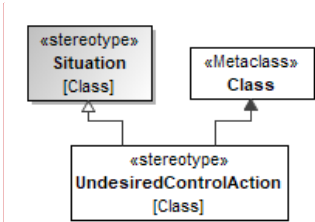


Figure 9.118 – UndesiredControlAction

UnsafeControlAction

Package: STPA Profile

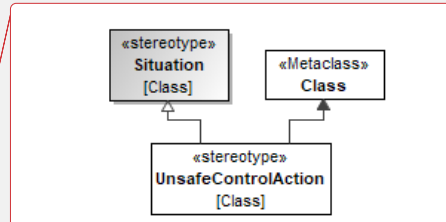
isAbstract: No

Generalization: UndesiredControlAction

Extension: Class

Description

Stereotype used to demarcate all the UnsafeControlActions.



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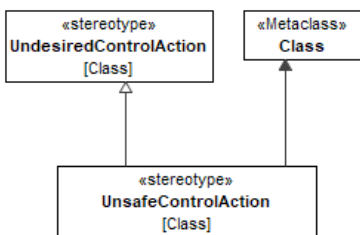


Figure 9.119 – UnsafeControlAction

ControlledProcess

Package: STPA Profile

isAbstract: No

Extension: Property, Class

Description

An abstract representation of the system and its behaviours that need to be supervised and governed.

Controller is controlling this process through the ControlAction via the Actuator.

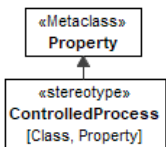


Figure 9.120 – ControlledProcess

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Actuator

**Package:** STPA Profile  
**isAbstract:** No  
**Extension:** Property, Class

Description

Actuator receives ControlActions from Controller and influences the ControlledProcess in some way.

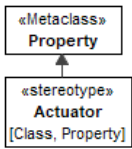


Figure 9.121 – Actuator

Sensor

**Package:** STPA Profile  
**isAbstract:** No  
**Extension:** Property, Class

Description

Sensor assesses the ControlledProcess (also environment or other controllers) and gives Feedback to the Controller.

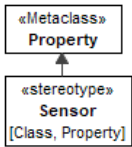


Figure 9.122 – Sensor

Controller

**Package:** STPA Profile  
**isAbstract:** No  
**Extension:** Property, Class

Description

Controller sends the ControlActions and receives Feedback.

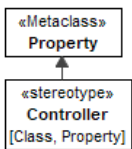


Figure 9.123 – Controller

ControlStructure

**Package:** STPA Profile

**isAbstract:** No  
**Generalization:** Block  
**Extension:** Class

Description

ControlStructure is a system-of-systems composed of ControlledProcess, Controller and their functional relationships - ControllActions, Feedbacks, describing feedback control loops.

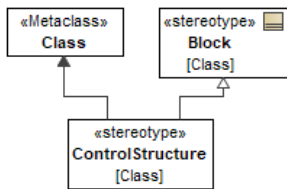


Figure 9.124 – ControlStructure

LossScenario

**Package:** STPA Profile  
**isAbstract:** No  
**Generalization:** [Situation](#)  
**Extension:** Class

Description

Stereotype used to demarcate all the LossScenarios.

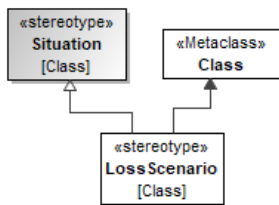


Figure 9.125 – LossScenario

## 9.7 GSN

The GSN profile is an implementation of the core notation described in the GSN version 2 standard. The GSN standard is made available under creative commons licence version 4:

“To view a copy of this license, visit <http://creativecommons.org/licenses/by/4.0/> or send a letter to Creative Commons, PO Box 1866, Mountain View, CA 94042, USA.”.

The OMG acknowledges the work of the SCSC ACWG in the production of the GSN standard.

Whilst GSN is an extension of the OMG SACM standard, which has a defined meta-model based on the OMG MOF standard, the objectives of RAAML to integrate with SysML 1.6 necessitate the use of a UML profile interpretation of the GSN standard.

## 9.7.1 GSN::GSN Profile

### Notation

Most of the stereotypes in GSN profile have stereotype images specified. Displaying the stereotyped GSN elements in UML Class diagram may follow the UML standard prescription (UML 2.5.1, Chapter 12.3.4.1 Icon presentation) for displaying elements having stereotypes with icons, namely:

- Showing model element as an image with element name below
- Showing model element as a box with the iconic form image inside the box at the top left



Figure 9.126 – Standard UML notation for stereotyped elements (from UML 2.5.1, Figure 12.25)

However, in addition to the notation described in UML standard, this standard allows additional notation. Namely – using stereotype image as a (resizable) outline/shape of the box, with the same compartments that are prescribed by the UML standard (including name/stereotype/tag values compartment) inside. This notation is recommended i.e., preferred over the standard UML notation.

An example of the SCSC/GSN standard representation of the GSN extension is shown in Figure 9.106. See the SCSC/GSN standard for the shapes and text placement to be used for various model element types.

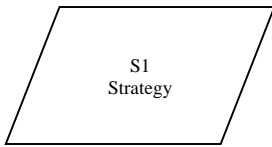


Figure 9.127 - Strategy notation

### Combined Stereotype Notation

The UML standard allows a combination of several stereotypes applied on the model element. Namely – the combination of Goal+Undeveloped stereotypes and Strategy+Undeveloped stereotypes is being used. An example of this notation is depicted in Figure 9.107. See the SCSC/GSN standard for the shapes and text placement to be used for various model element types.



Figure 9.128 - Combined notation

### GSNNode

**Package:** GSN Profile

**isAbstract:** Yes

**Extension:** Element



Description

Root type for all the different kinds of nodes in GSN.

Note: name versus human-readable ID

GSN domain elements frequently have both a short phrase, describing the element and human-readable identifier. For example:

G1 Control System is acceptably safe to operate

In this example “Control System is acceptably safe to operate” is a short phrase, describing the goal, while G1 is a human-readable identifier of the goal.

In this standard, the short phrase shall be captured as UML model element name – NamedElement::name field. Human-readable identifier shall be stored in a separate tag, defined in the Core profile – IDCarrier::id..

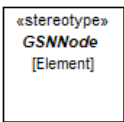


Figure 9.129 – GSNNode

Attributes

id : String[0..1]

GSNArgumentNode

Package: GSN Profile

isAbstract: Yes

Generalization: [GSNNode](#)

Extension: Element

Description

A [Goal](#) or a [Strategy](#).

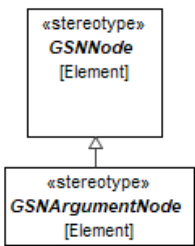


Figure 9.130 – GSNArgumentNode

Solution

**Package:** GSN Profile  
**isAbstract:** No  
**Generalization:** [GSNNode](#)  
**Extension:** Class

Description

A solution presents a reference to an evidence item or items.

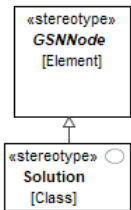


Figure 9.131 – Solution

Goal

**Package:** GSN Profile  
**isAbstract:** No  
**Generalization:** [GSNArgumentNode](#)  
**Extension:** Class

Description

A goal presents a claim forming part of the argument.

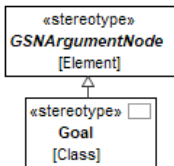


Figure 9.132 – Goal

Strategy

**Package:** GSN Profile  
**isAbstract:** No  
**Generalization:** [GSNArgumentNode](#)  
**Extension:** Class

Description

A strategy describes the nature of the inference that exists between a goal and its supporting goal(s).

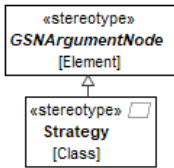


Figure 9.133 – Strategy

ContextualInformation

Package: GSN Profile

isAbstract: Yes

Extension: Element

Description

A [Context](#) or an [Assumption](#) or a [Justification](#).

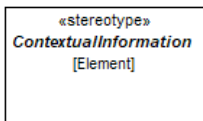


Figure 9.134 – ContextualInformation

Attributes

id : String[0..1]

Context

Package: GSN Profile

isAbstract: No

Generalization: [ContextualInformation](#)

Extension: Class

Description

A context presents a contextual artefact. This can be a reference to contextual information, or a statement.

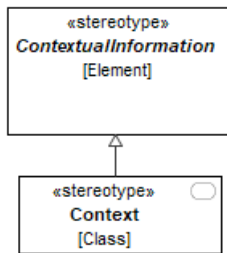


Figure 9.135 – ContextStatement

Assumption

**Package:** GSN Profile

**isAbstract:** No

**Generalization:** [SupportingInformation](#)

**Extension:** Class

Description

An assumption presents an intentionally unsubstantiated statement.

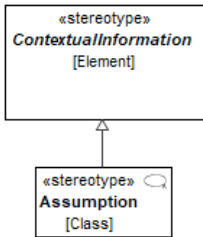


Figure 9.136 – Assumption

Justification

**Package:** GSN Profile

**isAbstract:** No

**Generalization:** [ContextualInformation](#)

**Extension:** Class

Description

A justification presents a statement of rationale.

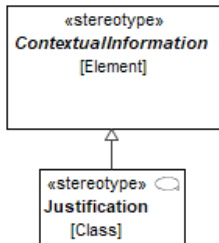


Figure 9.137 – Justification

InContextOf

**Package:** GSN Profile

**isAbstract:** No

**Extension:** Dependency

Description

InContextOf declares a contextual relationship.

Permitted connections are: goal-to-context, goal-to-assumption, goal-to-justification, strategy-to-context, strategy-to-assumption and strategy-to-justification.

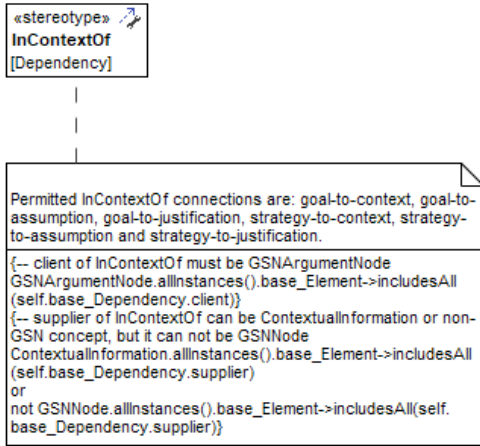


Figure 9.138 – InContextOf

Constraints

- [1] ClientIsArgumentNode -- client of InContextOf must be GSNArgumentNode  
GSNArgumentNode.allInstances().base\_Element->includesAll(self.base\_Dependency.client)
- [2] SupplierIsNotGSNNode -- supplier of InContextOf can be ContextualInformation or non-GSN concept, but it can not be GSNNode  
ContextualInformation.allInstances().base\_Element->includesAll(self.base\_Dependency.supplier)  
or  
not GSNNode.allInstances().base\_Element->includesAll(self.base\_Dependency.supplier)

SupportedBy

**Package:** GSN Profile  
**isAbstract:** No  
**Extension:** Dependency

Description

SupportedBy allows inferential or evidential relationships to be documented. Inferential relationships declare that there is an inference between goals in the argument. Evidential relationships declare the link between a goal and the evidence used to substantiate it. Permitted supported by connections are: goal-to-goal, goal-to-strategy, goal-to-solution, strategy to goal.

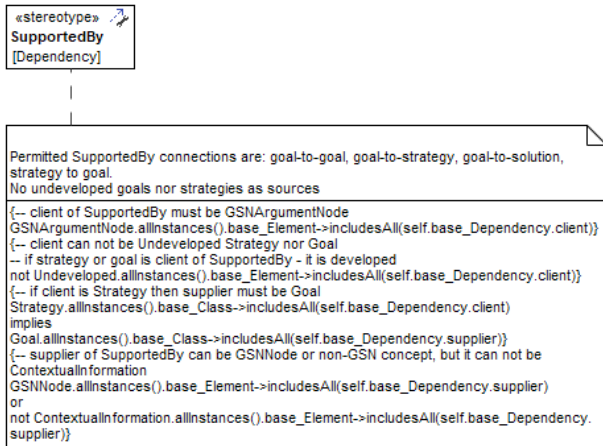


Figure 9.139 – SupportedBy

Constraints

- [1] ClientIsGSNAArgumentNode      -- client of SupportedBy must be GSNAArgumentNode  
GSNAArgumentNode.allInstances().base\_Element->includesAll(self.base\_Dependency.client)
- [2] StrategyToGoal                -- if client is Strategy then supplier must be Goal  
Strategy.allInstances().base\_Class->includesAll(self.base\_Dependency.client)  
implies  
Goal.allInstances().base\_Class->includesAll(self.base\_Dependency.supplier)
- [3] SupplierIsNotContextualInformation      -- supplier of SupportedBy can be GSNNode or non-GSN concept, but it can not be ContextualInformation  
GSNNode.allInstances().base\_Element->includesAll(self.base\_Dependency.supplier)  
or  
not ContextualInformation.allInstances().base\_Element->includesAll(self.base\_Dependency.supplier)
- [4] ClientIsNotUndeveloped        -- client can not be Undeveloped Strategy nor Goal  
-- if strategy or goal is client of SupportedBy - it is developed  
not Undeveloped.allInstances().base\_Element->includesAll(self.base\_Dependency.client)

## 9.8 Methods::ISO 26262

The ISO 26262 package contains elements supporting the analysis and requirement specification aspects of Functional Safety, as specified by ISO 26262 standard for automotive applications. ISO 26262 is a risk-based standard derived from IEC 61508. The ISO 26262 package redefines or extends concepts from the Core concepts package and the General Concepts package.

The ISO 26262 package enables modeling a HAZOP, which is typically used to identify malfunctioning behaviors. The failure modes concept is used from the General Concepts and specialized as a malfunctioning behavior. This allows the malfunctioning behavior to be related to the system behaviors through the HAZOP guidewords for construction of the HAZOP table. The risk analysis is performed by identifying Hazards that could result from the MalfunctioningBehavior, which in combination with a particular OperationalSituation could result in an AccidentScenario. This information is contained in the HazardousEvent which provides the risk level assessment for the event. Each of these concepts are modeled using elements defined in the ISO 26262 package as extensions of the Core and General concepts. This means that the same elements can be used in other analyses in the model, such as in an FMEA.

### 9.8.1 Methods::ISO 26262::ISO 26262 Library

TrafficAndPeople

**Package:** ISO 26262 Library

**isAbstract:** Yes

**Generalization:** [OperationalCondition](#)

**Applied Stereotype:** [«OperationalSituation»](#)

Description

TrafficAndPeople extends the <<situation>> class and is used to describe the presence and behaviour of any motorists or non-motorists considered in a hazardous event.

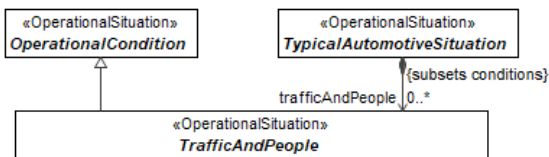


Figure 9.140 – TrafficAndPeople

VehicleUsage

**Package:** ISO 26262 Library

**isAbstract:** Yes

**Generalization:** [OperationalCondition](#)

**Applied Stereotype:** [«OperationalSituation»](#)

Description

VehicleUsage extends the <<situation>> class and is used to describe the usage of a vehicle during a hazardous event.

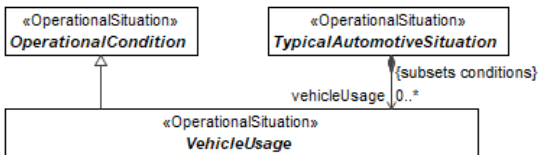


Figure 9.141 – VehicleUsage

RoadCondition

**Package:** ISO 26262 Library

**isAbstract:** Yes

**Generalization:** [OperationalCondition](#)

**Applied Stereotype:** [«OperationalSituation»](#)

Description

RoadConditions extends the <<situation>> class, and is used to describe the conditions or state of the surface a vehicle is driving on (Low-traction, Grade(Slope), etc.) during a hazardous event.

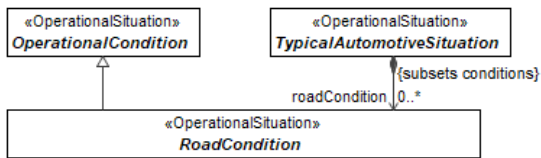


Figure 9.142 – RoadCondition

Location

**Package:** ISO 26262 Library

**isAbstract:** Yes

**Generalization:** [OperationalCondition](#)

**Applied Stereotype:** [«OperationalSituation»](#)

Description

VehicleLocation extends the <<situation>> class and is used to describe the physical location (high speed road, intersection, parking lot, etc.) of a vehicle during a hazardous event.

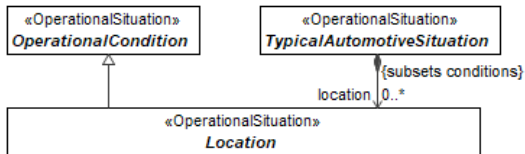


Figure 9.143 – Location

EnvironmentalCondition

**Package:** ISO 26262 Library

**isAbstract:** Yes

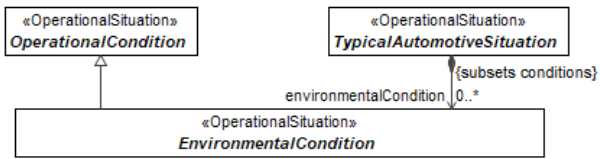
**Generalization:** [OperationalCondition](#)

**Applied Stereotype:** [«OperationalSituation»](#)

Description

EnvironmentalConditions extends the <<situation>> class and is used to describe the environmental conditions at the time of vehicle operation in a hazardous event.

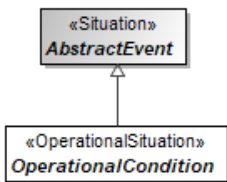




**Figure 9.144 – EnvironmentalCondition**

OperationalCondition  
 Package: ISO 26262 Library  
 isAbstract: Yes  
 Generalization: [AbstractEvent](#)  
 Applied Stereotype: [«OperationalSituation»](#)

Description  
 Component/part of operational situation.



**Figure 9.145 – OperationalCondition**

AbstractOperationalSituation  
 Package: ISO 26262 Library  
 isAbstract: Yes  
 Generalization: [OperationalCondition](#)  
 Applied Stereotype: [«OperationalSituation»](#)

Description  
 Operational situation is a scenario that can occur in vehicle's life.

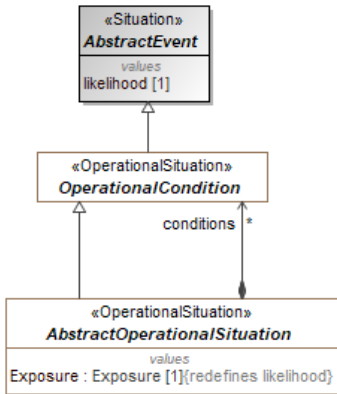


Figure 9.146 – AbstractOperationalSituation

Attributes

conditions : OperationalCondition[\*]  
 (member end of association)

Exposure : Exposure[1] , redefines likelihood

Likelihood of being in a particular operational situation.  
 Must have a Rationale attached.

TypicalAutomotiveSituation

Package: ISO 26262 Library

isAbstract: Yes

Generalization: AbstractOperationalSituation

Applied Stereotype: «OperationalSituation»

Description

A grouping of operational conditions, including traffic and people, vehicle usage, road conditions, location, and environmental conditions.

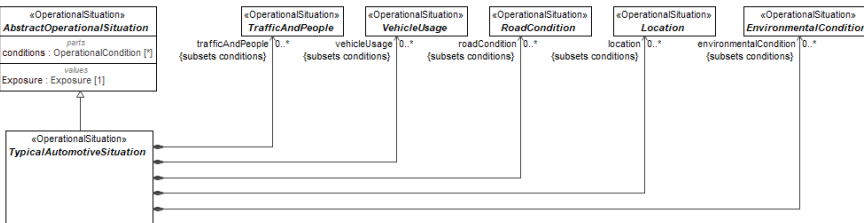


Figure 9.147 – TypicalAutomotiveSituation

Attributes

trafficAndPeople : TrafficAndPeople[0..\*]  
(member end of association, subsets [conditions](#))

vehicleUsage : VehicleUsage[0..\*]  
(member end of association, subsets [conditions](#))

roadCondition : RoadCondition[0..\*]  
(member end of association, subsets [conditions](#))

location : Location[0..\*] (member end of association, subsets [conditions](#))

environmentalCondition : EnvironmentalCondition[0..\*] (member end of association, subsets [conditions](#))

Exposure

**Package:** ISO 26262 Library

**isAbstract:** No

**Applied Stereotype:** «ValueType»

Description

Possible values of exposure.

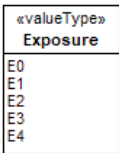


Figure 9.148 – Exposure

Severity

**Package:** ISO 26262 Library

**isAbstract:** No

**Applied Stereotype:** «ValueType»

Description

Possible values for severity.

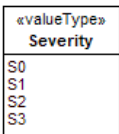


Figure 9.149 – Severity

## ASIL

**Package:** ISO 26262 Library

**isAbstract:** No

**Applied Stereotype:** «ValueType»

Description

Possible ASIL values.

«ValueType» ASIL
no assignment
QM
A
B
C
D
A(B)
A(C)
A(D)
B(C)
B(D)
C(D)
A(A)
B(B)
C(C)
D(D)
QM(A)
QM(B)
QM(C)
QM(D)

**Figure 9.150 – ASIL**

Controllability

**Package:** ISO 26262 Library

**isAbstract:** No

**Applied Stereotype:** «ValueType»

Description

Possible values of controllability.

«ValueType» Controllability
C0
C1
C2
C3

**Figure 9.151 – Controllability**

Less

**Package:** ISO 26262 Library

**isAbstract:** Yes

**Generalization:** [AnyMalfunction](#)

**Applied Stereotype:** [«MalfunctioningBehavior»](#)

Description

A subclass of malfunctioning behaviour used for classification purposes. Must be connected to a behavioural element (Use Case or Function). This kind of malfunctioning behaviour represents a failure resulting from providing less output/behaviour than required.

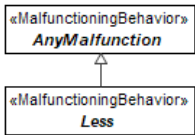


Figure 9.152 – Less

More

**Package:** ISO 26262 Library

**isAbstract:** Yes

**Generalization:** [AnyMalfunction](#)

**Applied Stereotype:** [«MalfunctioningBehavior»](#)

Description

A subclass of malfunctioning behaviour used for classification purposes. Must be connected to a behavioural element (Use Case or Function). This kind of malfunctioning behaviour represents a failure resulting from providing more output/behaviour than required.

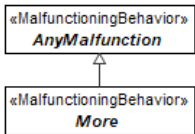


Figure 9.153 – More

No

**Package:** ISO 26262 Library

**isAbstract:** Yes

**Generalization:** [AnyMalfunction](#)

**Applied Stereotype:** [«MalfunctioningBehavior»](#)

Description

A subclass of malfunctioning behaviour used for classification purposes. Must be connected to a behavioural element (Use Case or Function). This kind of malfunctioning behaviour represents a failure resulting from the behaviour not being performed when required.

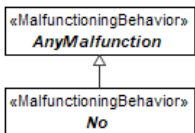


Figure 9.154 – No

Intermittent

**Package:** ISO 26262 Library

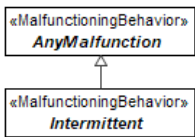
**isAbstract:** Yes

**Generalization:** [AnyMalfunction](#)

**Applied Stereotype:** [«MalfunctioningBehavior»](#)

Description

A subclass of malfunctioning behaviour used for classification purposes. Must be connected to a behavioural element (Use Case or Function). This kind of malfunctioning behaviour represents a failure from the behaviour being performed intermittently.



**Figure 9.155 – Intermittent**

Unintended

**Package:** ISO 26262 Library

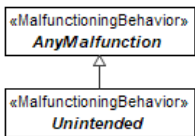
**isAbstract:** Yes

**Generalization:** [AnyMalfunction](#)

**Applied Stereotype:** [«MalfunctioningBehavior»](#)

Description

A subclass of malfunctioning behaviour used for classification purposes. Must be connected to a behavioural element (Use Case or Function). This kind of malfunctioning behaviour represents a failure resulting from the behaviour being provided when not required.



**Figure 9.156 – Unintended**

Early

**Package:** ISO 26262 Library

**isAbstract:** Yes

**Generalization:** [AnyMalfunction](#)

**Applied Stereotype:** [«MalfunctioningBehavior»](#)

Description

A subclass of malfunctioning behaviour used for classification purposes. Must be connected to a behavioural element (Use Case or Function). This kind of malfunctioning behaviour represents a failure resulting from the behaviour being performed earlier than required.

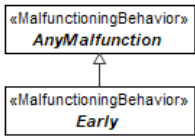


Figure 9.157 – Early

Late

**Package:** ISO 26262 Library

**isAbstract:** Yes

**Generalization:** [AnyMalfunction](#)

**Applied Stereotype:** [«MalfunctioningBehavior»](#)

Description

A subclass of malfunctioning behaviour used for classification purposes. Must be connected to a behavioural element (Use Case or Function). This kind of malfunctioning behaviour represents a failure resulting from the behaviour being performed later than required.

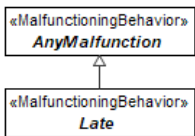


Figure 9.158 – Late

Inverted

**Package:** ISO 26262 Library

**isAbstract:** Yes

**Generalization:** [AnyMalfunction](#)

**Applied Stereotype:** [«MalfunctioningBehavior»](#)

Description

A subclass of malfunctioning behaviour used for classification purposes. Must be connected to a behavioural element (Use Case or Function). This kind of malfunctioning behaviour represents a failure resulting from the behaviour providing an inverted output.

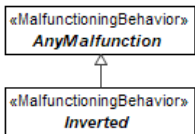


Figure 9.159 – Inverted

**HazardousEvent**

**Package:** ISO 26262 Library

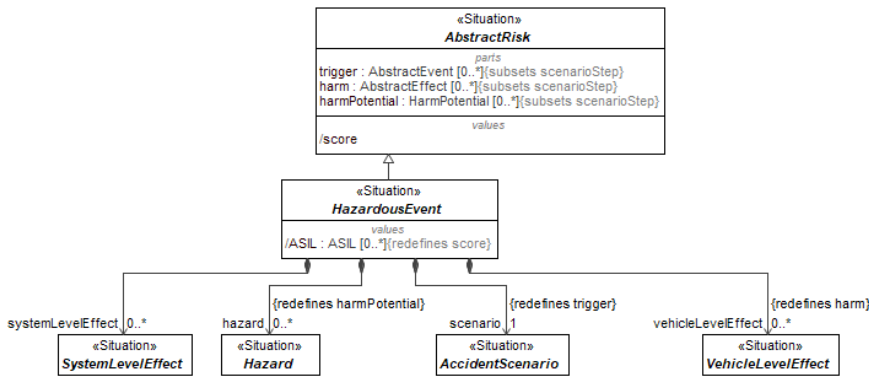
**isAbstract:** Yes

**Generalization:** [AbstractRisk](#)

**Applied Stereotype:** «Situation»

**Description**

Combination of hazard and operational situation to identify automotive safety integrity level.



**Figure 9.160 – HazardousEvent**

**Attributes**

scenario : AccidentScenario[1] (member end of association, redefines [trigger](#))

hazard : Hazard[0..\*] (member end of association, redefines [harmPotential](#))

systemLevelEffect : SystemLevelEffect[0..\*] (member end of association)

vehicleLevelEffect : VehicleLevelEffect[0..\*] (member end of association, redefines [harm](#))

ASIL : ASIL[0..\*], redefines [score](#)

Automotive Safety Integrity Level value - one of four levels to specify necessary requirements for ISO-26262 and safety measures for avoiding unreasonable risks.

**AnyMalfunction**

**Package:** ISO 26262 Library

**isAbstract:** Yes

**Generalization:** [UndesiredState](#)

**Applied Stereotype:** «MalfunctioningBehavior»



Description  
 Root of all malfunctioning behaviours.

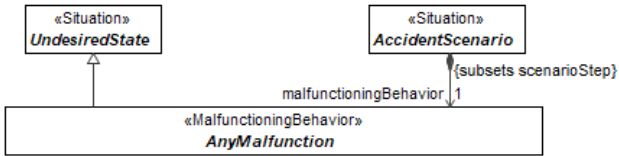


Figure 9.161 – AnyMalfunction

AutomotiveEffect  
 Package: ISO 26262 Library  
 isAbstract: Yes  
 Generalization: [AbstractEffect](#)  
 Applied Stereotype: [«Situation»](#)

Description  
 System- or vehicle-level effect which is or could result in harm.

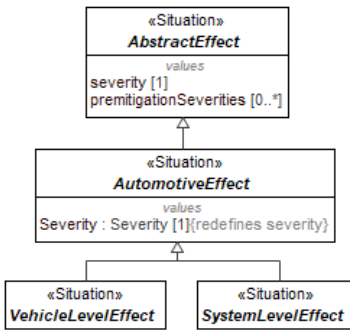


Figure 9.162 – AutomotiveEffect

Attributes  
 Severity : Severity[1], redefines [severity](#) Estimate of the extent of harm.  
 Must have a Rationale attached.

ISO26262SafetyRequirementTemplate  
 Package: ISO 26262 Library  
 isAbstract: No  
 Applied Stereotype: [«DependabilityRequirement»](#)

Description

A template for dependability requirements.

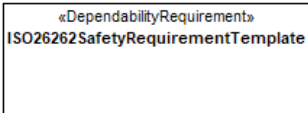


Figure 9.163 – ISO26262SafetyRequirementTemplate

Attributes

ASIL : ASIL[1] ASIL value of the requirement.  
 FTTI : time[1] Fault Tolerant Time Interval.

AccidentScenario

**Package:** ISO 26262 Library  
**isAbstract:** Yes  
**Generalization:** [DysfunctionalEvent](#), [Scenario](#)  
**Applied Stereotype:** «Situation»

Description

A combination of operational situation and malfunctioning behaviour.

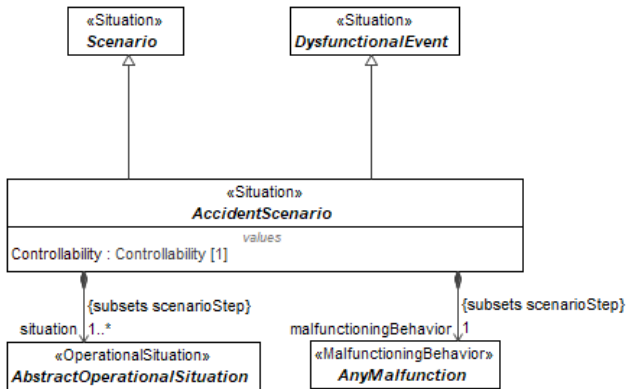


Figure 9.164 – AccidentScenario

Attributes

situation : AbstractOperationalSituation[1..\*]  
 (member end of association, subsets [scenarioStep](#))

Controllability : Controllability[1] Ability to avoid a specified harm or damage through timely reactions of individuals involved in the scenario.  
 Must have a Rationale attached.

malfunctioningBehavior :  
AnyMalfunction[1] (member end of  
association, subsets [scenarioStep](#))

AnyTrafficAndPeople

**Package:** ISO 26262 Library

**isAbstract:** No

**Generalization:** [OperationalCondition](#), [TrafficAndPeople](#)

**Applied Stereotype:** «OperationalSituation»

Description

TrafficAndPeople extends the <<situation>> class and is used to describe the presence and behaviour of any motorists or non-motorists considered in a hazardous event.



Figure 9.165 – AnyTrafficAndPeople

AnyVehicleUse

**Package:** ISO 26262 Library

**isAbstract:** No

**Generalization:** [OperationalCondition](#), [VehicleUsage](#)

**Applied Stereotype:** «OperationalSituation»

Description

TrafficAndPeople extends the <<situation>> class and is used to describe the presence and behaviour of any motorists or non-motorists considered in a hazardous event.

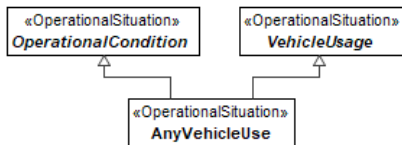


Figure 9.166 – AnyVehicleUse

AnyRoadCondition

**Package:** ISO 26262 Library

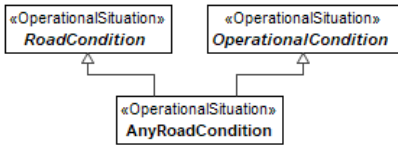
**isAbstract:** No

**Generalization:** [OperationalCondition](#), [RoadCondition](#)

**Applied Stereotype:** «OperationalSituation»

Description

TrafficAndPeople extends the <<situation>> class and is used to describe the presence and behaviour of any motorists or non-motorists considered in a hazardous event.



**Figure 9.167 – AnyRoadCondition**

AnyLocation

**Package:** ISO 26262 Library

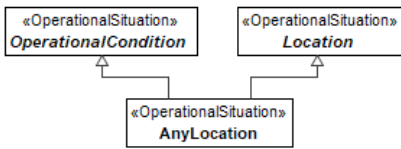
**isAbstract:** No

**Generalization:** [Location](#), [OperationalCondition](#)

**Applied Stereotype:** [«OperationalSituation»](#)

Description

TrafficAndPeople extends the <<situation>> class and is used to describe the presence and behavior of any motorists or non-motorists considered in a hazardous event.



**Figure 9.168 – AnyLocation**

AnyEnvironmentalCondition

**Package:** ISO 26262 Library

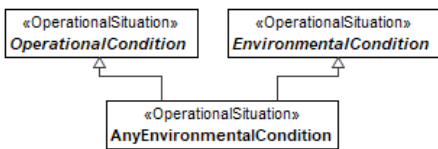
**isAbstract:** No

**Generalization:** [EnvironmentalCondition](#), [OperationalCondition](#)

**Applied Stereotype:** [«OperationalSituation»](#)

Description

TrafficAndPeople extends the <<situation>> class and is used to describe the presence and behaviour of any motorists or non-motorists considered in a hazardous event.



**Figure 9.169 – AnyEnvironmentalCondition**

SystemLevelEffect

**Package:** ISO 26262 Library

**isAbstract:** Yes

**Generalization:** [AutomotiveEffect](#)

**Applied Stereotype:** [«Situation»](#)

Description

System- or vehicle-level effect which is or could result in harm.

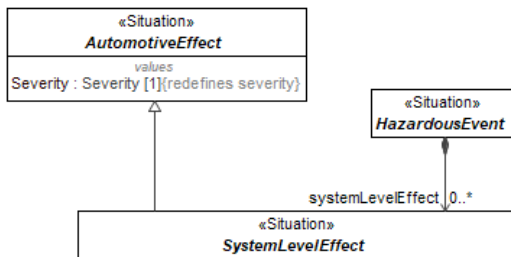


Figure 9.170 – SystemLevelEffect

VehicleLevelEffect

Package: ISO 26262 Library

isAbstract: Yes

Generalization: [AutomotiveEffect](#)

Applied Stereotype: «Situation»

Description

System- or vehicle-level effect which is or could result in harm.

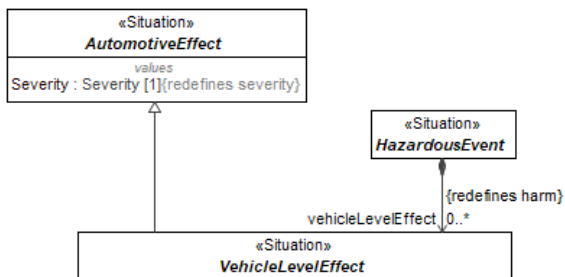


Figure 9.171 – VehicleLevelEffect

Methods::ISO 26262::ISO 26262 Library::Diagrams by elements

### 9.8.2 Methods::ISO 26262::ISO 26262 Profile

OperationalSituation

Package: ISO 26262 Profile

isAbstract: No

Generalization: [Situation](#)

Extension: Class

Description

A situation describes the operational scenario or driving scenario which is considered in a hazardous event, as part of the Hazard Analysis and Risk Assessment process.

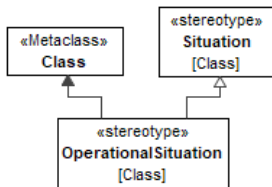


Figure 9.172 – OperationalSituation

MalfunctioningBehavior

Package: ISO 26262 Profile

isAbstract: No

Generalization: FailureMode

Extension: Class

Description

A malfunctioning behaviour describes a failure or unintended behaviour of an item with respect to its design intent. It is a subtype of failure mode.

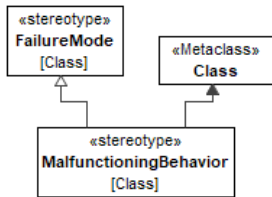


Figure 9.173 – MalfunctioningBehavior

Methods::ISO 26262::ISO 26262 Profile::RequirementManagement

IndependenceRequirement

Package: RequirementManagement

isAbstract: No

Generalization: DeriveReq

Extension: Abstraction

Description

A relationship between requirement elements indicating that the child requirement specifies an independence criterion that needs to be satisfied in order for an ASIL decomposition to be valid. The decomposition between the parent requirement and 2 other children requirements.

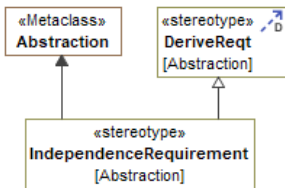


Figure 9.174 – IndependenceRequirement

ASILDecompose

Package: RequirementManagement

isAbstract: No

Generalization: DeriveReq

Extension: Abstraction

Description

An ASIL decompose relation is used to connect two safety requirements for the purposes of performing ASIL decomposition. The target requirement (supplier) should be of a higher abstraction than the source (client). ASIL decompose relations shall be applied in pairs (e.g., a requirement cannot be the supplier of a single ASIL decompose relation).

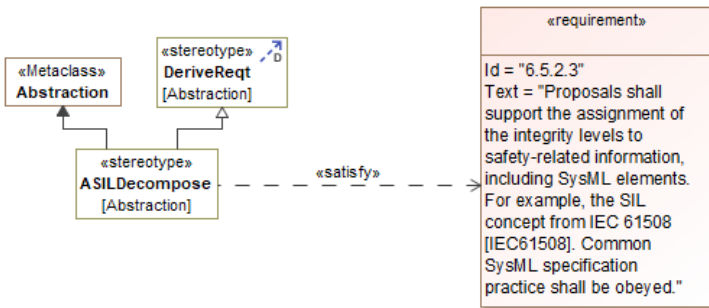


Figure 9.175 – ASILDecompose

SafeState

Package: RequirementManagement

isAbstract: No

Extension: Dependency

Description

A state of function realized by one or more architectural components. May be composed of several subfunctions or called by other functions. Associated with safety specific behaviours, typically (but not necessarily) triggered by a failure mode.

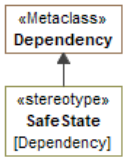


Figure 9.176 – SafeState

UserInfoRequirement

**Package:** RequirementManagement

**isAbstract:** No

**Generalization:** Satisfy

**Extension:** Abstraction

Description

A UserInfoRequirement relationship is a dependency which links a State to a requirement. The arrow direction points from a state (client) to a FSR or TSR (supplier). Linked requirements specify information that must be presented to vehicle occupants when the vehicle enters a safe state.

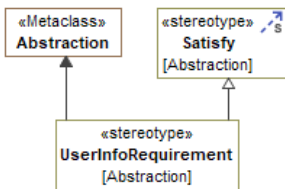


Figure 9.177 – UserInfoRequirement

RecoveryRequirement

**Package:** RequirementManagement

**isAbstract:** No

**Generalization:** Satisfy

**Extension:** Abstraction

Description

A RecoveryRequirement relationship is a dependency between a safe state and requirement where the requirement indicates the criteria to recover from the safe state to another operational mode.

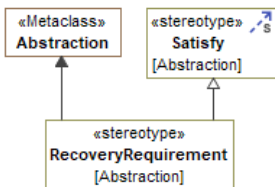


Figure 9.178 – RecoveryRequirement



### OperatingMode

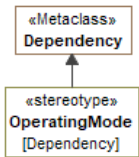
**Package:** RequirementManagement

**isAbstract:** No

**Extension:** Dependency

#### Description

A state of function realized by one or more architectural components. May be composed of several subfunctions or called by other functions. Associated with specific behaviours.



**Figure 9.179 – OperatingMode**

### FunctionalSafetyRequirement

**Package:** RequirementManagement

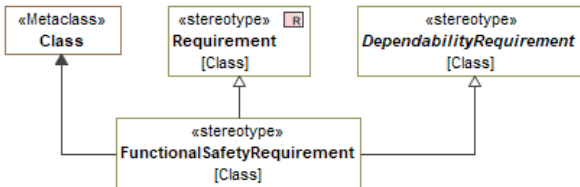
**isAbstract:** No

**Generalization:** [DependabilityRequirement](#), Requirement

**Extension:** Class

#### Description

A functional safety requirement specifies an implementation independent safety behaviour, or an implementation independent safety measure, required for achievement of a safety goal from which it is derived.



**Figure 9.180 – FunctionalSafetyRequirement**

### SoftwareSafetyRequirement

**Package:** RequirementManagement

**isAbstract:** No

**Generalization:** [DependabilityRequirement](#), Requirement

**Extension:** Class

#### Description

A software safety requirement provides implementation details for software. They can express behaviours or specific software mechanisms which realize the technical safety requirements from which they are derived.

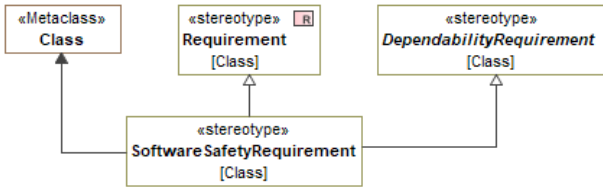


Figure 9.181 – SoftwareSafetyRequirement

HardwareSafetyRequirement

Package: RequirementManagement

isAbstract: No

Generalization: [DependabilityRequirement](#), Requirement

Extension: Class

Description

A hardware safety requirement specifies hardware behaviours or hardware specific details necessary for implementing the safety concept. Hardware safety requirements are implementation specific and assigned to components or subcomponents.

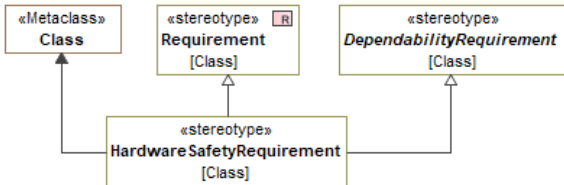


Figure 9.182 – HardwareSafetyRequirement

TechnicalSafetyRequirement

Package: RequirementManagement

isAbstract: No

Generalization: [DependabilityRequirement](#), Requirement

Extension: Class

Description

A technical safety requirement specifies the implementation of the functional safety requirement(s) from which it is derived. Technical safety requirements express the behaviours and details necessary to realize the safety aspects of the item at the system level. Additional details that do not act at the system level can be specified in the hardware safety requirements or software safety requirements.

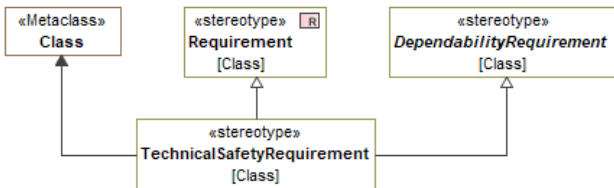


Figure 9.183 – TechnicalSafetyRequirement

SafetyGoal

Package: RequirementManagement

isAbstract: No

Generalization: [DependabilityRequirement](#), Requirement

Extension: Class

Description

A safety goal extends the SysML <<Requirement>> stereotype. It represents a top-level safety requirement, defined as a result of the Hazard Analysis and Risk Assessment process.

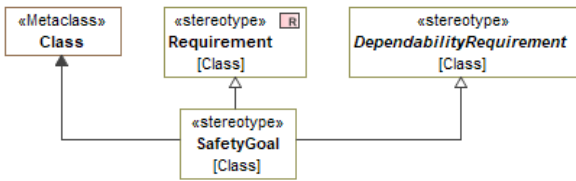


Figure 9.184 – SafetyGoal

DependabilityRequirement

Package: RequirementManagement

isAbstract: Yes

Generalization: AbstractRequirement, Block

Extension: Class

Description

Parent type of all subtypes of safety requirements

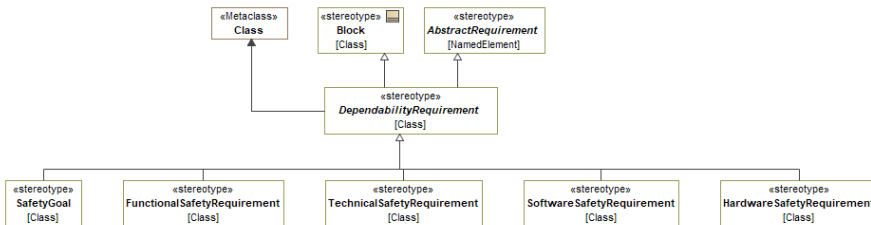


Figure 9.185 – DependabilityRequirement



Description  
 Grouping package for storing hazardous events.

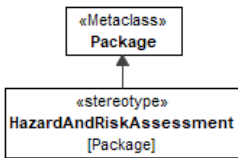


Figure 9.188 – HazardAndRiskAssessment

LessonLearned  
**Package:** ISO 26262 Profile  
**isAbstract:** No  
**Extension:** Comment

Description  
 Comments about lessons learned from hazard and risk assessment.

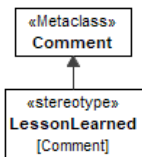


Figure 9.189 – LessonLearned

ASILAssignment  
**Package:** ISO 26262 Profile  
**isAbstract:** No  
**Extension:** Element

Description  
 Stereotype for assigning ASIL values on system design elements.

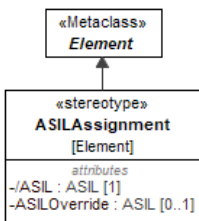


Figure 9.190 – ASILAssignment

#### Attributes

ASIL : ASIL[1]

ASIOVERRIDE : ASIL[0..1]

The associated ASIL value of the system design element.

An ASIL value which does not follow from the normal ASIL derivation rules but is exceptional. This exceptional value needs to have an associated rationale.

#### ASIOVERRIDERationale

**Package:** ISO 26262 Profile

**isAbstract:** No

**Generalization:** Rationale

**Extension:** Comment

#### Description

A rationale specifically justifying ASIL Override value.

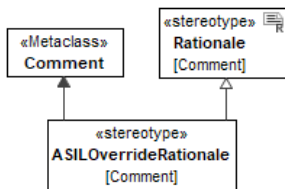


Figure 9.191 – ASIOVERRIDERationale

## 9.9 Methods::RBD

A Reliability Block Diagram (RBD) is a graphical representation used in reliability engineering to analyze the reliability and availability of complex systems. It is a method for assessing the performance of systems composed of multiple components, sub-systems, or processes. In an RBD, system elements (components or groups of components defined as an assemblies, subsystems, or other system architectural elements) are depicted as blocks, and these blocks are connected by lines to represent how they are interconnected or dependent on each other. The goal is to evaluate the overall reliability and availability of the entire system by considering the reliability characteristics of each component and their interconnections.

The method is based on IEC 61078:2016 (“Reliability block diagrams”) includes the following concepts:

- Probability distributions, cumulative distribution functions (CDFs), probability density functions (PDFs), and hazard functions (the exponential, Weibull, and lognormal distributions are included in the library but the framework allows for additional distributions)
- Component reliability, failure probability, restoration completion probability, failure rate, restoration rate, mean time to failure, and mean time to restore
- Restorable and non-restorable systems
- System reliability and availability calculations for series, parallel, homogeneous k-out-n, and heterogeneous k-out-of-n systems

Mathematical methods for calculation of cumulative distributions functions (CDFs), probability density functions (PDFs), hazard functions, and mean values of distributions are based on U.S. National Institute of Standards Handbook of Engineering Statistics (see references).

### 9.9.1 Methods::RBD::RBD Library

#### AbstractReliabilitySituation

**Package:** RBD Library

**isAbstract:** Yes

**Generalization:** AnySituation

**Applied Stereotype:** «Situation»

**Description**

The parent situation of the RBD library. Specialization of AnySituation from Core Library.

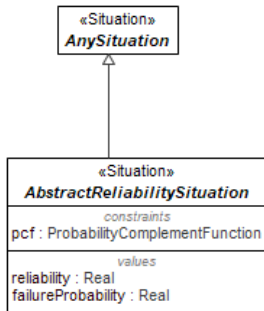


Figure 1.192 - AbstractReliabilitySituation

**Attributes**

reliability : Real

Value property for reliability in AbstractReliabilitySituation (used to hold result of system or component reliability in non-restorable and restorable systems)

failureProbability : Real

Value property that is the complement of reliability

pcf : ProbabilityComplementFunction

Constraint property for calculating the complement of a value between 0 and 1

#### Restorable

**Package:** RBD Library

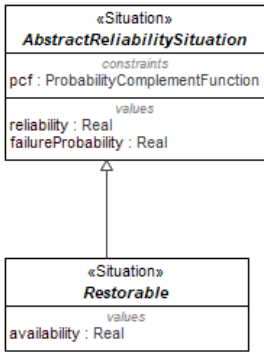
**isAbstract:** Yes

**Generalization:** AbstractReliabilitySituation

**Applied Stereotype:** «Situation»

**Description**

Specialization of AbstractReliabilitySituation for restorable systems. Parent of RestorableSystemReliabilitySituation and RestorableComponentReliabilitySituation. Also has composition relationship (owns) RestorableSystemReliabilitySituation to enable recursion



**Figure 1.193 - Restorable**  
Attributes

availability : Real

Availability value property of Restorable

**ComponentReliabilitySituation**

Package: RBD Library

isAbstract: Yes

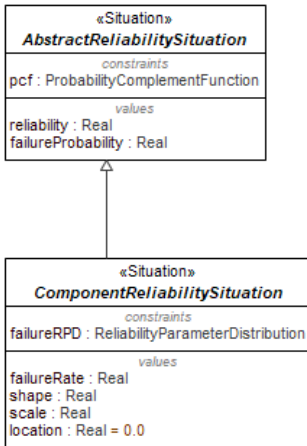
Generalization: AbstractReliabilitySituation

Applied Stereotype: «Situation»

Description

Situation for Components in RBDs. Specialization of AbstractReliabilitySituation and parent of RestorableComponentReliabilitySituation, NonrestorableComponentReliabilitySituations. Owns ReliabilityParameterGroup constraint and failurerate, shape, scale, and location distribution parameters that it provides its children





**Figure 1.194 - ComponentReliabilitySituation**  
Attributes

<u>failureRPD</u> :	<u>ReliabilityParameterDistribution</u>	Constraint property for expression of the reliability probability distribution
<u>failureRate</u> :	<u>Real</u>	Value property for the failure rate
<u>shape</u> :	<u>Real</u>	Value property for the shape parameter of the reliability probpability distribution
<u>scale</u> :	<u>Real</u>	Value property for the scale parameter of the reliability probpability distribution
<u>location</u> :	<u>Real</u>	Value property for the location parameter of the reliability probpability distribution

**RestorableComponentReliabilitySituation**

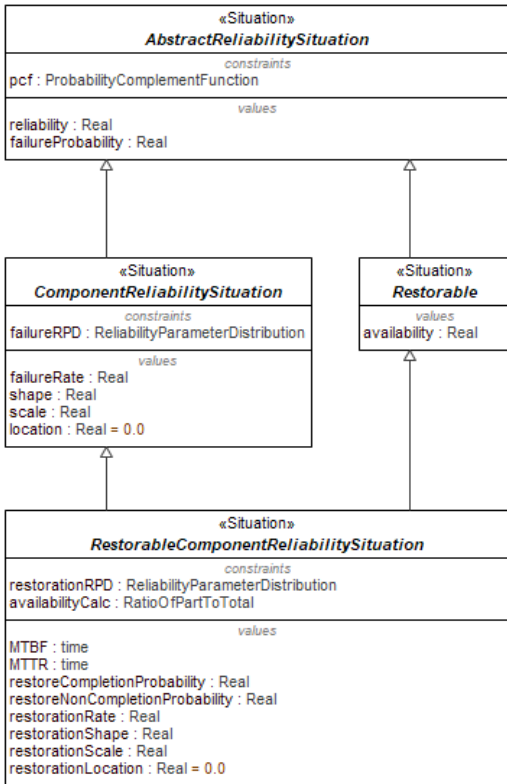
**Package:** RBD Library  
**isAbstract:** Yes

**Generalization:** ComponentReliabilitySituation, Restorable

**Applied Stereotype:** «Situation»

Description

Situation for restorable (repairable) component RBDs. Specialization of ComponentReliabilitySituation. Owns restorationRPG (Reliability Parameter Group) and RatioOfPartTotal (for determining availability). Value properties include MTBF, MTTR, restoration distribution parameters (shape, scale, and location), restorationCompletionProbability (calculated from restoration CDF) and restorationrate (calculated from restoration hazard function, i.e., ratio of PDF to CDF).



**Figure 1.195 - RestorableComponentReliabilitySituation**  
Attributes

<u>MTBF : time</u>	<u>Value property for Mean Time Between Failures (MTBF is used for restorable systems)</u>
<u>MTTR : time</u>	<u>Value property for Mean Time to Restoration</u>
<u>restorationRPD : ReliabilityParameterDistribution</u>	<u>Constraint property for restoration probability distribution</u>
<u>restoreCompletionProbability : Real</u>	<u>Value property for completion probability of restoration action (the value of the CDF for restoration at a specified time)</u>
<u>restoreNonCompletionProbability : Real</u>	<u>Value property for the complement of the restoration completion probability</u>
<u>restorationRate : Real</u>	<u>Value property for the ratio of the restoration pdf to the restoration CDF at a specified time</u>
<u>restorationShape : Real</u>	<u>Value property shape parameter of the restoration probability distribution</u>

restorationScale : Real Value property for the scale parameter of the restoration distribution  
 restorationLocation : Real Value property for the location parameter of the restoration distribution  
 (value of the location parameter must be less than the specified time)  
 availabilityCalc : RatioOfPartToTotal Constraint property for the calculation of availability

**NonRestorableComponentReliabilitySituation**

Package: RBD Library  
 isAbstract: Yes

Generalization: ComponentReliabilitySituation

Applied Stereotype: «Situation»

Description

Situation for nonrestorable component RBDs. Specialization of ComponentReliabilitySituation. Owns MTTF value property

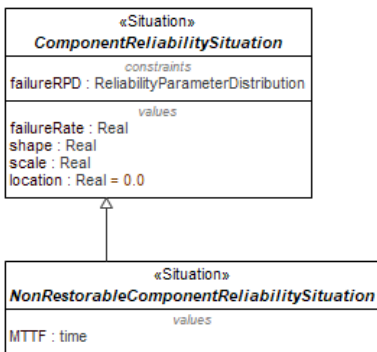


Figure 1.196 - NonRestorableComponentReliabilitySituation  
 Attributes

MTTF : time Value property for the Mean Time to Failure (MTTF is used for non-restorable components or systems)

**SystemReliabilitySituation**

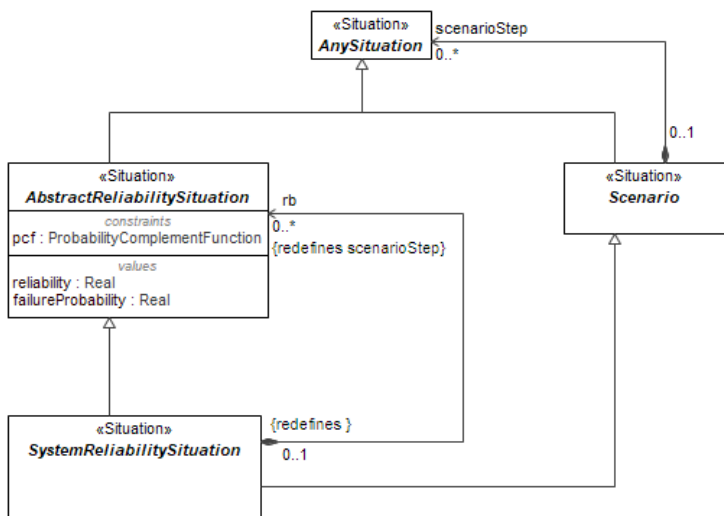
Package: RBD Library  
 isAbstract: Yes

Generalization: AbstractReliabilitySituation, Scenario

Applied Stereotype: «Situation»

Description

The parent situation for calculating a system reliability or availability. Specialization of AbstractReliabilitySituation.



**Figure 1.197 - SystemReliabilitySituation**

Attributes

rb : AbstractReliabilitySituation[0..\*]  
 (member end of association, redefines  
 scenarioStep)

Part property of SystemReliabilitySituation of type Restorable (see  
 Restorable situation)

**RestorableSystemReliabilitySituation**

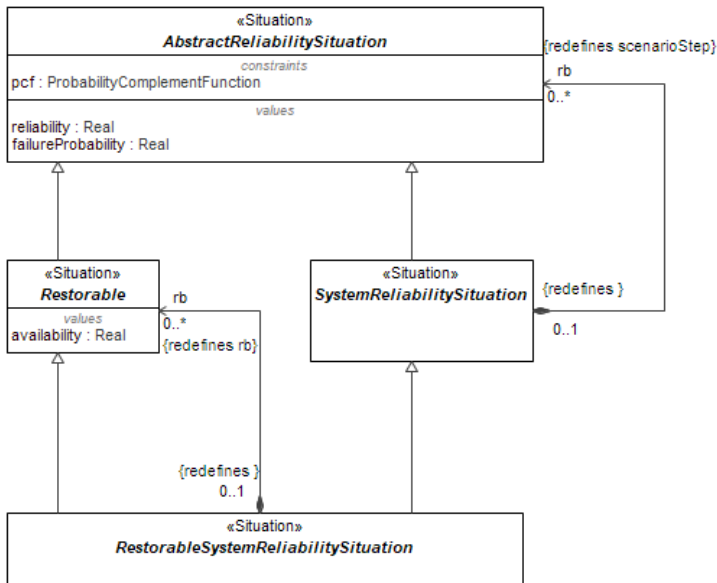
Package: RBD Library  
isAbstract: Yes

Generalization: Restorable, SystemReliabilitySituation

Applied Stereotype: «Situation»

Description

Situation for Resorable Systems. Specialization of SystemReliabilitySituation and part of Restorable Situation



**Figure 1.198 - RestorableSystemReliabilitySituation**

Attributes

rb : Restorable[0..\*] (member end of association, redefines rb)

Part property of RestorableSystemReliabilitySituation of type Restorable (see Restorable situation)

**InSeries**

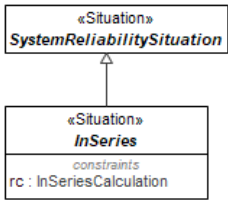
Package: RBD Library  
isAbstract: Yes

Generalization: SystemReliabilitySituation

Applied Stereotype: «Situation»

Description

Situation for calculation of reliability or availability for series systems. Specialization of SystemReliabilitySituation.  
Owns InSeries constraint block.



**Figure 1.199 - InSeries**  
Attributes

`rc : InSeriesCalculation`

Constraint property for series reliability calculation

### RestorableInSeries

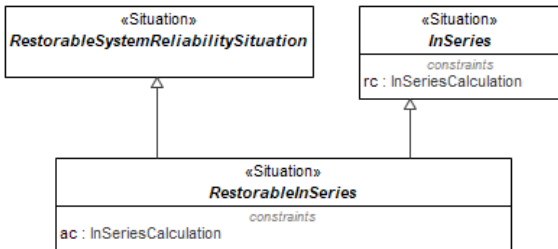
Package: RBD Library  
isAbstract: Yes

Generalization: InSeries, RestorableSystemReliabilitySituation

Applied Stereotype: «Situation»

Description

Situation for calculation of availability for restorable series systems. Specialization of SystemReliabilitySituation and the InSeries situation. Owns InSeries constraint block.



**Figure 1.200 - RestorableInSeries**  
Attributes

`ac : InSeriesCalculation`

Constraint property for availability

### InParallel

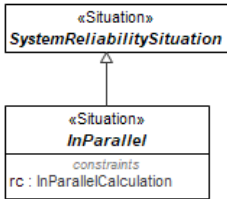
Package: RBD Library  
isAbstract: Yes

Generalization: SystemReliabilitySituation

Applied Stereotype: «Situation»

Description

Situation for calculation of reliability or availability for parallel systems. Specialization of SystemReliabilitySituation. Owns InParallel constraint block.



**Figure 1.201 - InParallel**

Attributes

rc : InParallelCalculation

Constraint property for availability

**RestorableInParallel**

Package: RBD Library

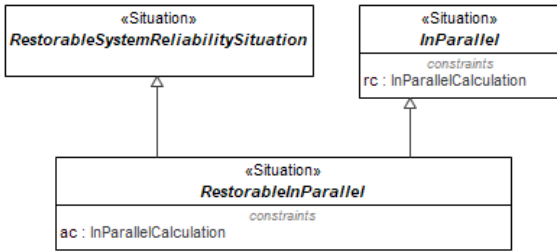
isAbstract: Yes

Generalization: InParallel, RestorableSystemReliabilitySituation

Applied Stereotype: «Situation»

Description

Situation for calculation of availability for restorable parallel systems. Specialization of RestorableSystemReliabilitySituation and InParallel situation. Owns InParallel constraint block.



**Figure 1.202 - RestorableInParallel**

Attributes

ac : InParallelCalculation

Constraint property for availability

**HomogeneousKofN**

Package: RBD Library

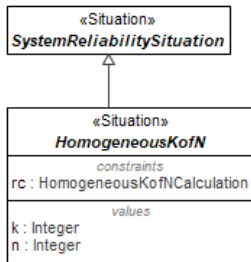
isAbstract: Yes

**Generalization:** SystemReliabilitySituation

**Applied Stereotype:** «Situation»

**Description**

Situation for calculation of reliability or availability for Homogeneous K out of N systems. Specialization of SystemReliabilitySituation. Owns HomogenousKofN constraint block.



**Figure 1.203 - HomogeneousKofN**

**Attributes**

rc : HomogeneousKofNCalculation

k : Integer

n : Integer

Constraint property for series reliability calculation

Value property for number of items needed for operation

Value property for Number of items installed or ready at start of operation

### **RestorableHomogeneousKofN**

**Package:** RBD Library

**isAbstract:** Yes

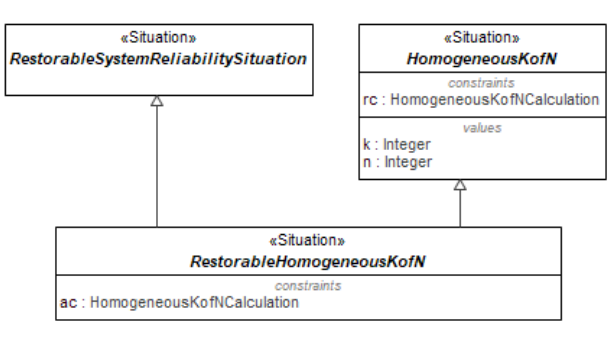
**Generalization:** HomogeneousKofN, RestorableSystemReliabilitySituation

**Applied Stereotype:** «Situation»

**Description**

Situation for calculation of availability for Homogeneous K out of N systems. Specialization of RestorableSystemReliabilitySituation and the InSeries situation. Owns KofN constraint block.





**Figure 1.204 - RestorableHomogeneousKofN**

Attributes

ac : HomogeneousKofNCalculation

Constraint property for availability

**HeterogeneousKofN**

Package: RBD Library

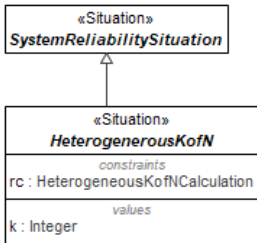
isAbstract: Yes

Generalization: SystemReliabilitySituation

Applied Stereotype: «Situation»

Description

Situation for calculation of reliability or availability for Heterogeneous K out of N systems. Specialization of SystemReliabilitySituation. Owns HeterogeneousKofN constraint block.



**Figure 1.205 - HeterogeneousKofN**

Attributes

rc : HeterogeneousKofNCalculation

Constraint property for series reliability calculation

k : Integer

Number of items needed for operation

**RestorableHeterogeneousKofN**

Package: RBD Library

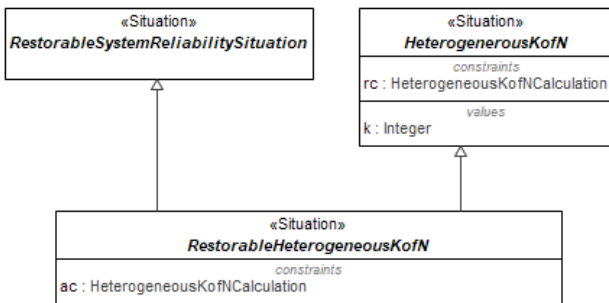
isAbstract: Yes

**Generalization:** HeterogeneousKofN, RestorableSystemReliabilitySituation

**Applied Stereotype:** «Situation»

**Description**

Situation for calculation of availability for Heterogeneous K out of N systems. Specialization of RestorableSystemReliabilitySituation and the InSeries situation. Owns HeterogeneousKofN constraint block.



**Figure 1.206 - RestorableHeterogeneousKofN**

**Attributes**

ac : HeterogeneousKofNCalculation      Constraint property for availability

## 9.9.2 Methods::RBD::RBD Library::ConstraintBlocks

### 9.9.2.1 Methods::RBD::RBD Library::ConstraintBlocks::Probability

#### OneVariableFunction

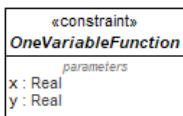
**Package:** Probability

**isAbstract:** Yes

**Applied Stereotype:** «ConstraintBlock»

**Description**

This is an abstract constraint block which defines an input and an output for a constraint expression which has a single input and output



**Figure 9.207 – OneVariableFunction**

**Attributes**

x : Real  
y : Real

The input parameter  
The output parameter

### **ProbabilityComplementFunction**

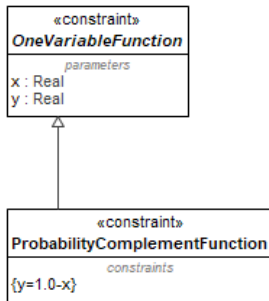
**Package:** Probability  
**isAbstract:** No

**Generalization:** OneVariableFunction

**Applied Stereotype:** «ConstraintBlock»

Description

This constraint block calculates the complement (i.e., 1 - ) the input and is used for converting behind reliability and failure probability or between restoration completion success probability and restoration completion failure probability



**Figure 9.208 – ProbabilityComplementFunction**

Constraints

[1] y=1.0-x

### **ReciprocalFunction**

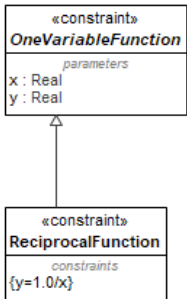
**Package:** Probability  
**isAbstract:** No

**Generalization:** OneVariableFunction

**Applied Stereotype:** «ConstraintBlock»

Description

Provides the reciprocal of the input



**Figure 9.209 – ReciprocalFunction**

Constraints

[1]  $y=1.0/x$

**RatioOfPartToTotal**

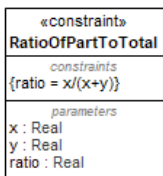
Package: Probability

isAbstract: No

Applied Stereotype: «ConstraintBlock»

Description

A constraint expression to calculate the proportion of one value to its sum (e.g., availability = MTBF/(MTBF+MTTR))



**Figure 9.210 – RationOfPartToTotal**

Attributes

<u>x : Real</u>	<u>The numerator</u>
<u>y : Real</u>	<u>The other value</u>
<u>ratio : Real</u>	<u>=x/(x+y)</u>

Constraints

[1]  $ratio = x/(x+y)$

**ProbabilityDensityFunction**

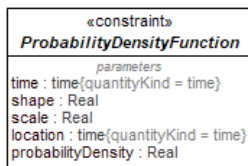
Package: Probability

**isAbstract:** Yes

**Applied Stereotype:** «ConstraintBlock»

**Description**

This is an abstract constraint block which defines 3 inputs (shape, scale, and location) and one output for a probability density function



**Figure 9.211 – ProbabilityDensityFunction**

**Attributes**

<b>time : time</b>	The specified operating (exposure) time
<b>shape : Real</b>	the shape parameter of a probability distribution (see NIST/Sematech Engineering Statistics Handbook, section 8.1.6) <a href="https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm">https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm</a>
<b>scale : Real</b>	the scale parameter of a probability distribution (see NIST/Sematech Engineering Statistics Handbook, section 8.1.6) <a href="https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm">https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm</a>
<b>location : time</b>	the location parameter of a probability distribution (see NIST/Sematech Engineering Statistics Handbook, section 8.1.6) <a href="https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm">https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm</a>
<b>probabilityDensity : Real</b>	The output parameter providing the value of the probability density function at the specified operating time

### **ExponentialProbabilityDensityFunction**

**Package:** Probability

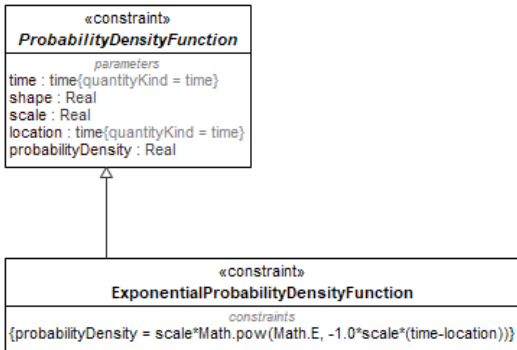
**isAbstract:** No

**Generalization:** ProbabilityDensityFunction

**Applied Stereotype:** «ConstraintBlock»

**Description**

This constraint block calculates the cumulative distribution (CDF) for function for the exponential distribution.



**Figure 9.212 – ExponentialProbabilityDensityFunction**

Constraints

[1] `probabilityDensity = scale*Math.pow(Math.E, -1.0*scale*(time-location))`

**WeibullProbabilityDensityFunction**

Package: Probability

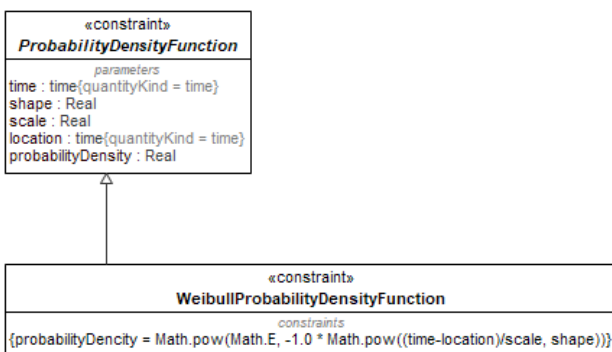
isAbstract: No

Generalization: ProbabilityDensityFunction

Applied Stereotype: «ConstraintBlock»

Description

This constraint block calculates the probability density function (PDF) for function for the Weibull distribution.



**Figure 9.213 – WeibullProbabilityDensityFunction**

#### Constraints

[1]  $probabilityDensity = \text{Math.pow}(\text{Math.E}, -1.0 * \text{Math.pow}((\text{time}-\text{location})/\text{scale}, \text{shape}))$

### **LognormalProbabilityDensityFunction**

**Package:** Probability

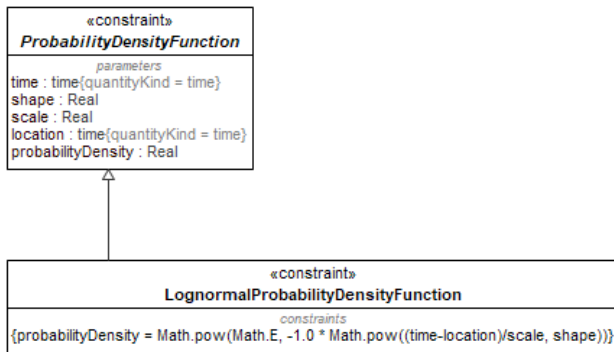
**isAbstract:** No

**Generalization:** ProbabilityDensityFunction

**Applied Stereotype:** «ConstraintBlock»

#### Description

This constraint block calculates the probability density function (PDF) for function for the lognormal distribution.



**Figure 9.214 – LognormalProbabilityDensityFunction**

#### Constraints

[1]  $probabilityDensity = \text{Math.pow}(\text{Math.E}, -1.0 * \text{Math.pow}((\text{time}-\text{location})/\text{scale}, \text{shape}))$

### **CumulativeDistributionFunction**

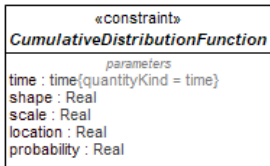
**Package:** Probability

**isAbstract:** Yes

**Applied Stereotype:** «ConstraintBlock»

#### Description

This abstract constraint block defines the parameters and is the parent of specific cumulative distribution constraint blocks (exponential, Weibull, lognormal, etc.). The parameters include the shape, scale, and location parameters of the distribution, the time at which the value is to be evaluated, and the resultant probability (an output result). This probability is defined for the reliability distribution. Note that the cumulative is for the reliability distribution, which is often the complement of the distribution used by other software tools (e.g., Excel or R).



**Figure 9.215 – CumulativeDistributionFunction**

**Attributes**

<u>time : time</u>	The time at which the CDF is evaluated. If a location parameter is used, then the value of time must be greater than the value of the location parameter
<u>shape : Real</u>	The shape parameter for the CDF
<u>scale : Real</u>	The scale parameter for the CDF
<u>location : Real</u>	The location parameter (in units of time) for the CDF
<u>probability : Real</u>	The output probability calculated by the CDF

**ExponentialCumulativeDistributionFunction**

**Package:** Probability

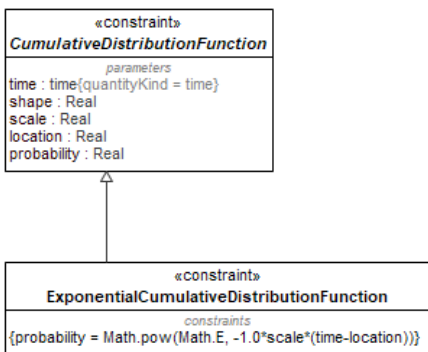
**isAbstract:** No

**Generalization:** CumulativeDistributionFunction

**Applied Stereotype:** «ConstraintBlock»

**Description**

This constraint block calculates the cumulative distribution (CDF) for function for the exponential distribution. See Cumulative Distribution Function constraint block note explaining how the CDF is defined.



**Figure 9.216 – ExponentialCumulativeDistributionFunction**



Constraints

[1]  $probability = \text{Math.pow}(\text{Math.E}, -1.0 * \text{scale} * (\text{time} - \text{location}))$

**WeibullCumulativeDistributionFunction**

Package: Probability

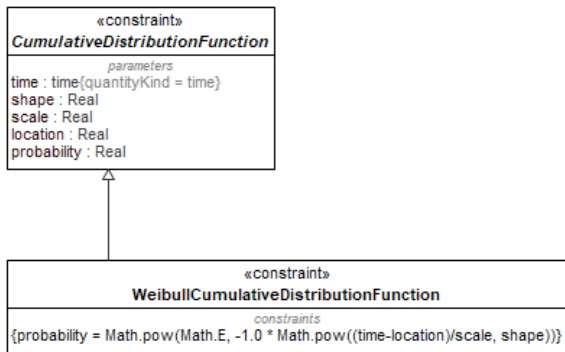
isAbstract: No

Generalization: CumulativeDistributionFunction

Applied Stereotype: «ConstraintBlock»

Description

This constraint block calculates the cumulative distribution (CDF) for function for the Weibull distribution. See Cumulative Distribution Function constraint block note explaining how the CDF is defined.



**Figure 9.217 – WeibullCumulativeDistributionFunction**

Constraints

[1]  $probability = \text{Math.pow}(\text{Math.E}, -1.0 * \text{Math.pow}((\text{time} - \text{location}) / \text{scale}, \text{shape}))$

**LognormalCumulativeDistributionFunction**

Package: Probability

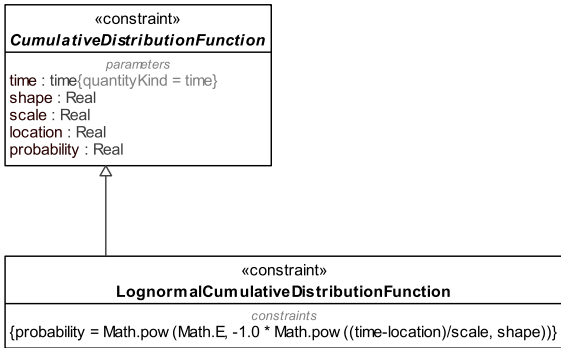
isAbstract: No

Generalization: CumulativeDistributionFunction

Applied Stereotype: «ConstraintBlock»

Description

This constraint block calculates the cumulative distribution (CDF) for function for the lognormal distribution. See Cumulative Distribution Function constraint block note explaining how the CDF is defined.



**Figure 9.218 – LognormalCumulativeDistributionFunction**

Constraints

[1] `probability = Math.pow(Math.E, -1.0 * Math.pow((time-location)/scale, shape))`

**MeanFunction**

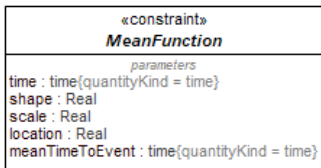
**Package:** Probability

**isAbstract:** Yes

**Applied Stereotype:** «ConstraintBlock»

Description

This abstract constraint block defines the input and output parameters for calculating the mean and is the parent of specific cumulative distribution constraint blocks (exponential, Weibull, lognormal, etc.). The parameters include the shape, scale, and location parameters of the distribution, the time at which the value is to be evaluated, and the resultant probability (an output result). The mean is defined for the reliability distribution.



**Figure 9.219 – MeanFunction**

Attributes

**time : time** The time at which the mean function is evaluated. If a location parameter is used, then the value of time must be greater than the value of the location parameter

shape : Real

The shape parameter for the probability distribution for which the mean is being calculated

scale : Real

The scale parameter of the probability distribution function for which the mean is being calculated

location : Real

The location parameter of the probability distribution function for which the mean is being calculated

meanTimeToEvent : time

The output of the mean function

### ExponentialMeanFunction

Package: Probability

isAbstract: No

Generalization: MeanFunction

Applied Stereotype: «ConstraintBlock»

#### Description

This constraint block calculates the mean of the exponential function (i.e., MTBF or MTTR). Note that for the exponential function, the mean is equivalent to the reciprocal of the hazard function.

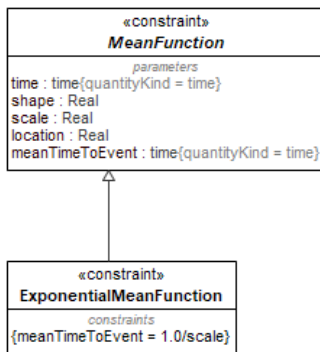


Figure 9.220 -- ExponentialMeanFunction

#### Constraints

[1] meanTimeToEvent = 1.0/scale

### WeibullMeanFunction

Package: Probability

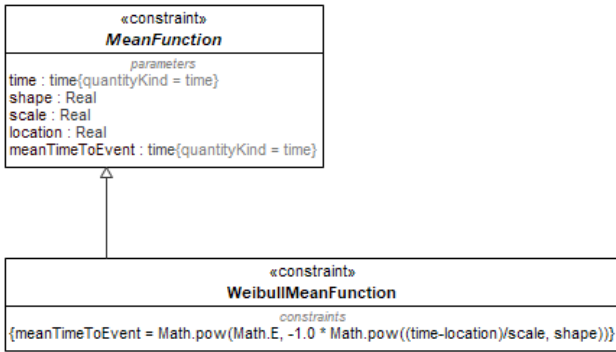
isAbstract: No

Generalization: MeanFunction

Applied Stereotype: «ConstraintBlock»

#### Description

This constraint block calculates the mean of the Weibull distribution (i.e., MTBF or MTTR). Note that for the exponential function, the mean is equivalent to the reciprocal of the hazard function.



**Figure 9.221 – WeibullMeanFunction**

Constraints

- [1]  $\text{meanTimeToEvent} = \text{Math.pow}(\text{Math.E}, -1.0 * \text{Math.pow}((\text{time}-\text{location})/\text{scale}, \text{shape}))$

**LognormalMeanFunction**

**Package:** Probability

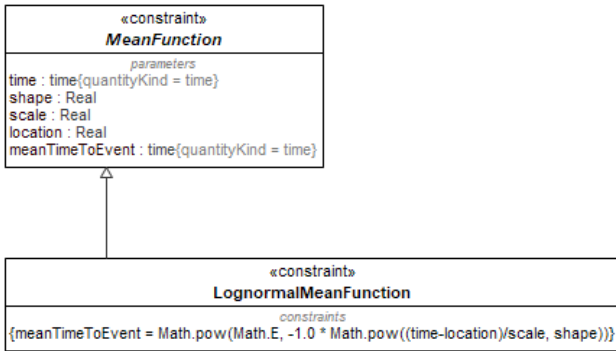
**isAbstract:** No

**Generalization:** MeanFunction

**Applied Stereotype:** «ConstraintBlock»

Description

This constraint block calculates the mean of the lognormal function (i.e., MTBF or MTTR). Note that for the exponential function, the mean is equivalent to the reciprocal of the hazard function.



**Figure 9.222 – LognormalMeanFunction**

Constraints

[1] `meanTimeToEvent = Math.pow(Math.E, -1.0 * Math.pow((time-location)/scale, shape))`

**HazardFunction**

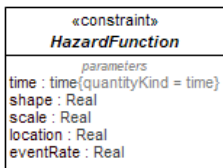
Package: Probability

isAbstract: Yes

Applied Stereotype: «ConstraintBlock»

Description

This abstract constraint block defines the parameters used in the hazard function. The hazard function is the ratio of the probability density function and the cumulative distribution function



**Figure 9.223 – HazardFunction**

Attributes

<u>time : time</u>	The time at which the hazard function is being evaluated
<u>shape : Real</u>	The shape parameter for the hazard for which the hazard is being calculated
<u>scale : Real</u>	The scale parameter for the hazard function for which the hazard is being calculated

location : Real

The location parameter for the hazard function for which the sis being calculated

eventRate : Real

The output of the hazard distribution function

## ExponentialHazardFunction

Package: Probability

isAbstract: No

Generalization: HazardFunction, MeanFunction

Applied Stereotype: «ConstraintBlock»

Description

This is the constraint block is a specialization of the hazard function constraint block and calculates the hazard function (failure rate) for the exponential distribution. Note that for the exponential distribution, the hazard function is a constant over time.

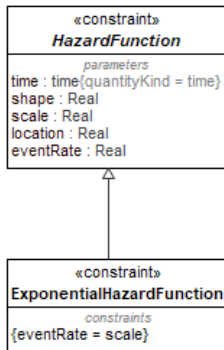


Figure 9.224 – ExponentialHazardFunction

Constraints

[1]

eventRate = scale

## WeibullHazardFunction

Package: Probability

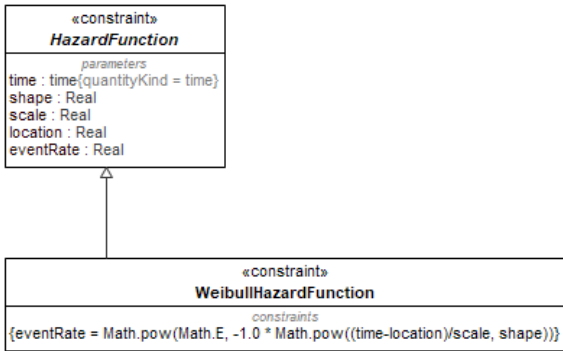
isAbstract: No

Generalization: HazardFunction, MeanFunction

Applied Stereotype: «ConstraintBlock»

Description

This is the constraint block is a specialization of the hazard function constraint block and calculates the hazard function (failure rate) for the Weibull distribution. . .



**Figure 9.225 – WeibullHazardFunction**

Constraints

[1] `eventRate = Math.pow(Math.E, -1.0 * Math.pow((time-location)/scale, shape))`

**LognormalHazardFunction**

Package: Probability

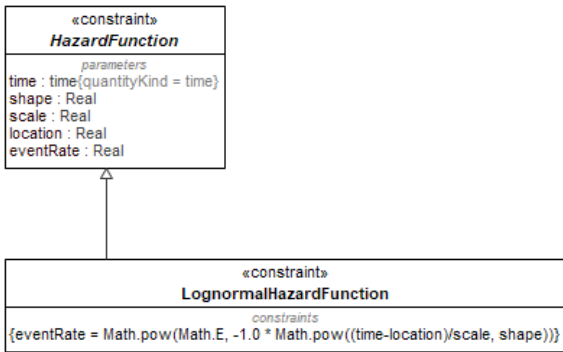
isAbstract: No

Generalization: HazardFunction, MeanFunction

Applied Stereotype: «ConstraintBlock»

Description

This is the constraint block is a specialization of the hazard function constraint block and calculates the hazard function (failure rate) for the lognormal distribution. . .



**Figure 9.226 – LognormalHazardFunction**

## Constraints

[1] `eventRate = Math.pow(Math.E, -1.0 * Math.pow((time-location)/scale, shape))`

## ReliabilityParameterDistribution

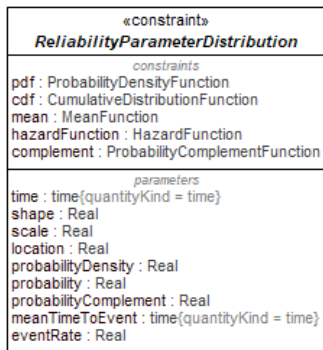
**Package:** Probability

**isAbstract:** Yes

**Applied Stereotype:** «ConstraintBlock»

### Description

This constraint block is the parent of probability distributions and parameters. It owns the pdf, cdf, mean, hazard function, and complement constraint blocks. The parameters inherited by the children distributions include shape, scale, location, the instantaneous probability density value, probability value, complement value (e.g., failure probability from reliability), mean time to event (e.g., mean time between failures or mean time to failure), and event rate (e.g., failure rate). It also includes a time parameter which is the argument for the other parameters



**Figure 9.227 – ReliabilityParameterDistribution**

### Attributes

<code>time : time</code>	The time at which the probability function is to be evaluated. Time must be greater than the location value
<code>shape : Real</code>	The shape parameter of the distribution
<code>scale : Real</code>	The scale parameter of the distribution
<code>location : Real</code>	The location parameter of the distribution
<code>probabilityDensity : Real</code>	The value of the probability density function at a specified time
<code>probability : Real</code>	The probability (i.e., value of the CDF) at a specified time
<code>pdf : ProbabilityDensityFunction</code>	The constraint expression of the probability density function
<code>cdf : CumulativeDistributionFunction</code>	The constraint expression for the cumulative density function
<code>mean : MeanFunction</code>	The constraint expression for the mean of the CDF
<code>hazardFunction : HazardFunction</code>	The constraint expression for the hazard function (ratio of PDF to CDF)



complement :  
ProbabilityComplementFunction  
probabilityComplement : Real

A general expression to take the complement (i.e., 1-value).

meanTimeToEvent : time

A general expression to take the complement of the probability (i.e., 1-value). The value for which the complement is calculated must be less than 1

eventRate : Real

The constraint expression to calculate the mean of the probability distribution

The constraint expression for determining the event rate (e.g., failure rate or repair rate) of the probability distribution

### **ExponentialDistribution**

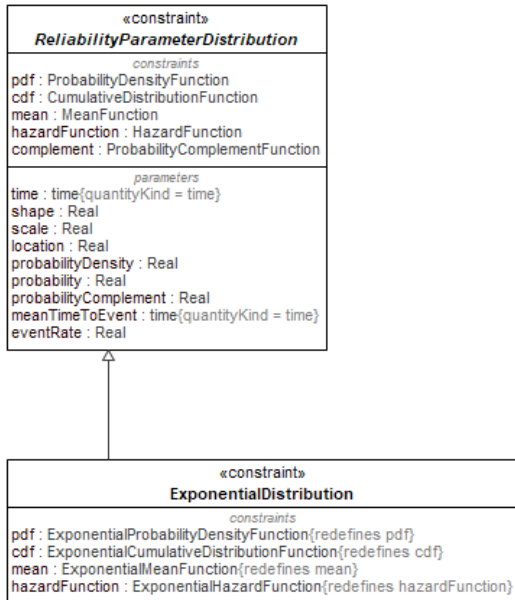
Package: Probability  
isAbstract: No

Generalization: ReliabilityParameterDistribution

Applied Stereotype: «ConstraintBlock»

#### Description

This constraint block calculates owns 4 lower level constraint blocks for calculating the values of the cumulative, density, and hazard functions, as well as the mean for the exponential distribution. Note that for the exponential distribution function, only scale and location parameters are defined



**Figure 9.228 – ExponentialDistribution**

## Attributes

<u>pdf</u> :	The PDF for the exponential distribution defined in the
<u>ExponentialProbabilityDensityFunction</u> , <u>redefines pdf</u>	<u>NIST/Sematech Engineering Statistics Handbook, section 8.1.6,</u> <u><a href="https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm">https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm</a></u>
<u>cdf</u> :	The CDF for the exponential distribution defined in the
<u>ExponentialCumulativeDistributionFunction</u> , <u>redefines cdf</u>	<u>NIST/Sematech Engineering Statistics Handbook, section 8.1.6,</u> <u><a href="https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm">https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm</a></u>
<u>mean</u> : <u>ExponentialMeanFunction</u> , <u>redefines</u> <u>mean</u>	The mean for the exponential distribution defined in the <u>NIST/Sematech Engineering Statistics Handbook, section 8.1.6,</u> <u><a href="https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm">https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm</a></u>
<u>hazardFunction</u> :	The hazard function for the exponential distribution defined in the
<u>ExponentialHazardFunction</u> , <u>redefines</u> <u>hazardFunction</u>	<u>NIST/Sematech Engineering Statistics Handbook, section 8.1.6,</u> <u><a href="https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm">https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm</a></u>

## **WeibullDistribution**

**Package:** Probability

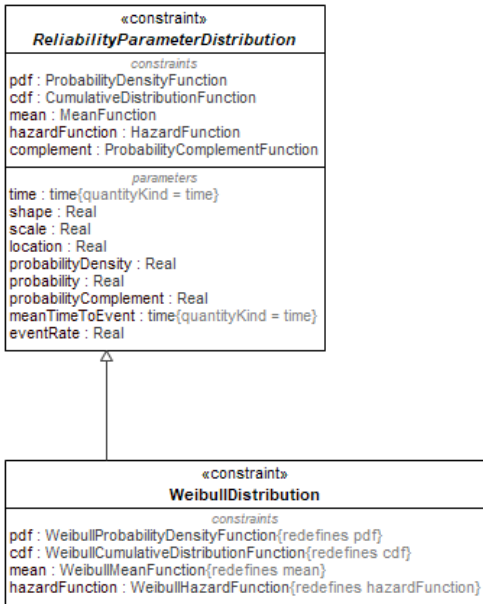
**isAbstract:** No

**Generalization:** ReliabilityParameterDistribution

**Applied Stereotype:** «ConstraintBlock»

### Description

This constraint block calculates owns 4 lower level constraint blocks for calculating the values of the cumulative, density, and hazard functions, as well as the mean for the Weibull distribution.



**Figure 9.229 – WeibullDistribution**

**Attributes**

- pdf** : WeibullProbabilityDensityFunction, redefines pdf  
 The PDF for the Weibull distribution defined in the NIST/Sematech Engineering Statistics Handbook, section 8.1.6, <https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm>
- cdf** : WeibullCumulativeDistributionFunction, redefines cdf  
 The PDF for the Weibull distribution defined in the NIST/Sematech Engineering Statistics Handbook, section 8.1.6, <https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm>
- mean** : WeibullMeanFunction, redefines mean  
 The mean for the Weibull distribution defined in the NIST/Sematech Engineering Statistics Handbook, section 8.1.6, <https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm>
- hazardFunction** : WeibullHazardFunction, redefines hazardFunction  
 The hazard function for the Weibull distribution defined in the NIST/Sematech Engineering Statistics Handbook, section 8.1.6, <https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm>

**LognormalDistribution**

**Package:** Probability  
**isAbstract:** No

**Generalization:** ReliabilityParameterDistribution

**Applied Stereotype:** «ConstraintBlock»

## Description

This constraint block calculates owns 4 lower level constraint blocks for calculating the values of the cumulative, density, and hazard functions, as well as the mean for the lognormal distribution.

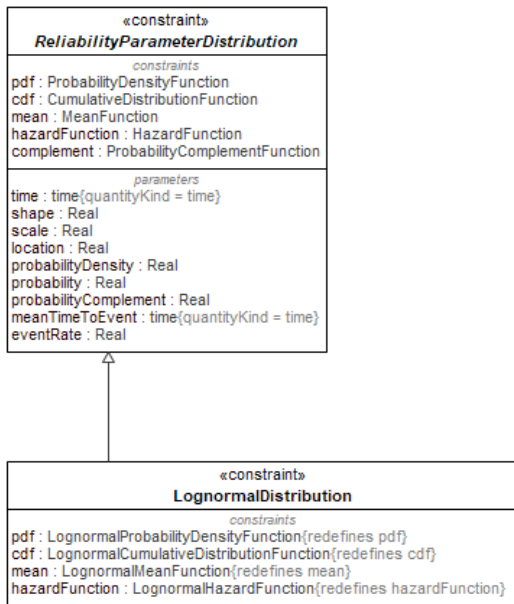


Figure 9.230 – LognormalDistribution

## Attributes

pdf :	The PDF for the lognormal distribution defined in the NIST/Sematech Engineering Statistics Handbook, section 8.1.6. <a href="https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm">https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm</a>
LognormalProbabilityDensityFunction, redefines pdf	
cdf :	The CDF for the lognormal distribution defined in the NIST/Sematech Engineering Statistics Handbook, section 8.1.6. <a href="https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm">https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm</a>
LognormalCumulativeDistributionFunction, redefines cdf	
mean : LognormalMeanFunction, redefines mean	The mean for the lognormal distribution defined in the NIST/Sematech Engineering Statistics Handbook, section 8.1.6. <a href="https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm">https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm</a>
hazardFunction :	The hazard function for the lognormal distribution defined in the NIST/Sematech Engineering Statistics Handbook, section 8.1.6. <a href="https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm">https://www.itl.nist.gov/div898/handbook/apr/section1/apr16.htm</a>
LognormalHazardFunction, redefines hazardFunction	

## 9.9.2.2 Methods::RBD::RBD Library::ConstraintBlocks::SystemBlocks

## InSeriesCalculation

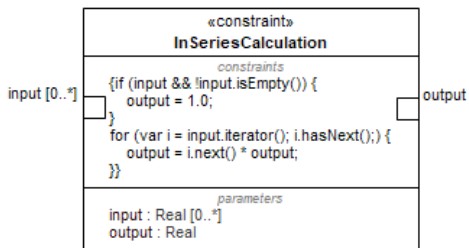
**Package:** SystemBlocks

**isAbstract:** No

**Applied Stereotype:** «ConstraintBlock»

**Description**

Constraint block for calculation of series system reliability or availability



**Figure 9.231 – InseriesCalculation**

**Attributes**

**input :** Real[0..\*]

Probabilities (reliability or availability) of input components

**output :** Real

Series system reliability or availability

**Constraints**

```
[1] if (input && !input.isEmpty()) {  
    output = 1.0;  
}  
for (var i = input.iterator(); i.hasNext();) {  
    output = i.next() * output;  
}
```

### **InParallelCalculation**

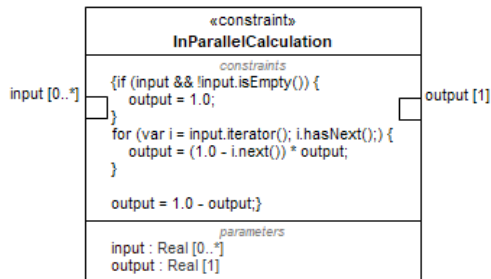
**Package:** SystemBlocks

**isAbstract:** No

**Applied Stereotype:** «ConstraintBlock»

**Description**

Constraint block for calculation of parallel system reliability or availability



**Figure 9.232 – InparallelCalculation**

Attributes

input : Real[0..\*]

output : Real[1]

Constraints

[1]

Reliability or availability of components

Reliability or availability of system

```

if (input && !input.isEmpty()) {
  output = 1.0;
}
for (var i = input.iterator(); i.hasNext(); ) {
  output = (1.0 - i.next()) * output;
}

output = 1.0 - output;
  
```

**HomogeneousKofNCalculation**

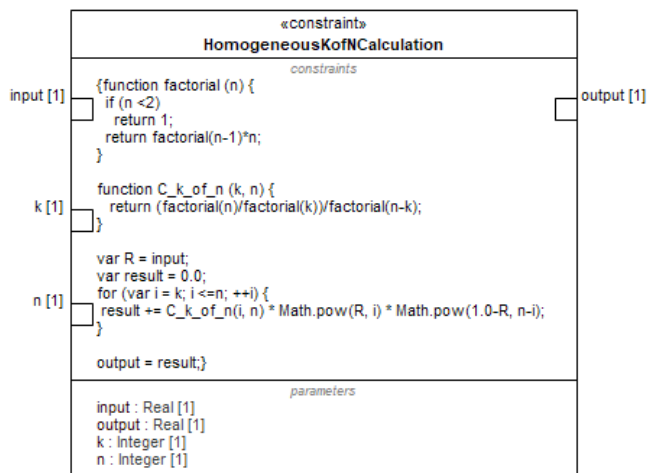
Package: SystemBlocks

isAbstract: No

Applied Stereotype: «ConstraintBlock»

Description

Constraint block for calculation of k out of n system reliability or availability



**Figure 9.233 – HomogeneousKofNCalculation**

**Attributes**

<u>input : Real [1]</u>	<u>Reliability or availability of components (all components must have equal reliability or availability)</u>
<u>output : Real [1]</u>	<u>k ou tof n system reliability or availability</u>
<u>k : Integer [1]</u>	<u>Number of components or channels needed for system ro operate</u>
<u>n : Integer [1]</u>	<u>Number of components installed in system</u>

**Constraints**

```

[1]
function factorial (n) {
  if (n <2)
  return 1;
  return factorial(n-1)*n;
}

function C_k_of_n (k, n) {
  return (factorial(n)/factorial(k))/factorial(n-k);
}

var R = input;
var result = 0.0;
for (var i = k; i <=n; ++i) {
  result += C_k_of_n(i, n) * Math.pow(R, i) * Math.pow(1.0-R, n-i);
}

output = result;
  
```

## HeterogeneousKofNCalculation

Package: SystemBlocks

isAbstract: No

Applied Stereotype: «ConstraintBlock»

### Description

Constraint block for calculation of k out of n system reliability or availability where components have different reliabilities or availabilities

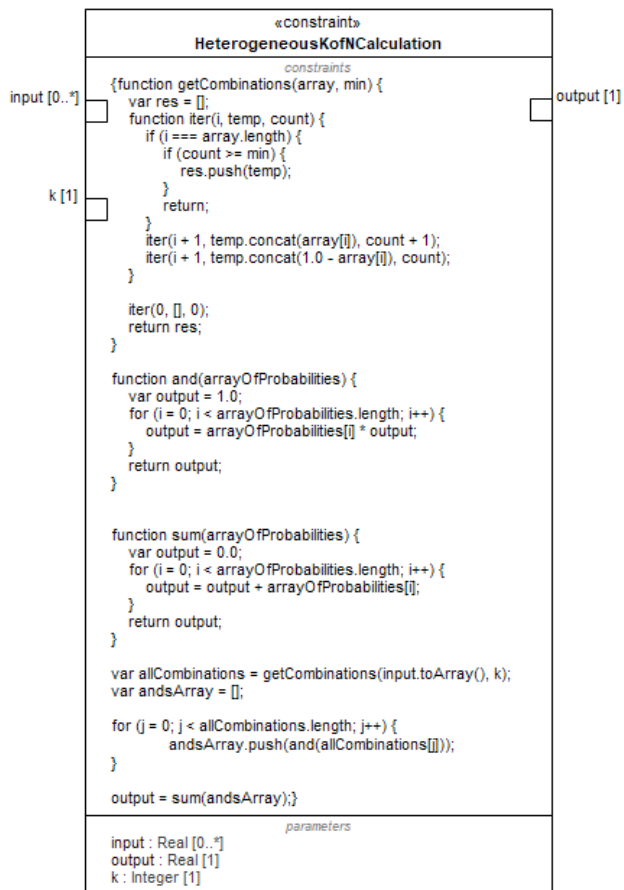


Figure 9.234 – HeterogeneousKofNCalculation



## Attributes

`input : Real[0..*]`

Reliability or availability of components (components do not necessarily have equal reliability or availability)

`output : Real[1]`

Reliability or availability of system

`k : Integer[1]`

Number of components or channels needed for system to operate

## Constraints

[1]

```
function getCombinations(array, min) {
  var res = [];
  function iter(i, temp, count) {
    if (i === array.length) {
      if (count >= min) {
        res.push(temp);
      }
      return;
    }
    iter(i + 1, temp.concat(array[i]), count + 1);
    iter(i + 1, temp.concat(1.0 - array[i]), count);
  }
  iter(0, [], 0);
  return res;
}

function and(arrayOfProbabilities) {
  var output = 1.0;
  for (i = 0; i < arrayOfProbabilities.length; i++) {
    output = arrayOfProbabilities[i] * output;
  }
  return output;
}

function sum(arrayOfProbabilities) {
  var output = 0.0;
  for (i = 0; i < arrayOfProbabilities.length; i++) {
    output = output + arrayOfProbabilities[i];
  }
  return output;
}

var allCombinations = getCombinations(input.toArray(), k);
var andsArray = [];
```

```
for (j = 0; j < allCombinations.length; j++) {  
  andsArray.push(and(allCombinations[j]));  
}
```

```
output = sum(andsArray);
```

### 9.9.3 Methods::RBD::RBD Profile

#### ReliabilitySituation

**Package:** RBD Profile

**isAbstract:** Yes

**Generalization:** Situation

**Extension:** Class

**Description**

A marker stereotype for all reliability situations. See AbstractReliabilitySituation library class for definition.

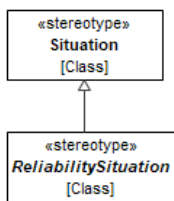


Figure 9.235 – ReliabilitySituation

#### Restorable

**Package:** RBD Profile

**isAbstract:** No

**Extension:** Class

**Description**

A mixin stereotype for all restorable reliability situations - both component and system. See Restorable library class for definition.

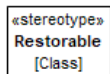


Figure 9.236 – Restorable

**Constraints**

[1] RestorableIsRestorable self.base\_Class->asSet()->closure(general).name->includes('Restorable')

### **ComponentReliability**

**Package:** RBD Profile

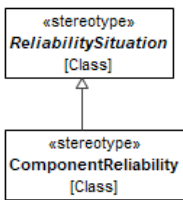
**isAbstract:** No

**Generalization:** ReliabilitySituation

**Extension:** Class

**Description**

A marker stereotype for non-composite reliability situations. See ComponentReliabilitySituation library class for definition.



**Figure 9.237 –ReliabilitySituation**

**Constraints**

[1] ComponentReliabilityIsComponentReliabilitySituation self.base\_Class->asSet()->closure(general).name->includes('ComponentReliabilitySituation')

### **SystemReliability**

**Package:** RBD Profile

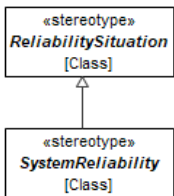
**isAbstract:** Yes

**Generalization:** ReliabilitySituation

**Extension:** Class

**Description**

A marker stereotype for composite reliability situations. See SystemReliabilitySituation library class for definition.



**Figure 9.238 –SystemReliability**

## InSeries

**Package:** RBD Profile

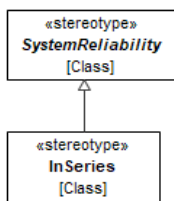
**isAbstract:** No

**Generalization:** SystemReliability

**Extension:** Class

**Description**

A marker stereotype for in-series composite reliability situations. See InSeries library class for definition.



**Figure 9.239 – InSeries**

**Constraints**

[1] InSeriesIsInSeries `self.base_Class->asSet()->closure(general).name->includes('InSeries')`

## InParallel

**Package:** RBD Profile

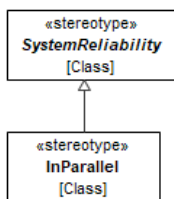
**isAbstract:** No

**Generalization:** SystemReliability

**Extension:** Class

**Description**

A marker stereotype for in-parallel composite reliability situations. See InParallel library class for definition.



**Figure 9.240 – InParallel**

**Constraints**

[1] InParallelIsInParallel `self.base_Class->asSet()->closure(general).name->includes('InParallel')`

## HomogeneousKofN

**Package:** RBD Profile

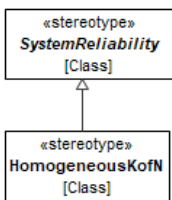
**isAbstract:** No

**Generalization:** SystemReliability

**Extension:** Class

**Description**

A marker stereotype for homogeneous k-of-n composite reliability situations. See HomogeneousKofN library class for definition.



**Figure 9.241 – HomogeneousKofN**

**Constraints**

[1] HomogeneousKofN is HomogeneousKofN self.base Class->asSet()->closure(general).name->includes('HomogeneousKofN')

## HeterogeneousKofN

**Package:** RBD Profile

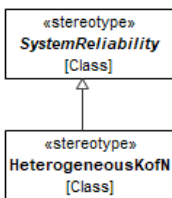
**isAbstract:** No

**Generalization:** SystemReliability

**Extension:** Class

**Description**

A marker stereotype for heterogeneous k-of-n composite reliability situations. See HeterogeneousKofN library class for definition.



**Figure 9.242 – HeterogeneousKofN**

**Constraints**

[11] self.base\_Class->asSet()->closure(general).name->includes('HeterogeneousKofN')

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## 10. Views

### 10.1 Core

#### 10.1.1 Core::Core Library

View Core::Core Library::Core Library

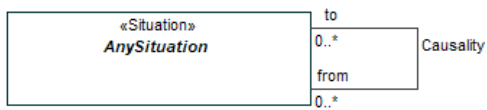


Figure 10.1 – Core Library

Elements

- [AnySituation](#)
- [Causality](#)

#### 10.1.2 Core::Core Profile

View Core::Core Profile::CoreProfile

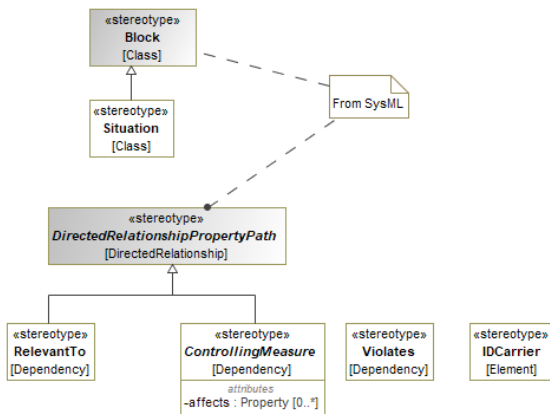


Figure 10.2 – CoreProfile

Elements

- [ControllingMeasure](#)
- [RelevantTo](#)
- [Situation](#)
- [Violates](#)

## 10.2 General

### 10.2.1 General::General Concepts Library

View General::General Concepts Library::General Concepts Library

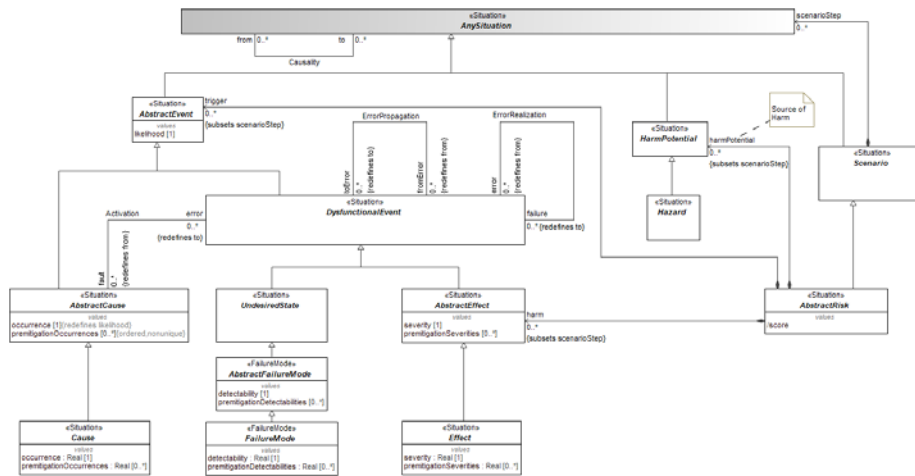


Figure 10.3 - General Concepts Library

Elements

- [AbstractCause](#)
- [AbstractEffect](#)
- [AbstractEvent](#)
- [AbstractFailureMode](#)
- [AbstractRisk](#)
- [Activation](#)
- [AnySituation](#)
- [Causality](#)
- [Cause](#)
- [DysfunctionalEvent](#)
- [Effect](#)
- [ErrorPropagation](#)
- [ErrorRealization](#)
- [FailureMode](#)
- [HarmPotential](#)
- [Hazard](#)
- [Scenario](#)
- [UndesiredState](#)

### 10.2.2 General::General Concepts Profile

View General::General Concepts Profile::General Concepts Profile



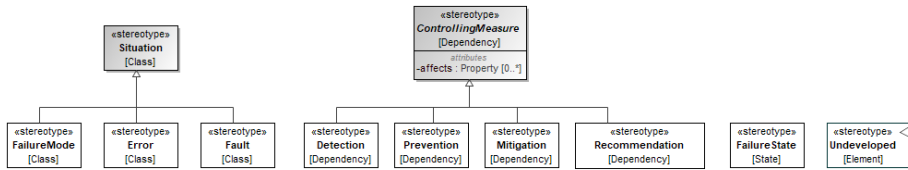


Figure 10.4 – General Concepts Profile

Elements

- [ControllingMeasure](#)
- [Detection](#)
- [Error](#)
- [FailureMode](#)
- [FailureState](#)
- [Fault](#)
- [Mitigation](#)
- [Prevention](#)
- [Recommendation](#)
- [Situation](#)
- [Undeveloped](#)

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### 10.3 General Security

#### 10.3.1 General Security::General Security Concepts Library

#### View General Security::General Security Concepts Library::General Security Concepts Library

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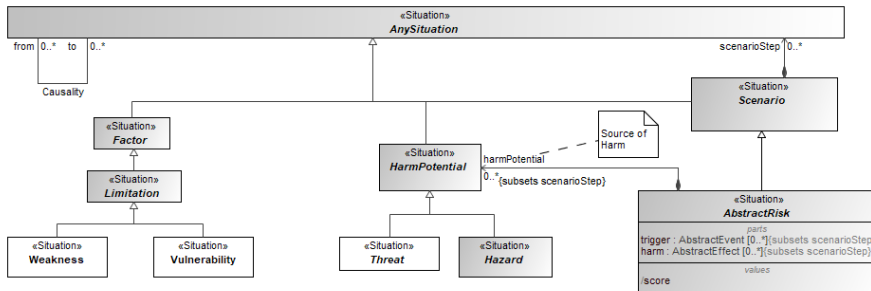


Figure 10.5 - General Security Concepts Library

Elements

- [AbstractRisk](#)
- [AnySituation](#)
- [Causality](#)
- [Factor](#)

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- HarmPotential
- Hazard
- Limitation
- Scenario
- Threat
- Vulnerability
- Weakness

### 10.3.2 General Security::General Security Concepts Profile

#### View General Security::General Security Concepts Profile::General Security Concepts Profile

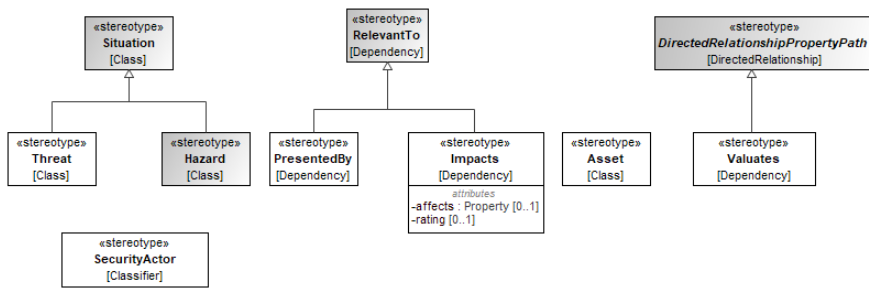


Figure 10.6 - General Security Concepts Profile Elements

- Asset
- Hazard
- Impacts
- PresentedBy
- RelevantTo
- SecurityActor
- Situation
- Threat
- Valuates

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## 10.4 Methods::FMEA

### 10.4.1 Methods::FMEA::FMEA Library

View Methods::FMEA::FMEA Library::FMEA Library

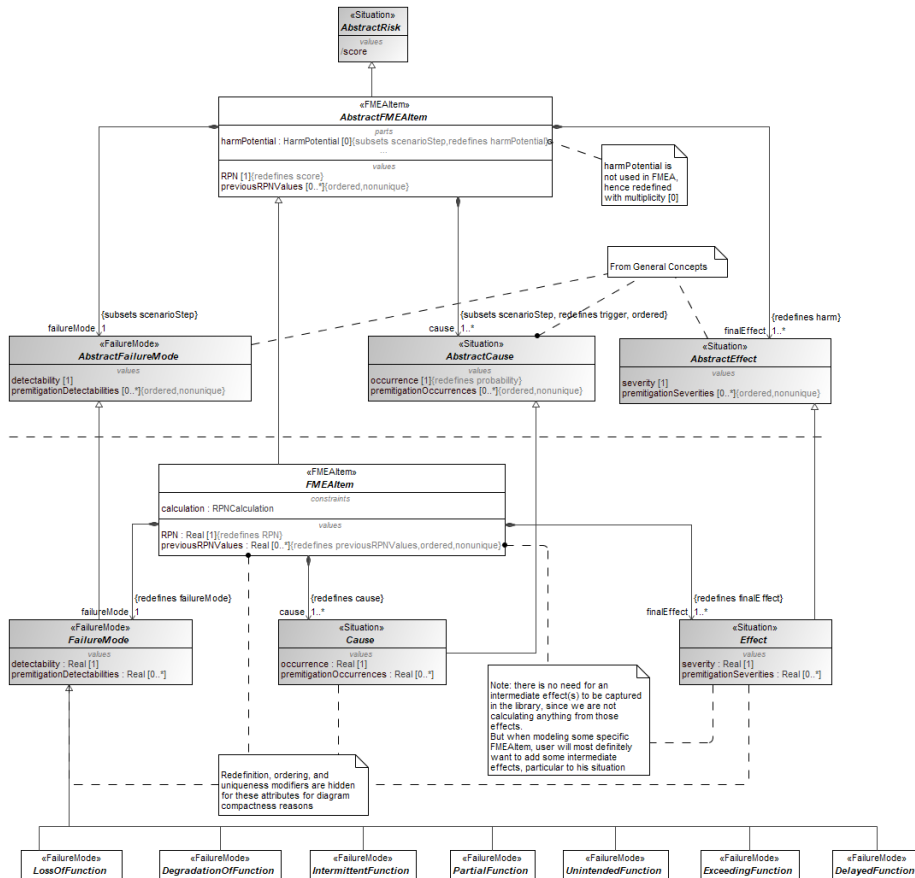


Figure 10.7 – FMEA Library

#### Elements

- [AbstractCause](#)
- [AbstractEffect](#)
- [AbstractFailureMode](#)
- [AbstractFMEAItem](#)
- [AbstractRisk](#)
- [Cause](#)
- [DegradationOfFunction](#)

- [DelayedFunction](#)
- [Effect](#)
- [ExceedingFunction](#)
- [FailureMode](#)
- [FMEAItem](#)
- [IntermittentFunction](#)
- [LossOfFunction](#)
- [PartialFunction](#)
- [UnintendedFunction](#)

### 10.4.2 Methods::FMEA::FMEA Profile

View Methods::FMEA::FMEA Profile::FMEA Profile

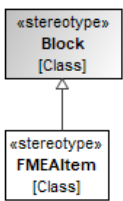


Figure 10.8 – FMEA Profile

Elements

- [FMEAItem](#)

## 10.5 Methods::FTA

### 10.5.1 Methods::FTA::FTALibrary

Methods::FTA::FTALibrary::Events

View Methods::FTA::FTALibrary::Events::Events

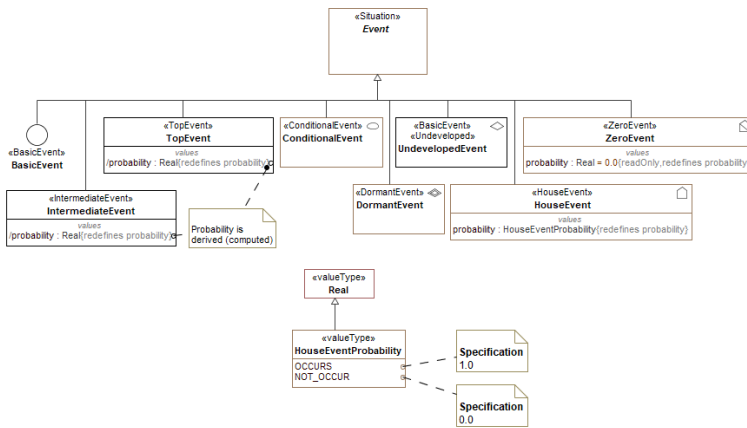


Figure 10.9 – Events

Elements

- [BasicEvent](#)
- [ConditionalEvent](#)
- [DormantEvent](#)
- [Event](#)
- [HouseEvent](#)
- [IntermediateEvent](#)
- [TopEvent](#)
- [UndevelopedEvent](#)
- [ZeroEvent](#)

View Methods::FTA::FTALibrary::FTA Library

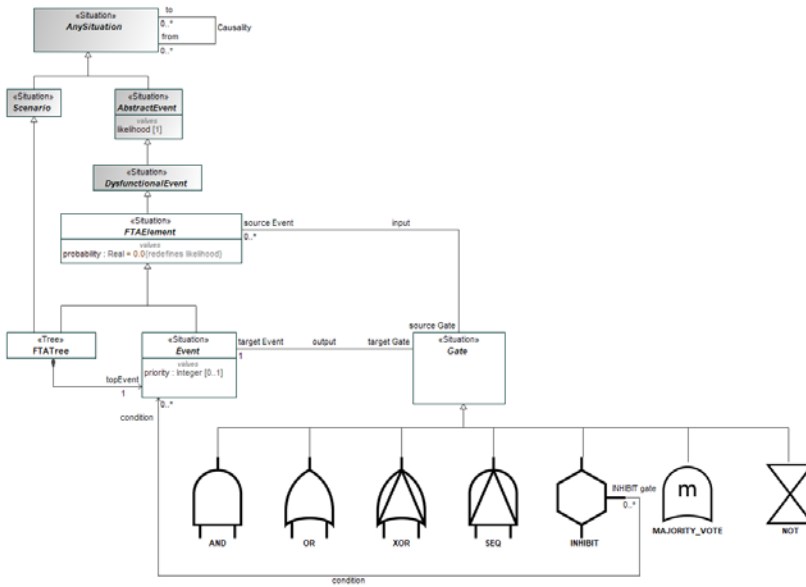


Figure 10.10 – FTA Library

Elements

- [AbstractEvent](#)
- [AND](#)
- [AnySituation](#)
- [Causality](#)
- [DysfunctionalEvent](#)
- [Event](#)
- [FTAElement](#)

- [FTATree](#)
- [Gate](#)
- [INHIBIT](#)
- [MAJORITY\\_VOTE](#)
- [NOT](#)
- [OR](#)
- [Scenario](#)
- [SEQ](#)
- [XOR](#)

### 10.5.2 Methods::FTA::FTAProfile

#### Methods::FTA::FTAProfile::Diagrams by elements

View Methods::FTA::FTAProfile::FTA Profile

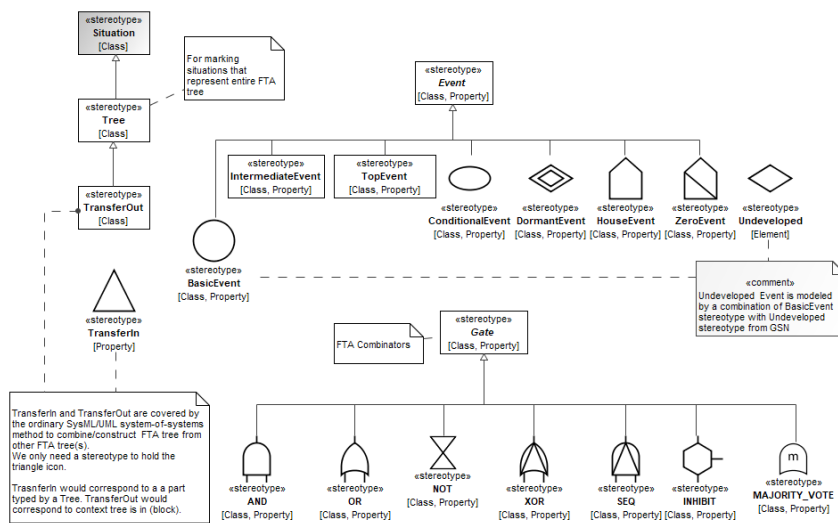


Figure 10.11 – FTA Profile

#### Elements

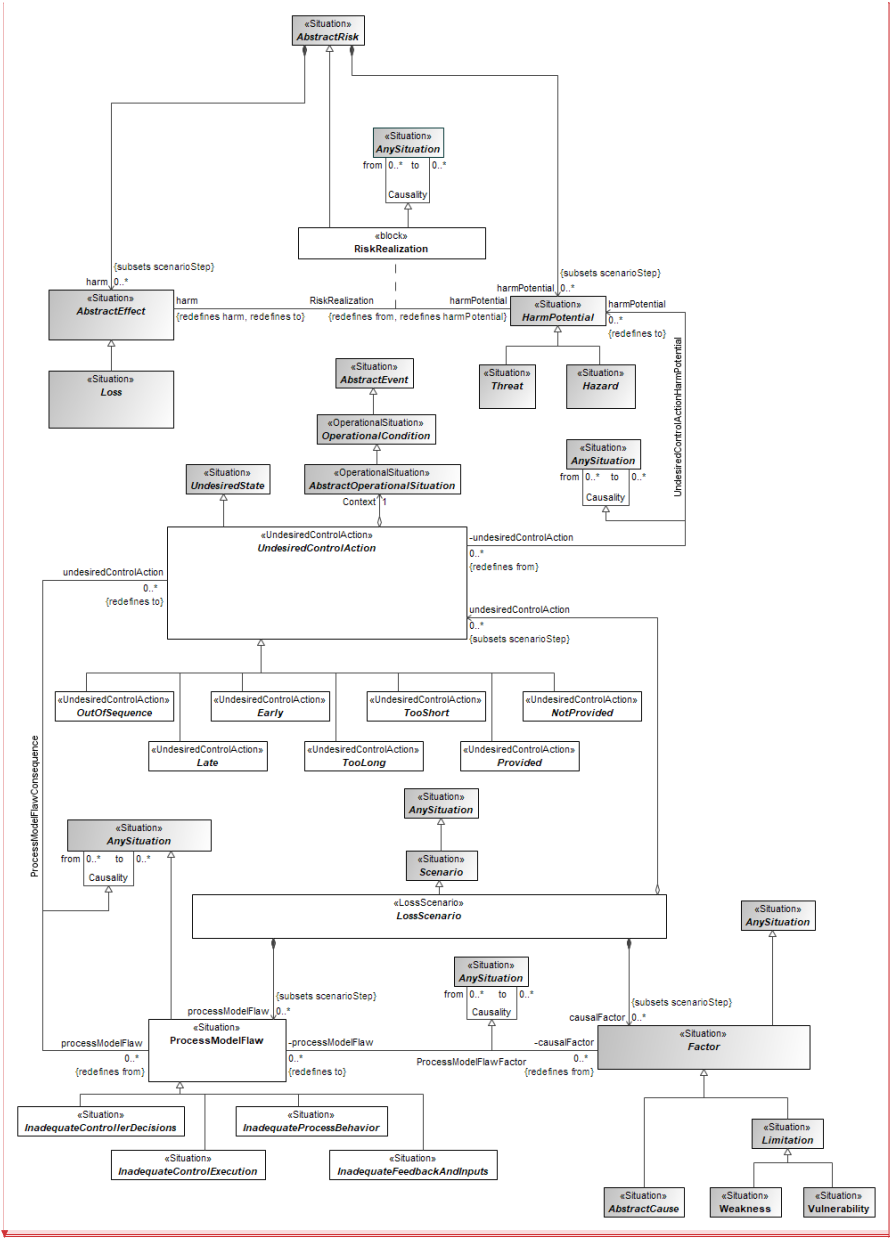
- [AND](#)
- [BasicEvent](#)
- [ConditionalEvent](#)
- [DormantEvent](#)
- [Event](#)
- [Gate](#)
- [HouseEvent](#)
- [INHIBIT](#)
- [IntermediateEvent](#)

- [MAJORITY\\_VOTE](#)
- [NOT](#)
- [OR](#)
- [SEQ](#)
- [Situation](#)
- [TopEvent](#)
- [TransferIn](#)
- [TransferOut](#)
- [Tree](#)
- [Undeveloped](#)
- [XOR](#)
- [ZeroEvent](#)

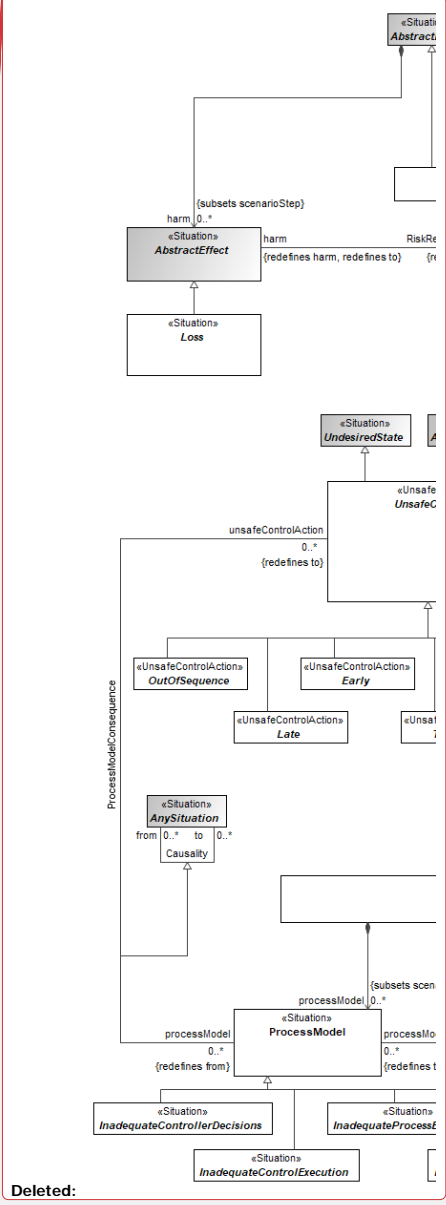
## 10.6 Methods::STPA

### 10.6.1 Methods::STPA::STPA Library

View [Methods::STPA::STPA Library::STPA Library](#)



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Figure 10.12 – STPA Library

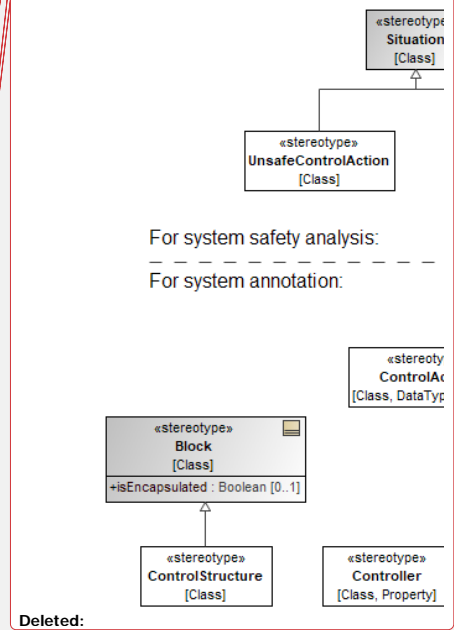
Elements

- [AbstractCause](#)
- [AbstractEffect](#)
- [AbstractEvent](#)
- [AbstractOperationalSituation](#)
- [AbstractRisk](#)
- [AnySituation](#)
- [Causality](#)
- [Early](#)
- [Factor](#)
- [HarmPotential](#)
- [Hazard](#)
- [Inadequate Control Execution](#)
- [Inadequate Controller Decisions](#)
- [Inadequate Feedback and Inputs](#)
- [Inadequate Process Behavior](#)
- [Late](#)
- [Limitation](#)
- [Loss](#)
- [LossScenario](#)
- [NotProvided](#)
- [OperationalCondition](#)
- [OutOfSequence](#)
- [ProcessModelFlaw](#)
- [ProcessModelFlawConsequence](#)
- [ProcessModelFlawFactor](#)
- [Provided](#)
- [RiskRealization](#)
- [Scenario](#)
- [Threat](#)
- [TooLong](#)
- [TooShort](#)
- [UndesiredState](#)
- [UndesiredControlAction](#)
- [UndesiredControlActionHarmPotential](#)
- [Vulnerability](#)
- [Weakness](#)

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- Deleted: [UnsafeControlAction](#)
- Deleted: [UnsafeControlActionHarmPotential](#)
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- Commented [AA80]: RAAML11-28

10.6.2 Methods::STPA::STPA Profile

View Methods::STPA::STPA Profile::STPA Profile



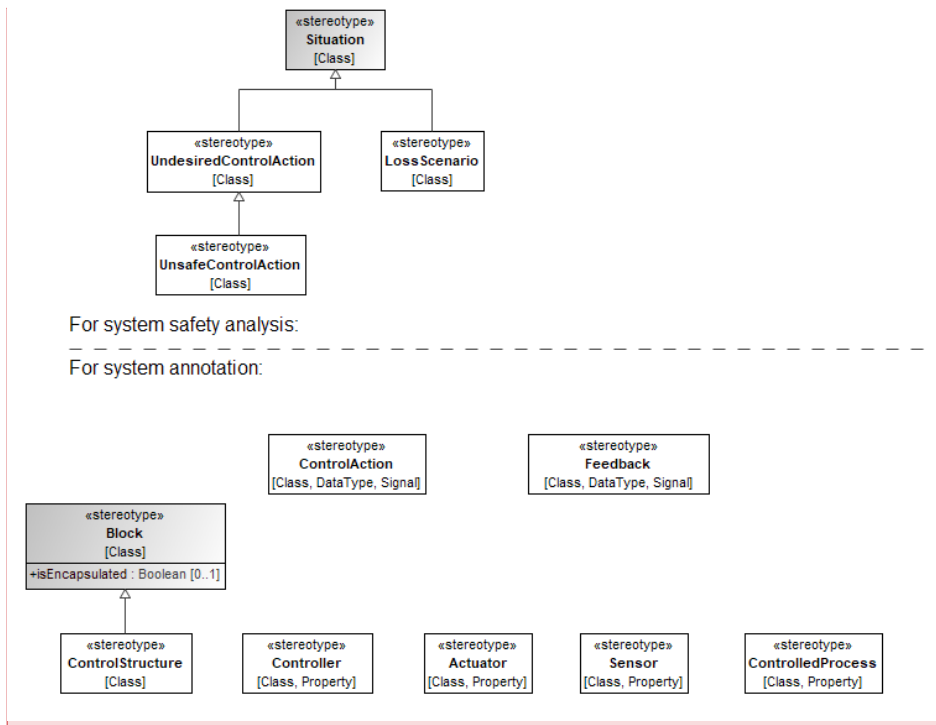


Figure 10.13 – STPA Profile

Elements

- [Actuator](#)
- [ControlAction](#)
- [ControlledProcess](#)
- [Controller](#)
- [ControlStructure](#)
- [FailureMode](#)
- [Feedback](#)
- [Sensor](#)
- [UndesiredControlAction](#)
- [UnsafeControlAction](#)

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## 10.7 GSN

### 10.7.1 GSN::GSN Profile

View GSN::GSN Profile::GSN Profile

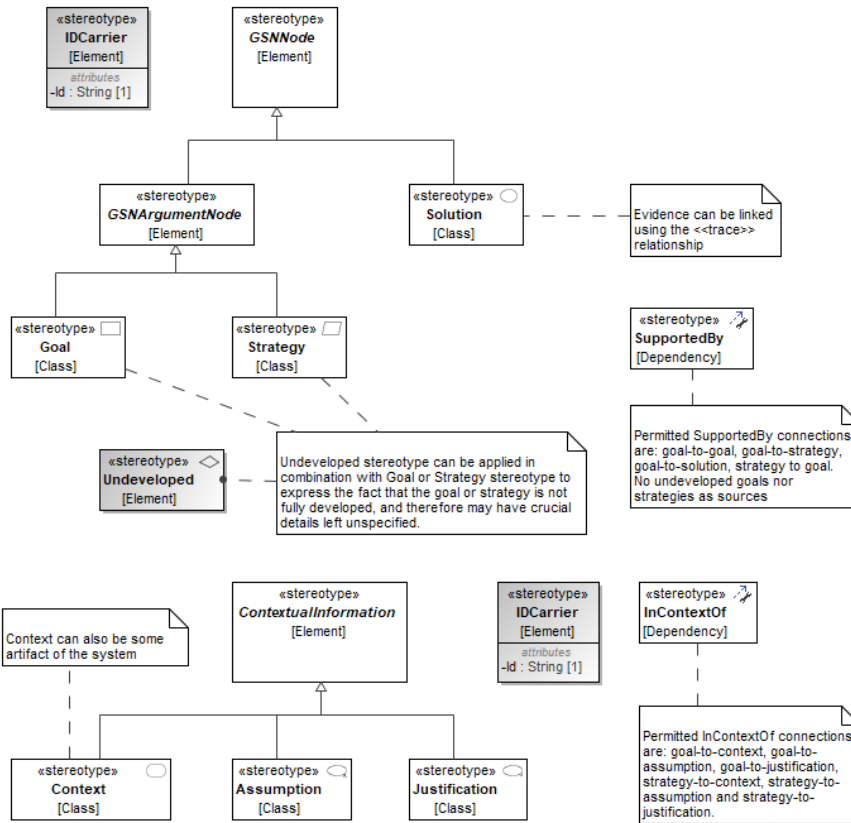


Figure 10.14 – GSN Profile

Elements

- [Assumption](#)
- [Context](#)
- [Goal](#)
- [GSNArgumentNode](#)
- [GSNNode](#)
- [InContextOf](#)
- [Justification](#)
- [Solution](#)
- [Strategy](#)
- [SupportedBy](#)
- [ContextualInformation](#)
- [Undeveloped](#)



- [Inverted](#)
- [ISO26262SafetyRequirementTemplate](#)
- [Late](#)
- [Less](#)
- [Location](#)
- [More](#)
- [No](#)
- [OperationalCondition](#)
- [RoadCondition](#)
- [Scenario](#)
- [Severity](#)
- [SystemLevelEffect](#)
- [TrafficAndPeople](#)
- [TypicalAutomotiveSituation](#)
- [UndesiredState](#)
- [Unintended](#)
- [VehicleLevelEffect](#)
- [VehicleUsage](#)

View Methods::ISO 26262::ISO 26262 Library::All-Encompassing Operational Situations

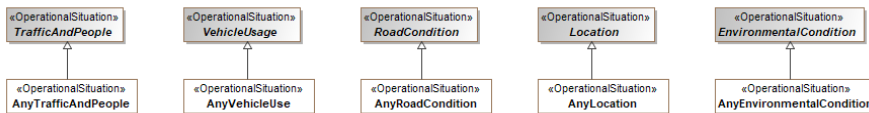


Figure 10.16 – All-Encompassing Operational Situations

Elements

- [AnyEnvironmentalCondition](#)
- [AnyLocation](#)
- [AnyRoadCondition](#)
- [AnyTrafficAndPeople](#)
- [AnyVehicleUse](#)
- [EnvironmentalCondition](#)
- [Location](#)
- [RoadCondition](#)
- [TrafficAndPeople](#)
- [VehicleUsage](#)

## 10.8.2 Methods::ISO 26262::ISO 26262 Profile

Methods::ISO 26262::ISO 26262 Profile::RequirementManagement

View Methods::ISO 26262::ISO 26262 Profile::RequirementManagement::RequirementManagement

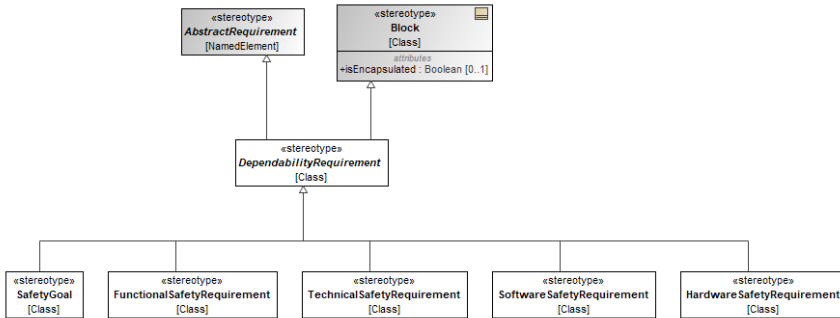
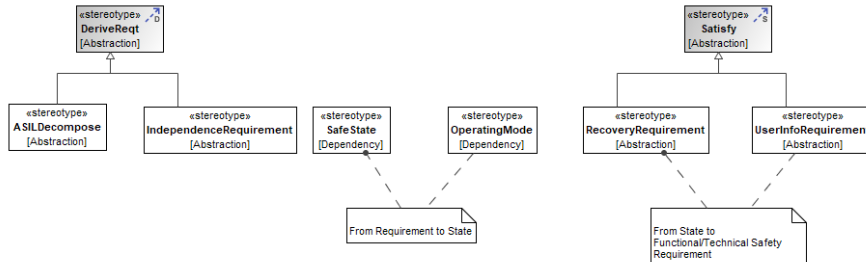


Figure 10.17 – RequirementManagement

Elements

- [ASILDecompose](#)
- [DependabilityRequirement](#)
- [FunctionalSafetyRequirement](#)
- [HardwareSafetyRequirement](#)
- [IndependenceRequirement](#)
- [OperatingMode](#)
- [RecoveryRequirement](#)
- [SafeState](#)
- [SafetyGoal](#)
- [SoftwareSafetyRequirement](#)
- [TechnicalSafetyRequirement](#)
- [UserInfoRequirement](#)

View Methods::ISO 26262::ISO 26262 Profile::ISO26262 Profile

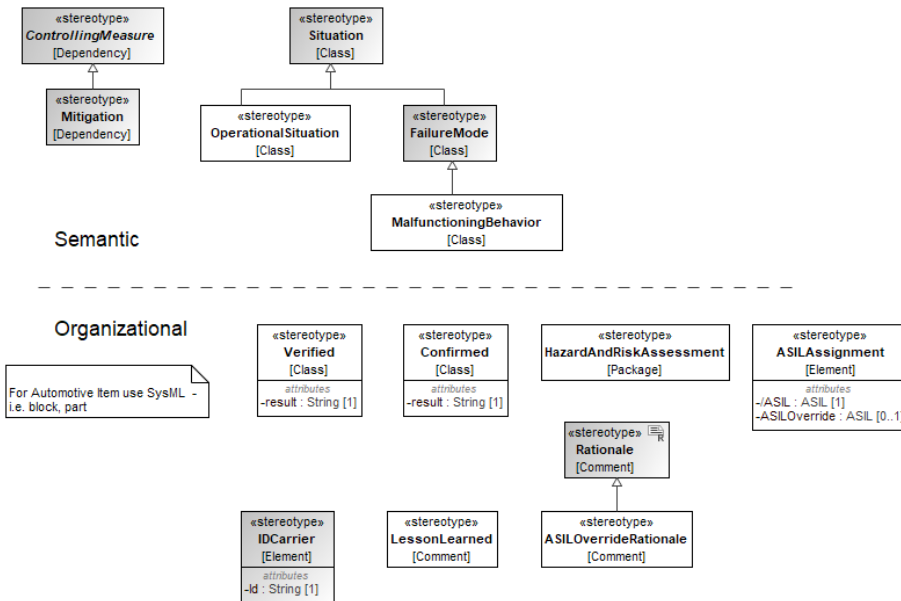


Figure 10.18 – ISO 26262 Profile

Elements

- [ASILAssignment](#)
- [ASILOverrideRationale](#)
- [Confirmed](#)
- [ControllingMeasure](#)
- [FailureMode](#)
- [HazardAndRiskAssessment](#)
- [IDCarrier](#)
- [LessonLearned](#)
- [MalfunctioningBehavior](#)
- [Mitigation](#)
- [OperationalSituation](#)
- [Situation](#)
- [Verified](#)

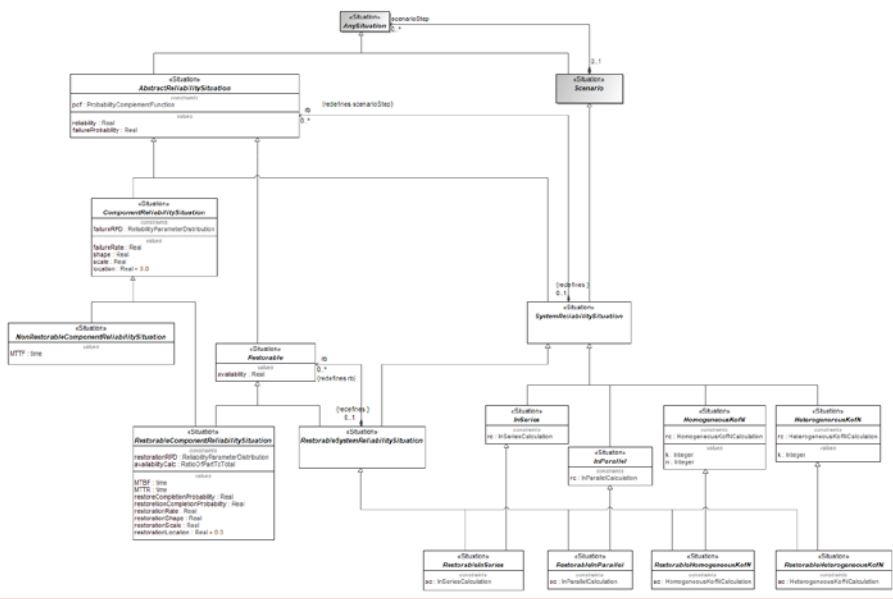
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## 10.9 Methods::RBD

### 10.9.1 Methods::RBD::RBD Library

[View Methods::RBD::RBD Library::RBD Library](#)



**Figure 0.19 - RBD Library Elements**

- [AbstractReliabilitySituation](#)
- [AnySituation](#)
- [ComponentReliabilitySituation](#)
- [HeterogeneousKofN](#)
- [HomogeneousKofN](#)
- [InParallel](#)
- [InSeries](#)
- [NonRestorableComponentReliabilitySituation](#)
- [Restorable](#)
- [RestorableComponentReliabilitySituation](#)
- [RestorableHeterogeneousKofN](#)
- [RestorableHomogeneousKofN](#)
- [RestorableInParallel](#)
- [RestorableInSeries](#)
- [RestorableSystemReliabilitySituation](#)
- [Scenario](#)
- [SystemReliabilitySituation](#)

**View Methods::RBD::RBD Library::AbstractReliabilitySituation::AbstractReliabilitySituation**



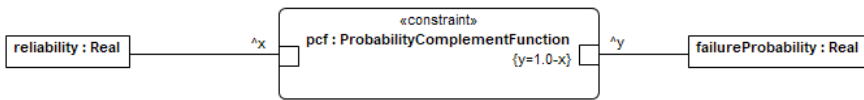


Figure 0.20 - AbstractReliabilitySituation

View Methods::RBD::RBD

Library::ComponentReliabilitySituation::ComponentReliabilitySituation

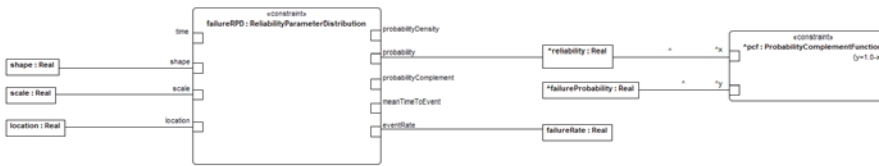


Figure 0.21 - ComponentReliabilitySituation

View Methods::RBD::RBD

Library::NonRestorableComponentReliabilitySituation::NonRestorableComponentReliabilitySituation

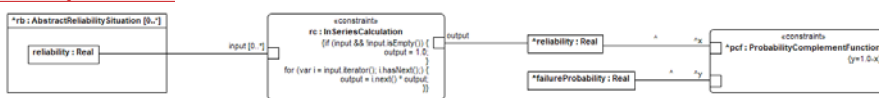


Figure 0.22 - InSeries

View Methods::RBD::RBD Library::RestorableInSeries::RestorableInSeries

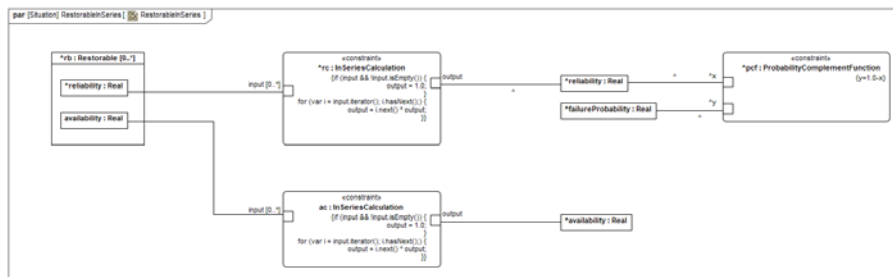


Figure 0.23 - RestorableInSeries

View Methods::RBD::RBD Library::InParallel::InParallel

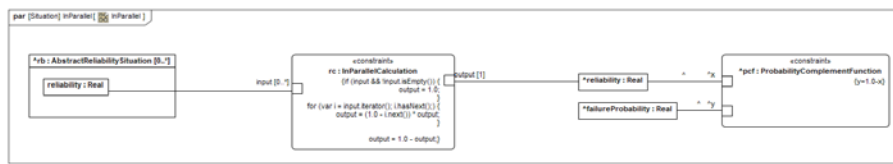


Figure 0.24 - InParallel

View Methods::RBD::RBD Library::RestorableInParallel::RestorableInParallel

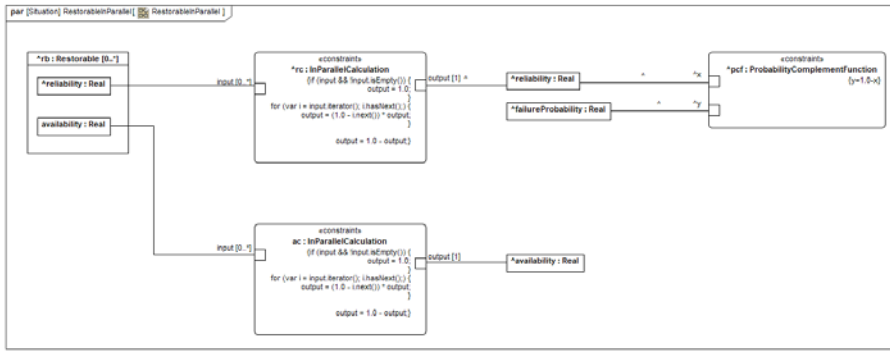


Figure 0.25 - RestorableInParallel

View Methods::RBD::RBD Library::HomogeneousKofN::HomogeneousKofN

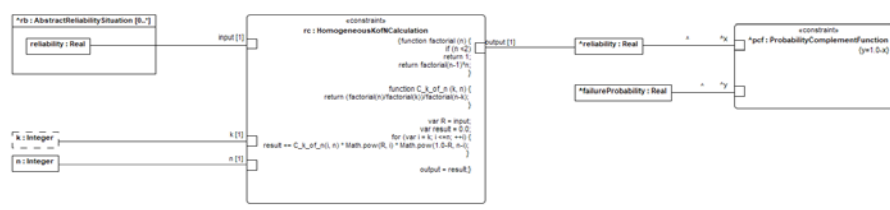


Figure 0.26 - HomogeneousKofN

View Methods::RBD::RBD

Library::RestorableHomogeneousKofN::RestorableHomogeneousKofN

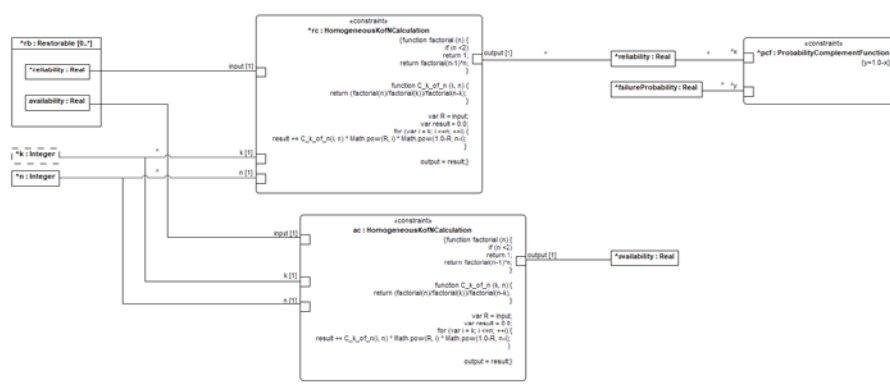


Figure 0.27 - RestorableHomogeneousKofN

View Methods::RBD::RBD Library::HeterogeneousKofN::HeterogeneousKofN

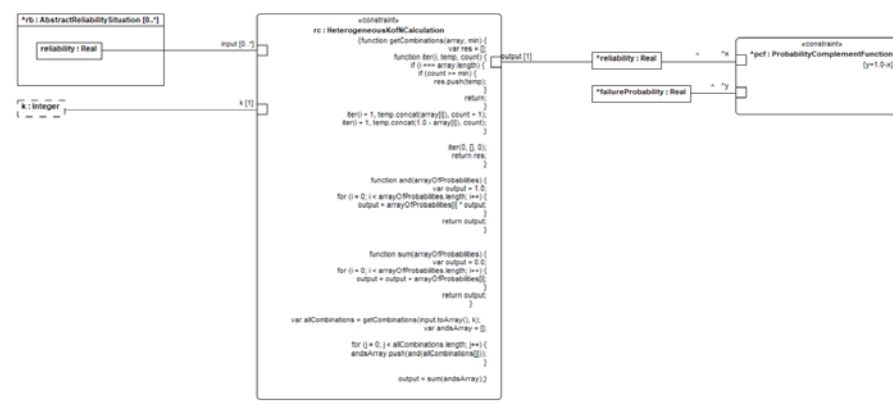


Figure 0.28 - HeterogeneousKofN

View Methods::RBD::RBD Library::RestorableHeterogeneousKofN::RestorableHeterogeneousKofN

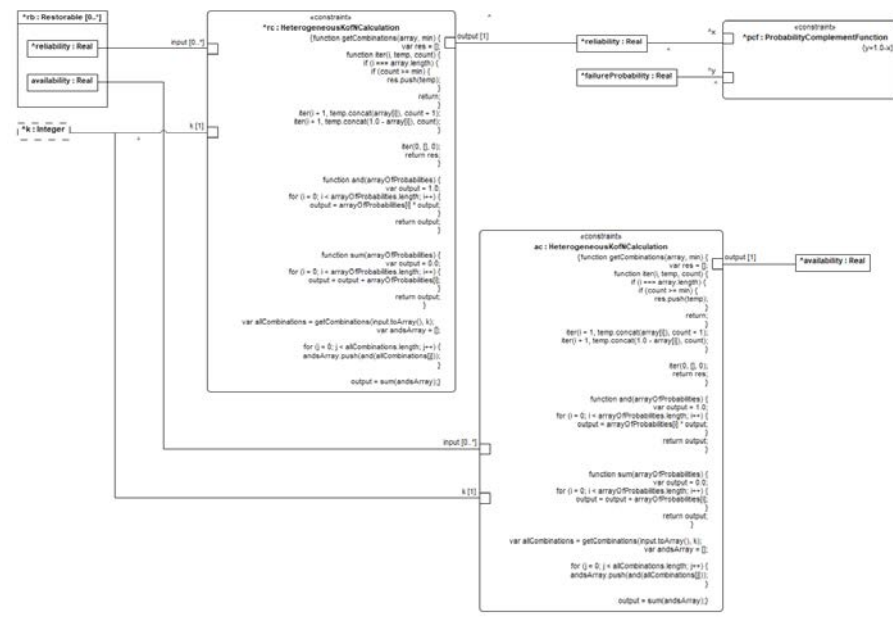


Figure 0.29 - RestorableHeterogeneousKofN

## 10.9.2 Methods::RBD::RBD Library::ConstraintBlocks

### 10.9.2.1 Methods::RBD::RBD Library::ConstraintBlocks::Probability

#### View Methods::RBD::RBD Library::ConstraintBlocks::Probability::Distributions

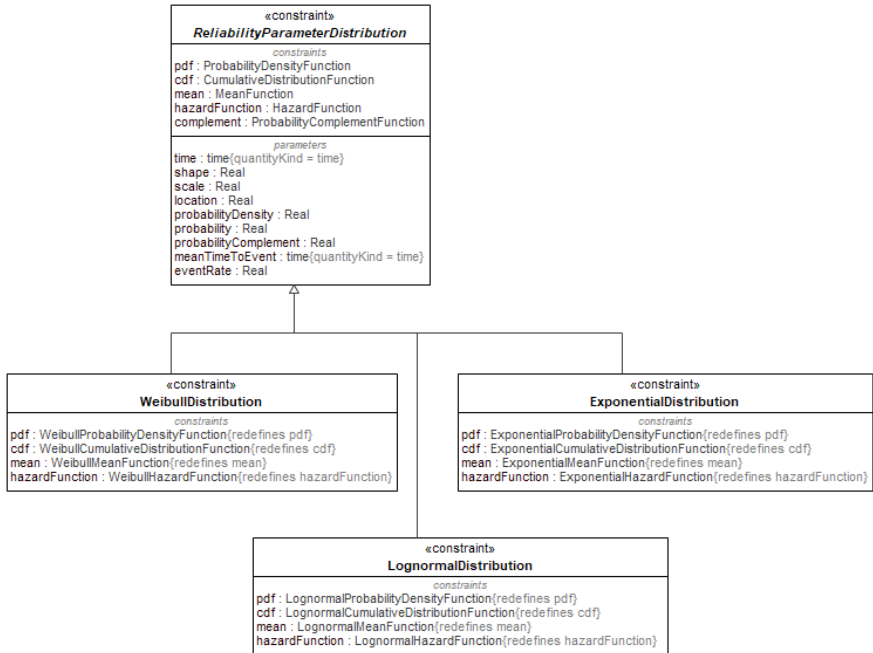


Figure 0.30 - Distributions

#### Elements

- [ExponentialDistribution](#)
- [LognormalDistribution](#)
- [ReliabilityParameterDistribution](#)
- [WeibullDistribution](#)

#### View Methods::RBD Library::ConstraintBlocks::Probability::ReliabilityParameterDistribution::ReliabilityParameterDistribution

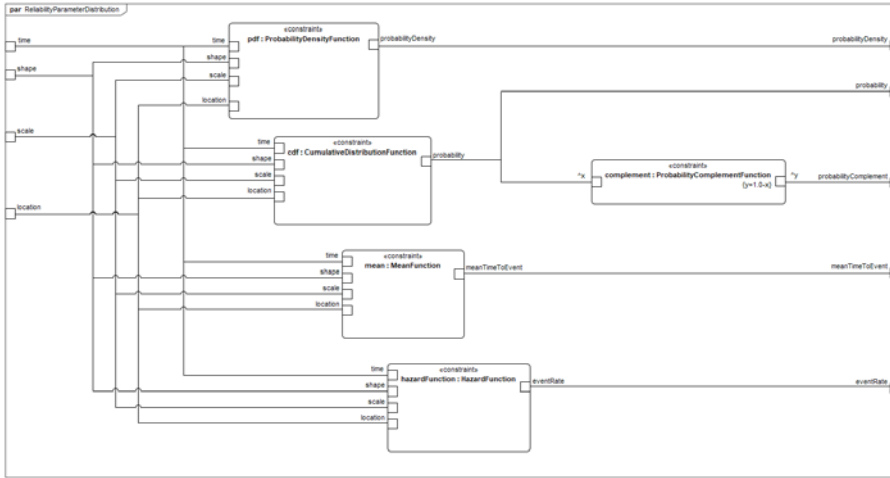


Figure 0.31 - ReliabilityParameterDistribution

### 10.9.3 Methods::RBD::RBD Profile

#### View Methods::RBD::RBD Profile::RBD Profile

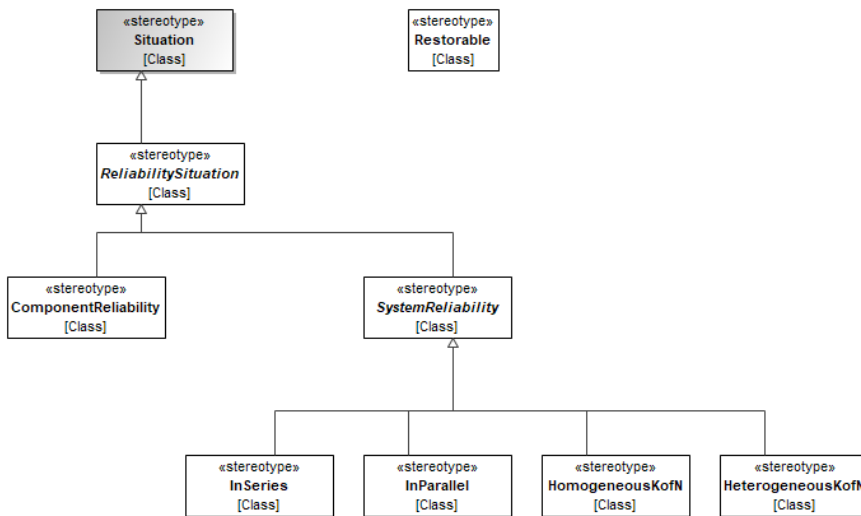


Figure 0.32 - RBD Profile

#### Elements

- [ComponentReliability](#)

- [HeterogeneousKofN](#)
- [HomogeneousKofN](#)
- [InParallel](#)
- [InSeries](#)
- [ReliabilitySituation](#)
- [Restorable](#)
- [Situation](#)
- [SystemReliability](#)

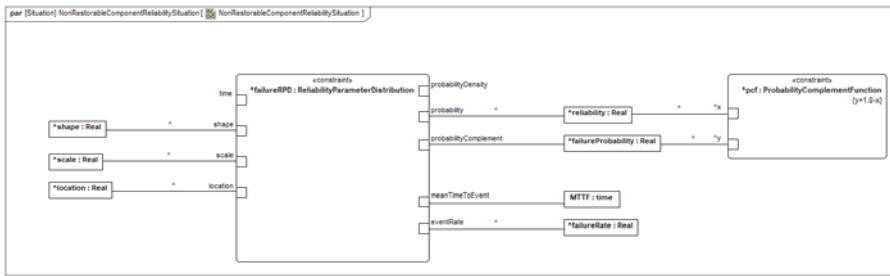


Figure 0.33 - NonRestorableComponentReliabilitySituation

**View Methods::RBD::RBD**  
**Library::RestorableComponentReliabilitySituation::RestorableComponentReliabilitySituation**

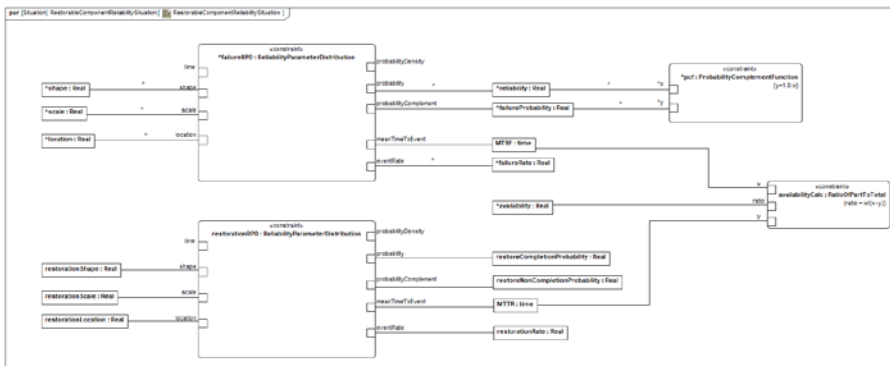


Figure 0.34 - RestorableComponentReliabilitySituation

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