



# PIM and PSM for Smart Antenna Specification

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## **Preface**

## **About the Object Management Group**

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Founded in 1989, the Object Management Group, Inc. (OMG) is an open membership, not-for-profit computer industry standards consortium that produces and maintains computer industry specifications for interoperable, portable and reusable enterprise applications in distributed, heterogeneous environments. Membership includes Information Technology vendors, end users, government agencies and academia.

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- CWM
- Profile specifications.

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- CORBA/IIOP
- IDL/Language Mappings
- Specialized CORBA specifications
- CORBA Component Model (CCM).

### **Platform Specific Model and Interface Specifications**

- CORBAservices
- CORBAfacilities
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Times/Times New Roman - 10 pt.: Standard body text

Helvetica/Arial - 10 pt. Bold: OMG Interface Definition Language (OMG IDL) and syntax elements.

Courier - 10 pt. Bold: Programming language elements.

Helvetica/Arial - 10 pt: Exceptions

**Note** – Terms that appear in *italics* are defined in the glossary. Italic text also represents the name of a document, specification, or other publication.

### Issues

The reader is encouraged to report any technical or editing issues/problems with this specification to <a href="http://www.omg.org/technology/agreement.htm">http://www.omg.org/technology/agreement.htm</a>.

## 1 Scope

This Specification responds to the requirements set by the "Request for Proposals of PIM and PSM for Smart Antenna" (sbc/06-12-10) of a smart antenna subsystem that can be utilized to expand a single antenna system to an array antenna system.

The Smart Antenna specification is physically partitioned into three major chapters: UML Profile for Smart Antenna (SA), SA PIM, and SA PSM. UML Profile for SA defines a language for modeling a smart antenna system by expanding the UML language.

SA PIM provides a set of interfaces for interfacing with the signal processing module, RF module, and controller module. SA PSM provides a rule for transforming the elements of the profile and SA PIM into the platform specific model for CORBA IDL and XML.

The SA specification is related to "Communication Channel and Equipment Specification (formal/07-03-02)" volume in such a way that stereotypes and classes that have not been commented in the SA specification are defined in it.

## 2 Conformance

There are two kinds of conformance with respect to the SA profile: conformance on the part of an SA model and conformance on the part of an MDA tool.

## 2.1 Conformance by a Model of a Specific Application

A UML model of a specific SA either conforms to the SA profile or it does not. Such a UML model conforms to the SA profile if it satisfies all the constraints imposed by the profile package.

## 2.2 Conformance by a Tool

### 2.2.1 Definition of Terms for Discussion of Tool Conformance

To support the discussion of conformance by a MDA tool, we define two terms: "identified subset of UML 2.0" and "all constructs defined by the profile." The identified subset of UML 2.0 for the profile is the set of packages contained in the UML 2.0 Superstructure specification Part 1 (Structure). Part 1 includes the following packages and the transitive closure of all packages contained by these packages and of all packages upon which these packages depend:

- Classes
- · Composite Structures
- · Components
- · Deployments

Here after we sometimes use the abbreviated term identified subset to refer to the identified subset of UML 2.0. The term all constructs defined by the profile is defined to mean all constructs that are part of the package's identified subset of UML 2.0, plus all extensions to that subset that the profile defines. Thus this term includes UML constructs that are part of the identified subset but that are not extended by the profile.

### 2.2.2 Categories of Tool Conformance

A tool is considered to be a conformant simple modeling tool for the communication channel profile if it does both of the following:

- Supports expression of all the constructs defined by the profile, via UML 2.0 notation.
- Supports the UML 2.0 XMI exchange mechanism for the identified subset and for UML 2.0 profiles.

A tool is considered to be a conformant CORBA/XML-based forward engineering tool for the profile if it does the following:

- Supports the PIM-to-PSM Mapping defined in Chapter 9.
- Produces comm channel manager components PSMs that are conformant to the behavior defined in the PIM.

Alternately, if a tool only produces a component skeleton, the skeleton must not make it impossible for a full component based on the skeleton to qualify as a conformant component – in other words, the skeleton must be able to form the basis of a conformant component.

A forward engineering tool that targets a platform technology other than CORBA/XML can legitimately claim a degree of conformance to the communication channel profile and PIM derived from the Profile if it conforms to the PIM-to-PSM Mapping and produces components PSMs that are conformant components to the behavior in defined in the PIM, or produces component skeletons that can form the basis of conformant components. In practice this requires the definition of an alternate PIM-PSM mapping.

A forward engineering tool of this nature for the platform "X" is considered to be a conformant X-Based forward engineering tool for the profile.

## 2.3 Conformance on the part of a Component PSM

The interfaces and components as defined in sections 7 and 8 of this specification are not required to be used for a given platform or application. A platform or application uses the interfaces and component definitions that meet their needs. Conformance is at the level of usage as follows:

- A PSM implementation (no matter what language) of an interface defined in this specification needs to be conformant to the interface definition as described in the specification.
- A PSM implementation (no matter what language) of a component defined in this specification needs to be conformant to the component definition (ports, interfaces realized, properties, etc.) as described in the specification.

A component is considered to be a conformant for CORBA/XML platform if it does all of the following:

- Implements the CORBA interfaces that the component PSM defines
- Implements the XML serialization formats that the component PSM defines.
- Implements the semantics that the component PIM defines.

Note that the component PIM essentially defines the semantics for the CORBA interfaces and XML serialization formats. The semantics for a CORBA interface defined in the component PSM are defined by the semantics of the corresponding element(s) in the component PIM. It is possible to deduce the corresponding elements in the PIM for such a CORBA interface by reversing the PIM-PSM Mapping.

## 3 References

### 3.1 Normative References

### 3.1.1 UML and Profile Specifications

### 3.1.1.1 UML Language Specification

Unified Modeling Language (UML) Superstructure Specification Version 2.1.2 Formal OMG Specification, document number: formal/2007-11-02 The Object Management Group, November 2007 [http://www.omg.org]

Unified Modeling Language (UML) Infrastructure Specification Version 2.1.2 Formal OMG Specification, document number: formal/2007-11-04 The Object Management Group, November 2007 [http://www.omg.org]

### 3.1.1.2 OCL Language Specification

Object Constraint Language (OCL) Specification Version 2.0 Formal OMG Specification, document number: formal/2006-05-01 The Object Management Group, May 2006 [http://www.omg.org]

### 3.1.1.3 UML Profile for CORBA Specification

UML Profile for CORBA Specification Version 1.0 Formal OMG Specification, document number: formal/2002-04-01 The Object Management Group, April 2002 [http://www.omg.org]

### 3.1.1.4 MOF 2.0/XMI Mapping Specification

Meta Object Facility (MOF) 2.0 XMI Mapping Specification, Version 2.1.1 Formal OMG Specification, document number: formal/2007-12-01 The Object Management Group, December 2007 [http://www.omg.org]

### 3.1.2 CORBA Core Specifications

### 3.1.2.1 CORBA Specification

Common Object Request Broker (CORBA/IIOP), Version 3.1 Formal OMG Specification, document number: formal/2007-12-01 The Object Management Group, December 2007 [http://www.omg.org]

### 3.1.2.2 Real-time CORBA Specifications

### 3.1.2.2.1 Real-time CORBA Specifications (Dynamic Scheduling)

Real-time - CORBA Specification (Dynamic Scheduling), Version 2.0 Formal OMG Specification, document number: formal/2003-11-01 The Object Management Group, November 2003 [http://www.omg.org]

### 3.1.2.2.2Real-time CORBA Specifications (Static Scheduling)

Real-time - CORBA Specification (Static Scheduling), Version 1.2 Formal OMG Specification, document number: formal/2005-01-04 The Object Management Group, January 2005 [http://www.omg.org]

### 3.1.2.3 CORBA/e Specification

CORBA/e Specification
Draft Adopted OMG Specification, document number: ptc/06-08-03
The Object Management Group, August 2006
[http://www.omg.org]

### 3.1.3 UML Models

### 3.1.3.1 UML Profile for Communication Channel

UML Profile for Communication Channel XMI File Formal OMG document number: formal/07-03-07 The Object Management Group, March 2007 [http://www.omg.org]

### 3.1.3.2 UML Profile for Component Framework

UML Profile for Component Framework XMI File Formal OMG document number: formal/07-03-07 The Object Management Group, March 2007 [http://www.omg.org]

### 3.1.3.3 Common and Data Link Layer Facilities PIM

Common and Data Link Layer Facilities PIM XMI File Formal OMG document number: formal/07-03-07 The Object Management Group, March 2007 [http://www.omg.org]

### 3.2 Non-normative References

### 3.2.1 Common and Data Link Layer Facilities Specification, v1.0

Common and Data Link Layer Facilities Specification Formal OMG document number: formal/2007-03-05 The Object Management Group, March 2007 [http://www.omg.org]

### 3.2.2 UML Profile for Component Framework Specification, v1.0

Component Framework Specification Formal OMG document number: formal/2007-03-05 The Object Management Group, March 2007 [http://www.omg.org]

### 3.2.3 Communication Channel and Equipment Specification, v1.0

Communication Channel and Equipment Specification Formal OMG document number: formal/2007-03-02 The Object Management Group, March 2007 [http://www.omg.org]

## 4 Terms and Definitions

For the purposes of this document, the following terms and definitions apply.

### Common Object Request Broker Architecture (CORBA)

An OMG distributed computing platform specification that is independent of implementation languages.

### Component

A component can always be considered an autonomous unit within a system or subsystem. It has one or more ports, and its internals are hidden and inaccessible other than as provided by its interfaces. A component represents a modular part of a system that encapsulates its contents and whose manifestation is replaceable within its environment. A component exposes a set of ports that define the component specification in terms of provided and required interfaces. As such, a component serves as a type, whose conformance is defined by these provided and required interfaces (encompassing both their static as well as dynamic semantics).

### **Facility**

The realization of certain functionality through a set of well defined interfaces.

### Interface Definition Language (IDL)

An OMG and ISO standard language for specifying interfaces and associated data structures.

### Metadata

The Data that represents a model. For example, a UML model; a CORBA object model expressed in IDL; and a relation database schema expressed using CWM.

### Metamodel

A model of models

### Model

A formal specification of the function, structure and/or behavior of an application or system.

### **Model Driven Architecture (MDA)**

An approach to IT system specification that separates the specification of functionality from the specification of the implementation of that functionality on a specific technology platform.

### **Platform**

A set of subsystems/technologies that provide a coherent set of functionality through interfaces and specified usage patterns that any subsystem that depends on the platform can use without concern for the details of how the functionality provided by the platform is implemented.

### Platform Independent Model (PIM)

A model of a subsystem that contains no information specific to the platform, or the technology that is used to realize it.

### Platform Specific Model (PSM)

A model of a subsystem that includes information about the specific technology that is used in the realization of it on a specific platform, and hence possibly contains elements that are specific to the platform.

### Request for Proposal (RFP)

A document requesting OMG members to submit proposals to the OMG's Technology Committee. Such proposals must be received by a certain deadline and are evaluated by the issuing task force.

### **Unified Modeling Language (UML)**

An OMG standard language for specifying the structure and behavior of systems. The standard defines an abstract syntax and a graphical concrete syntax.

### **UML Profile**

A standardized set of extensions and constraints that tailors UML to particular use.

## 5 Symbols and abbreviated terms

| Abbreviation | Definition                                |
|--------------|---|
| CORBA        | Common Object Request Broker Architecture |
| DOA          | Direction Of Arrival                      |
| DSP          | Digital Signal Processor                  |
| FPGA         | Field Programmable Gate Array             |
| GPP          | General Purpose Processor                 |
| I/O          | Input/Output                              |
| IDL          | Interface Definition Language             |
| IIOP         | Internet Inter-ORB Protocol               |
| ISO          | International Standards Organization      |
| N/A          | Not Applicable                            |
| OMG          | Object Management Group                   |
| ORB          | Object Request Broker                     |
| OS           | Operating System                          |
| PIM          | Platform Independent Model                |
| PSM          | Platform Specific Model                   |
| RF           | Radio Frequency                           |
| SA           | Smart Antenna                             |
| SDR          | Software Defined Radio                    |
| SWRadio      | Software Radio Components                 |
| UML          | Unified Modeling Language                 |
| XML          | eXtensible Markup Language                |

## 6 Additional Information

## 6.1 Changes to Adopted OMG Specifications

The specifications contained in this document require no changes to adopted OMG specifications.

## 6.2 Guide to this Specification

This specification consists of three major parts, contained in the following chapters 7 to 9.

• Chapter 7 defines the modeling language used in this specification in form of a UML profile for smart antenna components.

- Chapter 8 contains the Smart Anatenna Facilities Platform Independent Model (PIM). The UML language defined in Chapter 7 is used to specify this PIM.
- In chapter 9, the mapping process from the Platform Independent Model (PIM) to a Platform Specific Model (PSM) is described.

## 6.3 Acknowledgements

The following organizations (listed in alphabetical order) contributed to this specification:

- BAE Systems
- Hanyang University
- L-3 Communications
- MITRE
- PrismTech
- Raytheon
- SDR Forum
- Virginia Tech University

## 6.4 Security and Regulatory

There are two subjects that are not included herein: Security and Regulatory. These subjects impact the broader software radio (and other device-bound) topics (sensors, robotics, etc). As such, this document will, in a future release, address a specialization of the general solution adopted by the broader security and regulatory standardization community.

Therefore the following sections apply:

### 6.4.1 Security

This architecture document does not include the functionality for security regarding certification of the source code or over the air delivery of new characteristics for the Smart Antenna or security functional protection mechanisms. The addition of such mechanisms is not expected to alter the architecture defined herein.

### 6.4.2 Regulatory

This architecture document does not include the functionality for managing regulatory requirements for the Smart Antenna. The Smart Antenna herein described functionality could most likely require the addition of finer control and explicit regulatory controls. The addition of such controls is not expected to alter the architecture defined herein; although finer power/bandwidth/ERP may be required to meet regulations.

## 6.5 Smart Antenna System

A Smart antenna is an antenna array system that is aided by a processing system that processes the signals received by the array or transmitted by the array using suitable array algorithms to improve wireless system performance. An antenna array consists of a set of distributed antenna elements (dipoles, monopoles or directional antenna elements) arranged in certain geometry (e.g., linear, circular or rectangular grid) where the spacing between the elements can vary. The signals collected by individual elements are coherently combined in a manner that increases the desired signal strength and reduces the interference from other signals. A smart antenna can be viewed as a combination of antenna elements, using

some form of RF, IF or baseband array combination, that transmit or receive RF signals using "smart" algorithms. A software defined smart antenna is a smart antenna in which certain operating characteristics, such as the field of regard, frequency of operation, access mode, or transmit/receive waveforms can be altered by firmware or software download after its manufacture.

### 6.6 Classification of Smart Antennas

Based on the signal processing technique followed at the baseband output of the antenna array, smart antennas can be grouped into four basic types based on: 1) Beamforming 2) Space time equalization 3) Diversity combining 4) Multiple input multiple output(MIMO) processing.

### 6.6.1 Beamforming

Through Beamforming, a smart antenna algorithm can receive predominantly from a desired direction (direction of the desired source) compared to some undesired direction (direction of interfering sources). This implies that the digital processing has the ability to shape the radiation pattern for both reception and transmission and to adaptively steer beams in the direction of the desired signals and put nulls in the direction of the interfering signals. This enables low co-channel interference and large antenna gain to the desired signal. Beamforming systems can be implemented in two ways; fixed beamforming systems or fully adaptive systems. A fixed beamforming system has a beamforming network(BFN) followed by RF switches which operate in the RF/analog domain. The switches are controlled by a control logic which selects a particular beam. Here the processing required is minimal as the control logic has to choose one of the predetermined set of weights to select a beam. In adaptive beamforming, the antenna gains or weights are chosen adaptively through running array algorithms in the digital domain.

### 6.6.2 Diversity Combining

A major limiting factor in wireless communication is multipath fading where the amplitude of the received signal fluctuates over time. The occurrence of a deep fade where the signal amplitude becomes very small can impair the communications link for a conventional or a single antenna system. When multiple antennas are used it becomes less likely that two or more antennas undergo deep fades at the same time. This diversity in the received signal, for the same transmitted information, is exploited by smart antenna processing schemes. Many simple algorithms, such as maximal ratio combining, equal gain combining, and selection diversity have been developed to take advantage of using antenna arrays to exploit diversity reception in wireless systems. These algorithms weight the received signal similar to beamforming but based on a different criterion used in the algorithm.

### 6.6.3 Space-Time Equalization

The preceding two techniques usually assume that the signal of interest is a narrowband signal compared to the coherence bandwidth of the channel and is thus subjected to a flat fading across the bandwidth of the signal. Multipath fading in wireless communication can also introduce a frequency distortion to the received signal. By means of a temporal processing for each antenna element and a spatial combining of the temporally processed received signals, a frequency-selective fading introduced by the frequency distortion described above can significantly be mitigated.

### 6.6.4 Multiple Input Multiple Output (MIMO)

As the name suggests this scheme requires array processing at the transmitter and receiver. There are two different types of MIMO schemes: one uses spatial multiplexing to enhance data rate for a given bandwidth (thus, the spectral efficiency) and the other uses space time coding using diversity combining techniques to combat fading. In the multiplexing scheme, data is serial to parallel converted and transmitted simultaneously over multiple antenna elements. The receiver also uses multiple antenna elements to receive the signal and applies a maximum likelihood (ML) algorithm to retrieve the

simultaneously transmitted symbols. One key assumption in this case is that the propagation environment has to provide rich scattering; in other words, the propagation channel has to include a large number of scattering objects that will generate independent fading at the antenna elements. In the case of space-time coding, symbols to be transmitted are coded over multiple antennas and symbol time durations in such a way that the receiver can easily regenerate the transmitted signals by doing linear processing on a received signal. The space-time codes rely on the orthogonality present in the coded symbols for proper detection, and additionally they require the fading to be independent between the antenna elements for best performance results.

## 7 UML Profile for Smart Antenna

This section defines the UML Profile for a Smart Antenna only. The set of stereotypes and types that are not described in this section are defined in UML Profile for SWRadio components.

## 7.1 Types

- Complex (real: Float, imag: Float)
  Complex data type denote a general complex number.
- ComplexSequence ComplexSequence is an unbounded sequence of Complex.

## 7.2 CommEquipment for Smart Antenna

### 7.2.1 ArrayAntenna

### **Description**

The ArrayAntenna stereotype, shown in Figure 7.1, represents an antenna array which consists of multiple antenna elements. The ArrayAntenna class shall have one or more AntennaElements.

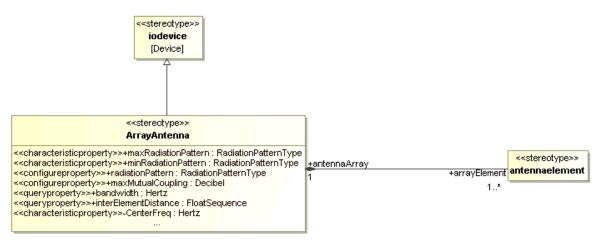


Figure 7.1 - ArrayAntenna Stereotype

#### **Attributes**

• <<characteristicproperty>>maxRadiationPattern: RadiationPatternType
The maxRadiationPattern attribute indicates the maximum radiation pattern that the device is able to achieve.

- <<characteristicproperty>>minRadiationPattern: RadiationPatternType
  The minRadiationPattern attribute indicates the minimum radiation pattern that the device is able to achieve.
- <<configureproperty>>radiationPattern: RadiationPatternType
  The radiationPattern attribute represents the current radiation pattern configured in the device.
- <<characteristicproperty>>type: ArrayAntennaType The type attribute indicates the physical type of the array antenna
- <<configureproperty>>maxMutualCoupling: Decibel
  The maxMutualCoupling is the maximum mutual coupling value between antenna elements.
- <<characteristicproperty>>bandwidth: Hertz
  The bandwidth attribute indicates the bandwidth of the physical array antenna.
- <<characteristicproperty>>interElementDistance: FloatSequence
  The interElementDistance attribute represents the physical distances between all the pairs of adjacent antenna elements in meter.
- <<characteristicproperty>>CenterFreq: Hertz
  The CenterFreq attribute represents the center of the operating frequency of the array antenna.

### M1 Associations

• arrayElemnt: AntennaElement [1..\*]
The individual radiating element object of the ArrayAntenna.

### Constraint

An ArrayAntenna shall have at least one AnalogInputPort or one AnalogOutputPort.

## 8 Platform Independent Model (PIM)

The SA PIM provides interfaces used to configure and control a Smart Antenna Subsystem. In order to specify a SA PSM, we have to first define a standard PIM because a SA specification should be valid regardless of platform types. The SA Facilities has a dependency on the Communication Channel and Equipment Physical Layer Facilities as shown in Figure 8.1. The SA PIM consists of three facilities each of which has been defined in accordance with their functions. These three facilities operate in conjunction with each other to define the PIM for Smart Antenna.

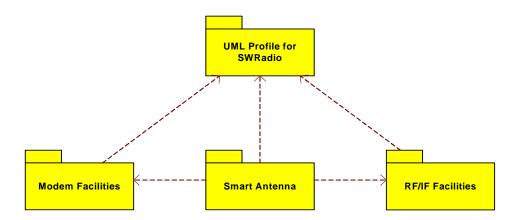


Figure 8.1 - Package Diagram

Three facilities are used to control the entire Smart Antenna Subsystem:

- Control Facilities
- Synchronization Facilities
- Algorithm Facilities

Figure 8.2 illustrates the relation of the three facilities of SA. The Control Facilities, which include SAControl component, RFControl interface, SynchronizationControl interface, and AlgorithmControl interface, are used to control all algorithm operations performed in the digital signal processing parts and RF/IF operations such as analog to digital or digital to analog conversion. The Synchronization Facilities, which include SASynchronization component, CalibrationComponent component, Calibration interface, SynchronizationComponent component, and Synchronization interface, are used for RF chain calibration and symbol (or frame) synchronization. The CalibrationComponent component processes signals fed by the RFIFComponent component and the SynchronizationComponent component processes signals fed by the ModemComponent component. The Algorithm Facilities, which include the SAAlgorithm component, the Algorithm components, and interfaces are used to execute all the algorithms that are needed for the Smart Antenna System to provide improved performance compared to Single Antenna System. The Algorithm components include BeamformingComponent, STCComponent, Spatial Multiplexing Component, DOAEstimation Component, and ChannelEstimationComponent respectively. The interfaces consist of Beamforming, SpaceTimeCoding, SpatialMultiplexing, DOAEstimation, and ChannelEstimation. Algorithm components process signals fed by the ModemComponent component of the Communication Channel and Equipment of the SWRadio components specification (refer to Section 3.2.3). The Smart Antenna Subsystem shall implement a single SAControl component and one or more Algorithm component(s). More detailed explanations about interfaces among facilities in the SA are provided in the following sections.

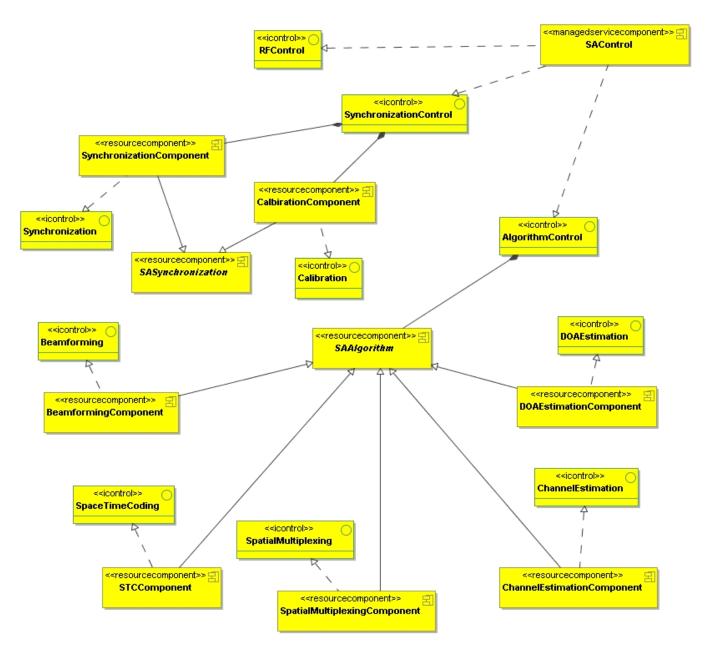


Figure 8.2 - SA Overview

### 8.1 Control Facilities

In this section, each function and interface provided by the Control Facilities is described. Figure 4 illustrates Control Facilities that include SAControl component, SynchronizationControl interface, AlgorithmControl interface, and RFControl interface. It can be observed from Figure 8.3 that RFControl interface, SynchronizationControl interface, and AlgorithmControl interface shall be realized by SAControl

component, in order for SAControl component to control RFIFComponent component, SASynchronization component, and SAAlgorithm component, respectively, according to the functions to be performed in the SAControl component.

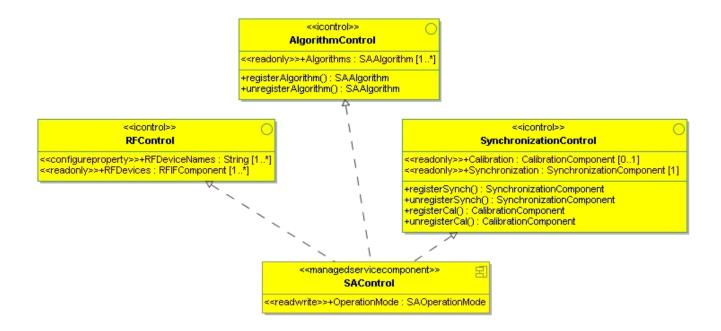


Figure 8.3 - Control Facilities

### 8.1.1 SAControl

### **Description**

The SAControl component takes on the definition as described in the UML Profile for Component Framework::Infrastructure::Service in addition to the realization of RFControl interface, AlgorithmControl interface, and SynchronizationControl interface. The SAControl component is used to control the entire Smart Antenna Subsystem.

### **Semantics**

The SAControl's operational state shall be based upon the operational state of its Device components. The SAControl's usage state shall be IDLE when all of its Device components are IDLE. The SAControl's usage state becomes ACTIVE when any of its Device components is not IDLE. The SAControl's usage state shall be BUSY when all of its Device components are not IDLE. If the SAControl's administrative state is SHUTTING\_DOWN or LOCKED, then its Device components shall be unavailable for application instantiation.

### **Attributes**

<<readwrite>>OperationMode: SAOperationMode
 The OperationMode attribute the operation mode of the Smart Antenna Subsystem. The operation mode shall be
 one of three modes, TRANSMIT, RECEIVE, and COMBINATION. This attribute is only used when the SAControl's
 state is ACTIVE.

### **Types and Exceptions**

• <<enumerationproperty>>SAOperationMode ( TRANSMIT, RECIEVE, COMBINATION ) The SAOperationMode defines the operation mode of the Smart Antenna Subsystem.

TRANSMIT: The Smart Antenna Subsystem operates in transmitting mode.

RECEIVE: The Smart Antenna Subsystem operates in receiving mode.

COMBINATION: The Smart Antenna Subsystem operates in both transmitting and receiving mode.

### 8.1.2 AlgorithmControl

### **Description**

The AlgorithmControl interface is used to control SAAlgorithm components.

### **Attributes**

• <<readonly>>Algorithms: SAAlgorithm [1..\*]
The AlgorithmControl interface shall contain the set of SAAlgorithm components. The SAAlgorithm references are used to control multiple SAAlgorithm components.

### **Operations**

- registerAlgorithm (SAAlgorithm registeringAlgorithm)

  This operation is used to register the SAAlgorithm component with the AlgorithmControl interface. The SAAlgorithm component shall be registered with the AlgorithmControl interface in its initialization process. When the AlgorithmControl interface receives a registerAlgorithm call from the SAAlgorithm component, a reference to the SAAlgorithm component is provided. The AlgorithmControl interface adds the SAAlgorithm reference to its Algorithms attribute.
- unregisterAlgorithm(SAAlgorithm registeringAlgorithm)
  This operation is used to unregister a SAAlgorithm component from the AlgorithmControl interface.

### **Types and Exceptions**

<<exception>>InvalidObjectReference
 The InvalidObjectReference exception is raised when the SAAlgorithm reference received in the registerAlgorithm call is nil or any error is encountered during the unregisterAlgorithm call on the AlgorithmControl interface.

### 8.1.3 SynchronizationControl

### **Description**

The SynchronizationControl interface is used to control the SynchronizationComponent and CalbrationComponent components.

### **Attributes**

- <<readonly>>Synchronization: SynchronizationComponent [1]
  The SynchronizationControl interface shall contain one SynchronizationComponent component. The SynchronizationComponent reference is used to control a SynchronizationComponent component.
- <<readonly>>Calibration: CalibrationComponent [0..1] If the Smart Antenna Subsystem is implemented with beamforming, then the SynchronizationControl shall contain one CalibrationComponent, otherwise the CalibrationComponent may not be required. The CalibrationComponent reference is used to control a CalibrationComponent component.

### **Operations**

- registerSynch (SynchronizationComponent registeringSynch)
  This operation is used to register SynchronizationComponent component with
  SynchronizationControl interface. The SynchronizationComponent component shall be registered
  with SynchronizationControl interface in its initialization process. When the
  SynchronizationControl interface receives a registerSynch call from a SynchronizationComponent
  component, the SynchronizationComponent reference is provided. The SynchronizationControl
  interface adds the SynchronizationComponent reference to the Synchronizations attribute.
- unregisterSynch(SynchronizationComponent registeringSynch)
  This operation is used to unregister a SynchronizationComponent component from the SynchronizationControl interface.
- registerCal(CalibrationComponent registeringCal)
  This operation is used to register CalibrationComponent component with SynchronizationControl interface. CalibrationComponent component shall be registered with SynchronizationControl interface in its initialization process. When the SynchronizationControl interface receives a registerSynch call from a CalibrationComponent component, the CalibrationComponent reference is provided. The SynchronizationControl interface adds the CalibrationComponent reference to the Synchronizations attribute.
- unregisterCal(CalibrationComponent registeringCal)
  This operation is used to unregister a CalibrationComponent component from the
  SynchronizationControl interface.

### **Types and Exceptions**

<<exception>>InvalidSynchObjectReference
 The InvalidObjectReference exception is raised when the SynchronizationComponent reference received in the registerSynch call is nil or any error is encountered during the unregisterSynch call on the SynchronizationControl interface.

<<exception>>InvalidCalObjectReference
 The InvalidCalObjectReference exception is raised when the CalibrationComponent reference received in the registerSynch call is nil or any error is encountered during the unregisterSynch call on the SynchronizationControl interface.

### 8.1.4 RFControl

### Description

The RFControl interface is used to control RFIFComponent components.

### **Attributes**

- <<readonly>>>RFDevices: RFIFComponent [1..\*]
  The RFControl interface shall contain the set of RFIFComponent components. The RFIFComponent references are used to control multiple RFIFComponent components.
- <<configureproperty>>RFDeviceNames: String [1..\*]
   This attribute represents the name of RFIFComponent. To get an RFIFComponent instance, RFControl interface requests a reference of the component from the NamingService with the name of the RFIFComponent.
- <<configureproperty>>AntennaCount: UShort
   The AntennaCount attribute represents the number of Antenna elements.

### 8.2 Synchronization Facilities

In this section each function and interface in Synchronization facilities is described. Figure 5 illustrates Synchronization Facilities that include the SASynchronization component, Calibration interface, CalibrationComponent component, SynchronizationComponent component, and Synchronization interface.

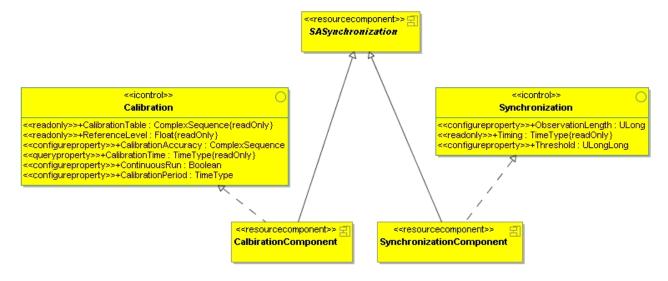


Figure 8.4 - Synchronization Facilities

### 8.2.1 SASynchronization

### **Description**

The SASynchronization component is an abstract component from which the CalibrationComponent component and SynchronizationComponent component shall inherit.

### Constraint

The SASynchronization component shall provide one ControlPort and at least one DataControlPort or DataPort.

### 8.2.2 Calibration

### **Description**

The Calibration interface is used to calibrate the entire RF/IF chains of the Smart Antenna System.

#### **Attributes**

- <<readonly>>CalibrationTable: ComplexSequence
  The CalibrationTable attribute represents the output of the Calibration. Each element of the CalibrationTable represents a calibration-output which corresponds to each of the RF/IF chains.
- <<readonly>>ReferenceLevel: Float
   The ReferenceLevel attribute represents the value normalized to a unit power or some non-unit input level.
- <<configureproperty>>ContinuousRun: Boolean
   The ContinuousRun attribute indicates whether or not the calibration is executed continuously.
- <<configureproperty>>CalibrationAccuracy: ComplexSequence
  The CalibrationAccuracy attribute represents the required variance of calibration-output. The required accuracy shall be configured in a ComplexSequence to represent both amplitude and phase.
- <<configureproperty>>CalibrationPeriod: TimeType
  The CalibrationPeriod attribute is used to control the calibration period.
- <<queryproperty>>CalibrationTime: TimeType
   The CalibrationTime attribute return the time required for processing a single calibration using the active settings.

### 8.2.3 CalibrationComponent

### **Description**

The CalibrationComponent component realizes the Calibration interface and extends the SASynchronization component. Calibration is to compensate for amplitude and phase differences of the RF/IF chain associated with each antenna in transmit and receive mode. The problem of calibration has arisen because the amplitude and phase characteristics of the signal path associated with each antenna are different from each other. Especially even if the optimal weight vector is computed from the received signal for uplink, downlink beam-forming can never be

optimized without accurate calibration. In other words, the objective of calibration is to compensate for the mutual coupling effects between antenna array elements as well as for the mismatches of channel amplitude and/or channel phase in Smart Antenna Systems.

### 8.2.4 Synchronization

### Description

The Synchronization interface is used for symbol (or frame) synchronization of the Smart Antenna Subsystem.

#### **Attributes**

- <<configureproperty>>ObservationLength: ULong
  The ObservationLength attribute is used to configure the observation length in samples.
- <<readonly>>Timing: TimeType
   The Timing attribute represents the acquired symbol (or frame) timing.
- <<configureproperty>>Threshold: ULongLong
   The Threshold attribute is used to configure the threshold for signal detection. Since signals in the baseband are represented by complex numbers without unit, the Threshold attribute also has no unit.

### 8.2.5 SynchronizationComponent

### **Description**

The SynchronizationComponent component realizes the Synchronization interface and extends the SASynchronization component. Symbol (or frame) synchronization is a process which detects the symbol (or frame) timing. Synchronization is performed prior to symbol demodulation (or frame decoding) and the smart antenna algorithm operation. To enhance the performance of the Smart Antenna System, accurate symbol (or frame) timing is required. In addition, to guarantee the QoS (Quality of Service) of the initial network access, fast and robust acquisition of the initial access signal shall be provided to the Smart Antenna System.

## 8.3 Algorithm Facilities

In this section each function and interface in the Algorithm facilities is described. Figure 6 illustrates the Algorithm Facilities which include the SAAlgorithm component, Algorithm components, and the interfaces. The Algorithm components are the BeamformingComponent, STCComponent, SpatialMultiplexingComponent, DOAEstimationComponent, and ChannelEstimationComponent. And, the interfaces are the Beamforming interface, SpaceTimeCoding interface, SpatialMultiplexing interface, ChannelEstimation interface, and DOAEstimation interface.

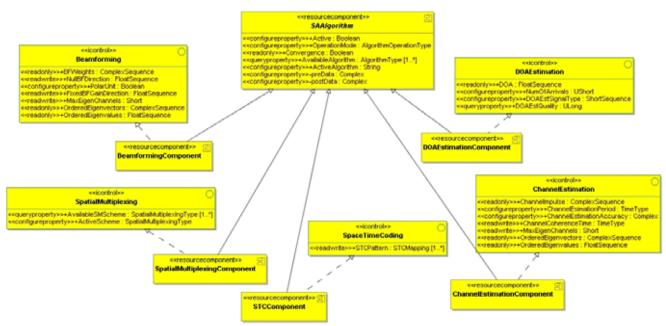


Figure 8.5 - Algorithm Facilities

### 8.3.1 SAAlgorithm

### **Description**

The SAAlgorithm component is an abstract component from which all the components in the Algorithm Facilities shall inherit. In other words, this component provides every interface for controlling all the Algorithm components.

### **Attributes**

- <<configureproperty>>Active: Boolean
  The Active attribute indicates that the SAAlgorithm component is activated.
- <<configureproperty>>OperationType: AlgorithmOperationType
   The OperationType attribute sets an operation type of SAAlgorithm components. The operation type shall be one of the following three types, CONTUINUOUS, SINGLE\_BURST, and REPEATED\_BURST.
- <<readonly>>Convergence: Boolean
   The Convergence attribute indicates whether the algorithm is confident that its link quality is high enough to satisfy the configured QoS.
- <<queryproperty>>AvailableAlgorithm: AlgorithmType[1..\*]
  The AvailableAlgorithm attribute represents a list of the algorithms available for use on the SAalgorithm.
- <<configureproperty>>ActiveAlgorithm: String
  The ActiveAlgorithm attribute either sets or gets the active algorithm.

- <<configureproperty>>preData: Complex
  The preData attribute represents the pre-processing data which are used for calculating the beamforming weight vector. For example, the pre-processing data denote the pre-despreading data for CDMA systems and the pre-FFT data for OFDM(A) systems.
- <<configureproperty>>postData: Complex
   The postData attribute represents the post-processing data which are used for calculating the beamforming weight vector. For example, the post-processing data denote the despread data for CDMA systems and the FFT data for OFDM(A) systems.

### **Types and Exceptions**

<<enumerationproperty>>AlgorithmOperationType ( CONTINUOUS, SINGLE\_BURST, REPEATED BURST )

The AlgorithmOperationType defines data processing operation type.

CONTINUOUS: SAAlgorithm components process input signals continuously.

SINGLE\_BURST: SAAlgorithm components process the single burst input signal.

REPEATED\_BURST: SAAlgorithm components process repetitively the single burst input signal.

• AlgorithmType(Name: String, Delay: TimeType, PowerConsumption: Float, TolerableBandwidth: Hertz)

Name: The name of an algorithm as a String.

Delay: The time required for a single execution.

PowerConsumption: The power consumption for a single algorithm execution.

TolerableBandwidth: The maximum bandwidth that a given algorithm can guarantee its normal operation.

### Constraint

The SAAlgorithm component shall provide one ControlPort and at least one DataControlPort or DataPort.

### 8.3.2 Beamforming

### **Description**

The Beamforming interface is used to control the BeamformingComponent.

### Attributes

- <<readonly>>BFWeights: ComplexSequence
  - The BFWeights attribute weight vectors are computed by the BeamformingComponent. When this attribute is read, the BeamformingComponent computes a new value from the received signals. When this attribute is set up, the BeamformingComponent applies a given vector that provides the desired radiation pattern.
- <<configureproperty>>PolarUnit: Boolean
   The PolarUnit attribute is used to switch between the real/imag mode and the mag/phase mode of the Weights attribute.
- <<readwrite>>NullBFDirection: FloatSequence
   The NullBFDirection attribute is used to specify the directions of the nulls in degrees to block known sources of interference.

- <<readwrite>>FixedBFGainDirection: FloatSequence
   The FixedBFGainDirection attribute is used to specify fixed gains (dB) in fixed directions (degrees) to amplify
   weak signals in known directions.
- <<readwrite>>SideLobeLevel: FloatSequence
   The SideLobeLevel attribute is used to limit the side lobe level in decibel (dB).
- <<readonly>>OrderedEigenvalues: FloatSequence
   The OrderedEigenvalues attribute presents the eigen channel quality metrics used in the
   BeamformingComponent.
- <<readonly>>OrderedEigenvectors: ComplexSequence
  The OrderedEigenvectors attribute presents the eigen channel quality metrics used in the
  BeamformingComponent.
- <<readwrite>>MaxEigenChannels: Short
   The MaxEigenChannels attribute configures maximum number of eigen channels to be used in the
   BeamformingComponent.

### 8.3.3 BeamformingComponent

### **Description**

The BeamformingComponent component extends the SAAlgorithm component and realizes the Beamforming interface. A beamforming algorithm in the BeamformingComponent computes the weight vectors for both RX and TX operations. The weight vectors adaptively steer beams along the direction of desired signals and puts nulls along the direction of interfering signals..

### 8.3.4 SpaceTimeCoding

### **Description**

The SpaceTimeCoding interface is used to control STCComponent.

### **Attributes**

• <<readwrite>>STCPattern: STCMapping[1..\*]
The STCPattern attribute represents the actual definition of the STC mapping. Each input symbol of the STCComponent is mapped to one of the transmit antennas according to the STCMapping.

### **Types and Exceptions**

• STCMapping (NumAnt: UShort, codePattern: ComplexSequence)
NumAnt: Number of transmit antenna.
codePattern: The actual space time code pattern is a ComplexSequence. If the number of transmit antennas (i.e.
NumAnt) is N, the space time codes are represented as an N by N matrix. Each element of the codePattern corresponds
to each element of the matrix in the following manner. The first element of the codePattern corresponds to the first
element of the first column of the matrix. Similarly, the second element of the codePattern is for the second element of
the first column of the matrix. And N+1th element of the codePattern is for the first element of the second column of
the matrix and N+2th element of the codePattern is for the second element of the second column of the matrix. Finally,
N2th element of the codePattern is for the last (Nth) element of the last (Nth) column of the matrix.

### 8.3.5 STCComponent

### Description

The STCComponent component extends the SAAlgorithm component and realizes the SpaceTimeCoding interface. The STCComponent is for Space Time Coding (STC) processing. Space Time Coding (STC) is a method employed to improve the reliability of data transmission in wireless communication systems by using multiple transmit antennas. STCs rely on transmitting multiple, redundant copies of a data stream to the receiver in the hope that at least some of them may survive the physical path between transmission and reception in a good enough state to allow reliable decoding.

### 8.3.6 SpatialMultiplexing

### **Description**

The Spatial Multiplexing interface is used to control the Spatial Multiplexing Component.

### **Attributes**

- <<queryproperty>>AvailableSMScheme: SpatialMultiplexingType[1..\*]
  The AvailableSMScheme attribute represents a list of the spatial multiplexing schemes available for use on the SpatialMultiplexingComponent.
- <<configureproperty>>ActiveSMScheme: SpatialMultiplexingType The ActiveSMScheme attribute either sets or activates the SpatialMultiplexingType.

### **Types and Exceptions**

<<Primitive>>SpatialMultiplexingType
 The SpatialMultiplexingType, a specialization of String, denotes the type of the algorithm used for spatial multiplexing.(e.g.,V-BLAST, D-BLAST, H-BLAST, etc.).

### 8.3.7 SpatialMultiplexingComponent

### Description

The SpatialMultiplexingComponent component extends the SAAlgorithm component and realizes the SpatialMultiplexing interface. The SpatialMultiplexingComponent is for spatial multiplexing. Spatial multiplexing is a transmission technique in MIMO wireless communication that transmits independent and separately encoded data signals from each of the multiple transmit antennas.

### 8.3.8 ChannelEstimation

### **Description**

The ChannelEstimation interface is used to control the ChannelEstimationComponent.

### **Attributes**

- <<readonly>>ChannelImpulse: ComplexSequence
  The ChannelImpulse attribute represents the channel estimation vector that is calculated by the
  ChannelEstimationComponent component.
- <<readwrite>>ChannelCoherenceTime: TimeType
  The ChannelCoherenceTime attribute represents the channel coherence time.
- <<configureproperty>>ChannelEstimationPeriod: TimeType
  The ChannelEstimationPeriod attribute is used to control the channel estimation period. This attribute would be especially important to trade overhead time and processing against the rate of change in the channel due to platform motion, etc.
- <<configureproperty>> ChannelEstimationAccuracy: Complex
  The ChannelEstimationAccuracy attribute represents the required accuracy of the channel estimation.
- <<readonly>>OrderedEigenvalues: FloatSequence
  The OrderedEigenvalues attribute presents the eigen channel quality metrics used in
  ChannelEstimationComponent.
- <<readonly>>OrderedEigenvectors: ComplexSequence
  The OrderedEigenvectors attribute presents the eigen channel quality metrics used in
  ChannelEstimationComponent.
- <<readwrite>>MaxEigenChannels: Short
  The MaxEigenChannels attribute configures the maximum number of eigen channels to be used in ChannelEstimationComponent.

### 8.3.9 ChannelEstimationComponent

### **Description**

The ChannelEstimationComponent component extends the SAAlgorithm component and realizes the ChannelEstimation interface. The Space-time equalization system or diversity combining system is implemented using the ChannelEstimationComponent. Space-time Equalization is a receiving technique which makes use of temporal processing on the signals received from multiple antennas to correct frequency distortion in the received signal path. And, diversity combining is another receiving technique that mitigates the multipath fading effects, which are inherent in pratical wireless networks, by combining the signals of multiple antennas.

### 8.3.10 DOAEstimation

### Description

The DOAEstimation interface is used to control the DOAEstimationComponent.

### **Attributes**

• <<readonly>>DOA: FloatSequence
The DOA attribute represents the direction of arrival (DOA) angle in degree.

- <<configureproperty>>NumOfArrivals: UShort
  The NumOfArrivals specifies the maximum number of DOA estimations for a single signal having multipath.
- <<configureproperty>>DOAEstSignalType: ShortSequence
  The DOAEstimationSignalType attribute specifies the type of the various signals to estimate.
- <<queryproperty>>DOAEstQuality: ULong
  The DOAEstQuality attribute indicates the DOA estimation quality.

## 8.3.11 DOAEstimationComponent

### Description

The DOAEstimationComponent component extends the SAAlgorithm component and realizes the DOAEstimation interface.

## 9 PSM for Smart Antenna

### 9.1 Mapping Rule

This section defines a reference PSM that consists of the normative CORBA interface and the normative XML that are based upon the PIM and UML Profile for Smart Antenna. The PIM to PSM transformation rules are not universal rules for creating \*any\* PSM, but only used for the purpose of this specification. Non-CORBA PSMs may also be fully compliant to this specification as a whole. The rule set for transforming Smart Antenna PIM (UML packages, interfaces, types, and exceptions) to the CORBA interface and the XML is as follows:

- 1. UML interfaces and interface extensions are mapped to CORBA interfaces. The CORBA interface names are without the prefix "I" in the interface name as used in the radio Management PIM Facilities.
- 2. UML attributes with readonly and readwrite map to CORBA attributes in CORBA interfaces.
- 3. UML attributes with configureproperty, queryproperty, and testproperty do not map to CORBA attributes in CORBA interfaces. Instead XML definitions are used that follow the Property types as defined in UML Profile for Component Framework::Application, Device Components::Properties section and UML Profile for Smart Antenna in the Chapter 7.
- 4. UML classes without operations that are not stereotyped and used for type definitions map to CORBA Struct stereotypes in the CORBA interfaces and modules. The parent classes do not get translated into CORBA types, instead the parent class attributes are added to the subclass in the CORBA definition.
- 5. UML <<datatype>> map to CORBA basic types. Primitive types are mapped to CORBA primitive types and primitive sequence types are mapped to CORBA Typedef of primitive sequence types.
- 6. UML exceptions and exception extensions map to CORBA exceptions. There is no specialization of exceptions in CORBA so the (UML Profile for Component Framework::Application and Device Components::BaseTypes) SystemException definition does not appear in the generated CORBA interfaces but all the specialization exceptions of SystemException are in the CORBA interfaces with the same attributes as defined for SystemException.
- 7. UML attributes that have a cardinality of many [\*] map to a CORBA Typedef of sequence types.
- 8. UML operations and <<optional>> operations map to operations in the CORBA interfaces.
- 9. Transformations are only performed for concrete classes, not for template classes. Concrete classes that bind to template classes are used in the PSM.
- 10. For Interfaces that reference a component stereotype for a type, the "component" qualifier is removed from the name. For Example, FileManagerComponent would become FileManager as the type for the parameter or attribute.
- 11. UML attributes with constant stereotype map to CORBA constants in CORBA interfaces.
- 12. Basic types (e.g., Any, Object) map to CORBA types.
- 13. Object references map to the name of CORBA objects.

## 9.2 IDL Mapping

Table 9.1 - IDL Mapping

| PIM Name               | IDL FileName              |
|------------------------|---------------------------|
| SAControl              | DfSWRadioSmartAntenna.idl |
| AlgorithmControl       | DfSWRadioSmartAntenna.idl |
| RFControl              | DfSWRadioSmartAntenna.idl |
| SynchronizationControl | DfSWRadioSmartAntenna.idl |
| Calibration            | DfSWRadioSmartAntenna.idl |
| ChannelEstimation      | DfSWRadioSmartAntenna.idl |
| SAAlgorithmDevice      | DfSWRadioSmartAntenna.idl |
| Beamforming            | DfSWRadioSmartAntenna.idl |
| DOAEstimation          | DfSWRadioSmartAntenna.idl |
| SpaceTimeCoding        | DfSWRadioSmartAntenna.idl |
| SpatialMultiplexing    | DfSWRadioSmartAntenna.idl |
| Synchronization        | DfSWRadioSmartAntenna.idl |

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